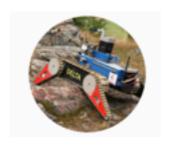
# Learning for vision III Convolutional networks

**Karel Zimmermann** 

http://cmp.felk.cvut.cz/~zimmerk/



Vision for Robotics and Autonomous Systems <a href="https://cyber.felk.cvut.cz/vras/">https://cyber.felk.cvut.cz/vras/</a>



Center for Machine Perception <a href="https://cmp.felk.cvut.cz">https://cmp.felk.cvut.cz</a>



Department for Cybernetics
Faculty of Electrical Engineering
Czech Technical University in Prague

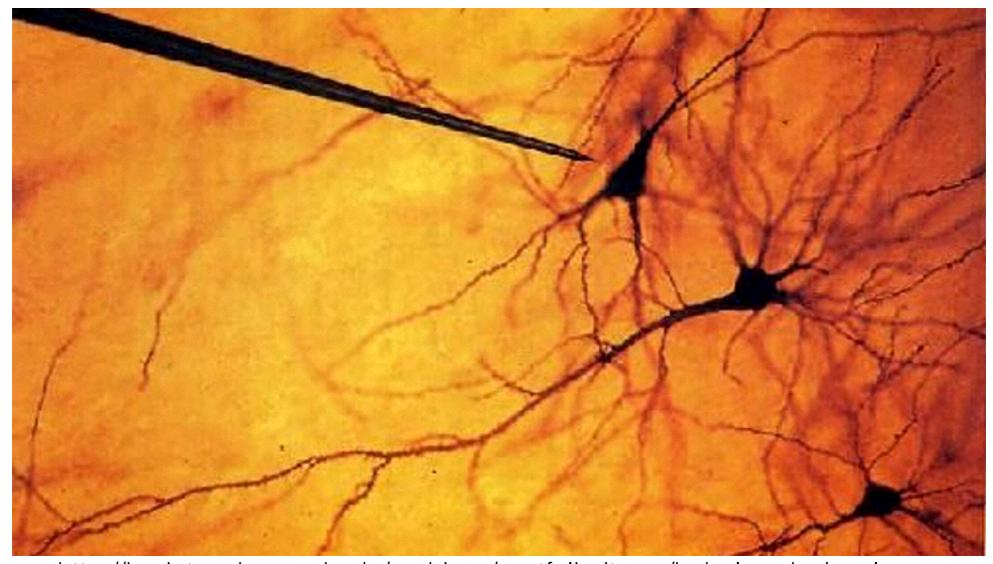


#### Outline

- Avoid overfitting by search for the NN model suitable for image processing [Hubel and Wiesel 1960].
- Feedforward and Backprop in ConvNets.



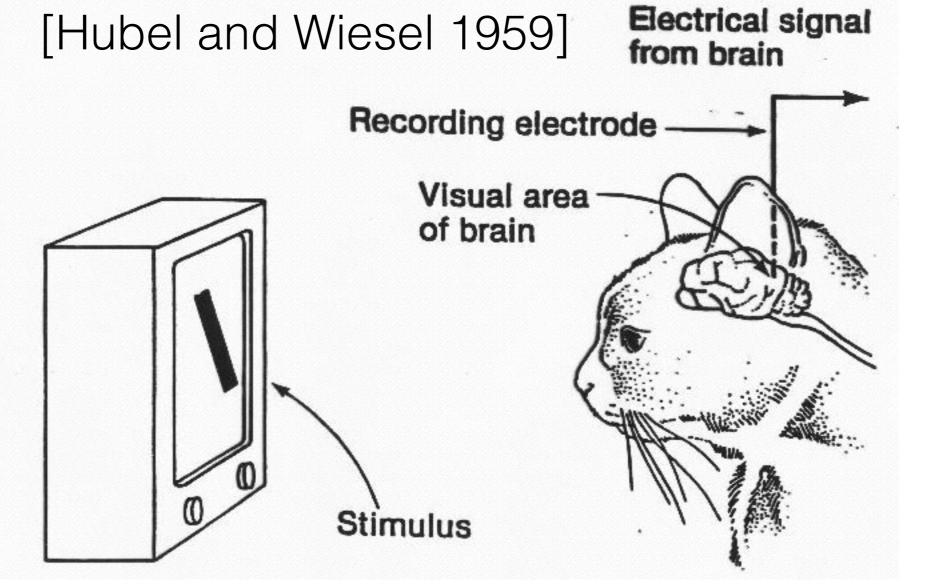
## The Tungsten Electrode [Hubel-Science-1957]



http://braintour.harvard.edu/archives/portfolio-items/hubel-and-wiesel

Device capable to record signal from a single neuron





- Experiment with anaesthetised paralysed cat
- Recording of electrical signal reveals:
  - 1. Nearby neurons process information from nearby visual fields (topographical map).
  - 2. Neurons with similar function organized into columns
  - 3. Neurons are sensitive to edges and its orientation



[Hubel and Wiesel 1960]



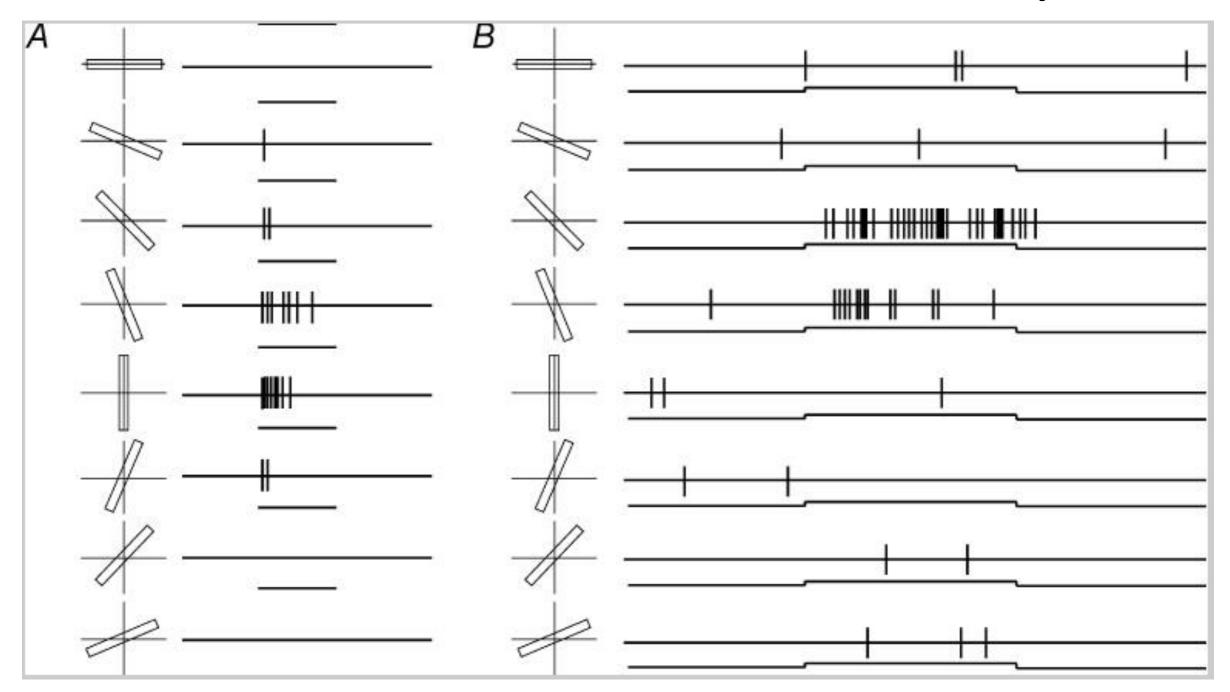
https://knowingneurons.com/2014/10/29/hubel-and-wiesel-the-neural-basis-of-visual-perception/



#### [Hubel and Wiesel 1960]

paralysed cat

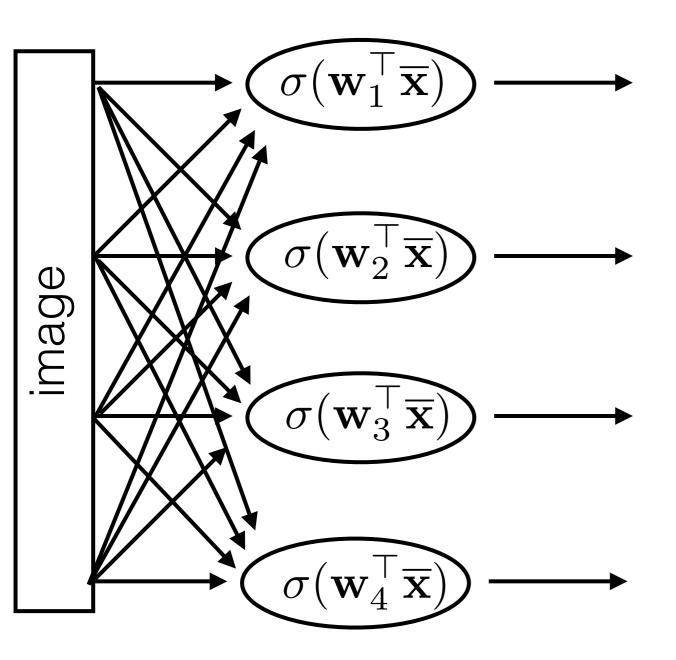
awake monkey



https://knowingneurons.com/2014/10/29/hubel-and-wiesel-the-neural-basis-of-visual-perception/



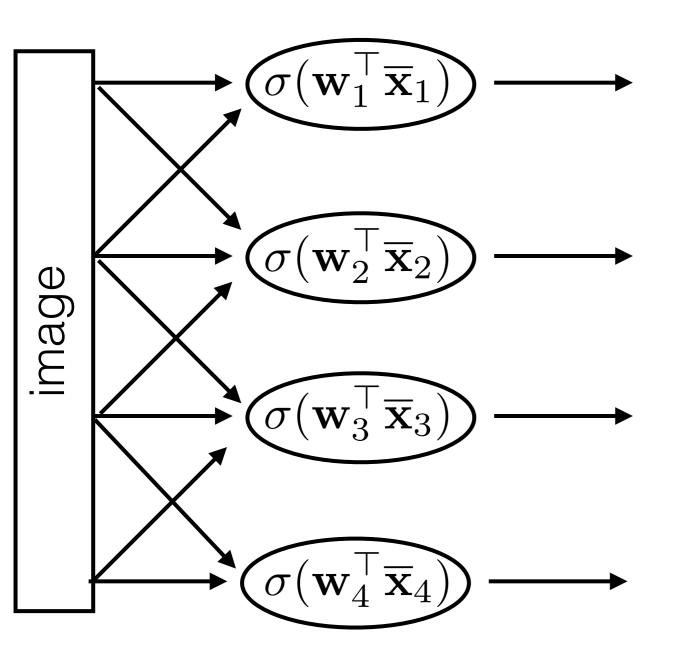
1. Nearby neurons process information from nearby visual field (topographical map).



 Processing of visual information in cortex is not fully connected.

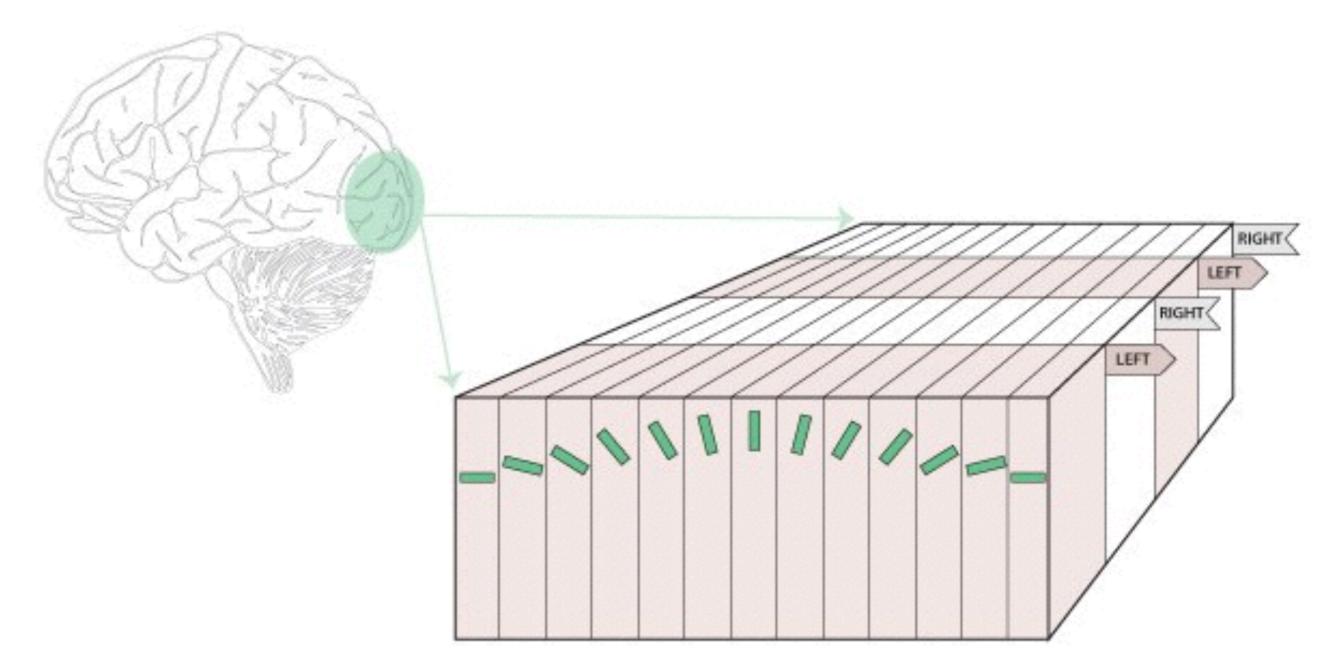


1. Nearby neurons process information from nearby visual field (topographical map).



 What is dimensionality reduction for N-pixel image and n-dimensional spatial neighbourhood?

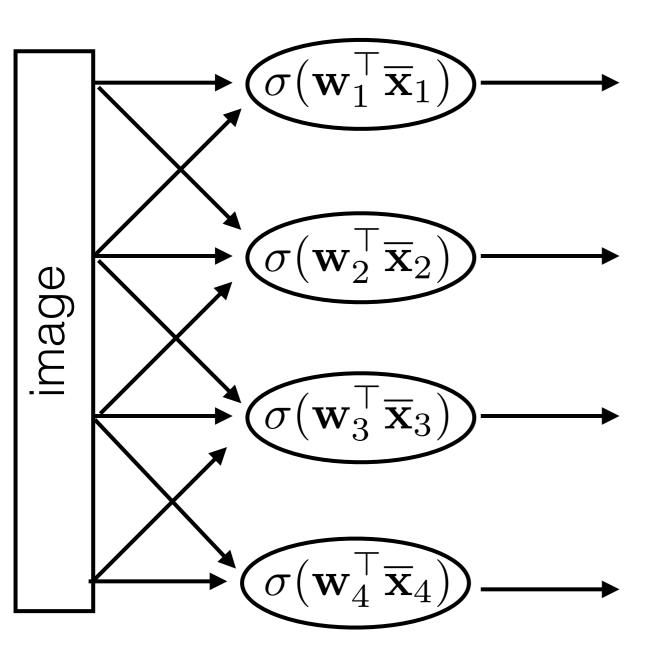




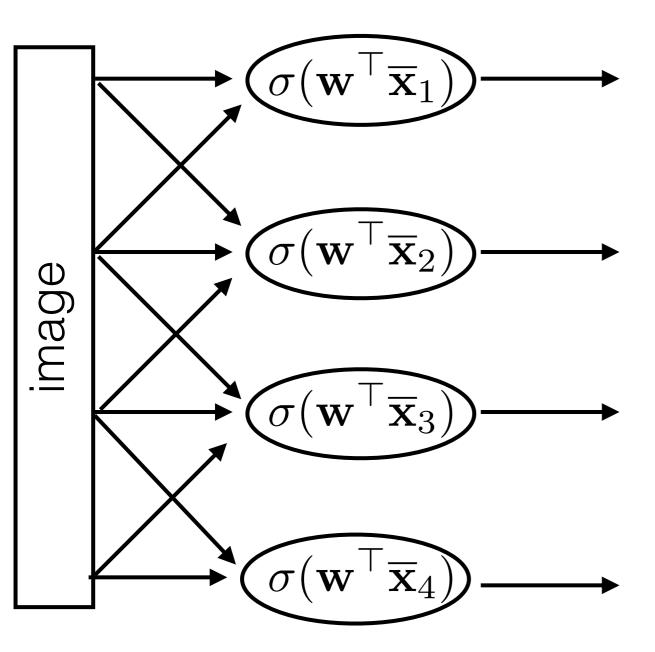
 There are neurons which detect an edge on the left and there are different neurons which detect the same edge on the right

https://knowingneurons.com/2014/10/29/hubel-and-wiesel-the-neural-basis-of-visual-perception/



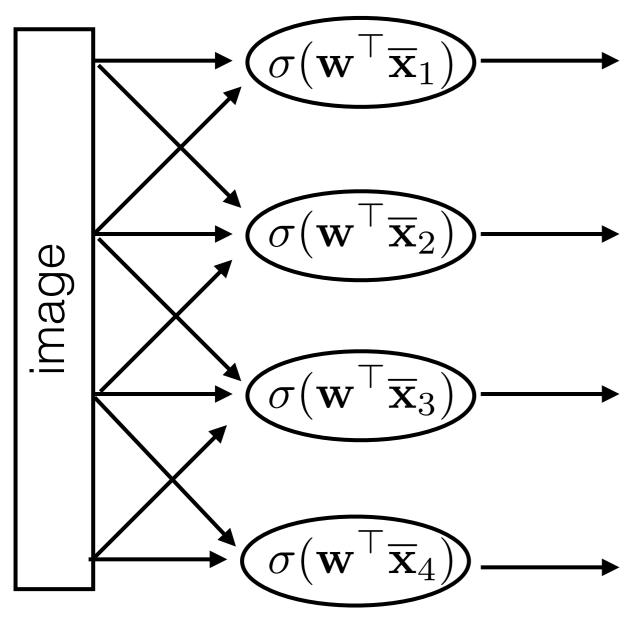




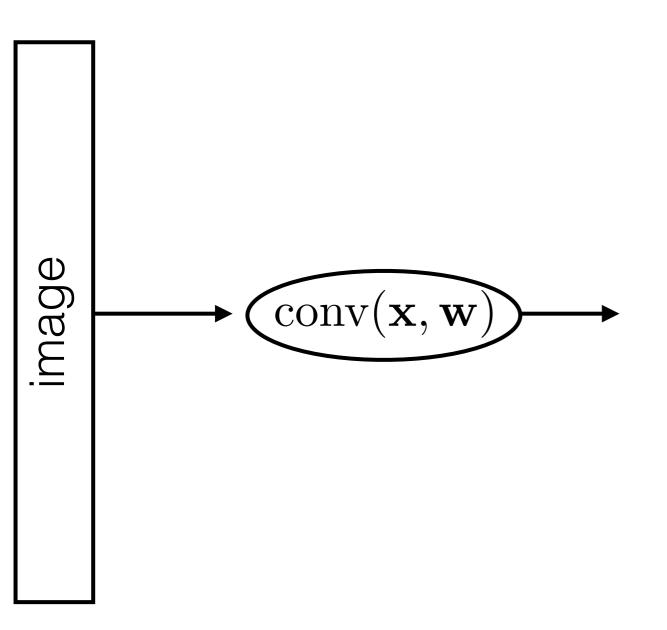


 What is dimensionality reduction for N pixel image and n-dimensional spatial neighbourhood?





- N^2 vs n (it does not depend on the image resolution)
- It corresponds to convolution of image  $\mathbf{x}$  with kernel  $\mathbf{w}$  followed by activation function

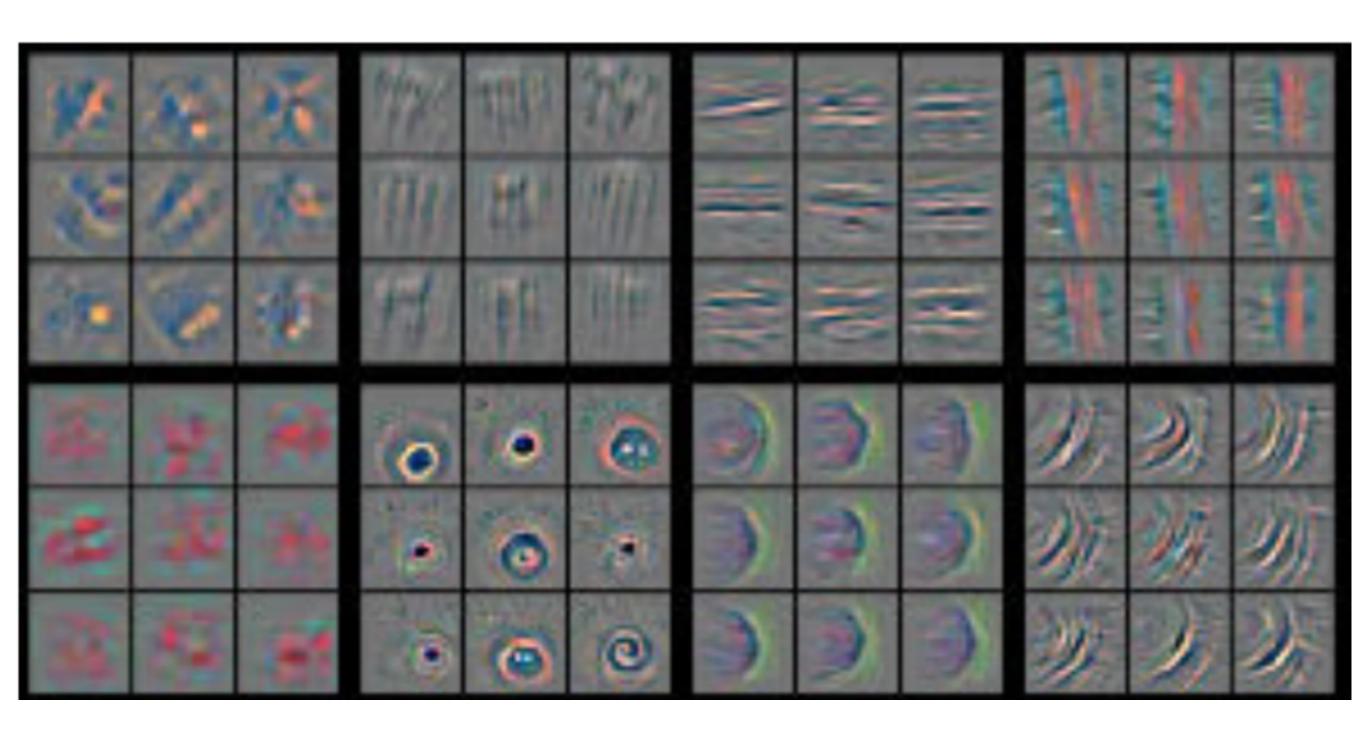


- N^2 vs n (it does not depend on the image resolution)
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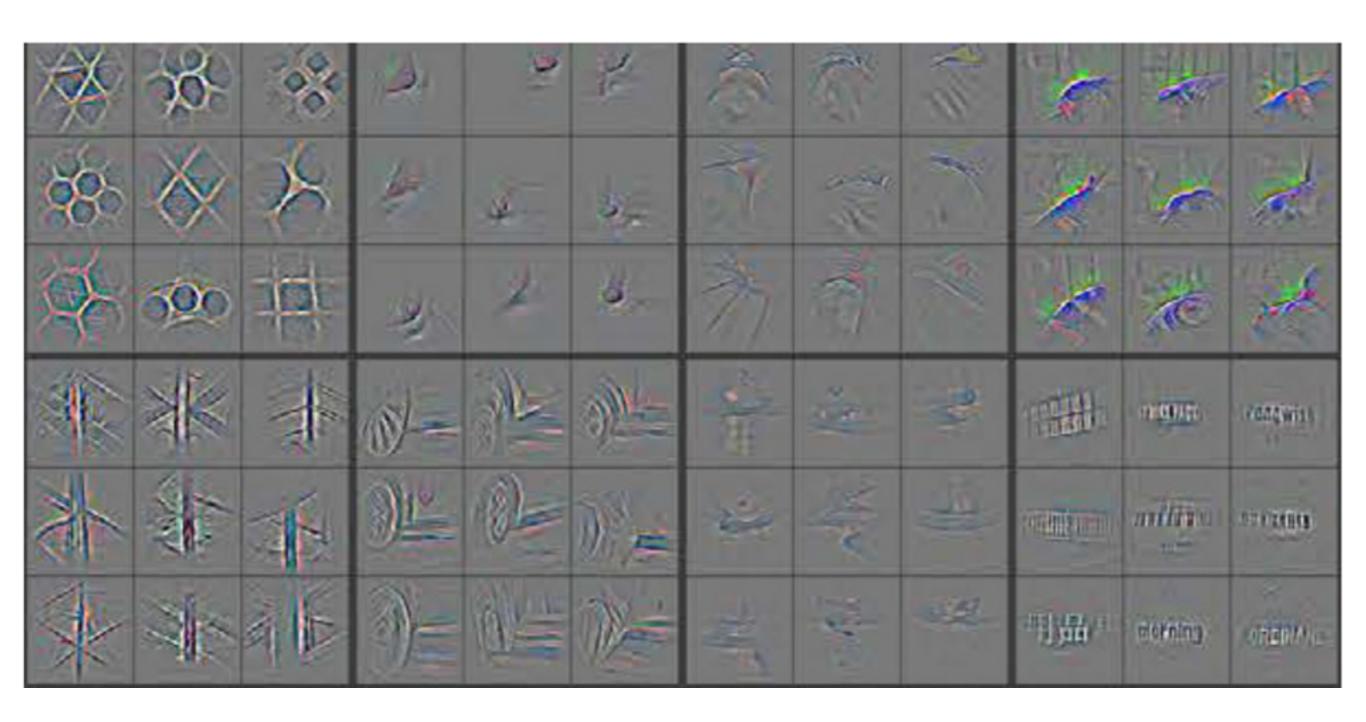


[Zeiler and Fergus, ECCV, 2014]

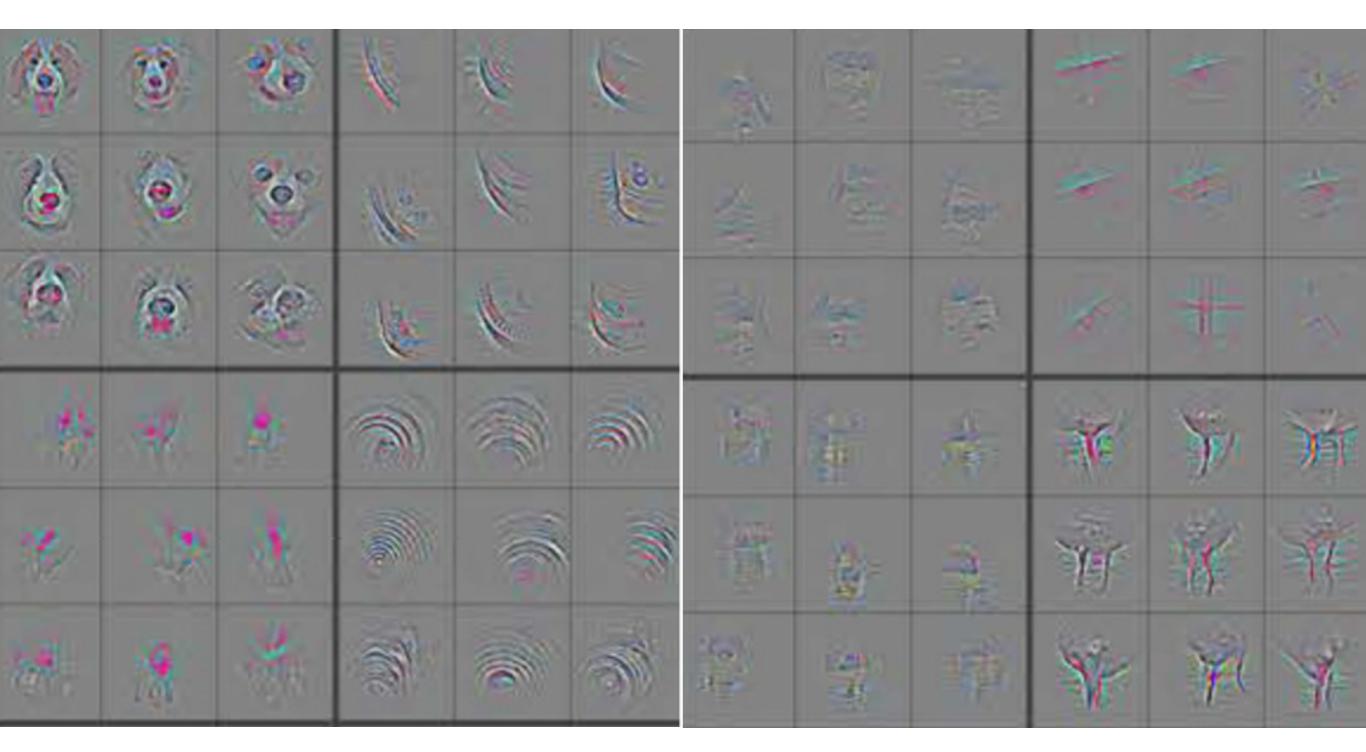




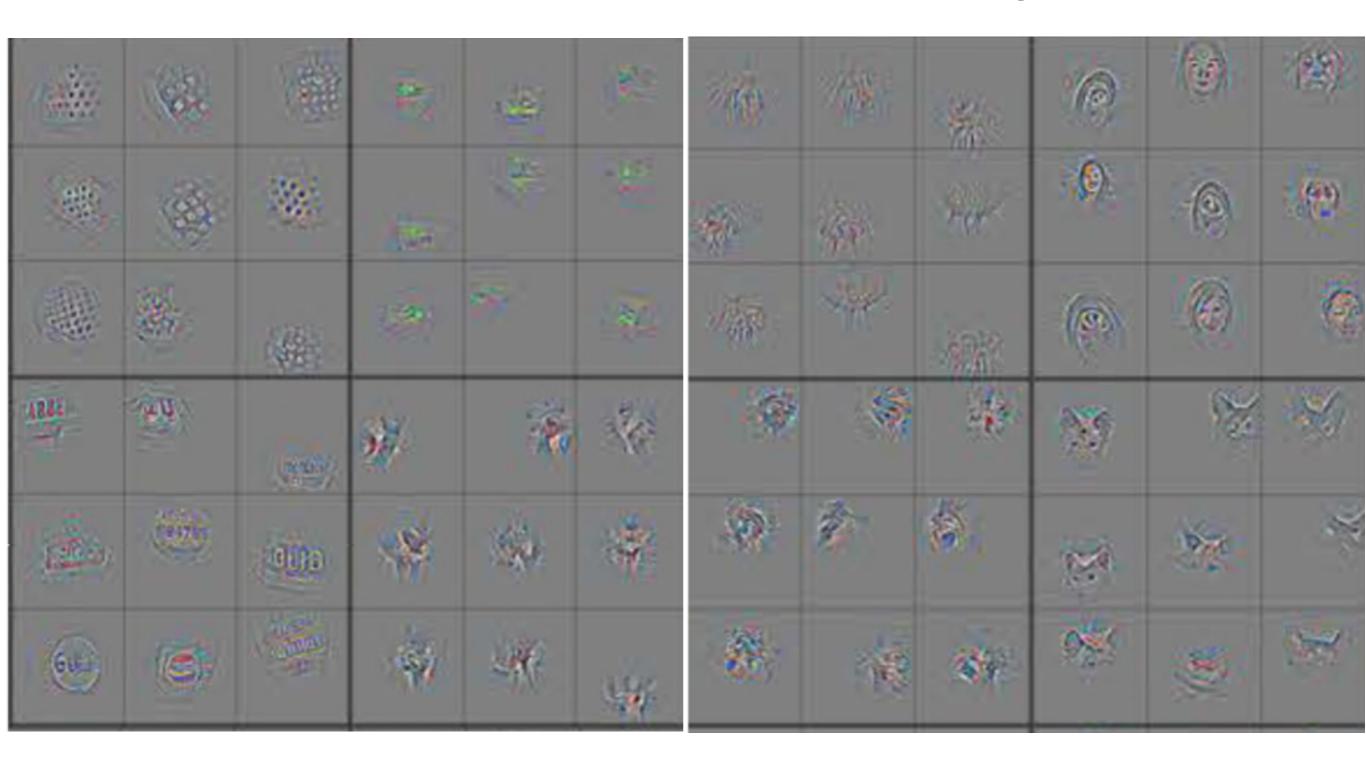














### Hubel and Wiesel experiments in 1950s and 1960s



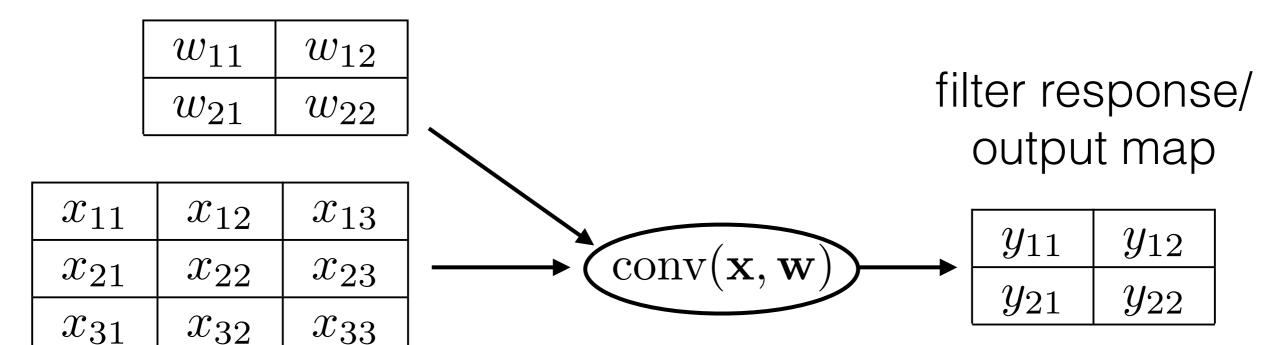
- Nobel Prize in Physiology and Medicine in 1981
- Dr. Hubel: "There has been a myth that the brain cannot understand itself. It is compared to a man trying to lift himself by his own bootstraps. We feel that is nonsense.

The brain can be studied just as the kidney can."

https://knowingneurons.com/2014/10/29/hubel-and-wiesel-the-neural-basis-of-visual-perception/ Czech Technical University in Prague

# Convolution forward pass y = conv(x, w)

#### kernel/filter



image



			$r_{-1}$	$x_{10}$	$x_{10}$		
	<u> </u>		$x_{11}$	$x_{12}$	$x_{13}$		211-1
$y_{11}$	$y_{12}$		$r_{01}$	$x_{22}$	$r_{00}$		$\omega_{11}$
		$\equiv$ conv	$x_{21}$	$x_{22}$	$x_{23}$	•	21201
$y_{21}$	$y_{22}$	<b>\</b>	$x_{31}$	$x_{32}$	$ x_{33} $		$\omega_{21}$
		l	$\lfloor \frac{w_{31}}{} \rfloor$	$\frac{32}{100}$	$\begin{bmatrix} u33 \end{bmatrix}$		

$$y_{11} = w_{11}x_{11} + w_{12}x_{12} + w_{21}x_{21} + w_{22}x_{22}$$

$$y_{12} = w_{11}x_{12} + w_{12}x_{13} + w_{21}x_{22} + w_{22}x_{23}$$

$$y_{21} = w_{11}x_{21} + w_{12}x_{22} + w_{21}x_{31} + w_{22}x_{32}$$

$$y_{22} = w_{11}x_{22} + w_{12}x_{23} + w_{21}x_{32} + w_{22}x_{33}$$



# Convolution forward pass y = conv(x, w)

				$x_{11}$	$x_{12}$	$x_{13}$				1 、
	$y_{11}$	$y_{12}$						$w_{11}$	$w_{12}$	\
Ī	$y_{21}$	$y_{22}$	$\equiv \text{conv}$				,	$w_{21}$	$w_{22}$	
Į	021	022	J	$x_{31}$	$x_{32}$	$x_{33}$	]			•

$$y_{11} = w_{11}x_{11} + w_{12}x_{12} + w_{21}x_{21} + w_{22}x_{22}$$

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		<b>/</b>	$x_{11}$	$x_{12}$	$x_{13}$		$w_{11}$	21112	1 \
$y_{11}$	$y_{12}$	= conv	$x_{21}$	$x_{22}$	$x_{23}$	,		$w_{12}$	)
$y_{21}$	$y_{22}$		$x_{31}$	$x_{32}$	$x_{33}$		$w_{21}$	$w_{22}$	/
	l	l	$\begin{bmatrix} w31 \end{bmatrix}$	$\omega_{32}$	$\begin{bmatrix} \omega_{33} \end{bmatrix}$	J			

$$y_{11} = w_{11}x_{11} + w_{12}x_{12} + w_{21}x_{21} + w_{22}x_{22}$$

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Г			1	$x_{11}$	$x_{12}$	$x_{13}$		211	011.5	1 \
	$y_{11}$	$y_{12}$	= conv	$x_{21}$	$x_{22}$	$x_{23}$			$w_{12}$	)
	$y_{21}$	$y_{22}$			$x_{32}$		,	$w_{21}$	$w_{22}$	/
_		-	J	$\begin{bmatrix} w_{31} \end{bmatrix}$	$\frac{32}{2}$	$\omega_{33}$	J			

$$y_{11} = w_{11}x_{11} + w_{12}x_{12} + w_{21}x_{21} + w_{22}x_{22}$$

$$y_{12} = w_{11}x_{12} + w_{12}x_{13} + w_{21}x_{22} + w_{22}x_{23}$$

$$y_{21} = w_{11}x_{21} + w_{12}x_{22} + w_{21}x_{31} + w_{22}x_{32}$$

$$y_{22} = w_{11}x_{22} + w_{12}x_{23} + w_{21}x_{32} + w_{22}x_{33}$$



	Г		,	$x_{11}$	$x_{12}$	$x_{13}$			249
$y_{11}$	$y_{12}$	= conv		$x_{21}$	$x_{22}$	$x_{23}$		$w_{11}$	$w_{12}$
$y_{21}$	$y_{22}$		\	$\overline{x_{31}}$	$x_{32}$	$x_{33}$	,	$w_{21}$	$w_{22}$
		l	L	$x_{31}$	$\frac{x}{32}$	$\begin{bmatrix} x & 33 \end{bmatrix}$			

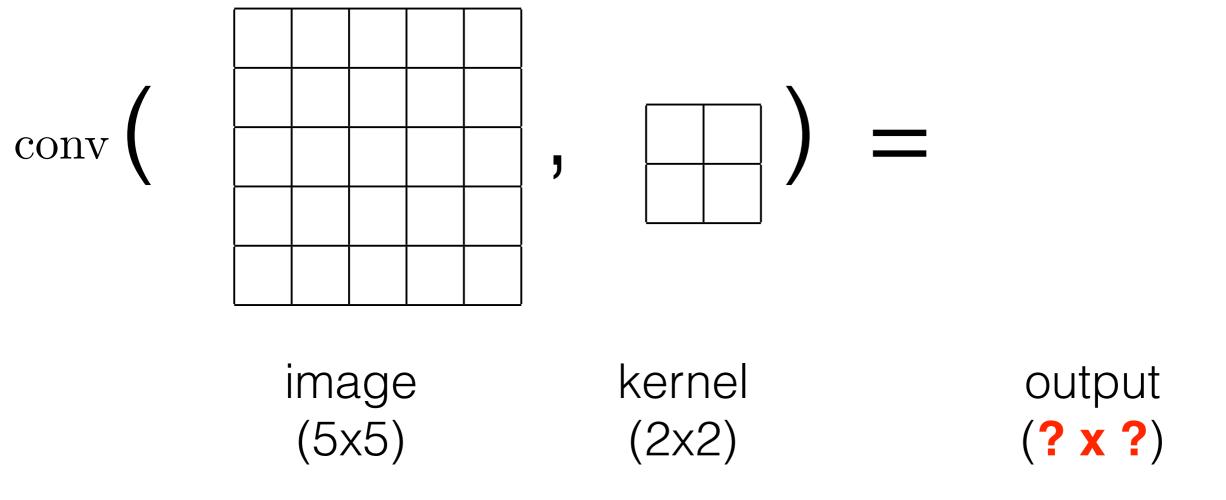
$$y_{11} = w_{11}x_{11} + w_{12}x_{12} + w_{21}x_{21} + w_{22}x_{22}$$

$$y_{12} = w_{11}x_{12} + w_{12}x_{13} + w_{21}x_{22} + w_{22}x_{23}$$

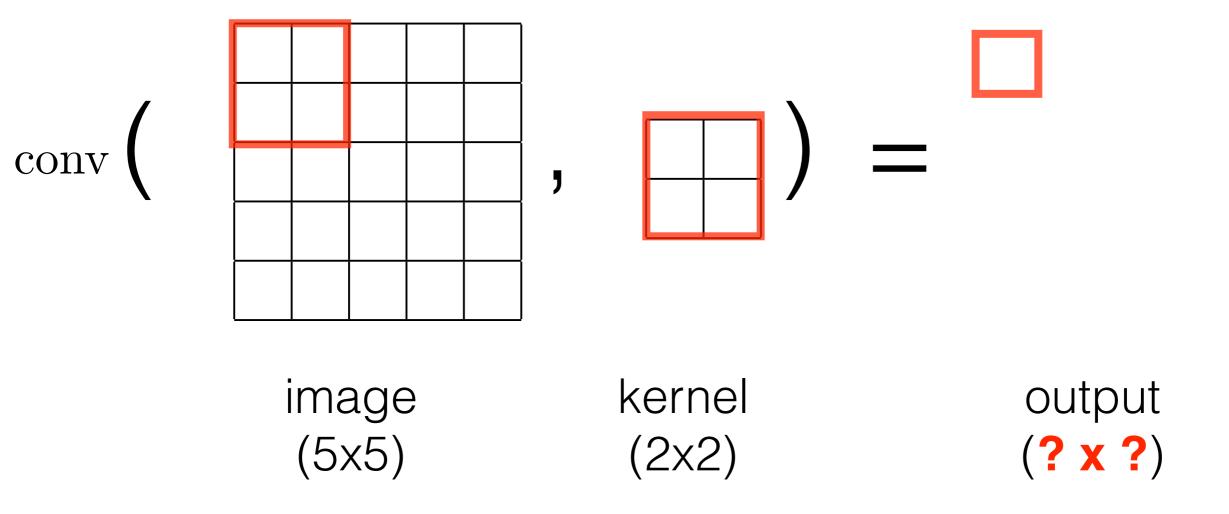
$$y_{21} = w_{11}x_{21} + w_{12}x_{22} + w_{21}x_{31} + w_{22}x_{32}$$

$$y_{22} = w_{11}x_{22} + w_{12}x_{23} + w_{21}x_{32} + w_{22}x_{33}$$

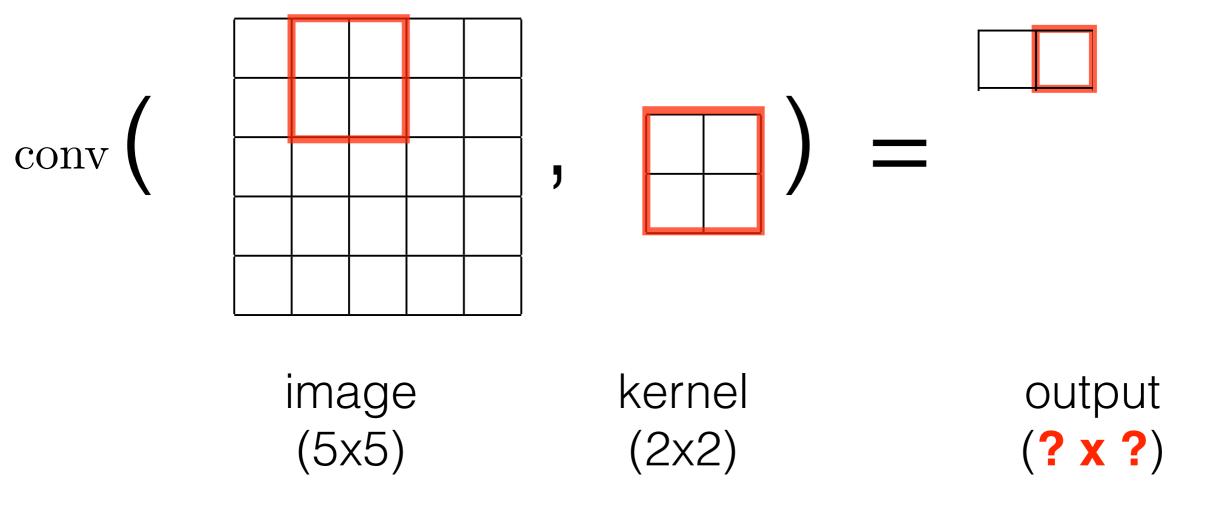




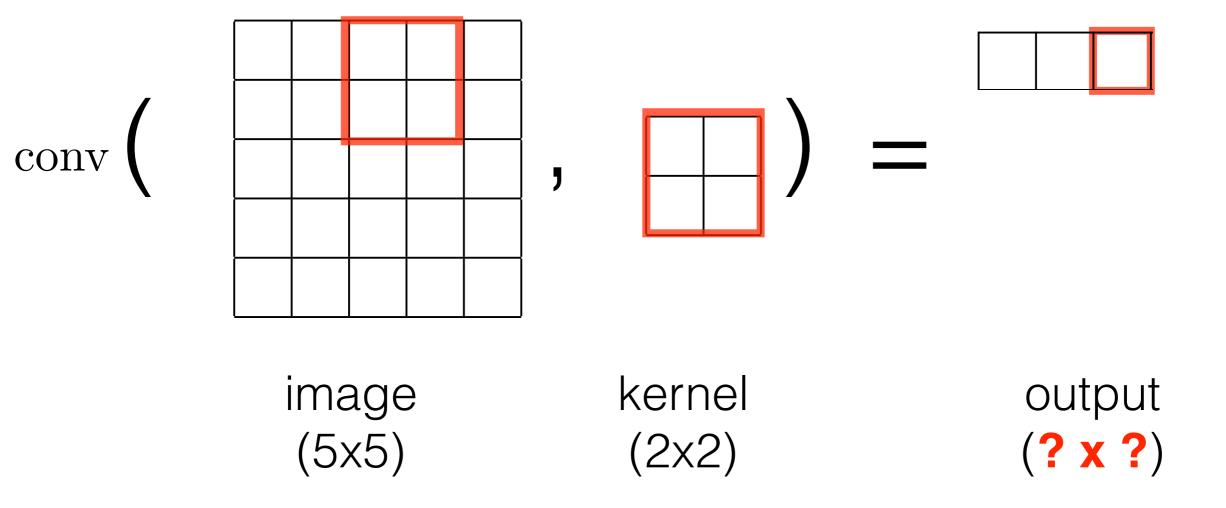




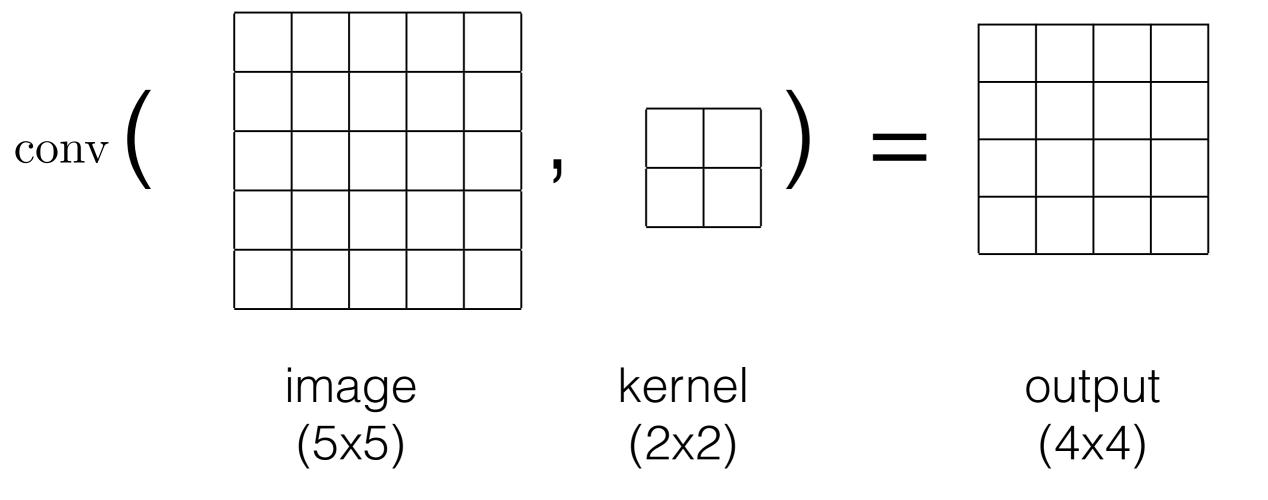








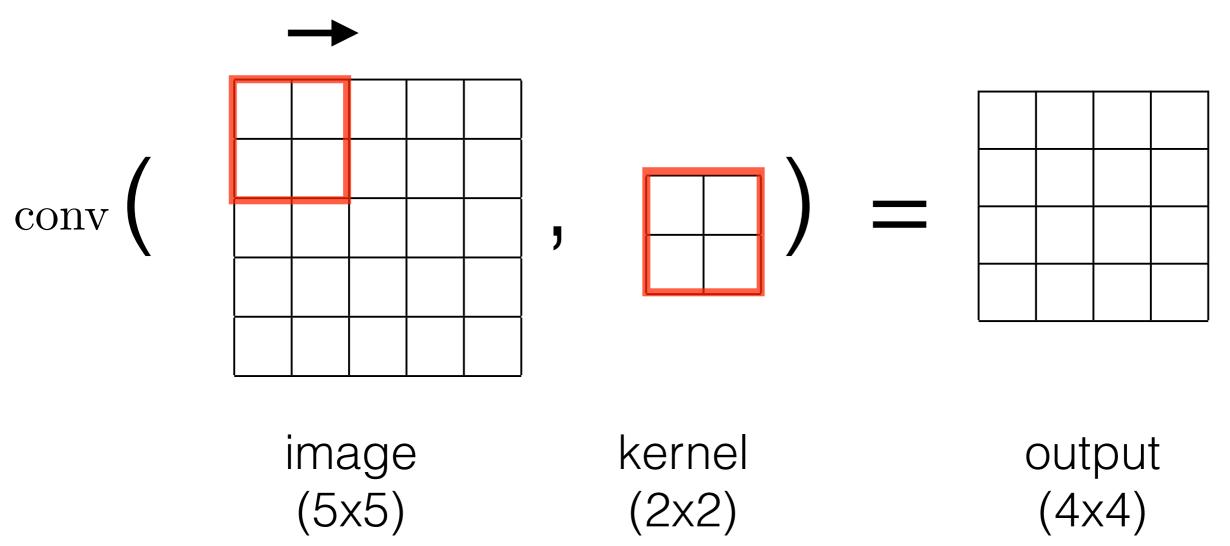






stride = 1

kernel moves by 1 pixel





$$stride = 3$$

kernel moves by 3 pixels

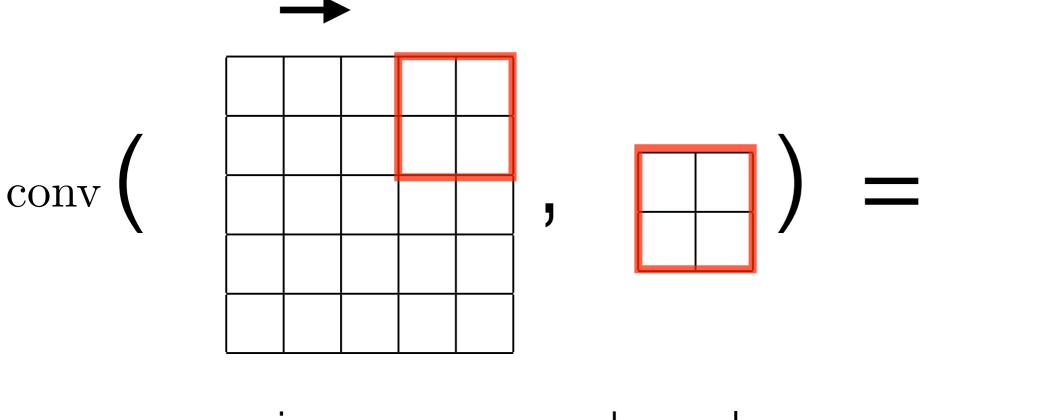


image (5x5)

kernel (2x2)

output (? x ?)



$$stride = 3$$

kernel moves by 3 pixels

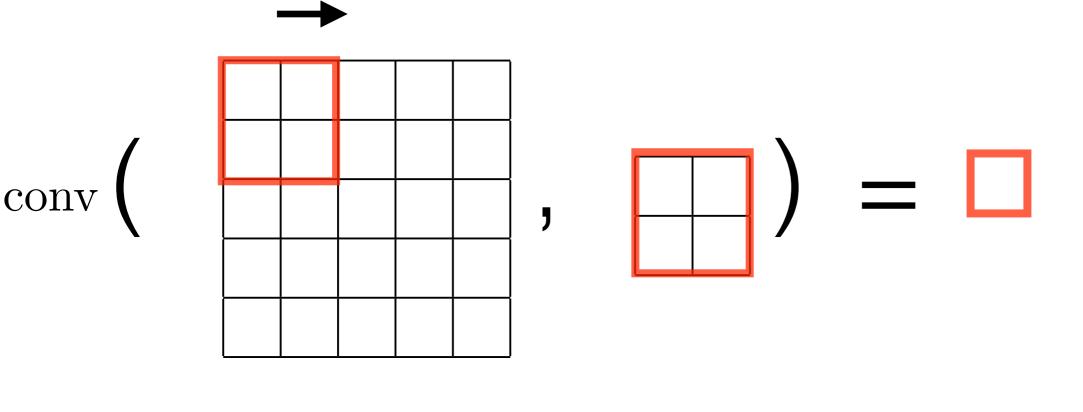


image (5x5)

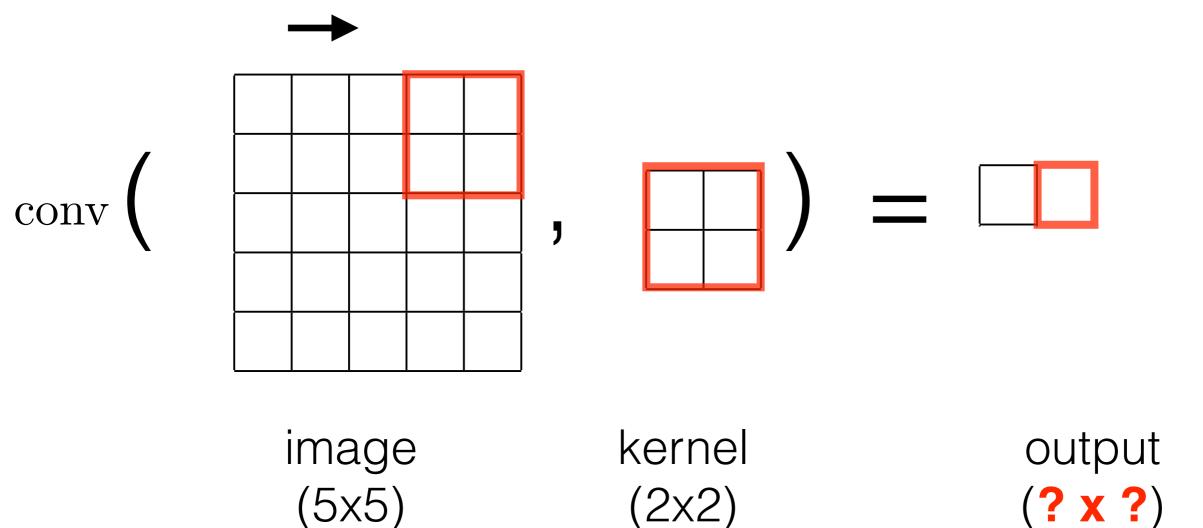
kernel (2x2)

output (? x ?)



stride = 3

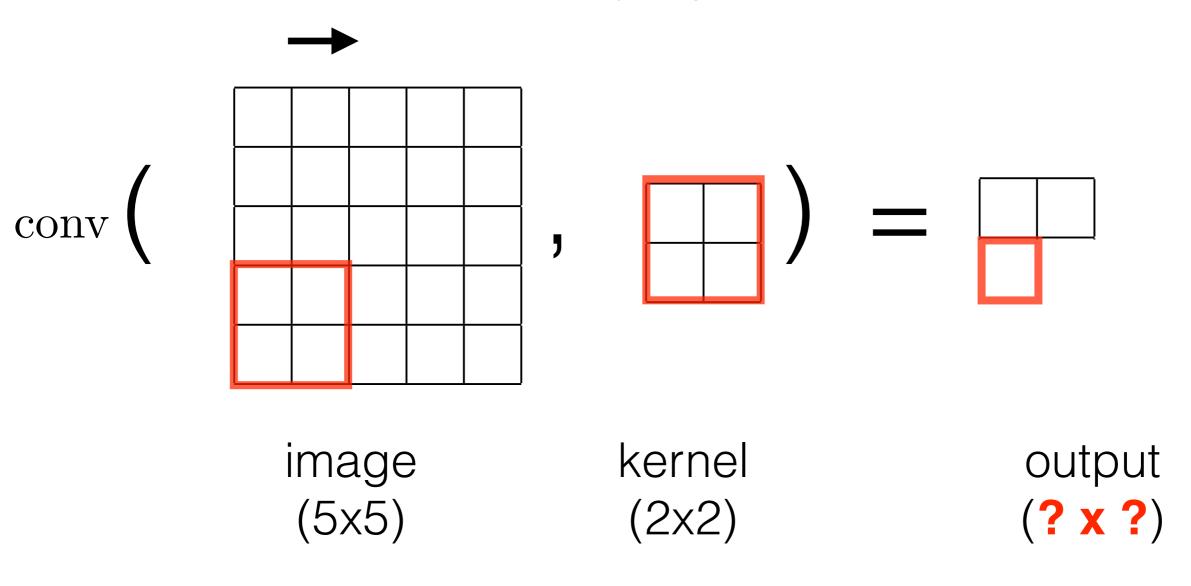
kernel moves by 3 pixels





$$stride = 3$$

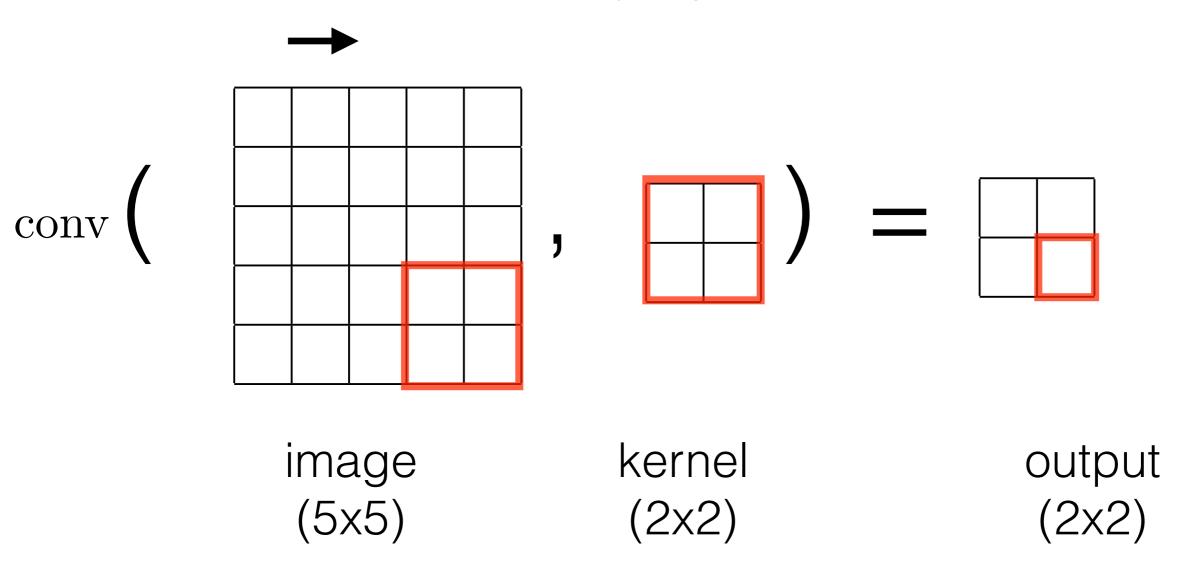
kernel moves by 3 pixels





$$stride = 3$$

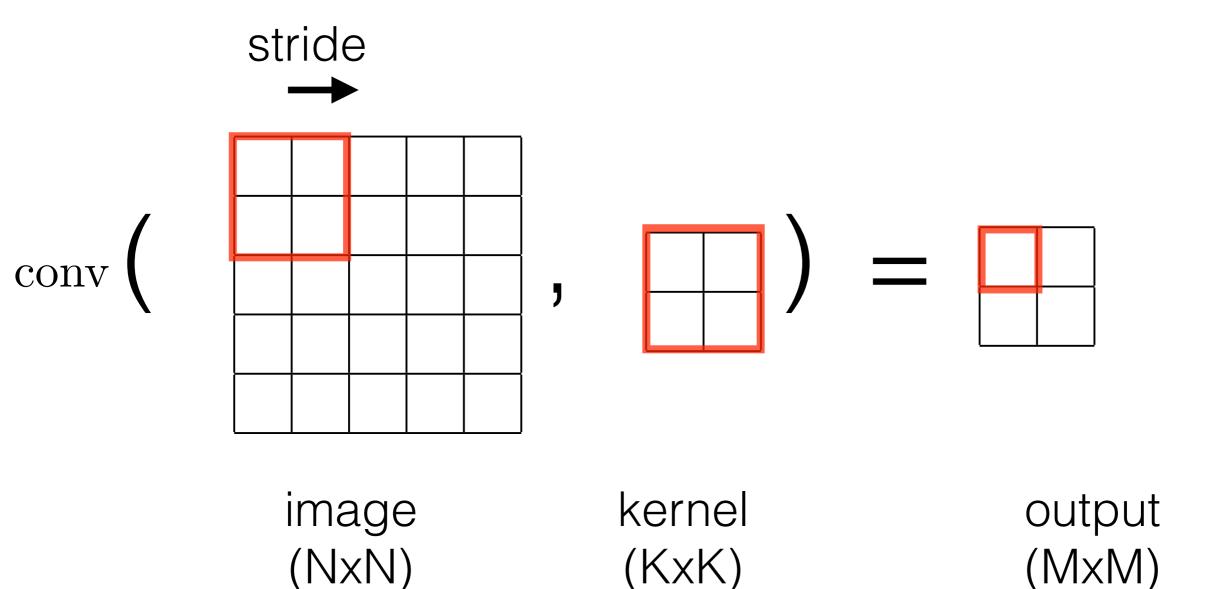
kernel moves by 3 pixels





## Convolution layer properties - stride

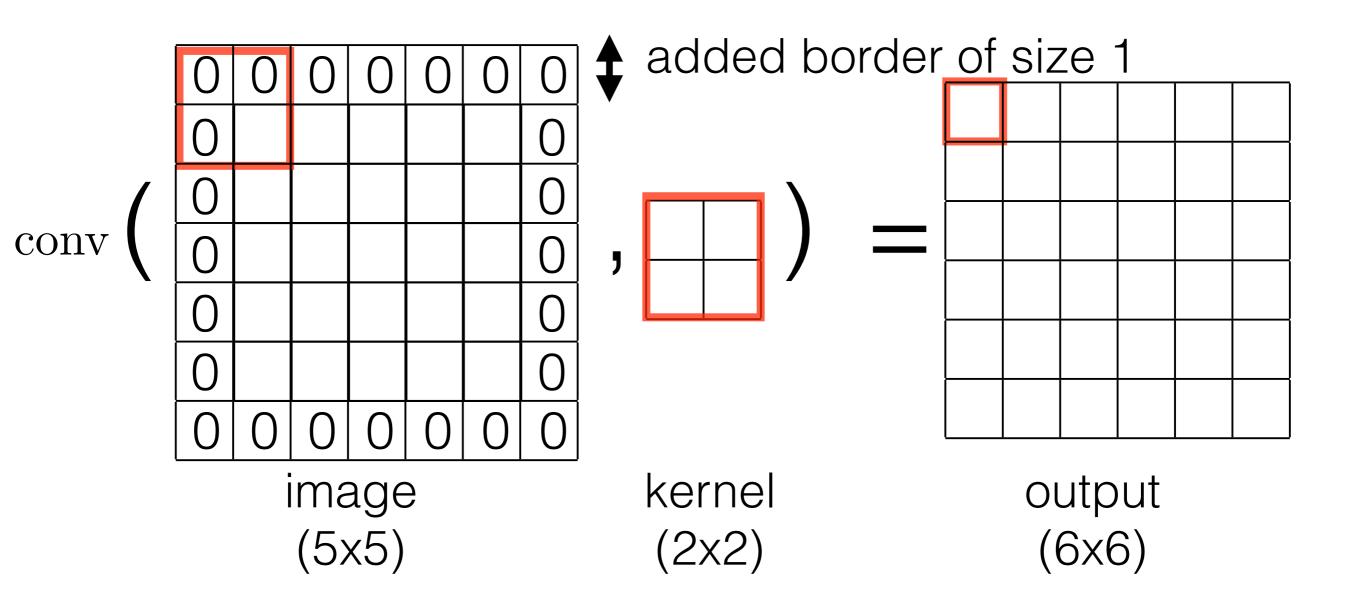
$$M = (N-K) / stride + 1$$



e.g. 
$$M = (5-2) / 3 + 1 = 2$$



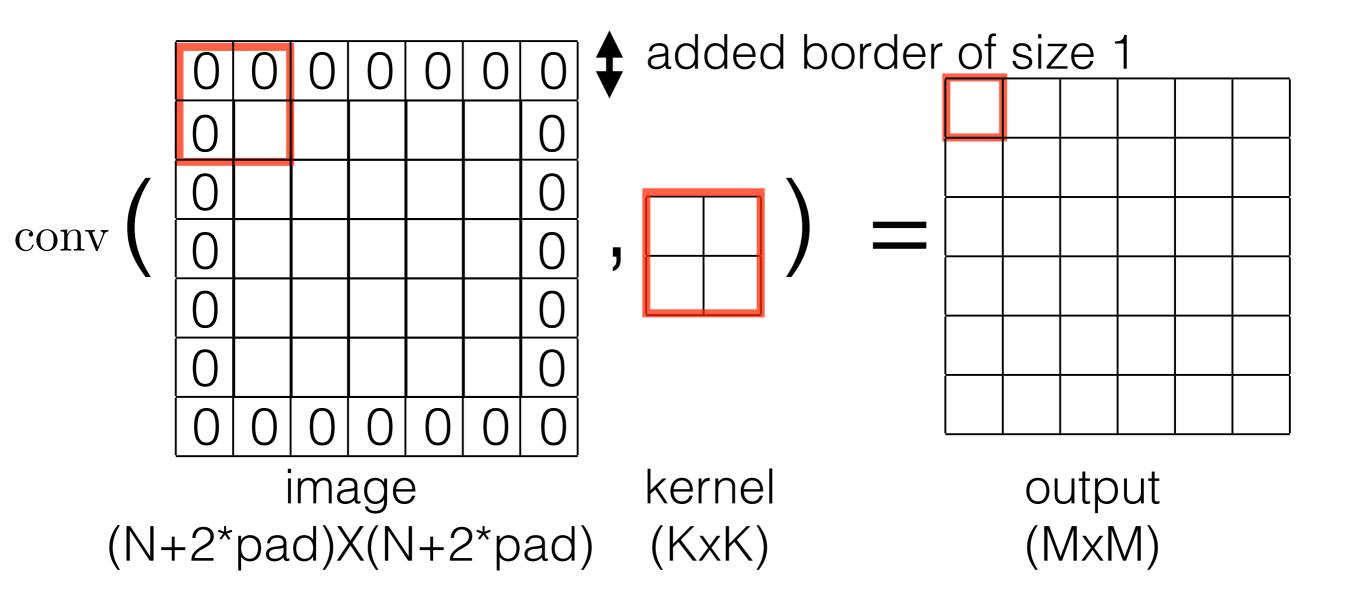
# Convolution layer properties - pad pad = 1



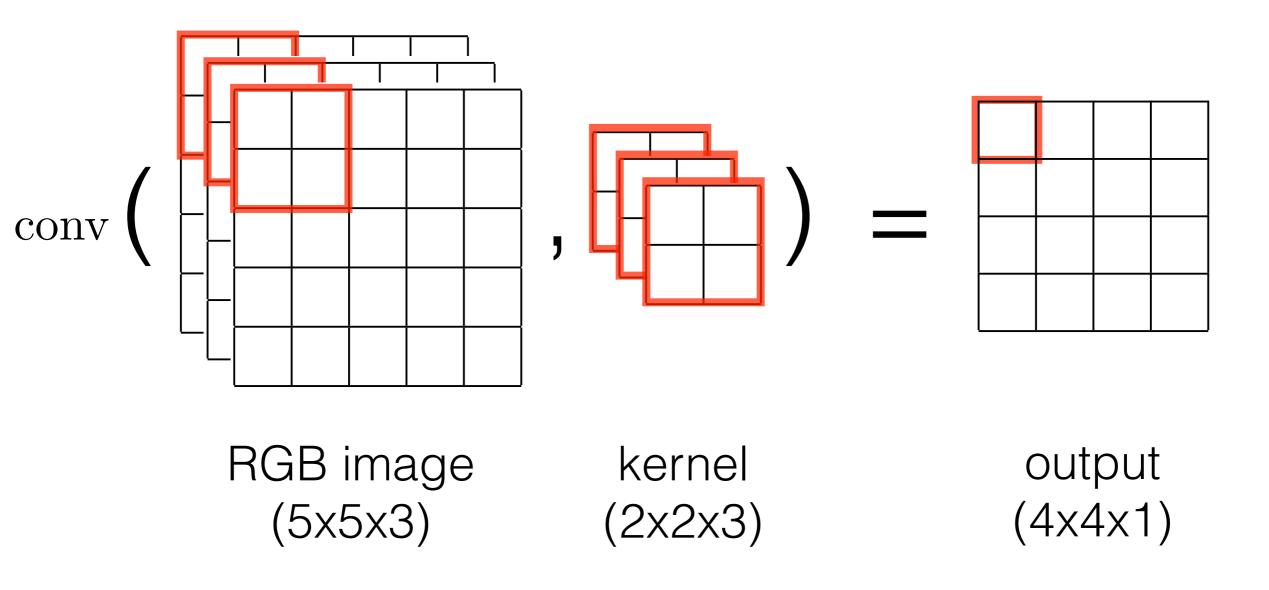


## Convolution layer properties - pad

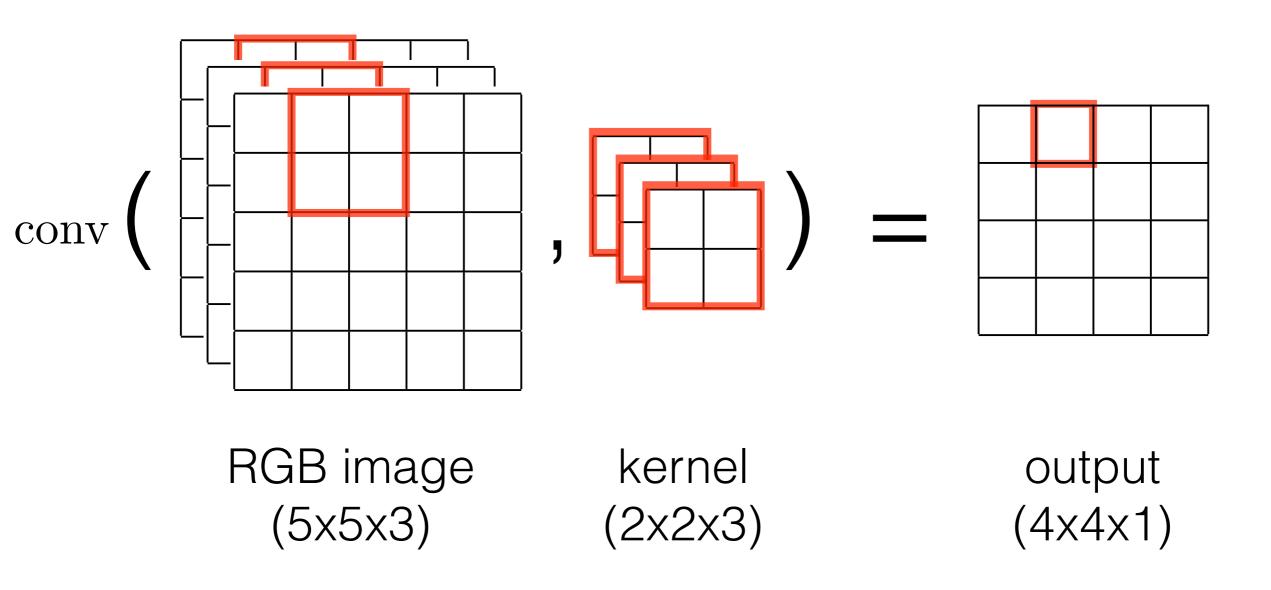
$$M = (N+2*pad-K) / stride + 1$$



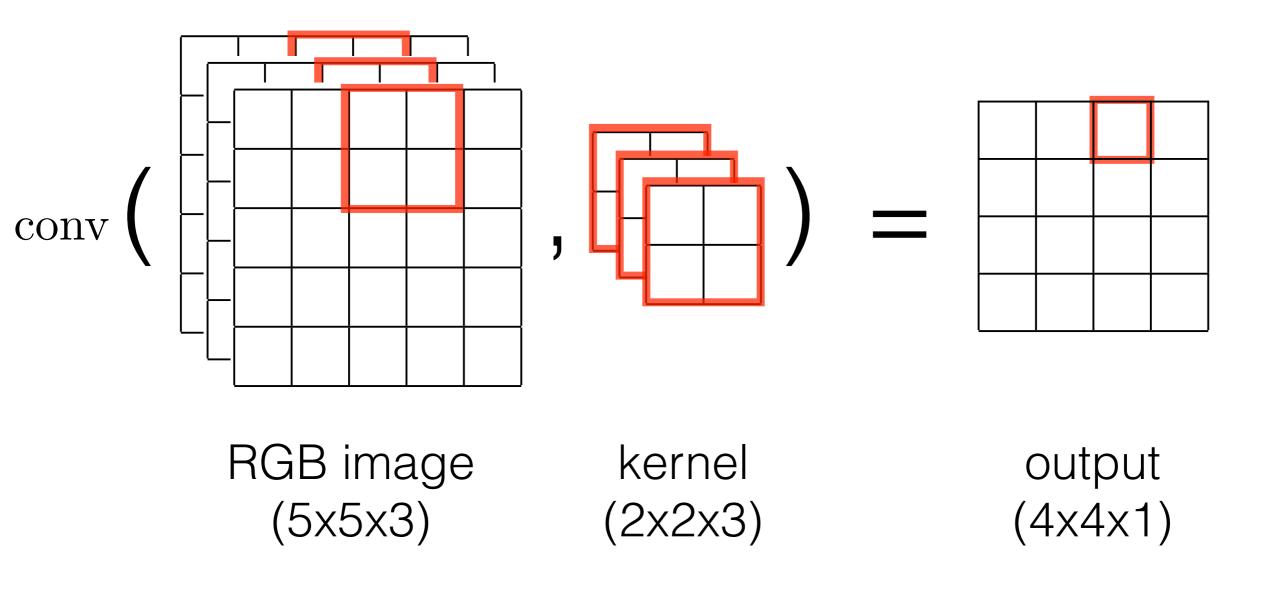




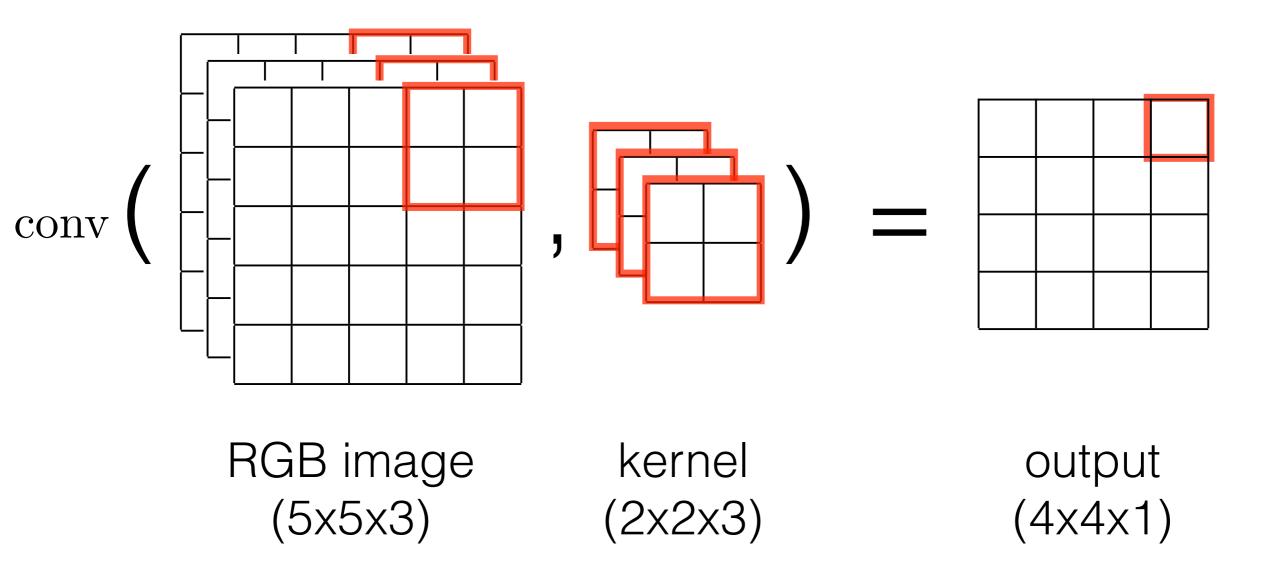




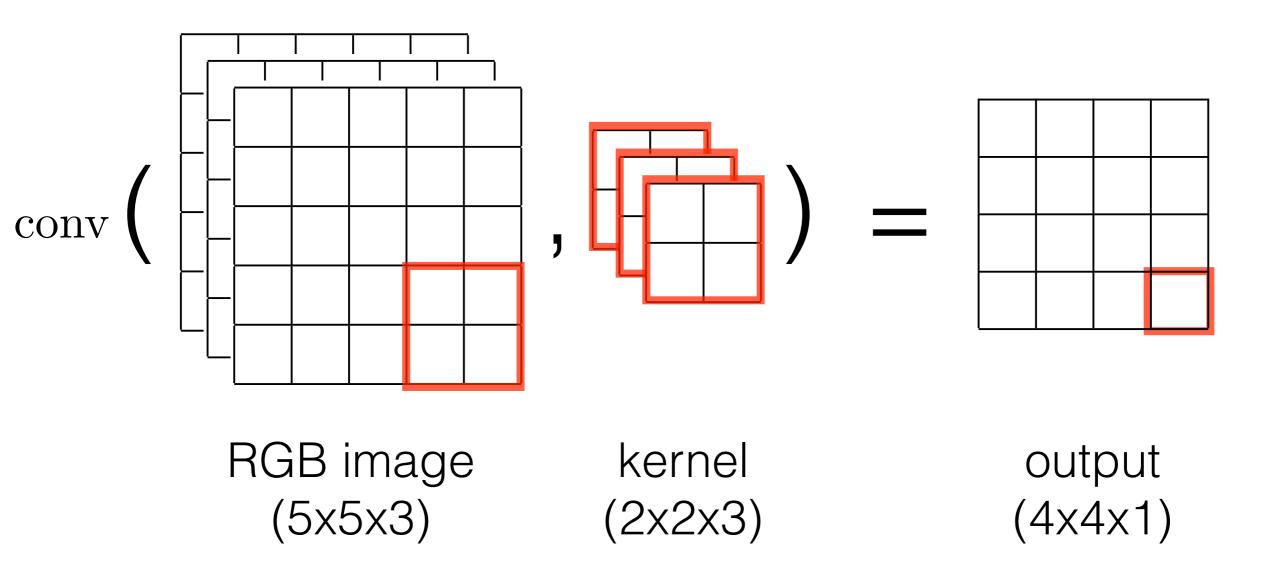




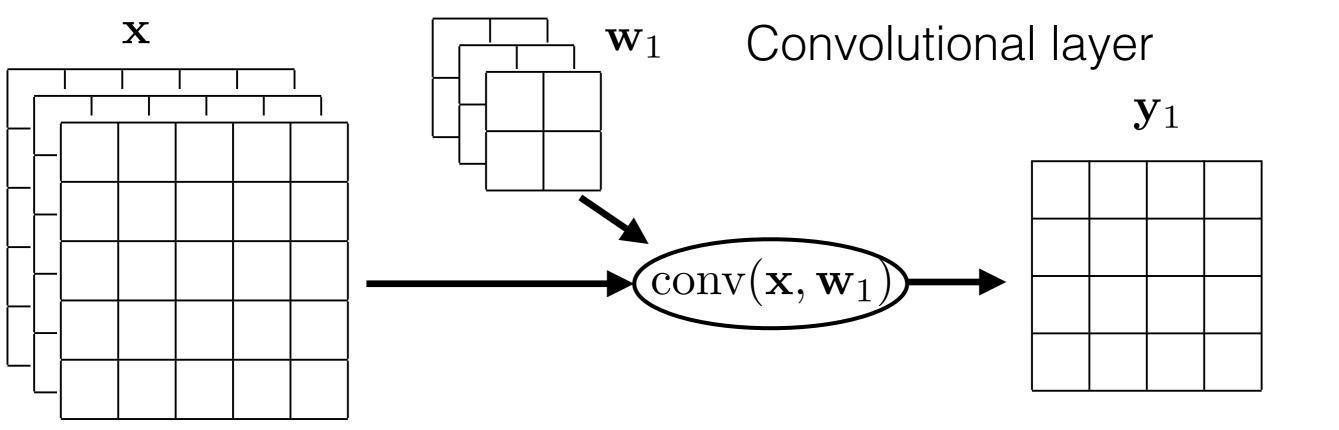




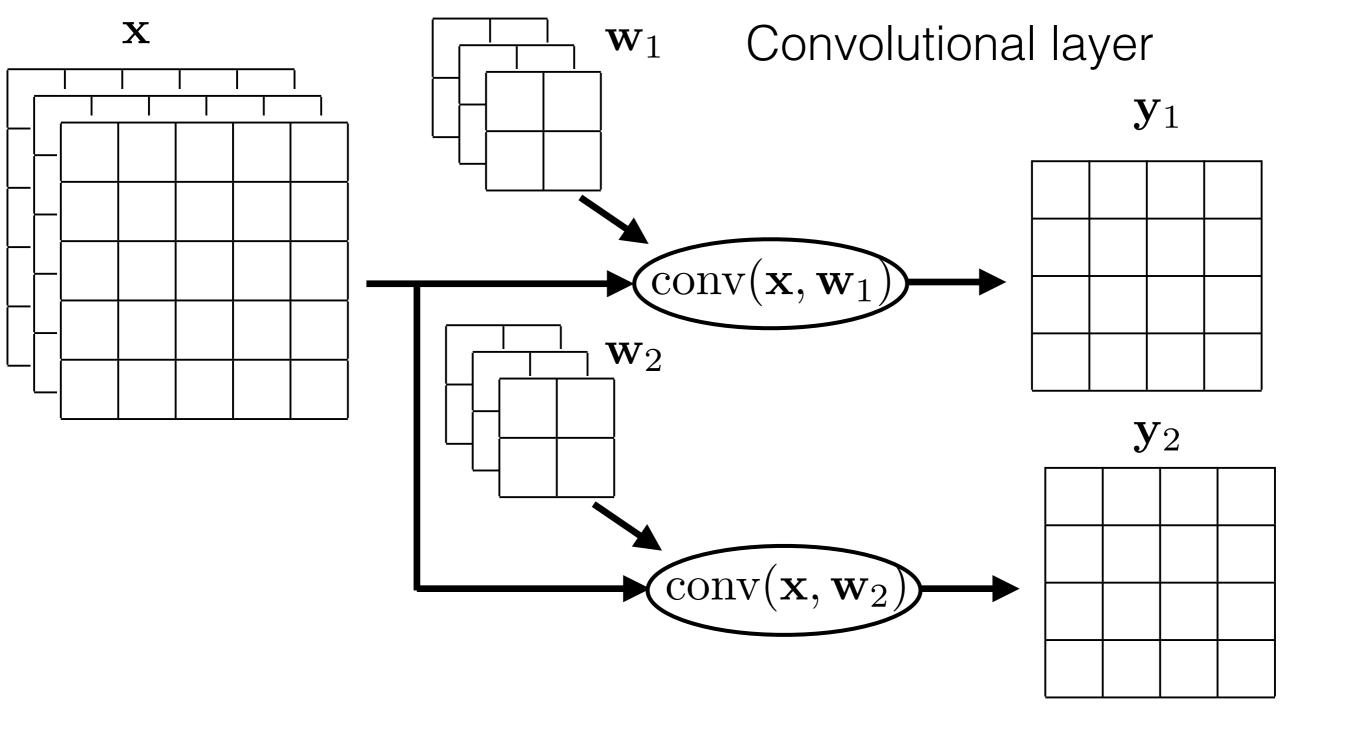




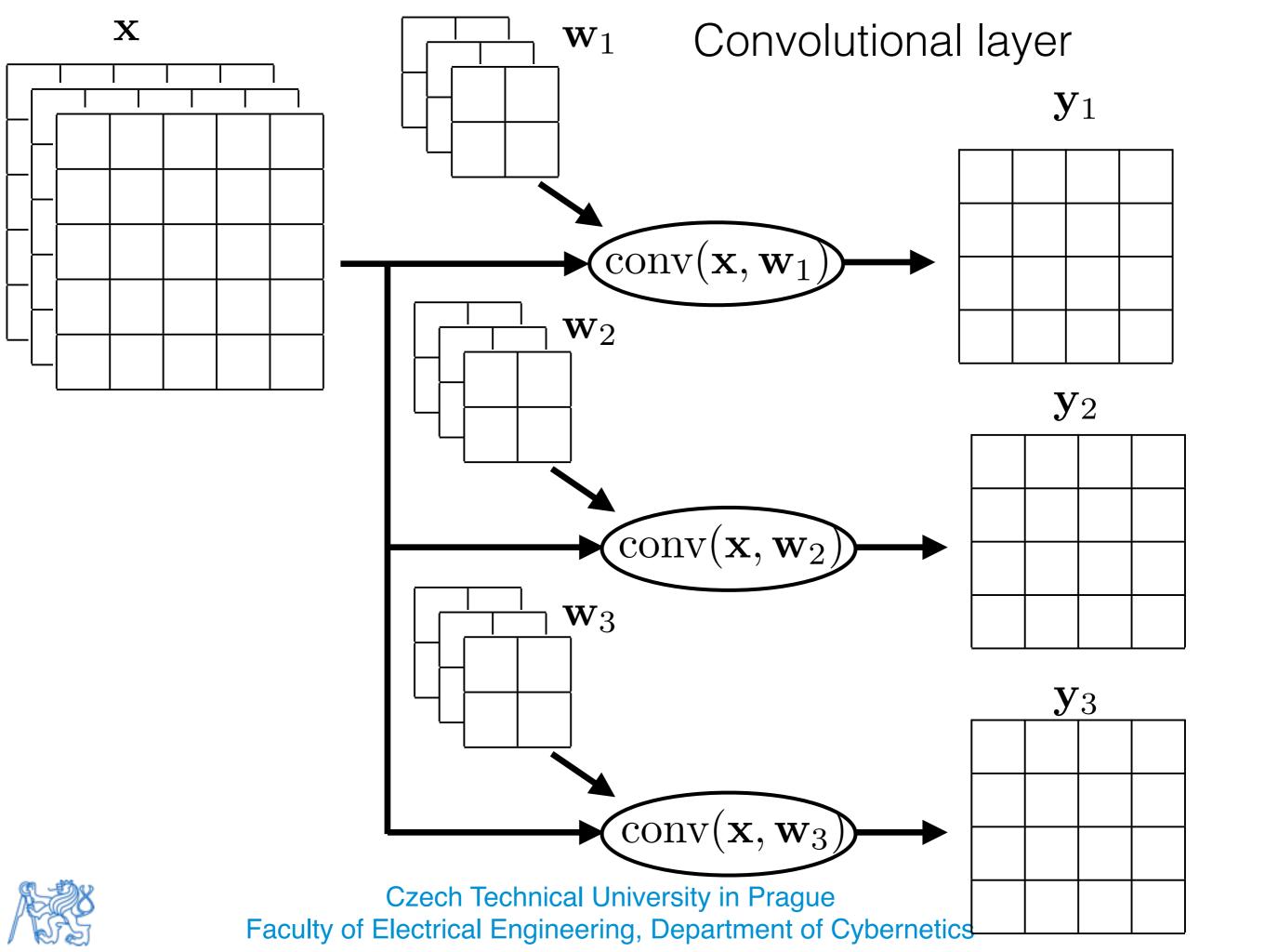




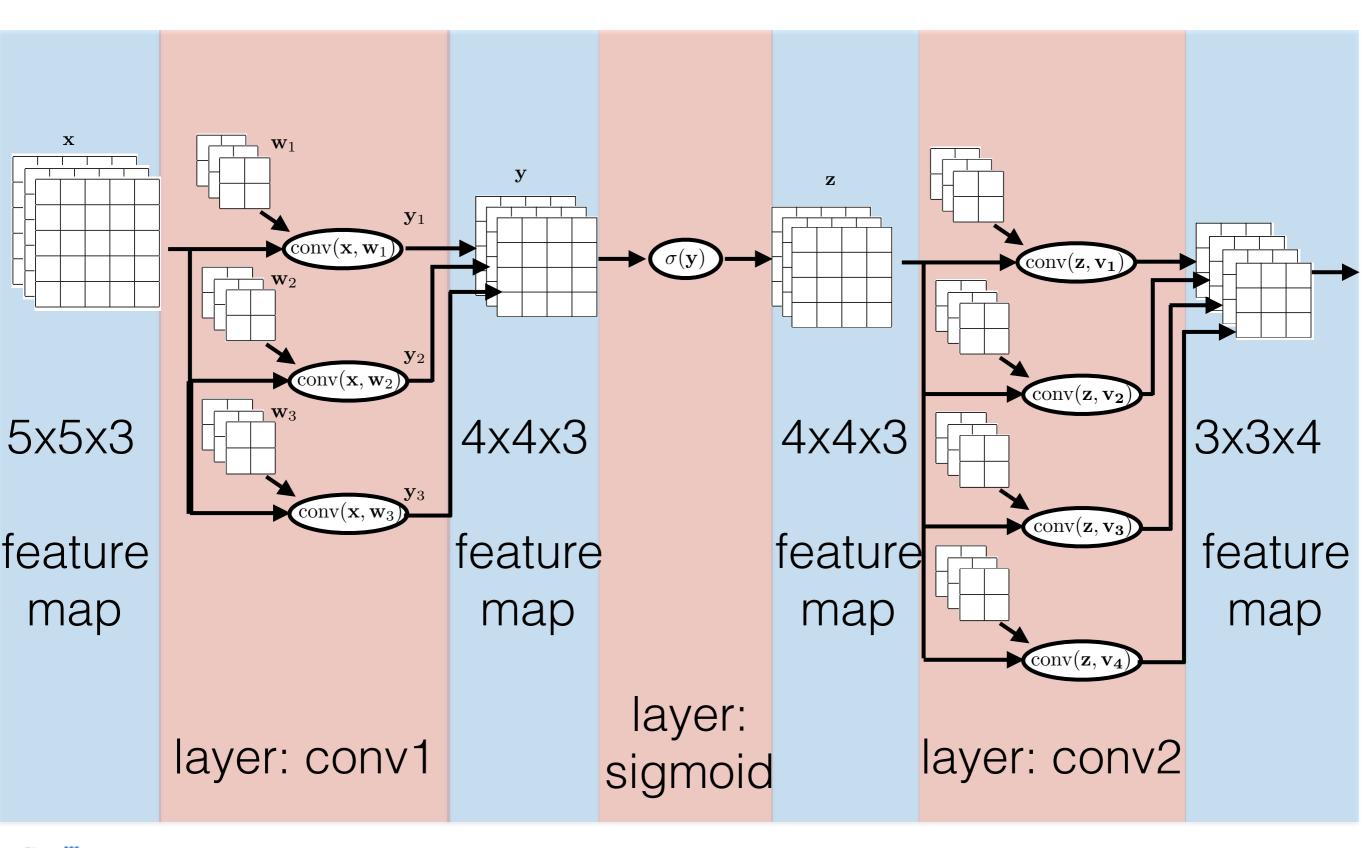






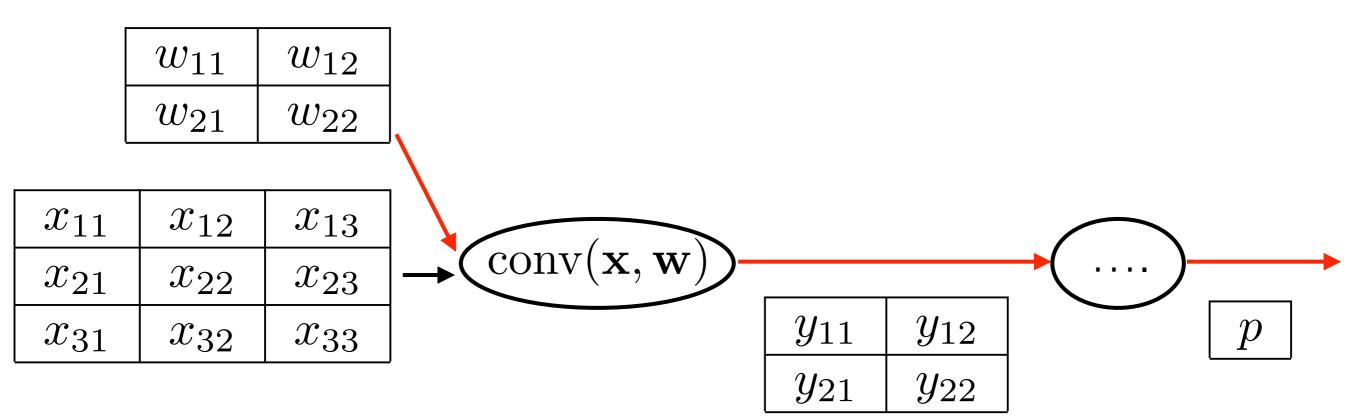


## Convolutional network (ConvNet)



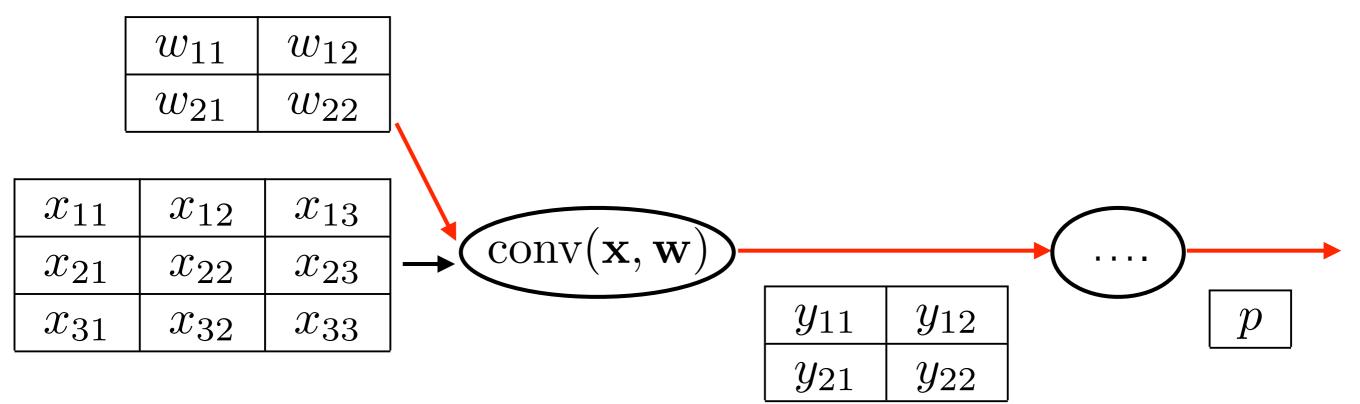


Learning of convolutional neuron => backpropagation





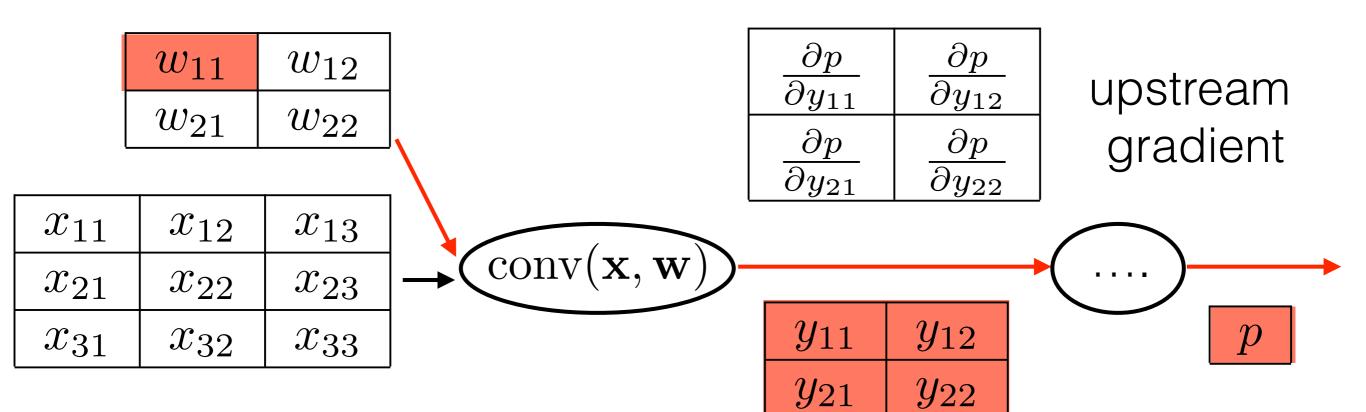
$\frac{\partial p}{\partial w_{11}}$	$\frac{\partial p}{\partial w_{12}}$	_2
$\frac{\partial p}{\partial w_{21}}$	$\frac{\partial p}{\partial w_{22}}$	= !





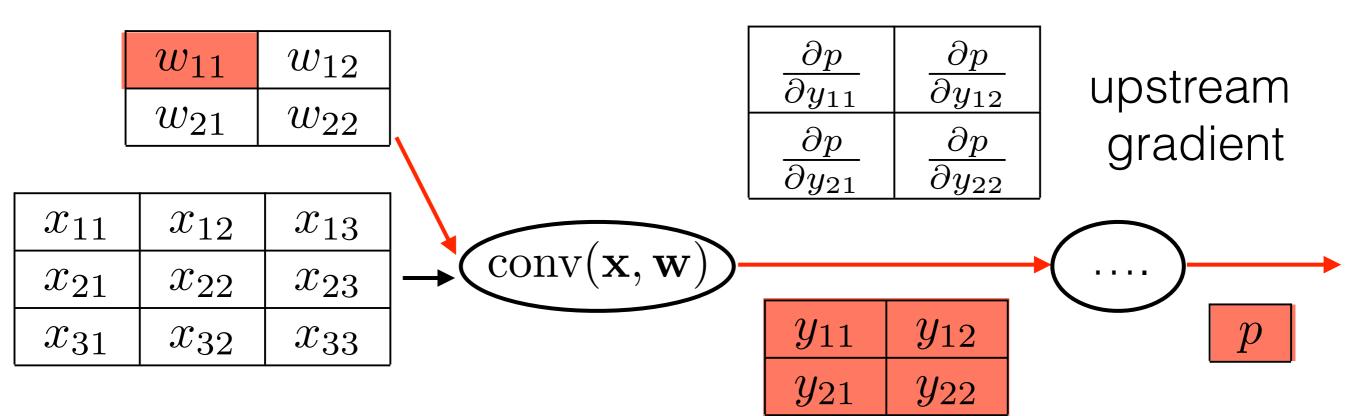
Czech Technical University in Prague Faculty of Electrical Engineering, Department of Cybernetics

$$\frac{\partial p}{\partial w_{11}} = ?$$





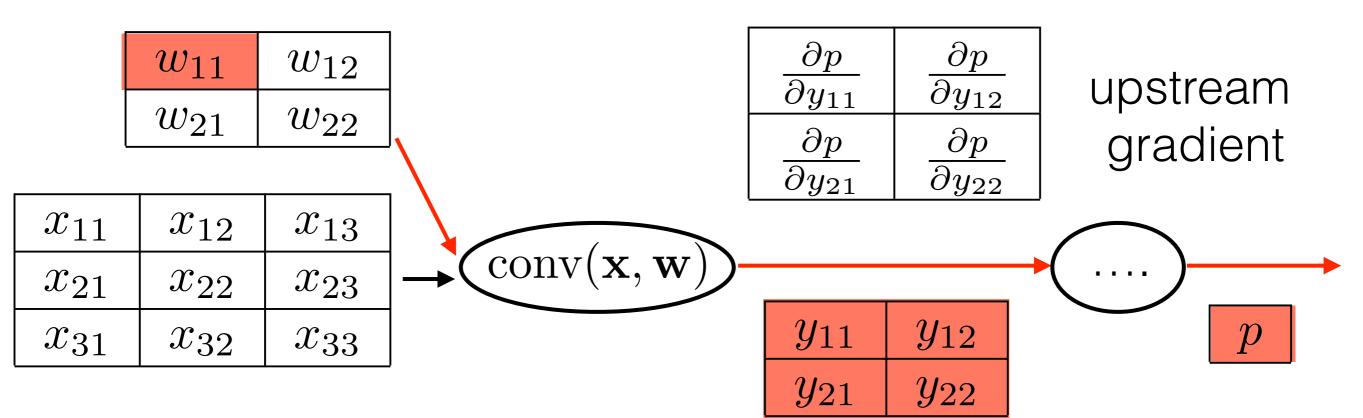
$$\frac{\partial p}{\partial w_{11}} = \frac{\partial p}{\partial y_{11}} \frac{\partial y_{11}}{\partial w_{11}} + \frac{\partial p}{\partial y_{12}} \frac{\partial y_{12}}{\partial w_{11}} + \frac{\partial p}{\partial y_{21}} \frac{\partial y_{21}}{\partial w_{11}} + \frac{\partial p}{\partial y_{22}} \frac{\partial y_{22}}{\partial w_{11}} + \frac{\partial p}{\partial y_{22}} \frac{\partial y_{22}}{\partial w_{11}}$$





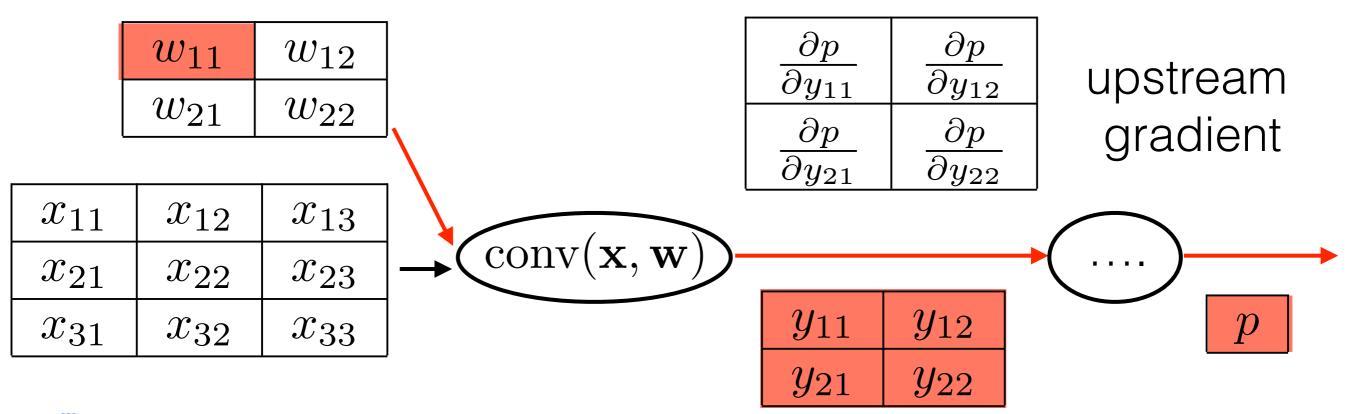
$$\frac{\partial p}{\partial w_{11}} = \frac{\partial p}{\partial y_{11}} \frac{\partial y_{11}}{\partial w_{11}} + \frac{\partial p}{\partial y_{12}} \frac{\partial y_{12}}{\partial w_{11}} + \frac{\partial p}{\partial y_{21}} \frac{\partial y_{21}}{\partial w_{11}} + \frac{\partial p}{\partial y_{22}} \frac{\partial y_{22}}{\partial w_{11}}$$

$$\frac{\partial y_{11}}{\partial w_{11}} = \frac{\partial (w_{11}x_{11} + w_{12}x_{12} + w_{21}x_{21} + w_{22}x_{22})}{\partial w_{11}} = x_{11}$$





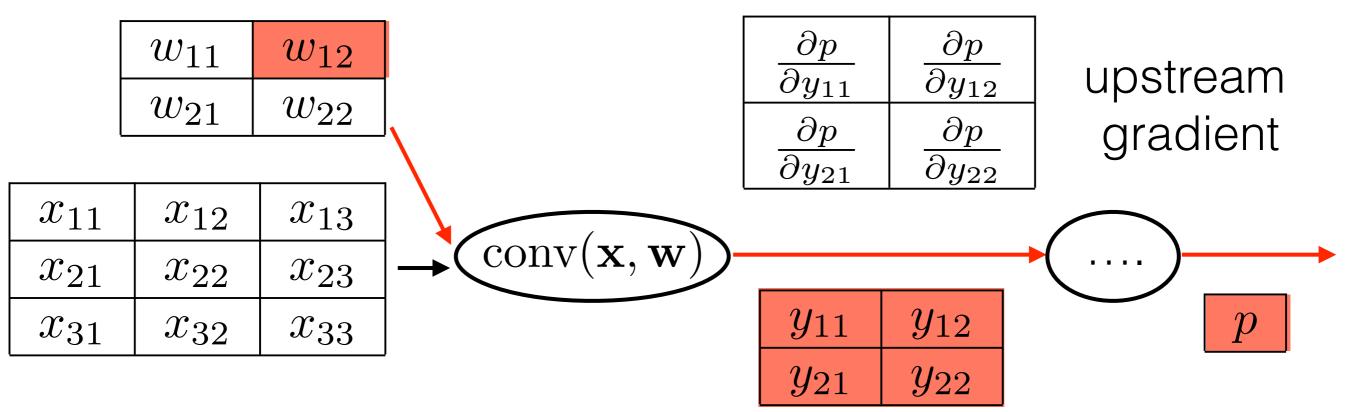
$$\frac{\partial p}{\partial w_{11}} = \frac{\partial p}{\partial y_{11}} x_{11} + \frac{\partial p}{\partial y_{12}} x_{12} + \frac{\partial p}{\partial y_{21}} x_{21} + \frac{\partial p}{\partial y_{22}} x_{22}$$





$$\frac{\partial p}{\partial w_{11}} = \frac{\partial p}{\partial y_{11}} x_{11} + \frac{\partial p}{\partial y_{12}} x_{12} + \frac{\partial p}{\partial y_{21}} x_{21} + \frac{\partial p}{\partial y_{22}} x_{22}$$

$$\frac{\partial p}{\partial w_{12}} = \frac{\partial p}{\partial y_{11}} x_{12} + \frac{\partial p}{\partial y_{12}} x_{13} + \frac{\partial p}{\partial y_{21}} x_{22} + \frac{\partial p}{\partial y_{22}} x_{23}$$

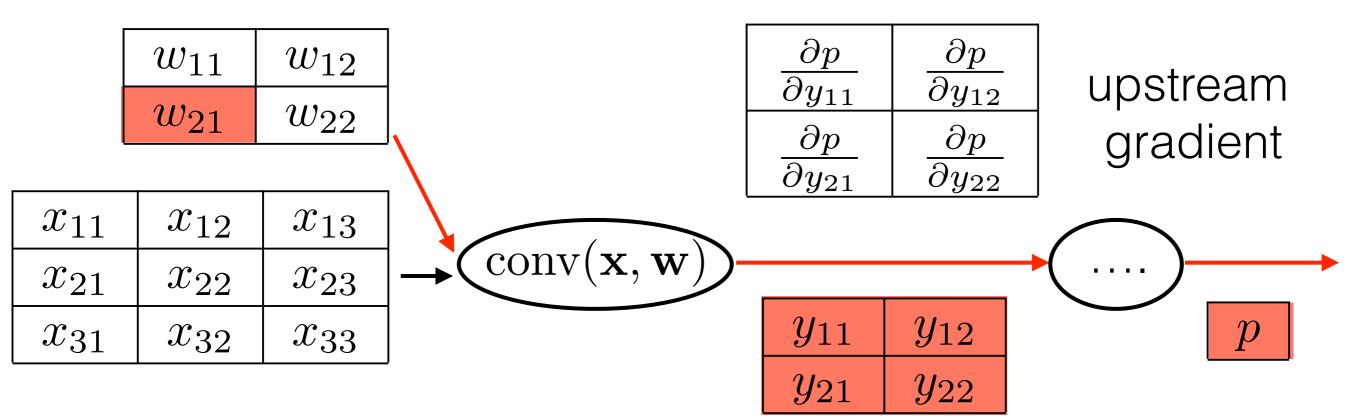




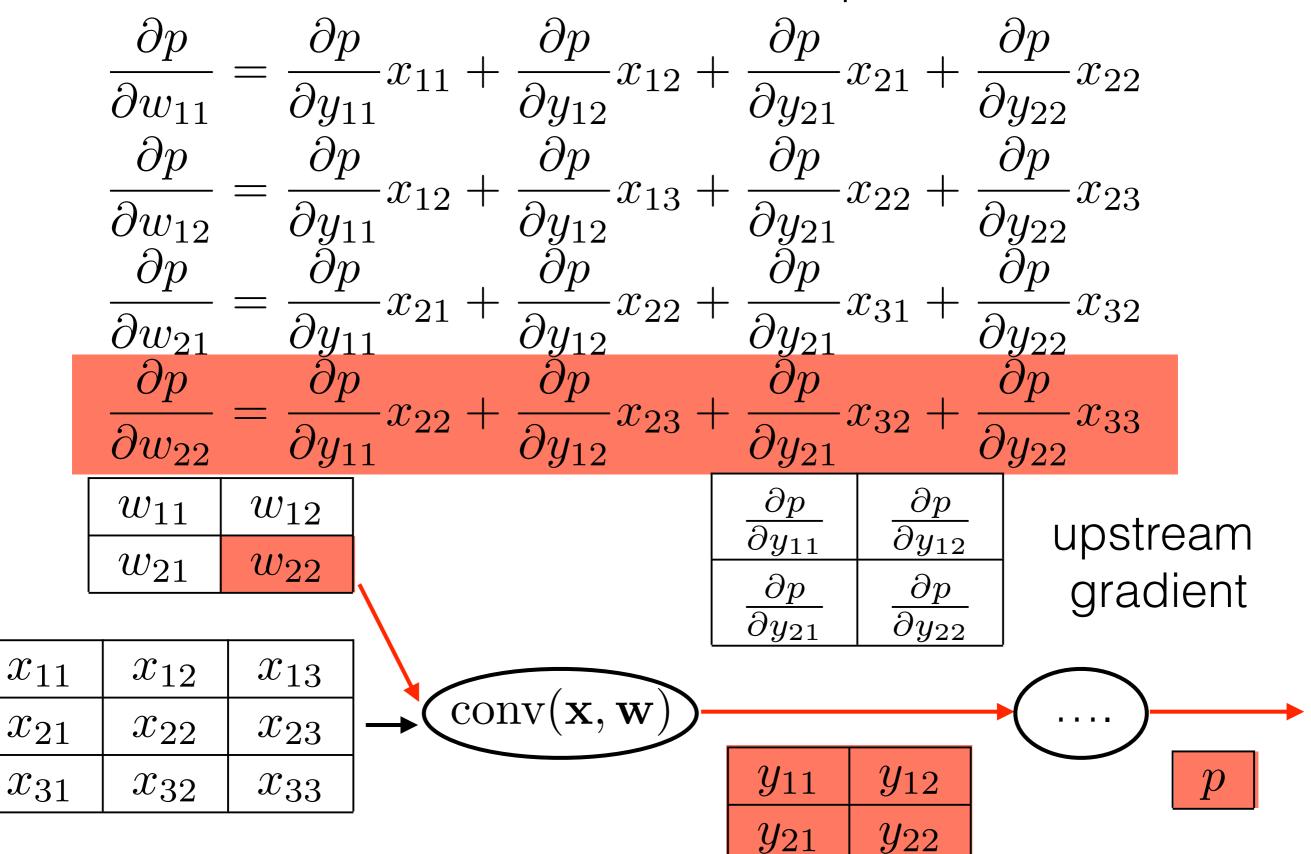
$$\frac{\partial p}{\partial w_{11}} = \frac{\partial p}{\partial y_{11}} x_{11} + \frac{\partial p}{\partial y_{12}} x_{12} + \frac{\partial p}{\partial y_{21}} x_{21} + \frac{\partial p}{\partial y_{22}} x_{22}$$

$$\frac{\partial p}{\partial w_{12}} = \frac{\partial p}{\partial y_{11}} x_{12} + \frac{\partial p}{\partial y_{12}} x_{13} + \frac{\partial p}{\partial y_{21}} x_{22} + \frac{\partial p}{\partial y_{22}} x_{23}$$

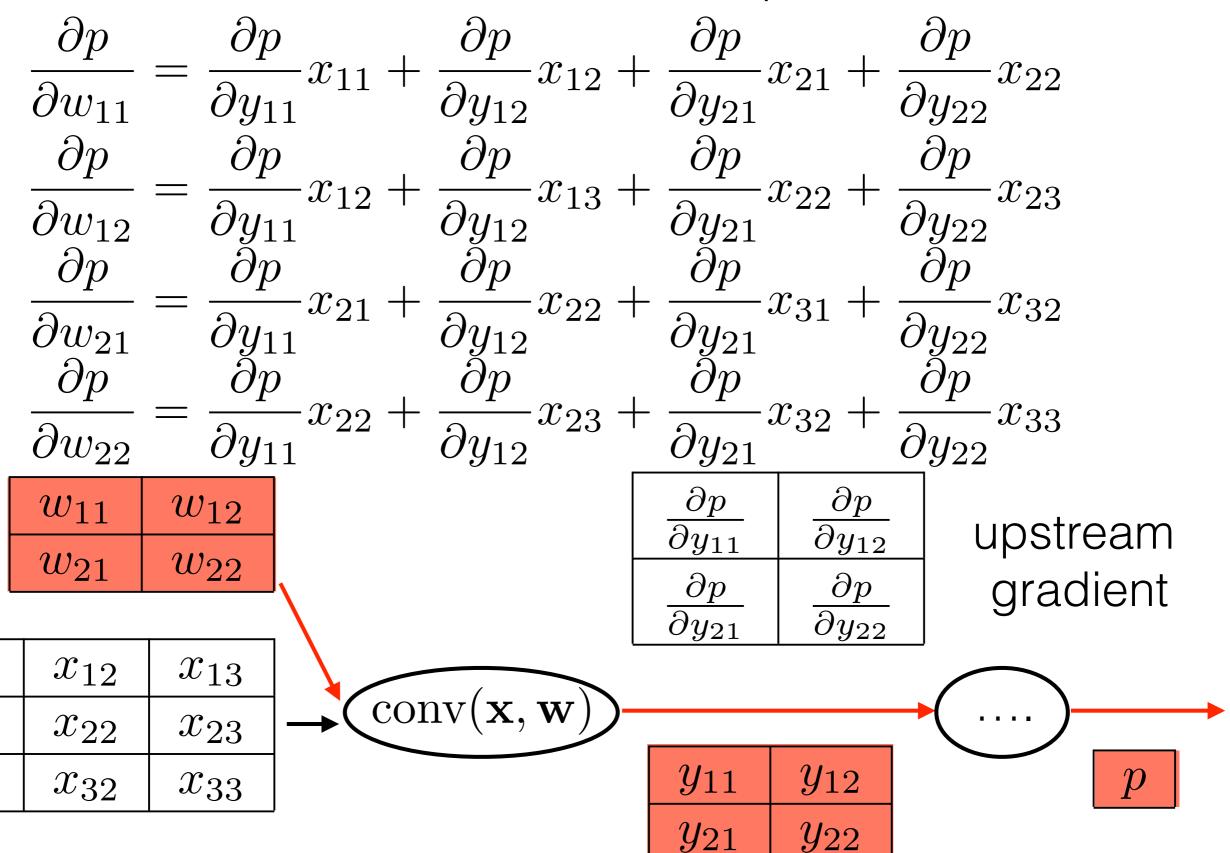
$$\frac{\partial p}{\partial w_{21}} = \frac{\partial p}{\partial y_{11}} x_{21} + \frac{\partial p}{\partial y_{12}} x_{22} + \frac{\partial p}{\partial y_{21}} x_{31} + \frac{\partial p}{\partial y_{22}} x_{32}$$













 $x_{11}$ 

 $x_{21}$ 

 $x_{31}$ 

$$\frac{\partial p}{\partial w_{11}} = \frac{\partial p}{\partial y_{11}} x_{11} + \frac{\partial p}{\partial y_{12}} x_{12} + \frac{\partial p}{\partial y_{21}} x_{21} + \frac{\partial p}{\partial y_{22}} x_{22}$$

$$\frac{\partial p}{\partial w_{12}} = \frac{\partial p}{\partial y_{11}} x_{12} + \frac{\partial p}{\partial y_{12}} x_{13} + \frac{\partial p}{\partial y_{21}} x_{22} + \frac{\partial p}{\partial y_{22}} x_{23}$$

$$\frac{\partial p}{\partial w_{21}} = \frac{\partial p}{\partial y_{11}} x_{21} + \frac{\partial p}{\partial y_{12}} x_{22} + \frac{\partial p}{\partial y_{21}} x_{31} + \frac{\partial p}{\partial y_{22}} x_{32}$$

$$\frac{\partial p}{\partial w_{22}} = \frac{\partial p}{\partial y_{11}} x_{22} + \frac{\partial p}{\partial y_{12}} x_{23} + \frac{\partial p}{\partial y_{21}} x_{32} + \frac{\partial p}{\partial y_{22}} x_{33}$$

$\frac{\partial p}{\partial w_{11}}$	$\frac{\partial p}{\partial w_{12}}$	(
$rac{\partial p}{\partial w_{21}}$	$rac{\partial p}{\partial w_{22}}$	<b>=</b> conv (

,	$x_{11}$	$x_{12}$	$x_{13}$	
	$x_{21}$	$x_{22}$	$x_{23}$	
,	$x_{31}$	$x_{32}$	$x_{33}$	<b>ر</b>
'			<u> </u>	,

$rac{\partial p}{\partial y_{11}}$	$rac{\partial p}{\partial y_{12}}$
$rac{\partial p}{\partial y_{21}}$	$rac{\partial p}{\partial y_{22}}$



$$\frac{\partial p}{\partial w_{11}} = \frac{\partial p}{\partial y_{11}} x_{11} + \frac{\partial p}{\partial y_{12}} x_{12} + \frac{\partial p}{\partial y_{21}} x_{21} + \frac{\partial p}{\partial y_{22}} x_{22}$$

$$\frac{\partial p}{\partial w_{12}} = \frac{\partial p}{\partial y_{11}} x_{12} + \frac{\partial p}{\partial y_{12}} x_{13} + \frac{\partial p}{\partial y_{21}} x_{22} + \frac{\partial p}{\partial y_{22}} x_{23}$$

$$\frac{\partial p}{\partial w_{21}} = \frac{\partial p}{\partial y_{11}} x_{21} + \frac{\partial p}{\partial y_{12}} x_{22} + \frac{\partial p}{\partial y_{21}} x_{31} + \frac{\partial p}{\partial y_{22}} x_{32}$$

$$\frac{\partial p}{\partial w_{22}} = \frac{\partial p}{\partial y_{11}} x_{22} + \frac{\partial p}{\partial y_{12}} x_{23} + \frac{\partial p}{\partial y_{21}} x_{32} + \frac{\partial p}{\partial y_{22}} x_{33}$$

$rac{\partial p}{\partial w_{11}}$	$\frac{\partial p}{\partial w_{12}}$
$rac{\partial p}{\partial w_{21}}$	$rac{\partial p}{\partial w_{22}}$

 $= \operatorname{conv} \left( \begin{array}{c|cccc} x_{11} & x_{12} & x_{13} \\ \hline x_{21} & x_{22} & x_{23} \\ \hline x_{31} & x_{32} & x_{33} \end{array} \right)$ 

$rac{\partial p}{\partial y_{11}}$	$rac{\partial p}{\partial y_{12}}$
$rac{\partial p}{\partial y_{21}}$	$\frac{\partial p}{\partial y_{22}}$



$$\frac{\partial p}{\partial w_{11}} = \frac{\partial p}{\partial y_{11}} x_{11} + \frac{\partial p}{\partial y_{12}} x_{12} + \frac{\partial p}{\partial y_{21}} x_{21} + \frac{\partial p}{\partial y_{22}} x_{22}$$

$$\frac{\partial p}{\partial w_{12}} = \frac{\partial p}{\partial y_{11}} x_{12} + \frac{\partial p}{\partial y_{12}} x_{13} + \frac{\partial p}{\partial y_{21}} x_{22} + \frac{\partial p}{\partial y_{22}} x_{23}$$

$$\frac{\partial p}{\partial w_{21}} = \frac{\partial p}{\partial y_{11}} x_{21} + \frac{\partial p}{\partial y_{12}} x_{22} + \frac{\partial p}{\partial y_{21}} x_{31} + \frac{\partial p}{\partial y_{22}} x_{32}$$

$$\frac{\partial p}{\partial w_{22}} = \frac{\partial p}{\partial y_{11}} x_{22} + \frac{\partial p}{\partial y_{12}} x_{23} + \frac{\partial p}{\partial y_{21}} x_{32} + \frac{\partial p}{\partial y_{22}} x_{33}$$

$\partial p$	$\partial p$		$x_{11}$
$\partial w_{11}$	$\partial w_{12}$	= conv	$x_{21}$
$rac{\partial p}{\partial w_{21}}$	$rac{\partial p}{\partial w_{22}}$		$x_{31}$

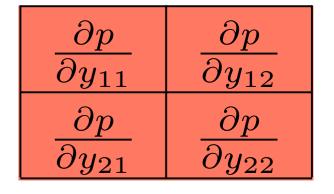
,	$x_{11}$	$x_{12}$	$x_{13}$
	$x_{21}$	$x_{22}$	$x_{23}$
	$x_{31}$	$x_{32}$	$x_{33}$

$rac{\partial p}{\partial y_{11}}$	$\frac{\partial p}{\partial y_{12}}$
$rac{\partial p}{\partial y_{21}}$	$rac{\partial p}{\partial y_{22}}$



$$\frac{\partial p}{\partial w_{11}} = \frac{\partial p}{\partial y_{11}} x_{11} + \frac{\partial p}{\partial y_{12}} x_{12} + \frac{\partial p}{\partial y_{21}} x_{21} + \frac{\partial p}{\partial y_{22}} x_{22} 
\frac{\partial p}{\partial w_{12}} = \frac{\partial p}{\partial y_{11}} x_{12} + \frac{\partial p}{\partial y_{12}} x_{13} + \frac{\partial p}{\partial y_{21}} x_{22} + \frac{\partial p}{\partial y_{22}} x_{23} 
\frac{\partial p}{\partial w_{21}} = \frac{\partial p}{\partial y_{11}} x_{21} + \frac{\partial p}{\partial y_{12}} x_{22} + \frac{\partial p}{\partial y_{21}} x_{31} + \frac{\partial p}{\partial y_{22}} x_{32} 
\frac{\partial p}{\partial w_{22}} = \frac{\partial p}{\partial y_{11}} x_{22} + \frac{\partial p}{\partial y_{12}} x_{23} + \frac{\partial p}{\partial y_{21}} x_{32} + \frac{\partial p}{\partial y_{22}} x_{33}$$

$oxed{\partial p}$	$\partial p$		$x_{11}$	$x_{12}$	$x_{13}$
$\overline{\partial w_{11}}$	$\partial w_{12}$	<b>c</b> onv	$x_{21}$	$x_{22}$	$x_{23}$
$\frac{\partial p}{\partial w_{21}}$	$rac{\partial p}{\partial w_{22}}$	\	$x_{31}$	$x_{32}$	$x_{33}$

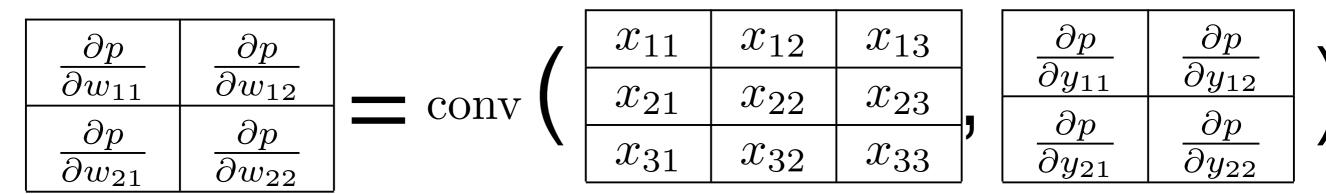




## Convolution backward pass wrt weights

Backpropagation in convolutional layer wrt weights is:

## "convolution of input feature map with upstream gradient"



	$w_{11}$ $w_{21}$	$w_{12}$ $w_{22}$		$\frac{\partial p}{\partial y_{11}}$ $\frac{\partial p}{\partial y_{21}}$	$\frac{\partial p}{\partial y_{12}}$ $\frac{\partial p}{\partial y_{22}}$	upstream gradient
$x_{11}$	$x_{12}$	$x_{13}$			, ,	
$x_{21}$	$x_{22}$	$x_{23}$	$\rightarrow$ $(conv(\mathbf{x}, \mathbf{w}))$			• • • • • • • • • • • • • • • • • • • •
$x_{31}$	$x_{32}$	$x_{33}$		$y_{11}$	$y_{12}$	p
				7/01	7/22	

921

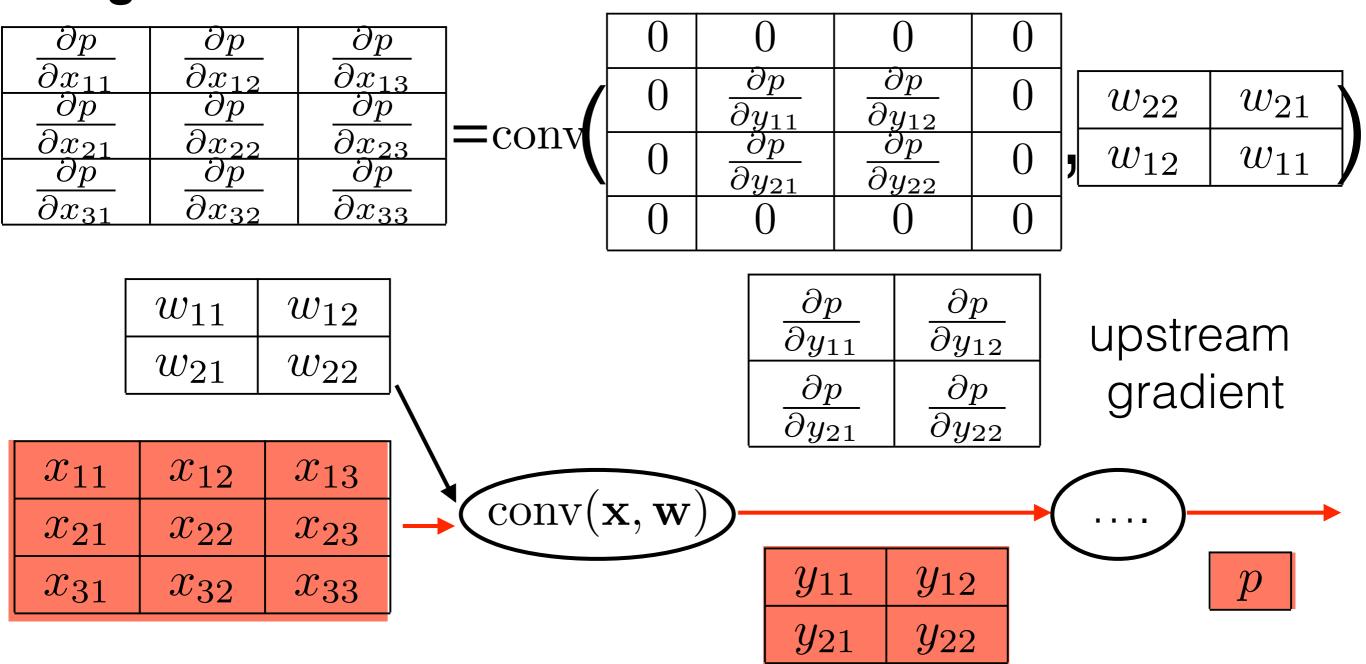
922



## Convolution backward pass wrt input feature map

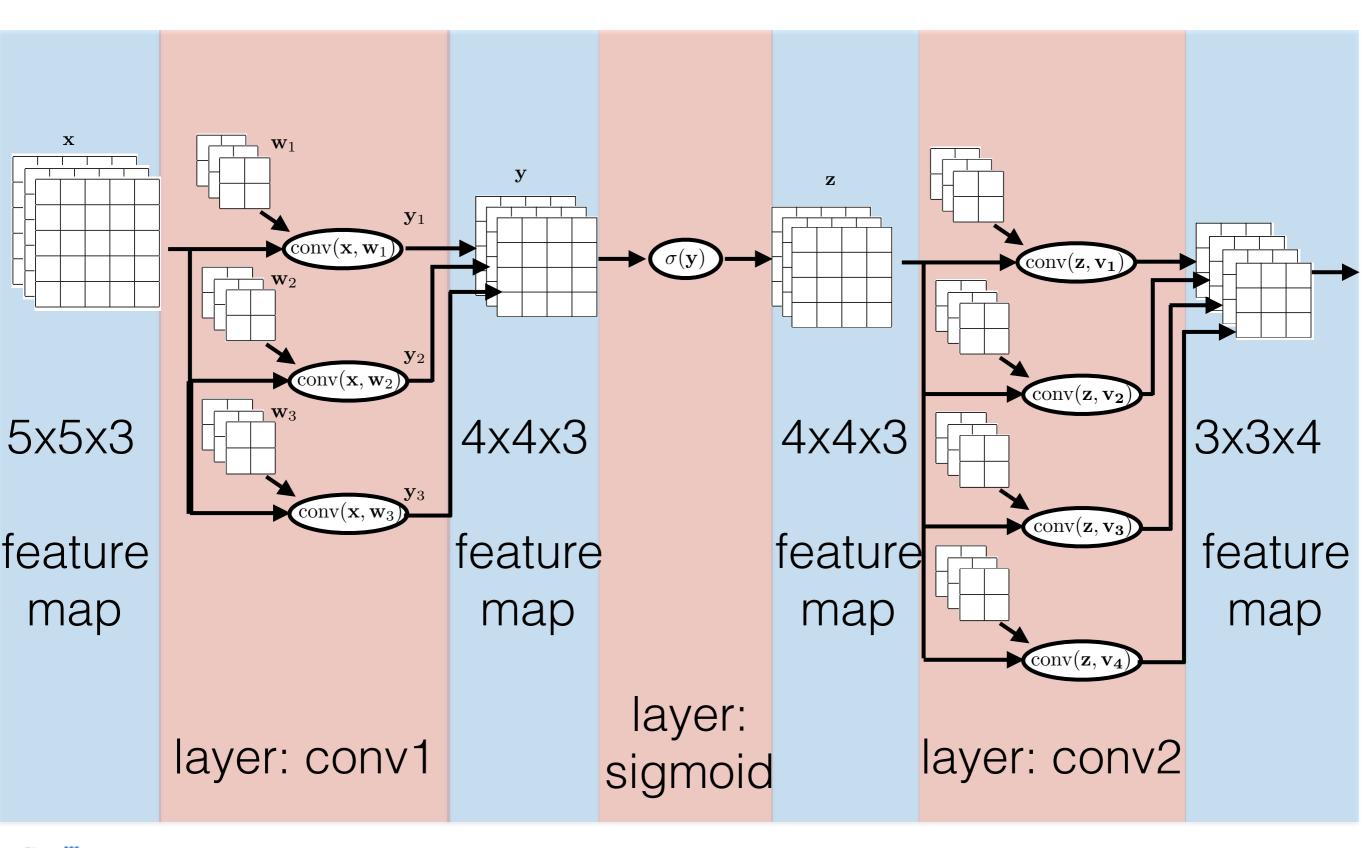
Backpropagation in convolutional layer is:

## "convolution of padded upstream gradient with mirrored weights"





## ???? Convolutional network backprop ?????



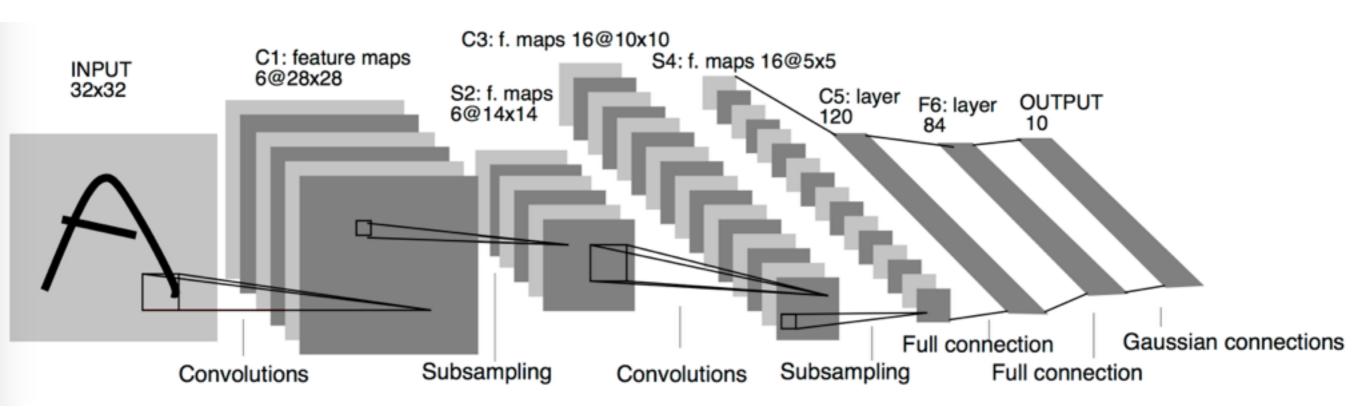


#### Convolutional net

- Convolutional network (ConvNet) is concatenation of convolutional layers
- Backprop in ConvNet is convolution of feature maps or kernels with upstream gradient.
- Feed-forward and backprop are concolutions => efficient implementation on GPU



## LeCun's letter recognition 1998 (over 13k citations !!!)

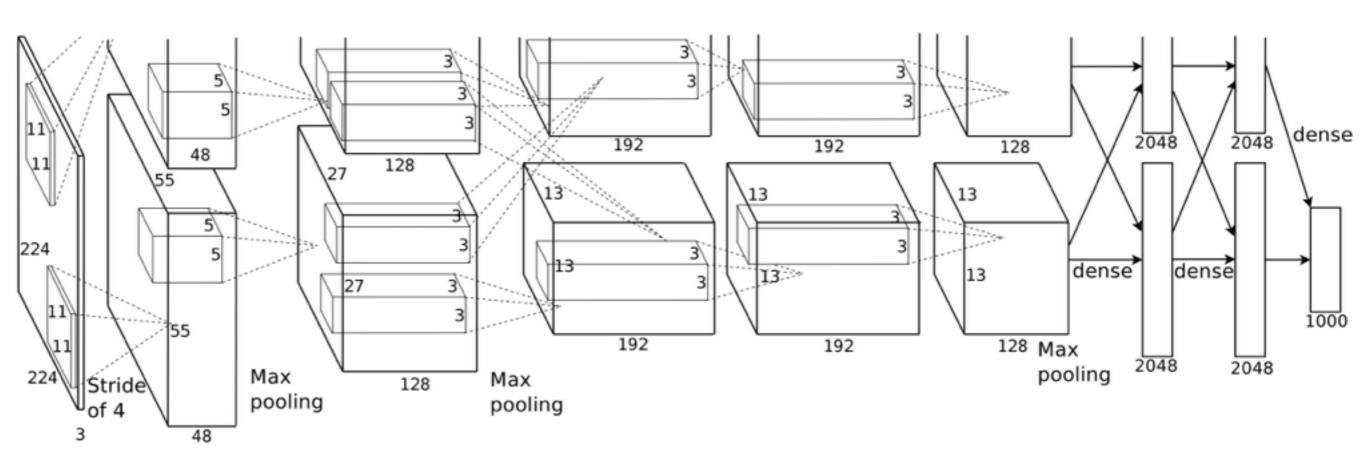


LeCun et al, Gradient based learning applied to document recognition, IEEE, 1998

http://yann.lecun.com/exdb/publis/pdf/lecun-01a.pdf



## AlexNet on ImageNet 2012 (over 27k citations !!!)



Alex Krizhevsky et al, Imagenet classification with deep convolutional neural networks, NIPS, 2012 <a href="https://papers.nips.cc/paper/4824-imagenet-classification-with-deep-convolutional-neural-networks.pdf">https://papers.nips.cc/paper/4824-imagenet-classification-with-deep-convolutional-neural-networks.pdf</a>





http://image-net.org/challenges/LSVRC/2017/index

#### Steel drum



#### Output:

Scale
T-shirt
Steel drum
Drumstick
Mud turtle



#### Output:

Scale T-shirt Giant panda Drumstick Mud turtle



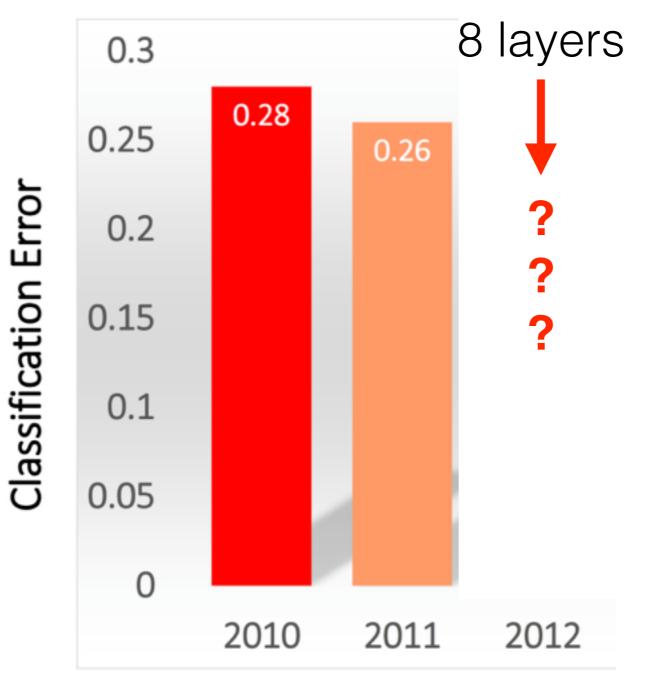
Error = 
$$\frac{1}{100,000}$$
 1[incorrect on image i]

100,000 images





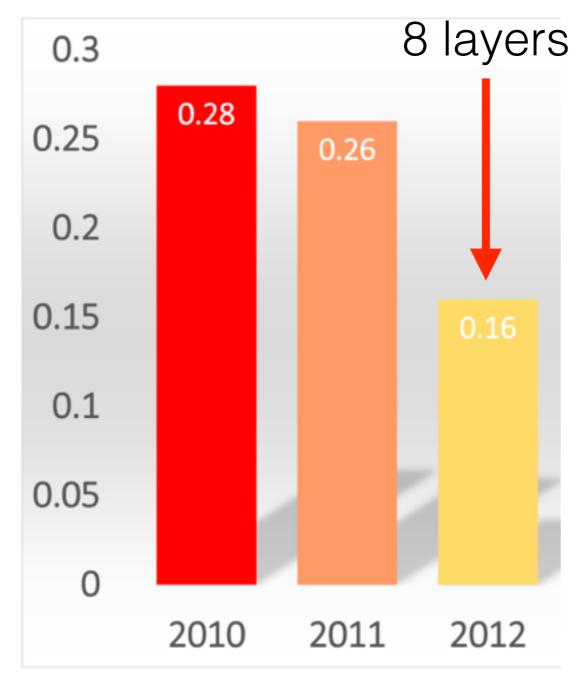
AlexNet







AlexNet

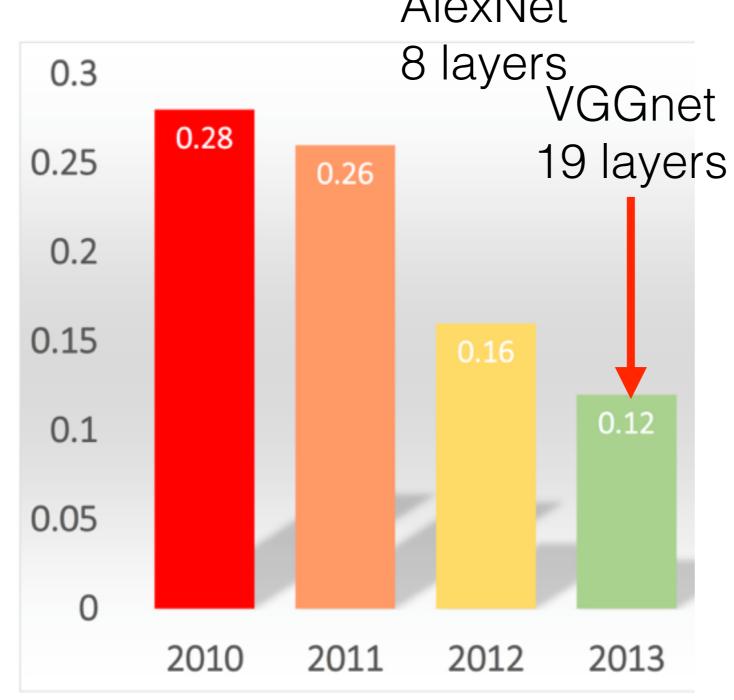




Classification Error





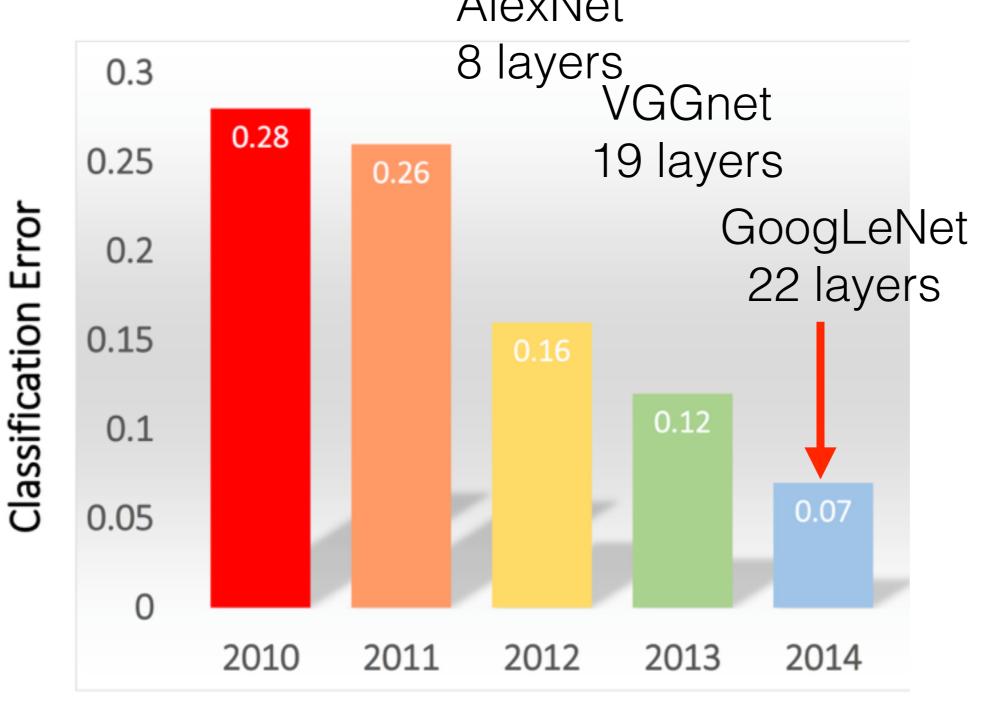




Classification Error



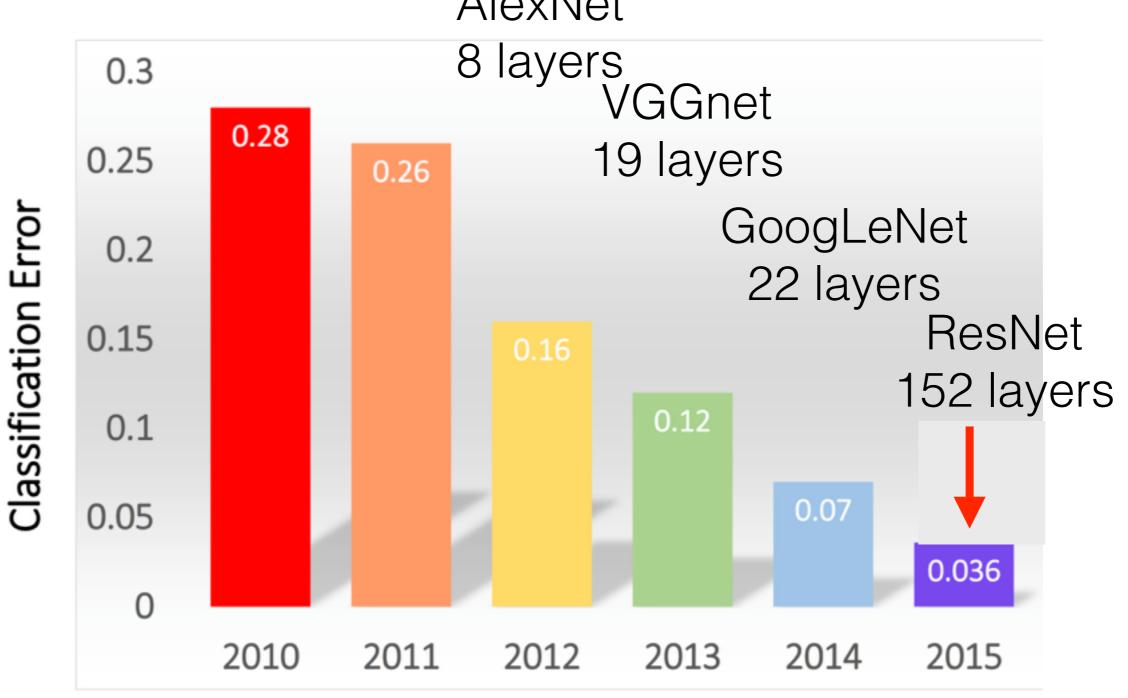
Classification results AlexNet







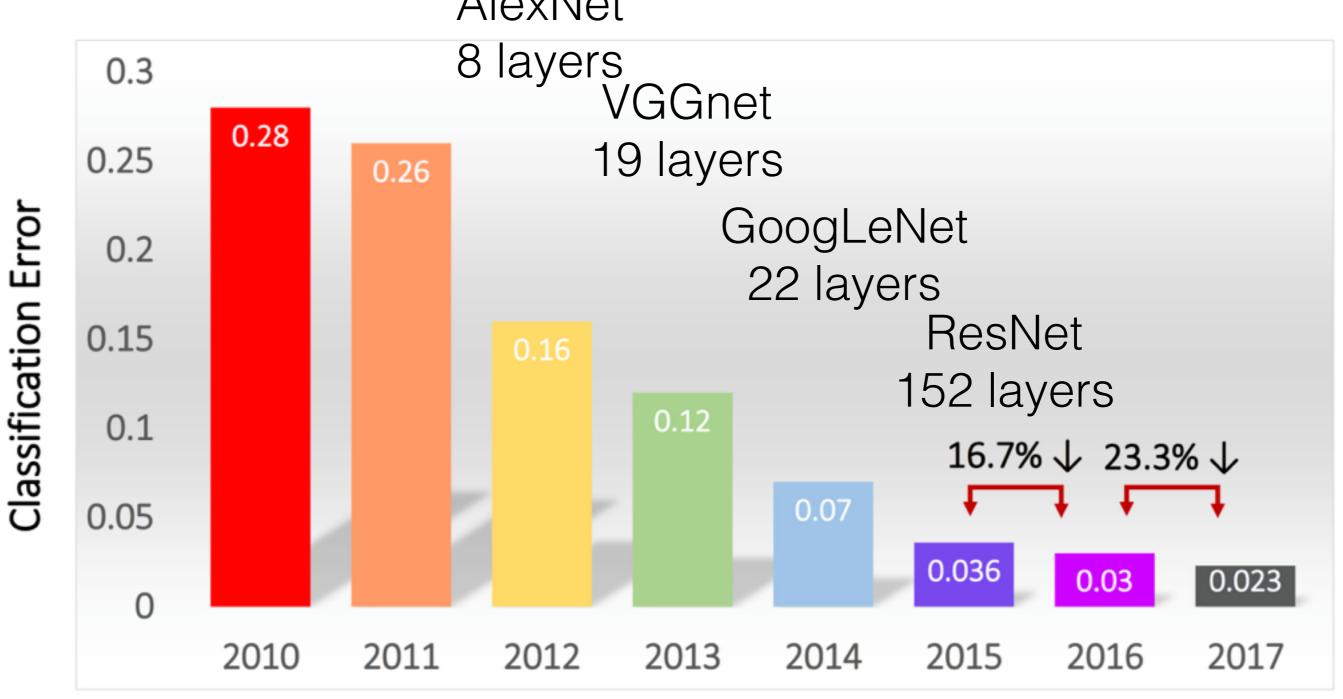
AlexNet







AlexNet





#### Demo

 convnet demo from Karpathy: <a href="https://cs.stanford.edu/people/karpathy/convnetjs/demo/cifar10.html">https://cs.stanford.edu/people/karpathy/convnetjs/demo/cifar10.html</a>



#### Next lecture

- gradient learning (what make it tough)
- other layers:
  - activation function,
  - batch normalization,
  - drop out,
  - loss layers

