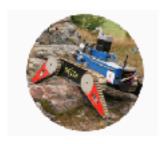
Learning for vision II Neural networks

Karel Zimmermann

http://cmp.felk.cvut.cz/~zimmerk/



Vision for Robotics and Autonomous Systems https://cyber.felk.cvut.cz/vras/



Center for Machine Perception https://cmp.felk.cvut.cz



Department for Cybernetics
Faculty of Electrical Engineering
Czech Technical University in Prague



Outline

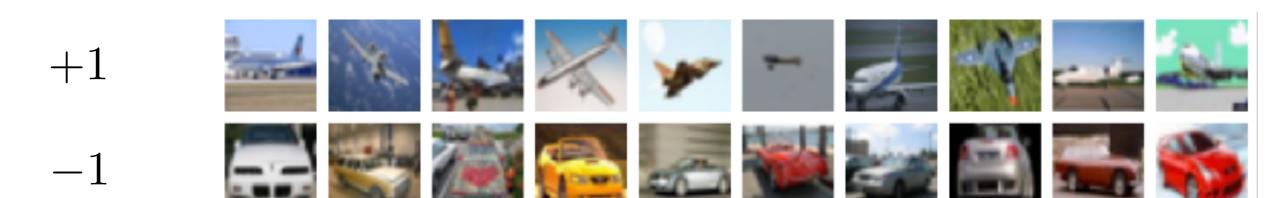
- Neuron+ computational graph
- Fully connected neural network



Linear classifier and neuron

Labels

RGB images



def classify():



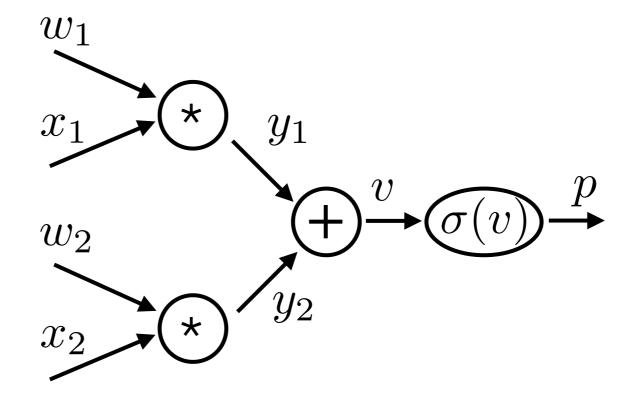
Linear classifier

$$\mathbf{x} = \text{vec}($$

$$p = \sigma\left(\mathbf{w}^{\top}\mathbf{x}\right)$$

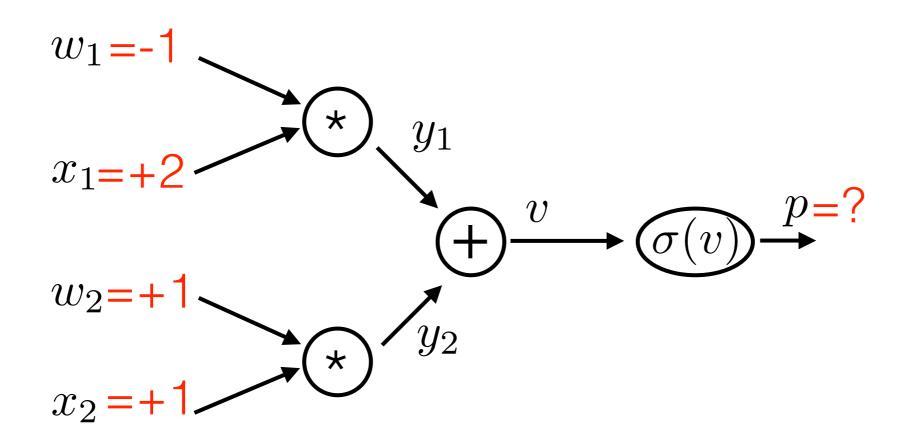
return p

Computational graph of linear classifier



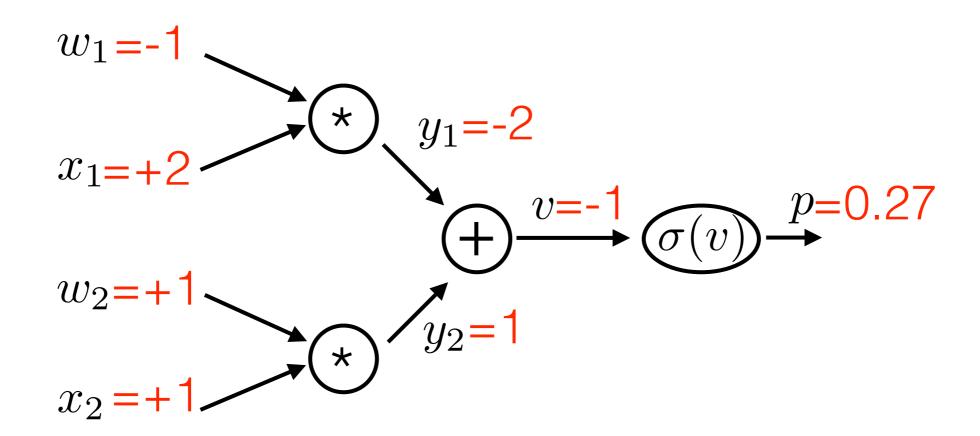


Example I: given trained neuron, and input, what is output?



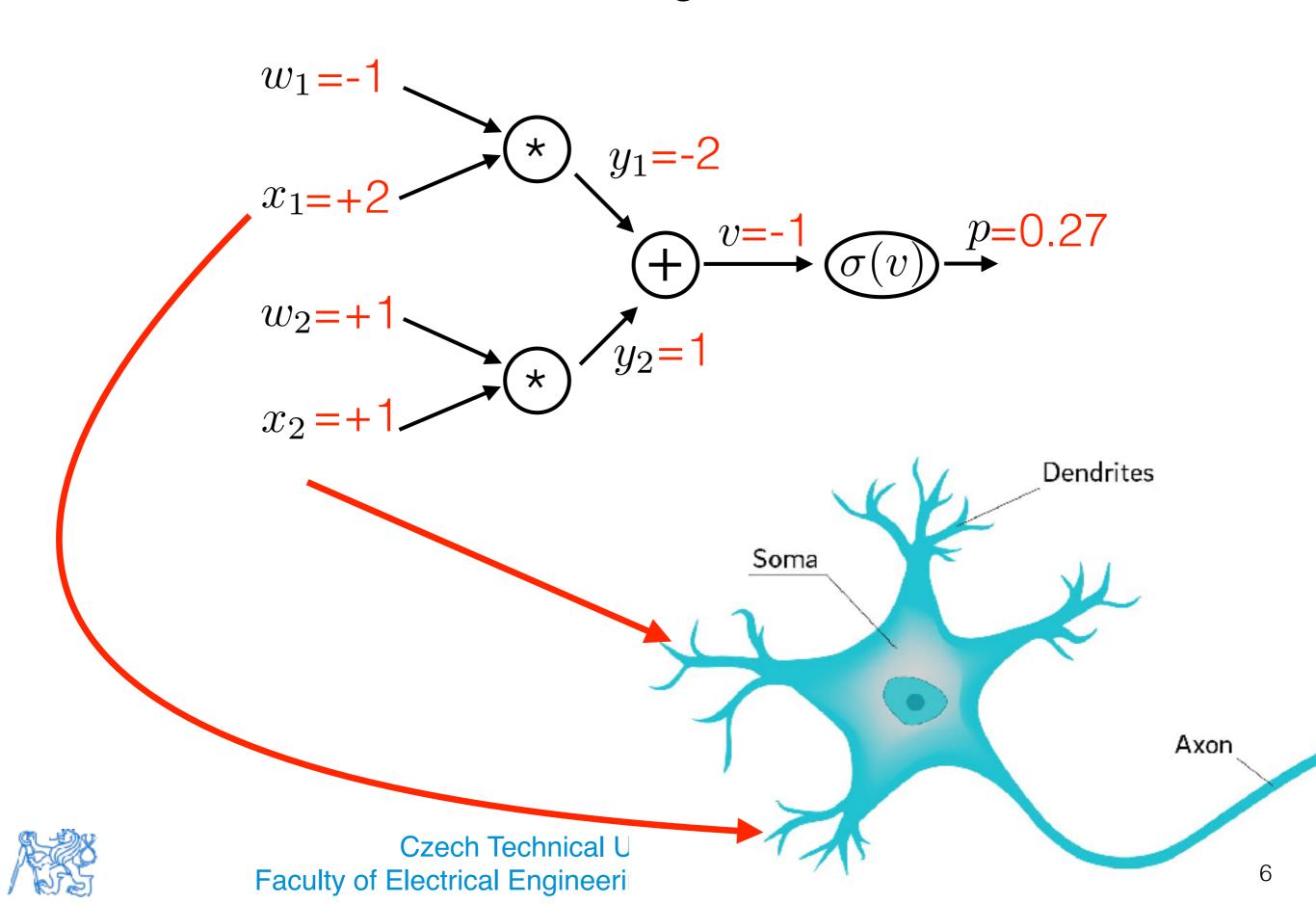


Example I: given trained classifier, and input, what is output?

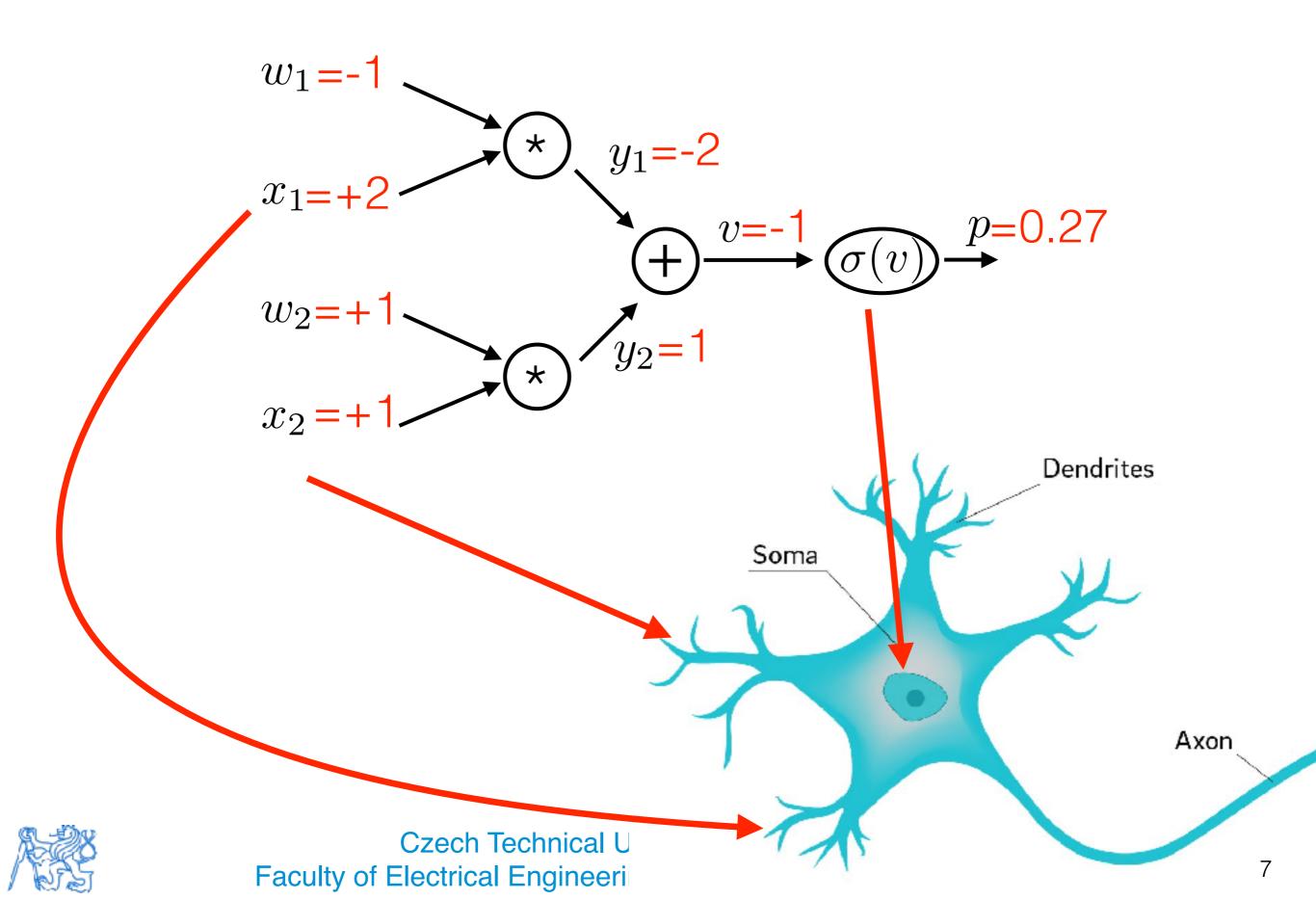




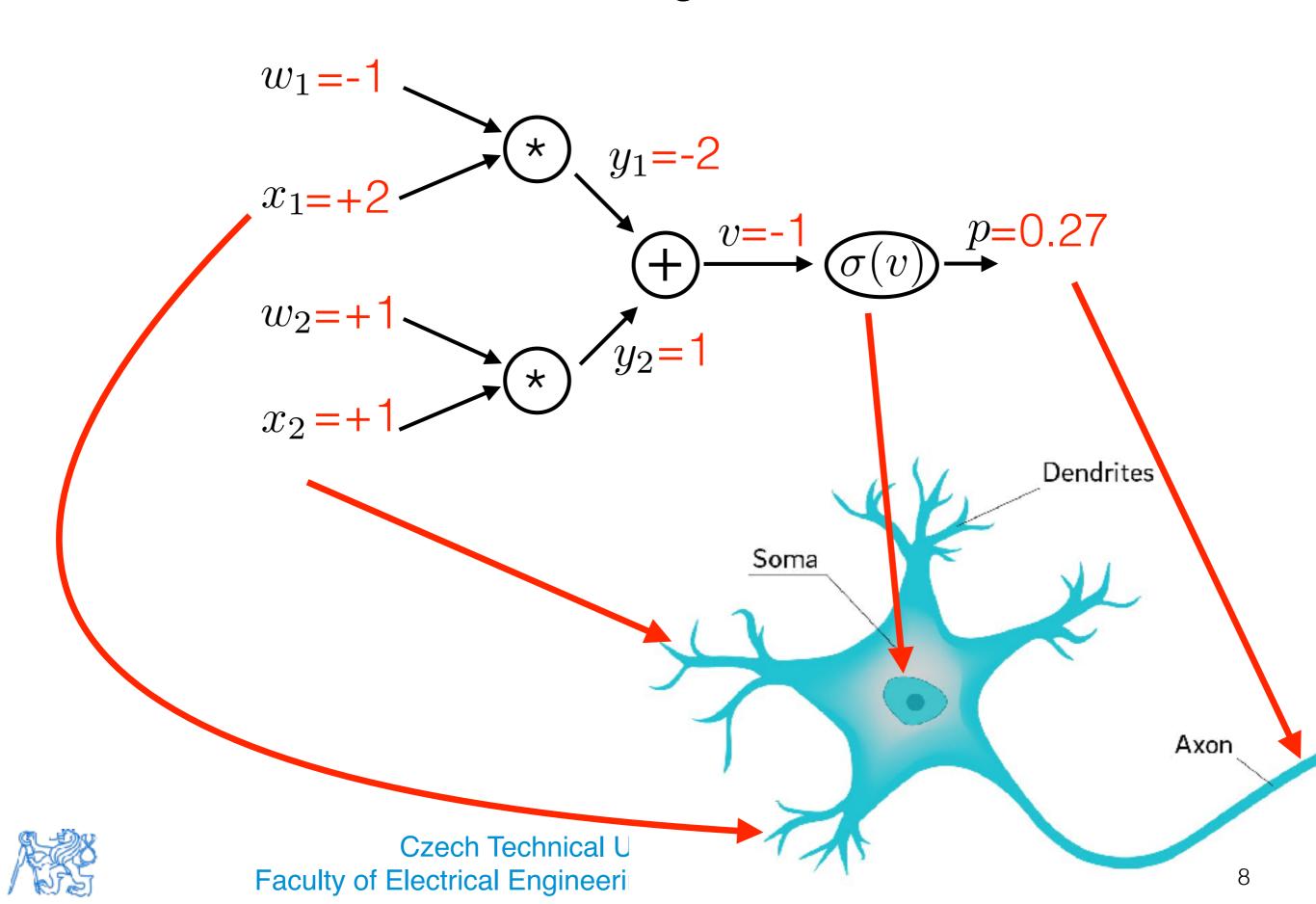
Relation to biological neuron



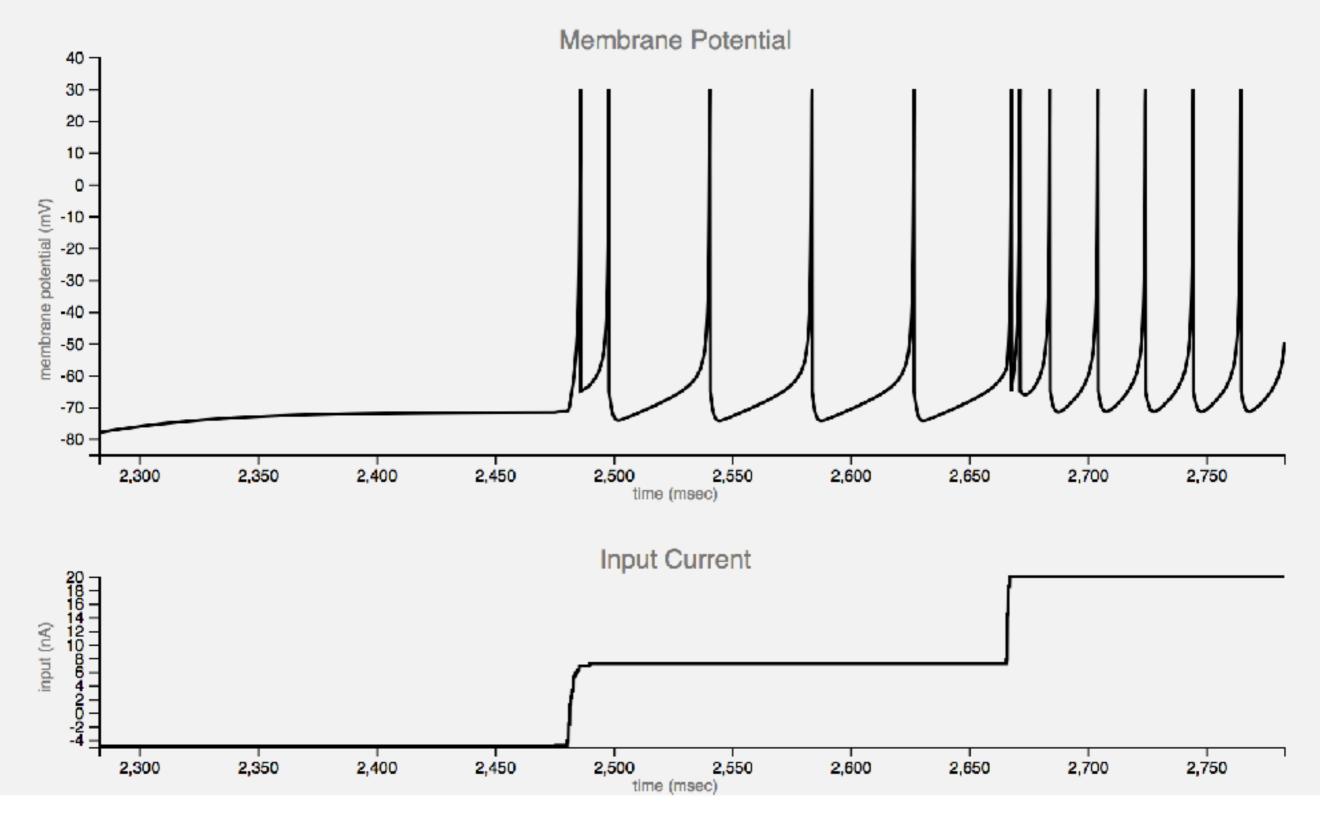
Relation to biological neuron



Relation to biological neuron



Modeling dynamic neuron behaviour



http://jackterwilliger.com/biological-neural-networks-part-i-spiking-neurons/

Linear classifier and neuron

Labels

RGB images













































def classify():



Linear classifier

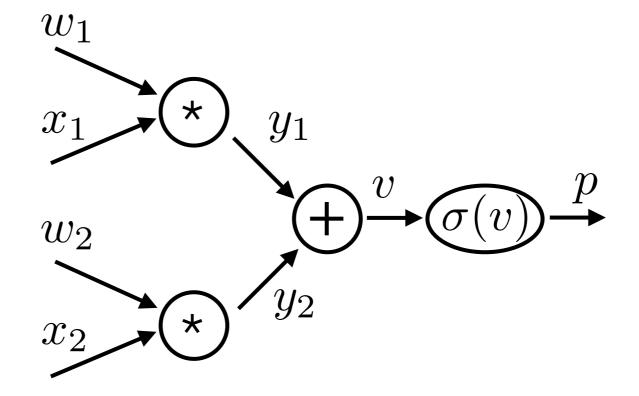
$$\mathbf{x} = \text{vec}($$



$$p = \sigma\left(\mathbf{w}^{\top}\mathbf{x}\right)$$

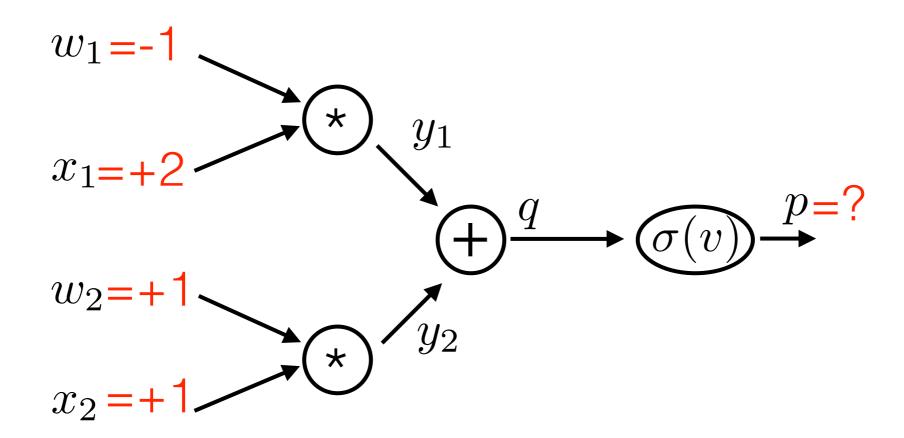
return p

Computational graph of linear classifier



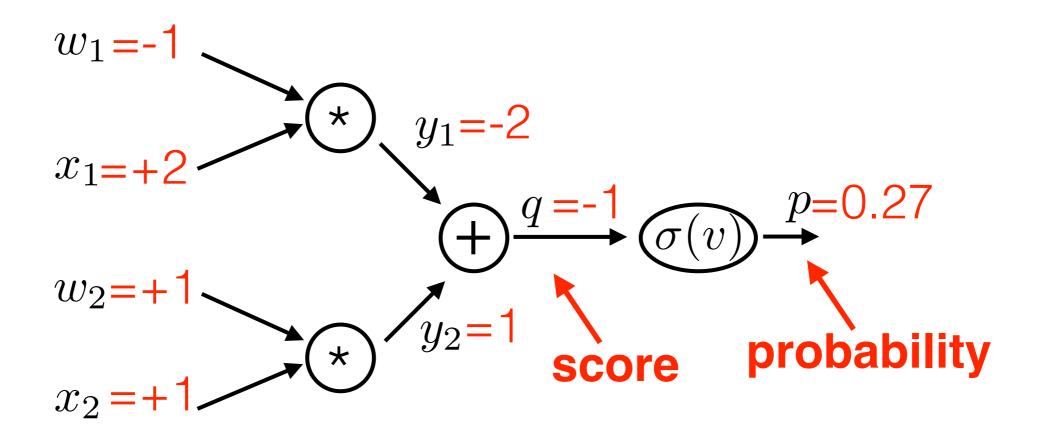


Example I: given trained neuron, and input, what is output?

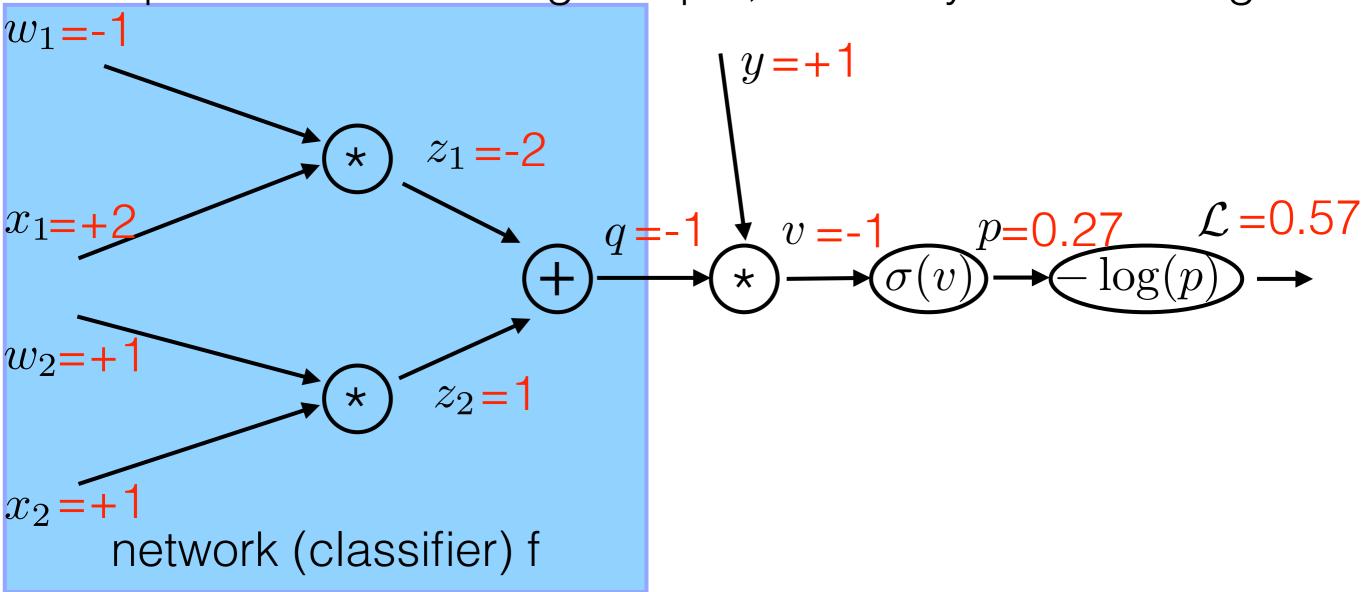




Example I: given trained classifier, and input, what is output?

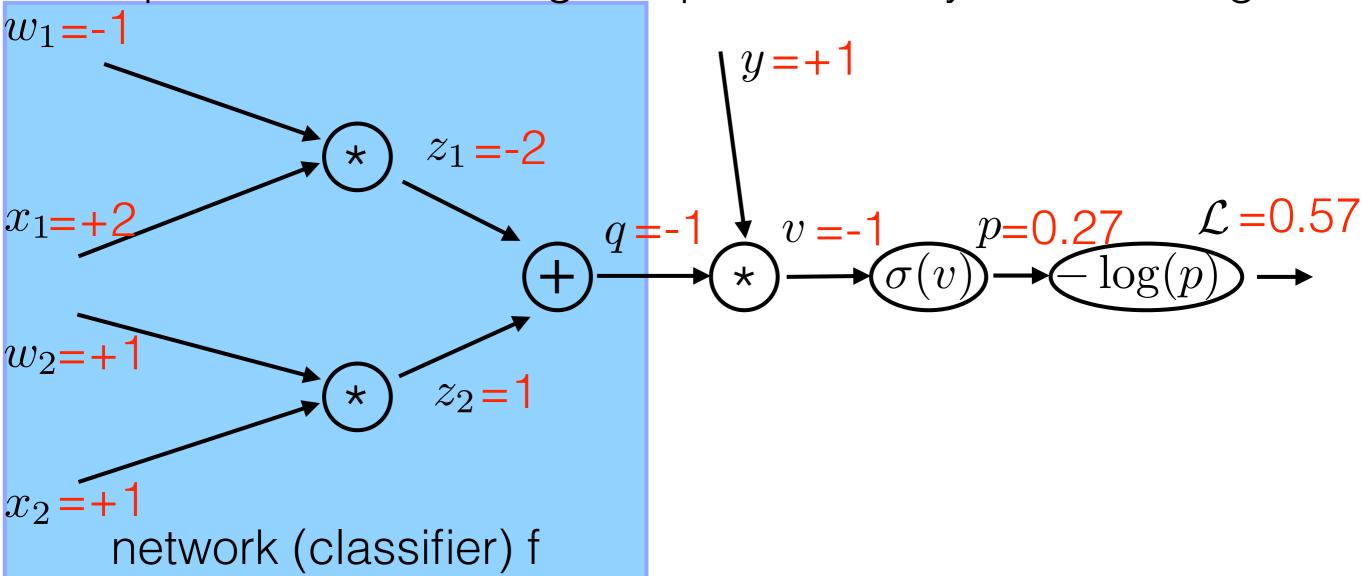




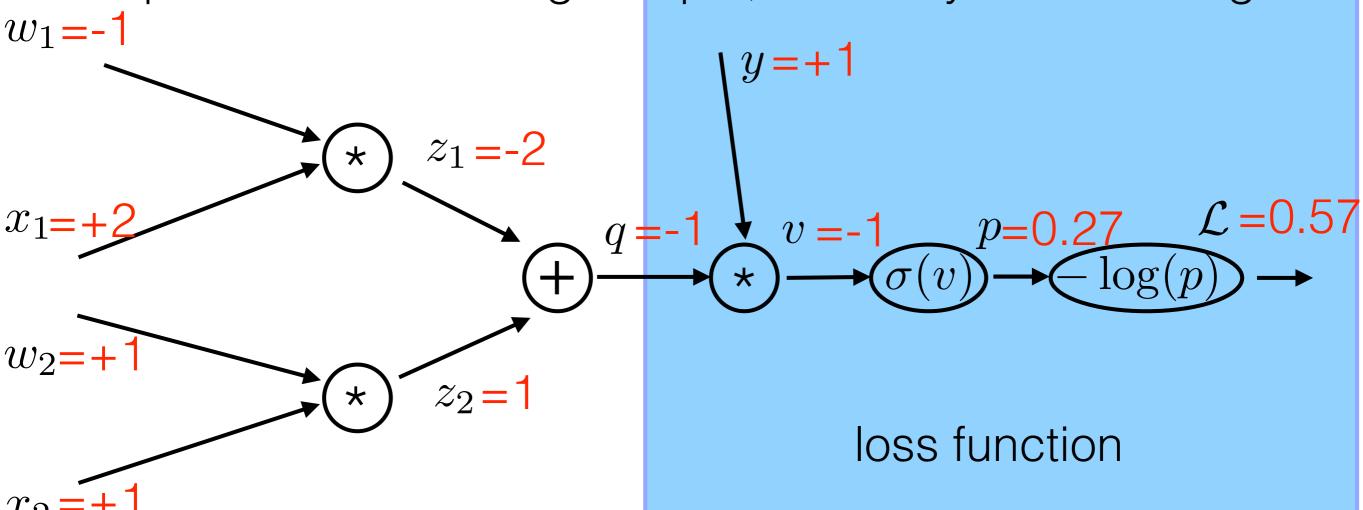


$$\arg\min_{\mathbf{w}} \left(-\log \left[\sigma(y_i f(\mathbf{x}_i, \mathbf{w})) \right] \right)$$

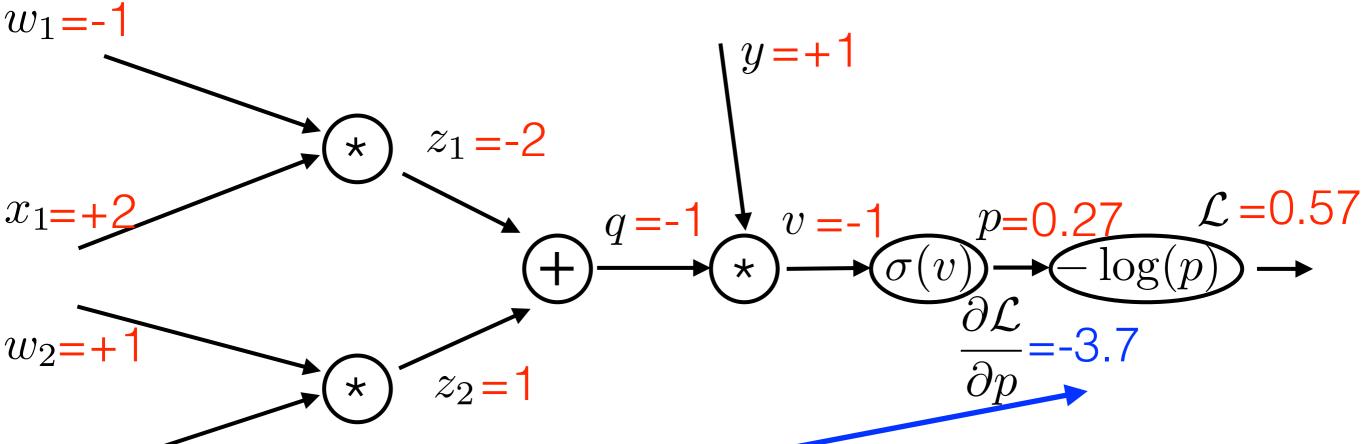






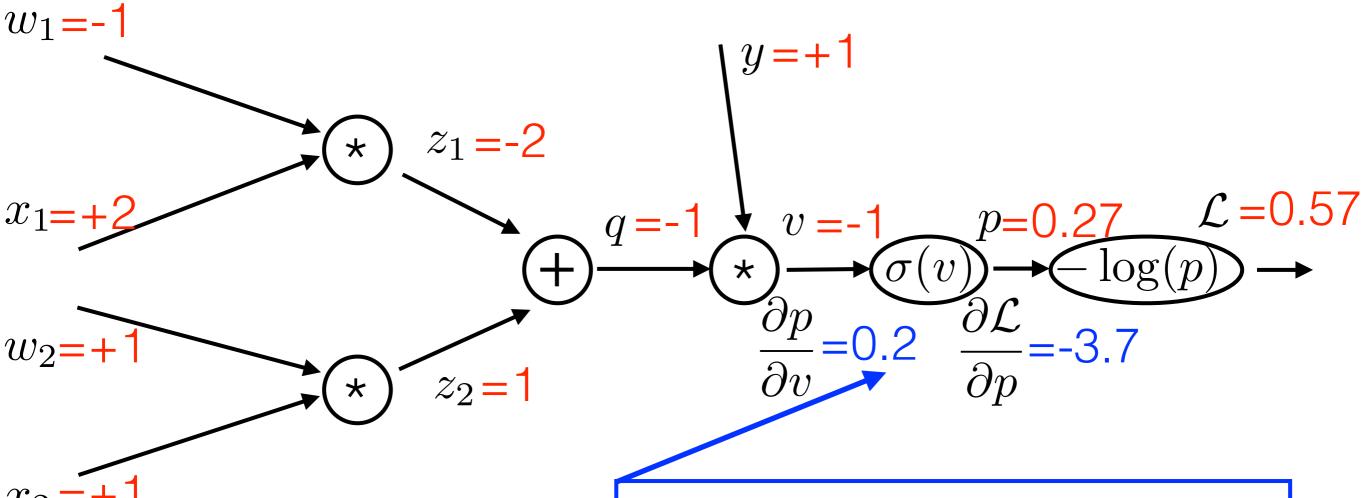






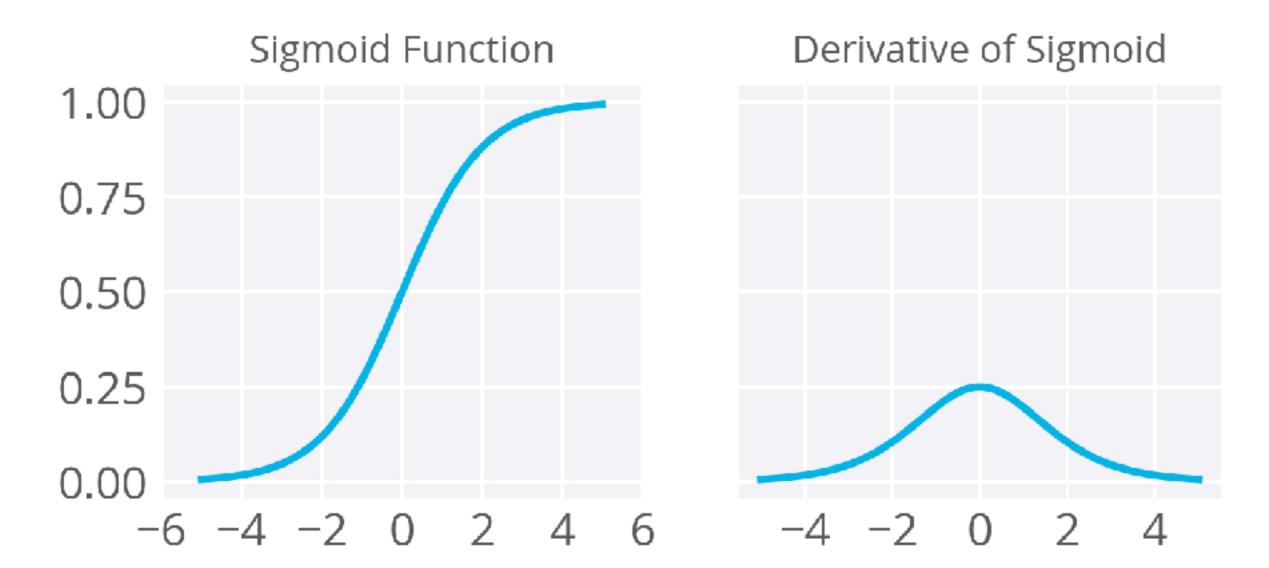
$$\frac{\partial \mathcal{L}}{\partial p} = \frac{\partial (-\log(p))}{\partial p} = -\frac{1}{p}$$





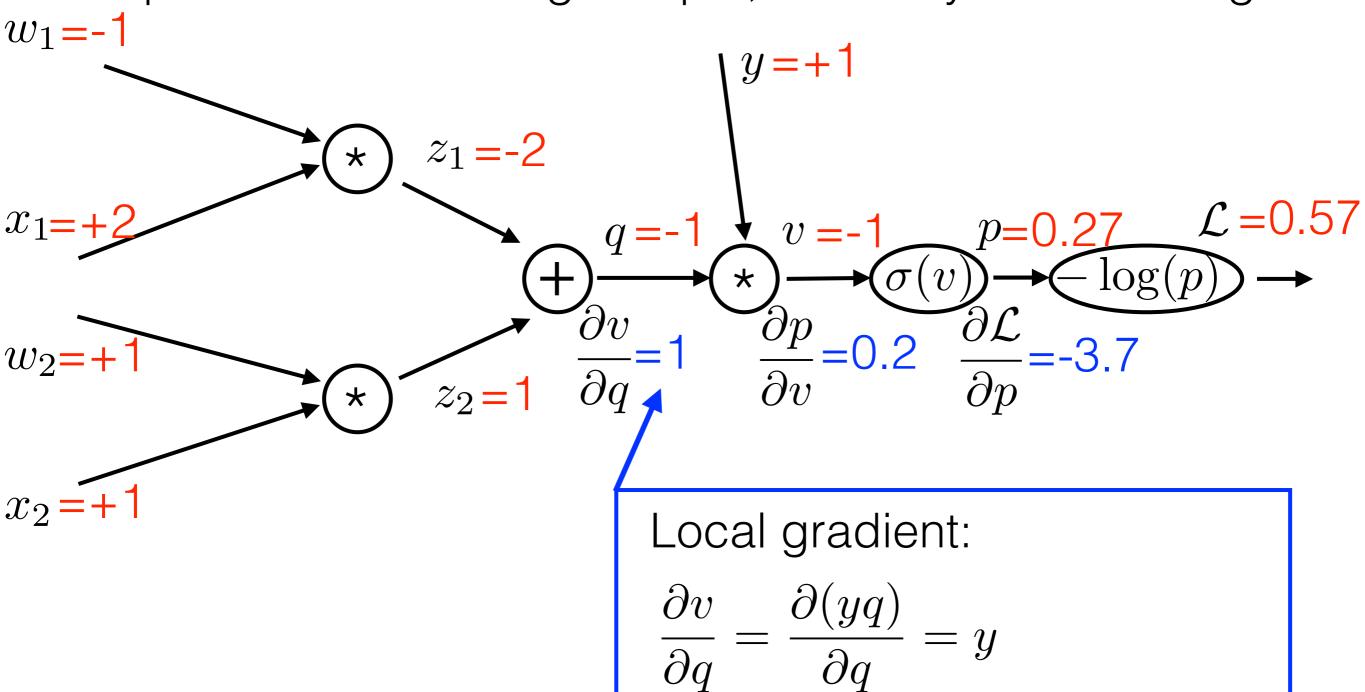
$$\frac{\partial p}{\partial v} = \frac{\partial \sigma(v)}{\partial v} = \sigma(v)(1 - \sigma(v))$$



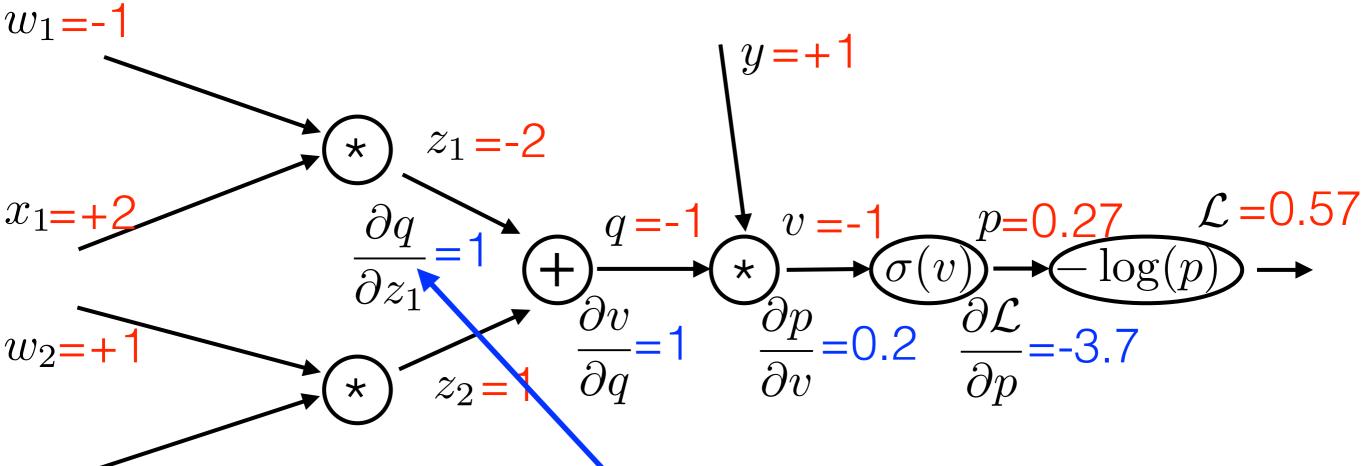


$$\frac{\partial p}{\partial v} = \frac{\partial \sigma(v)}{\partial v} = \sigma(v)(1 - \sigma(v))$$



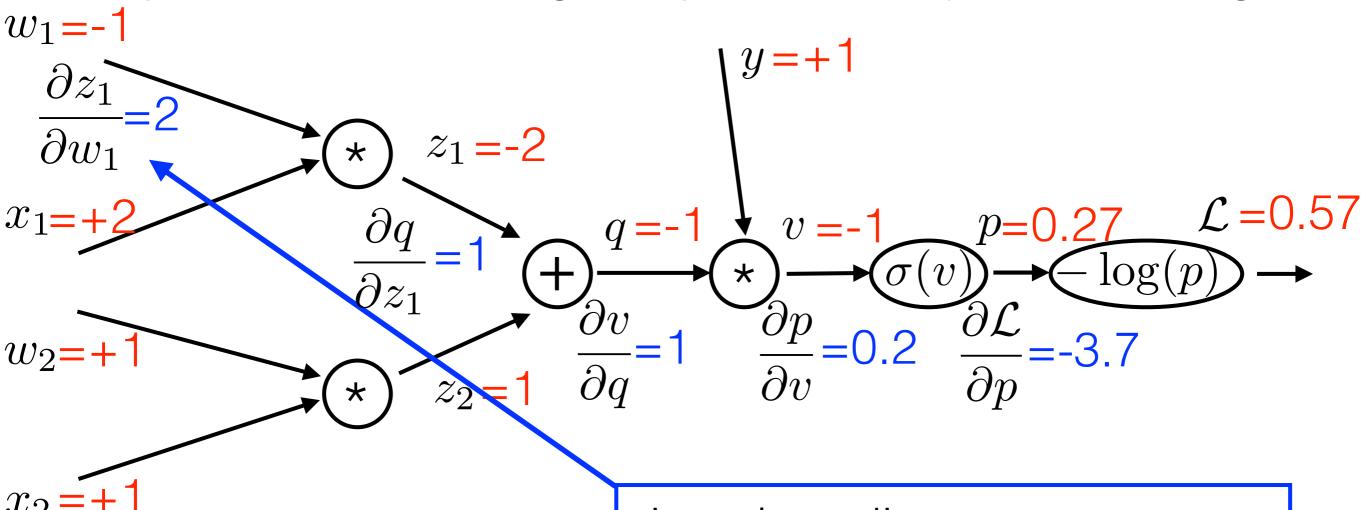






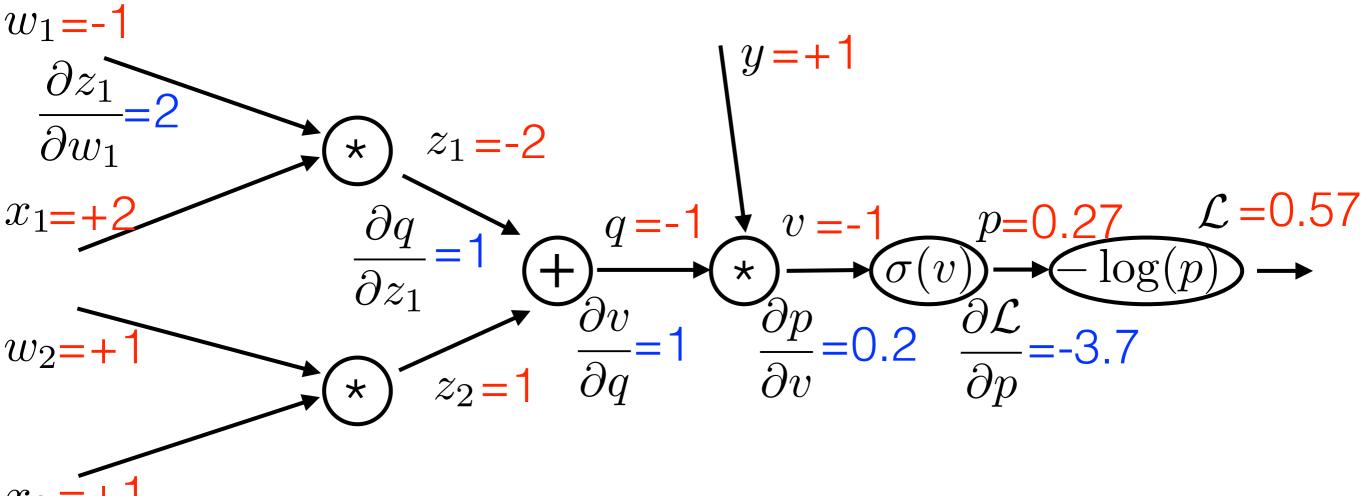
$$\frac{\partial q}{\partial z_1} = \frac{\partial (z_1 + z_2)}{\partial z_1} = 1$$





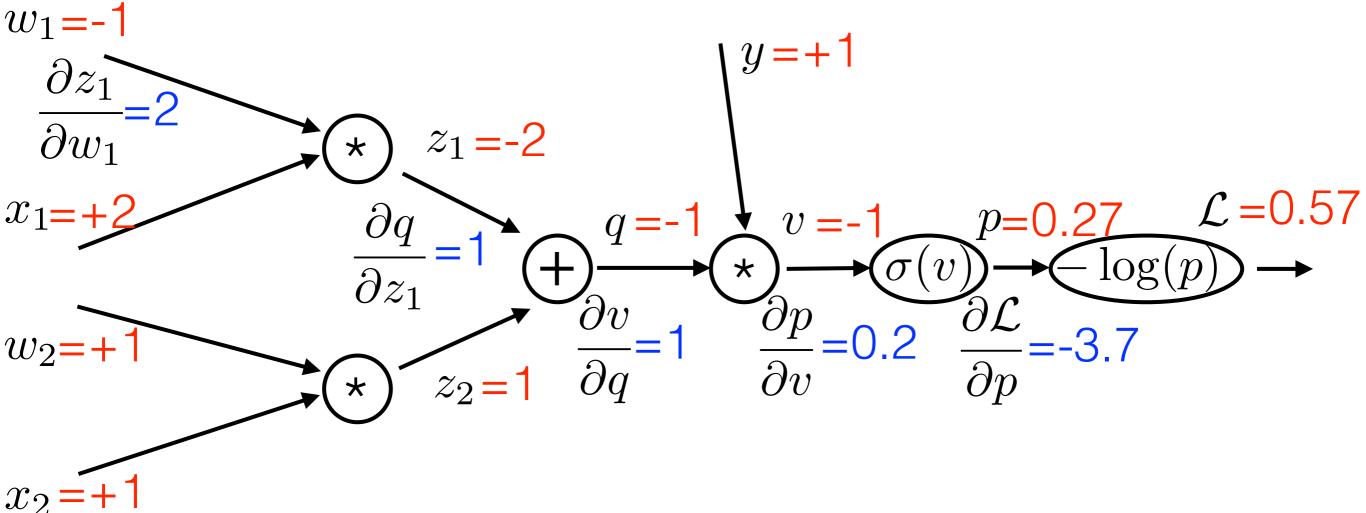
$$\frac{\partial z_1}{\partial w_1} = \frac{\partial (w_1 x_1)}{\partial w_1} = x_1$$





$$\frac{\partial \mathcal{L}}{\partial w_1} = \frac{\partial \mathcal{L}}{\partial p} \frac{\partial p}{\partial v} \frac{\partial v}{\partial q} \frac{\partial q}{\partial z_1} \frac{\partial z_1}{\partial w_1} = -3.7^*0.2^*1^*1^*2 = -1.48$$

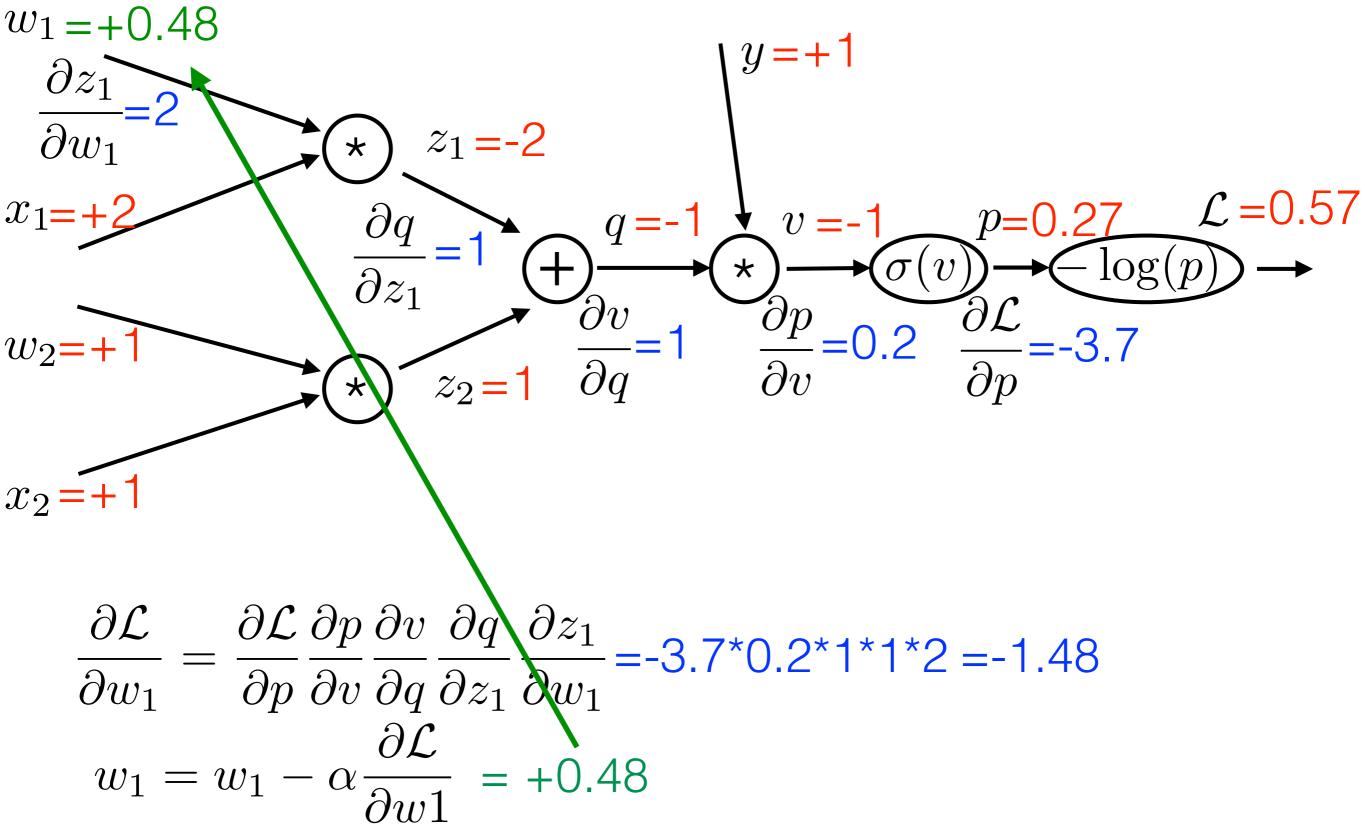




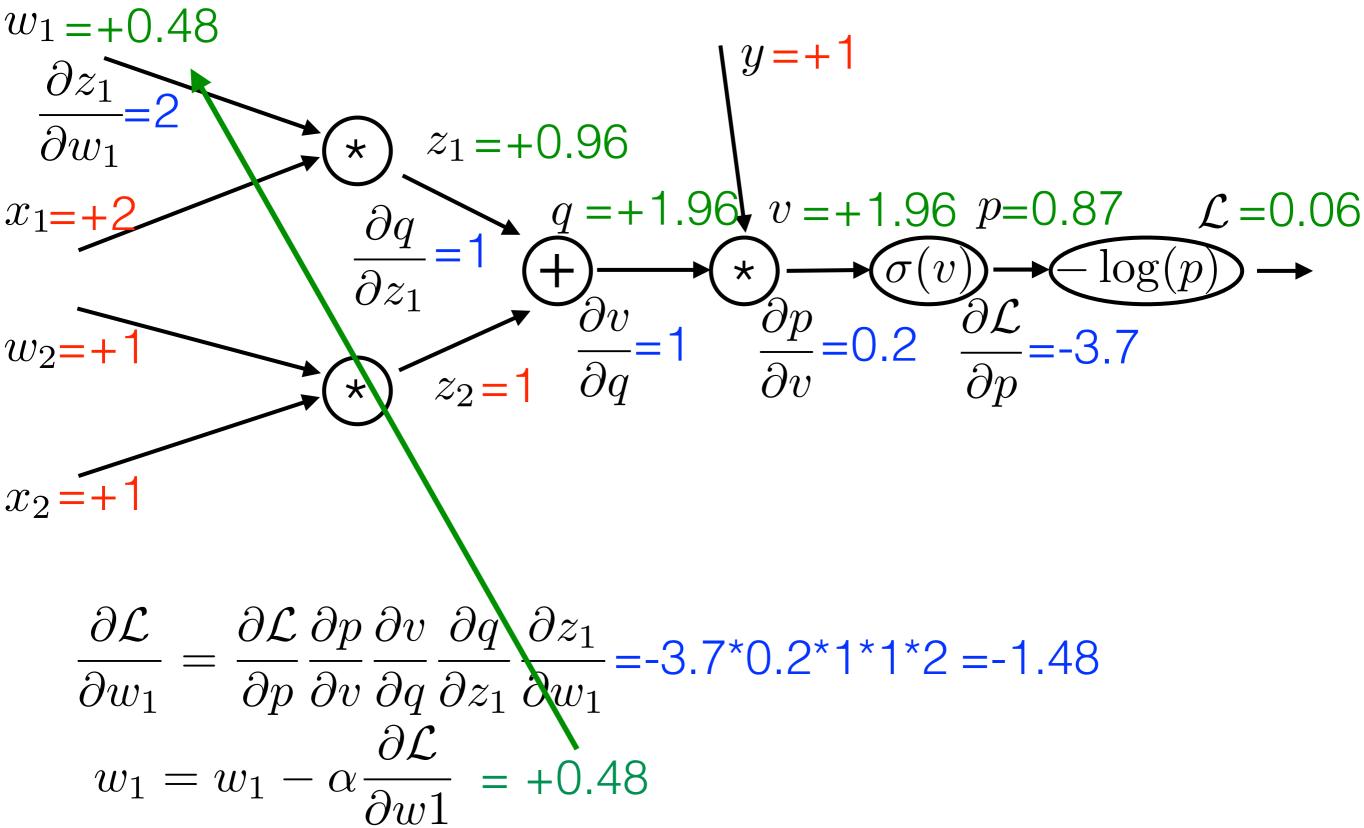
$$\frac{\partial \mathcal{L}}{\partial w_1} = \frac{\partial \mathcal{L}}{\partial p} \frac{\partial p}{\partial v} \frac{\partial v}{\partial q} \frac{\partial q}{\partial z_1} \frac{\partial z_1}{\partial w_1} = -3.7^*0.2^*1^*1^*2 = -1.48$$

$$w_1 = w_1 - \alpha \frac{\partial \mathcal{L}}{\partial w_1} = +0.48$$



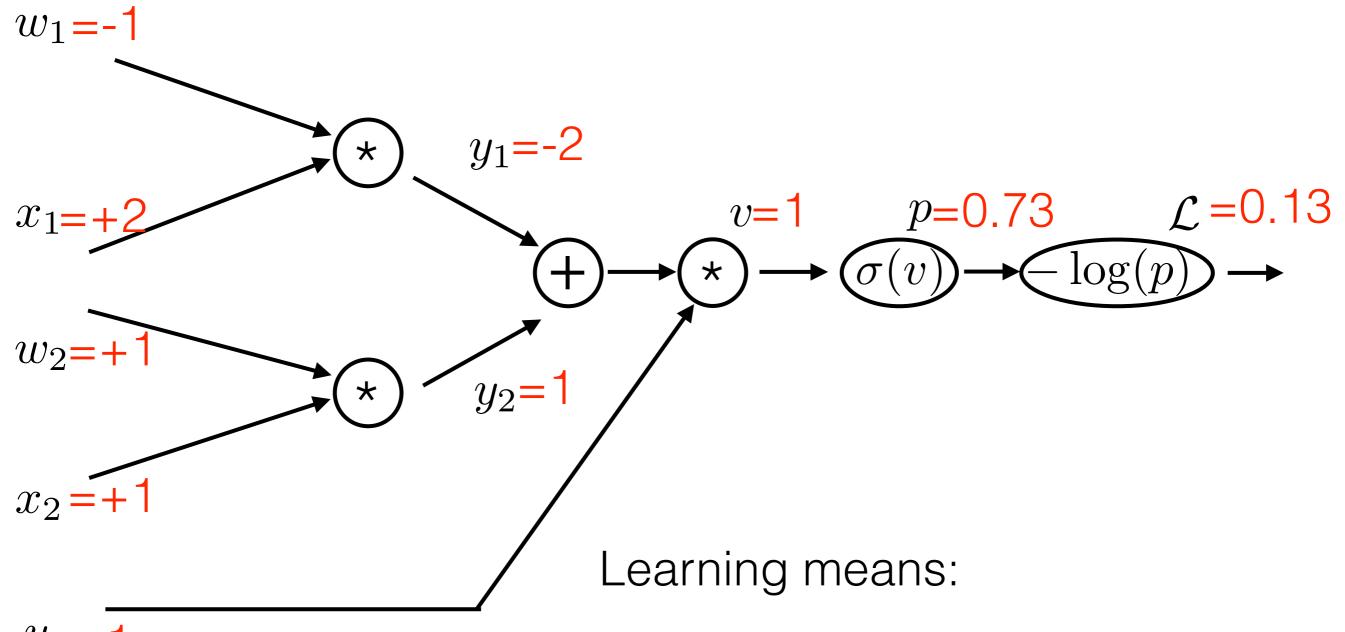








Example III: vector representation

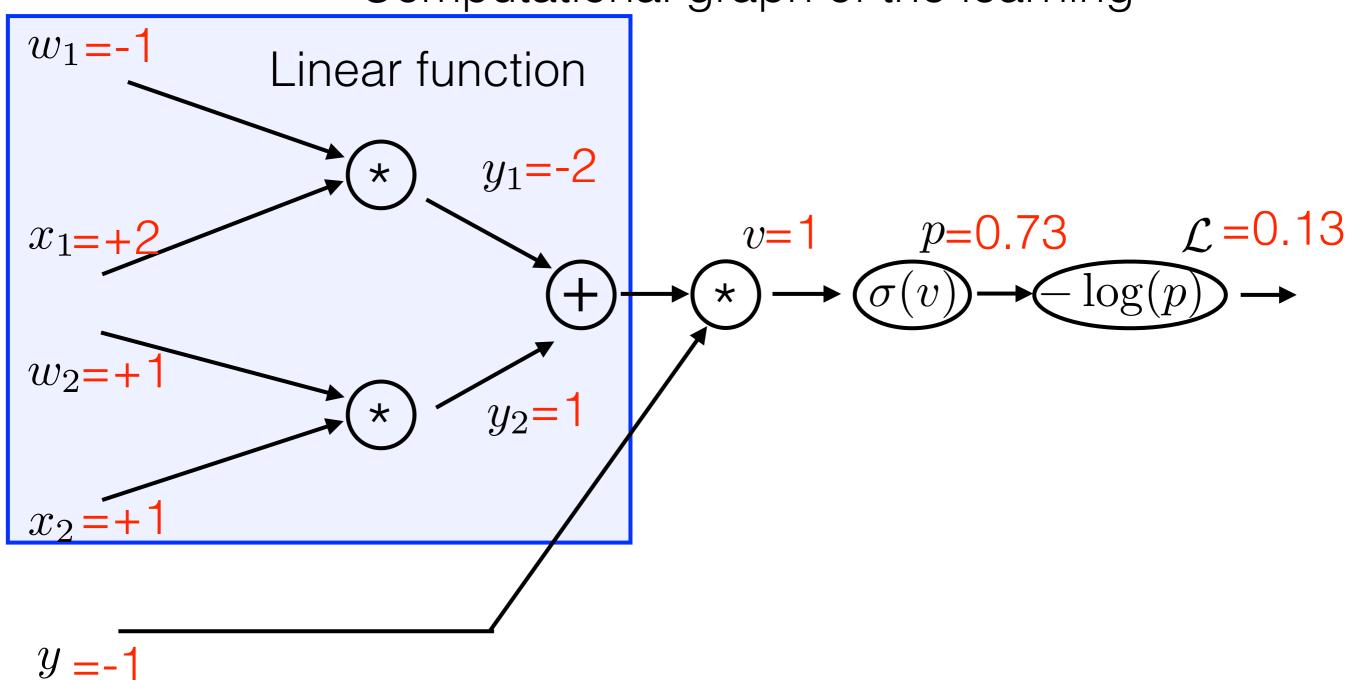


y=-1 Iteratively change all weights w to minimize \mathcal{L}

$$\mathbf{w} = \mathbf{w} - \alpha \left[\frac{\partial \mathcal{L}(\mathbf{w})}{\partial \mathbf{w}} \right]^{\mathsf{T}}$$
 where $\frac{\partial \mathcal{L}}{\partial \mathbf{w}} = \left[\frac{\partial \mathcal{L}}{\partial w_1}, \frac{\partial \mathcal{L}}{\partial w_2}, \dots \right]$

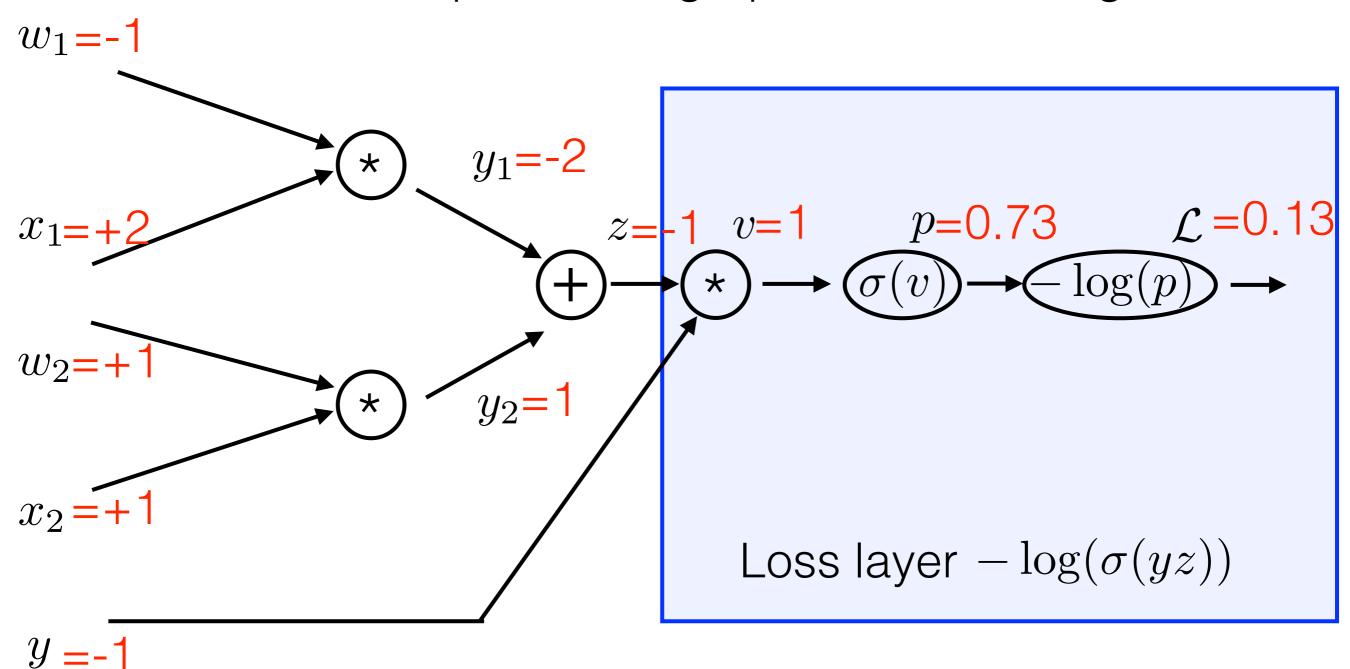


Computational graph of the learning

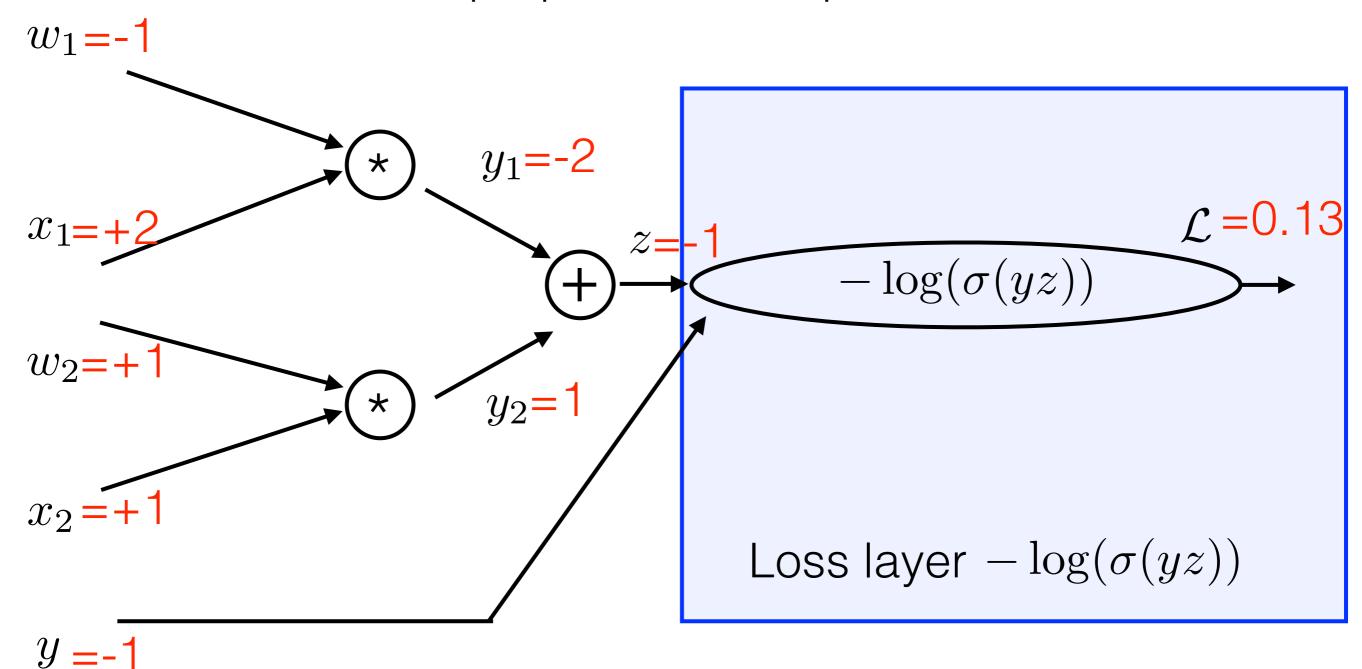




Computational graph of the learning



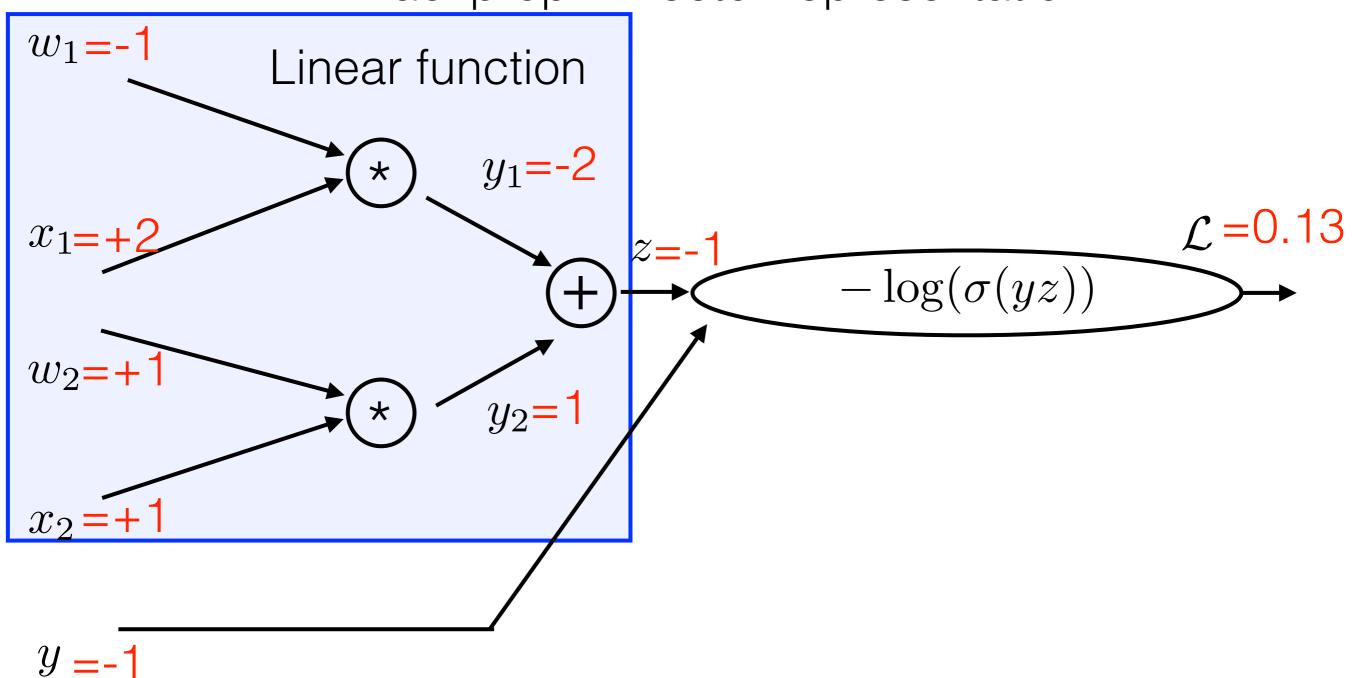




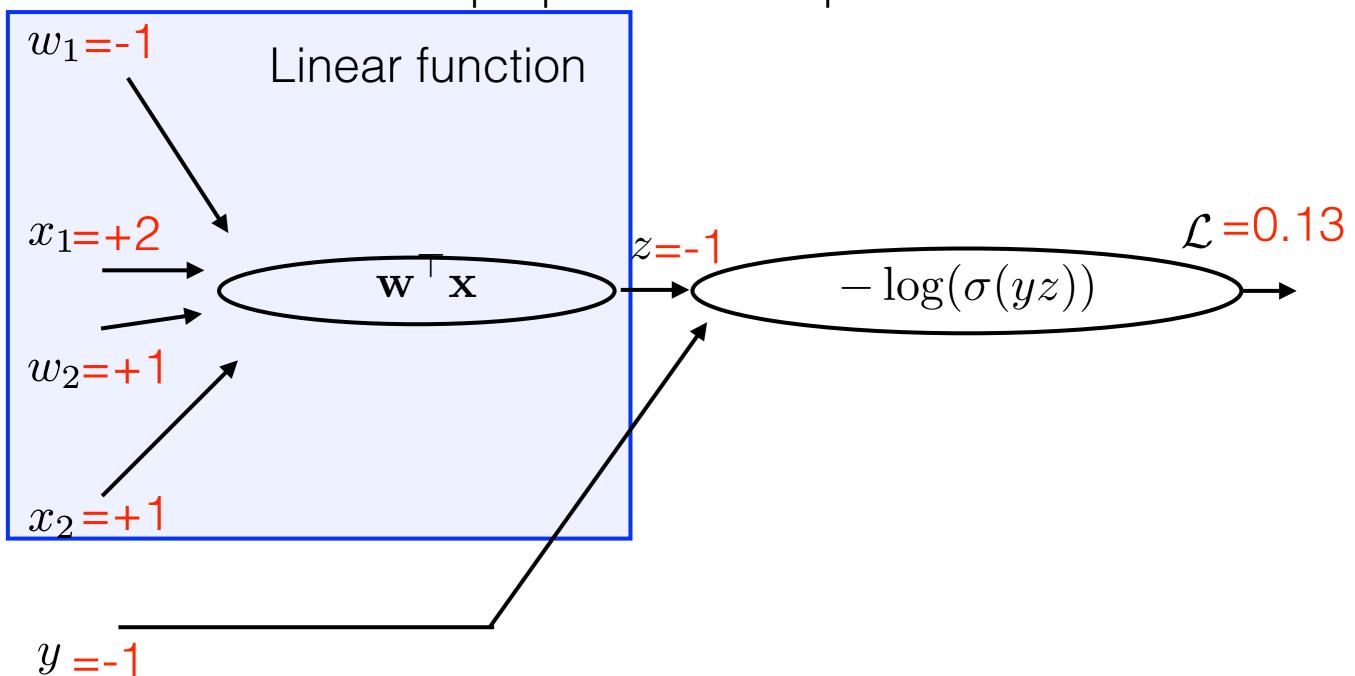
This is the logistic loss!

$$\mathcal{L}(y,z) = -\log(\sigma(yz)) = \log(1 + \exp(-yz))$$

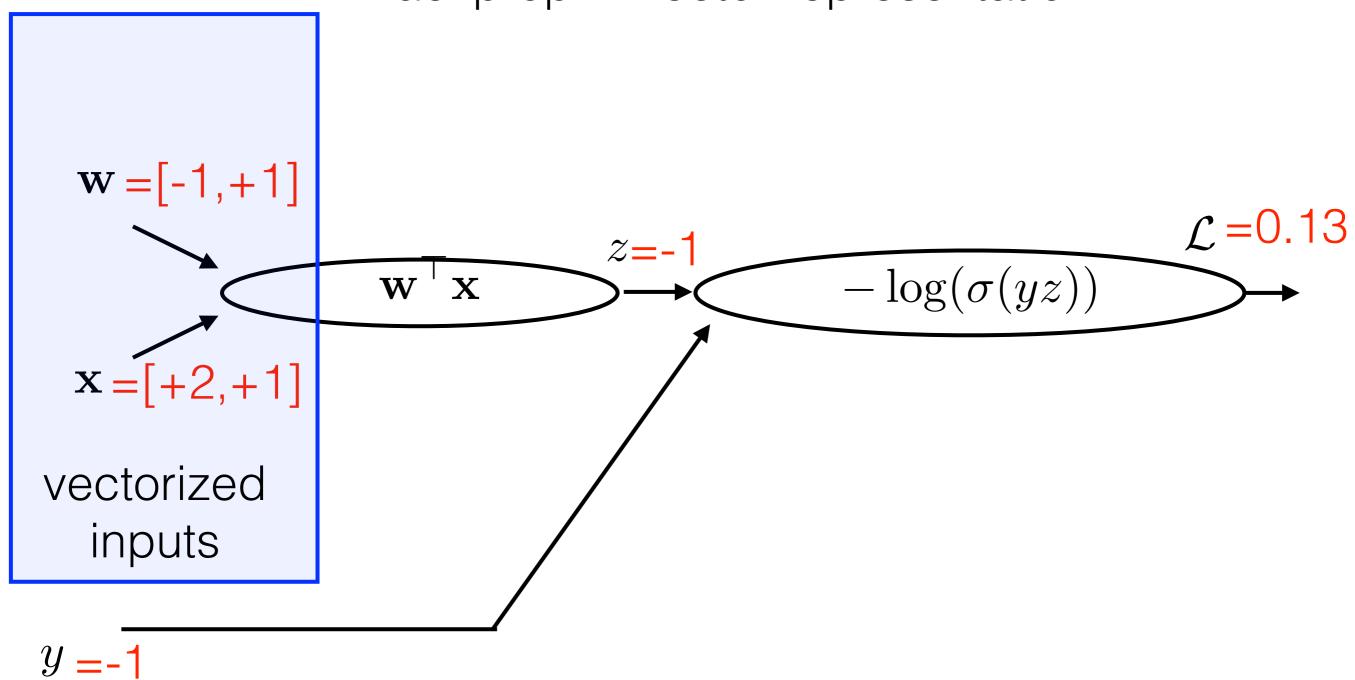




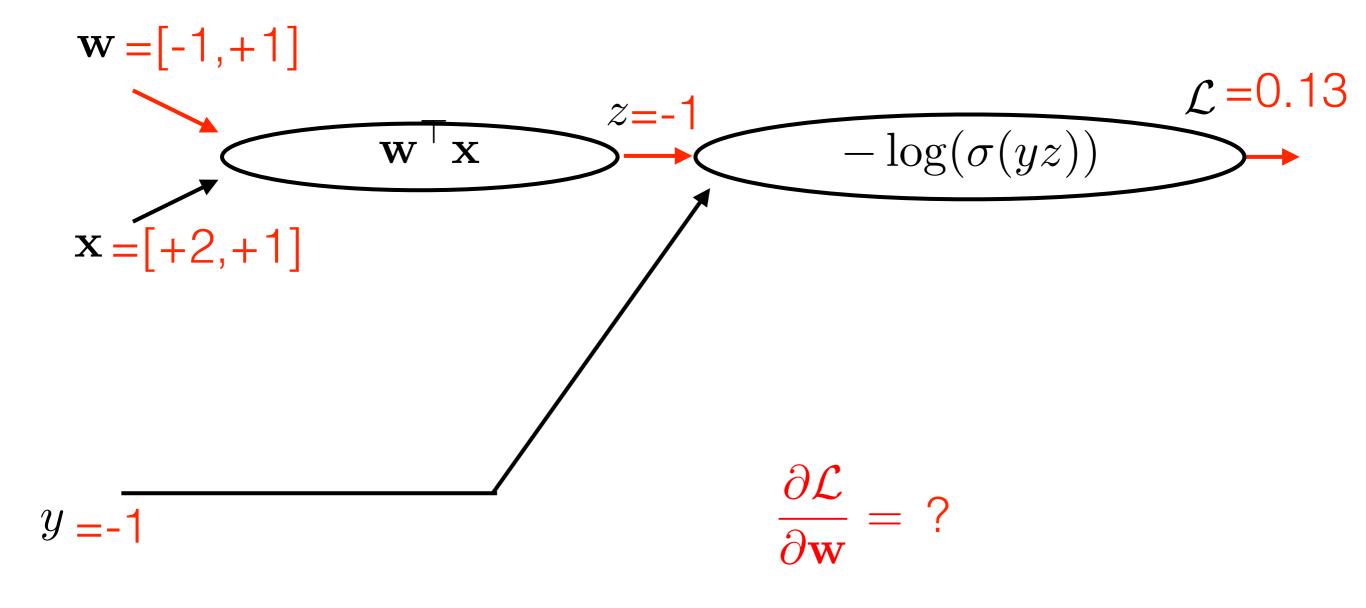




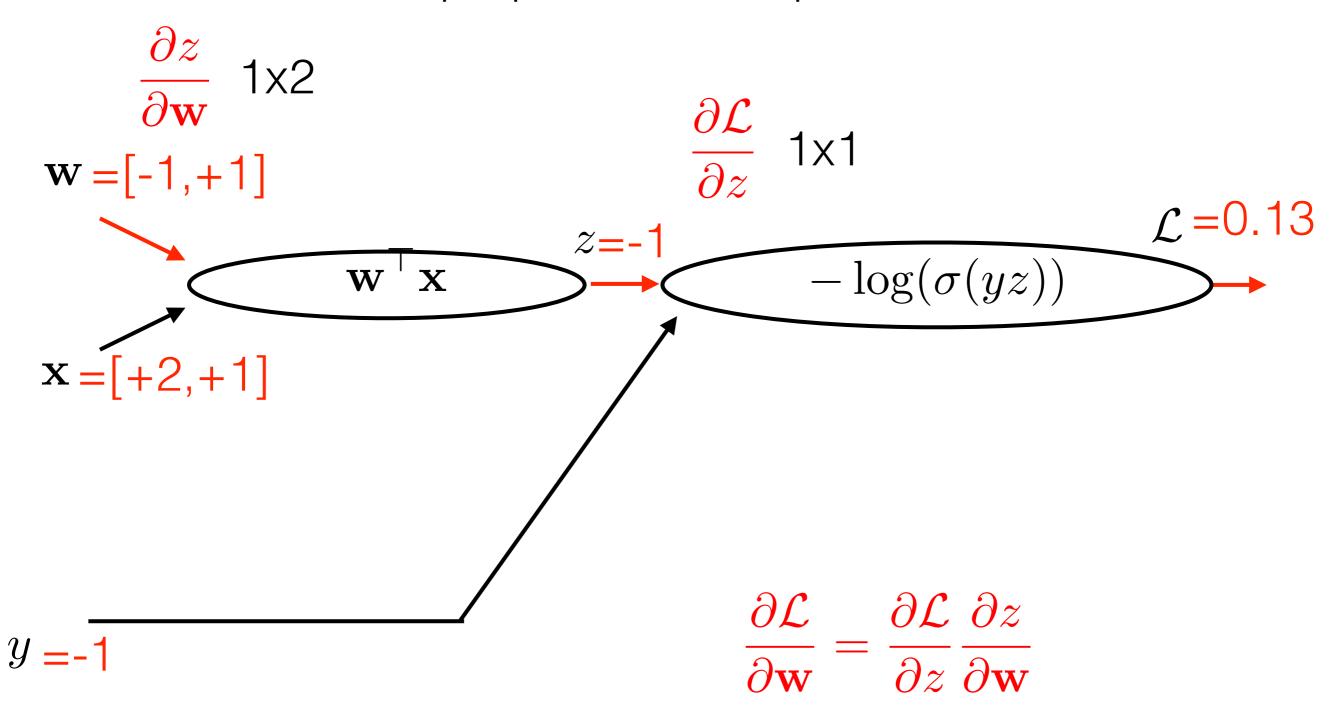




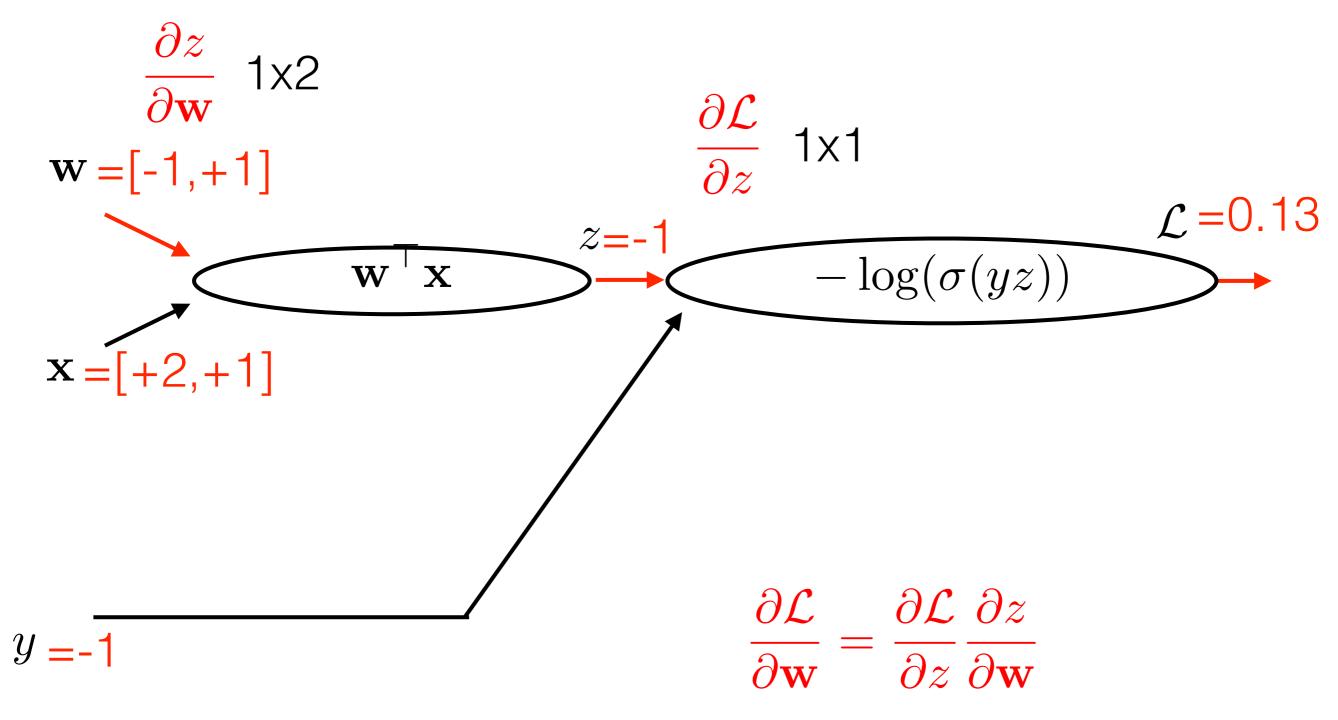








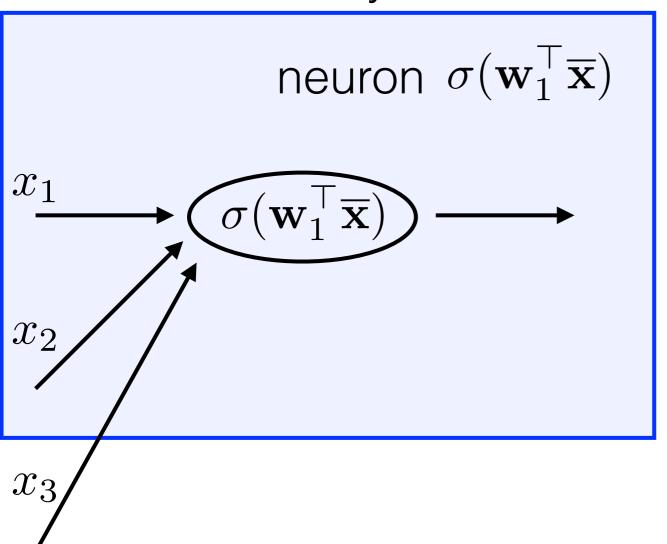




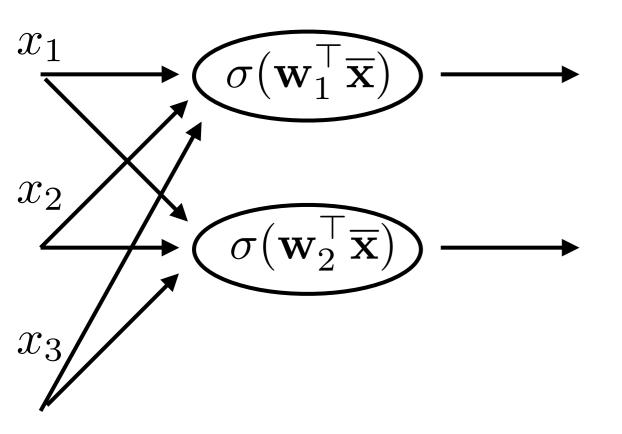
Learning from multiple training samples means summing up the gradient over all samples



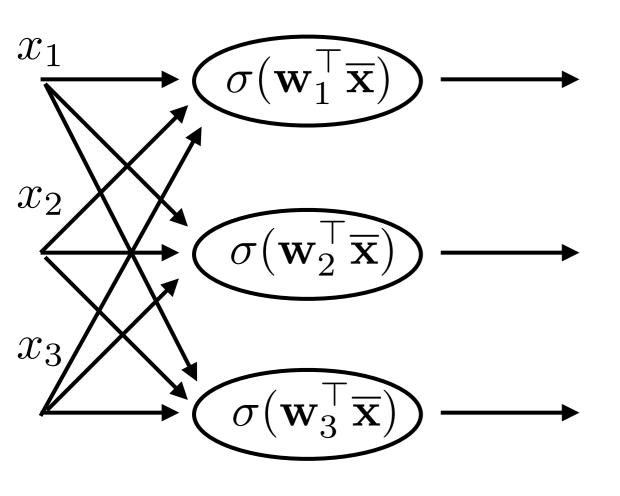
Fully connected neural network



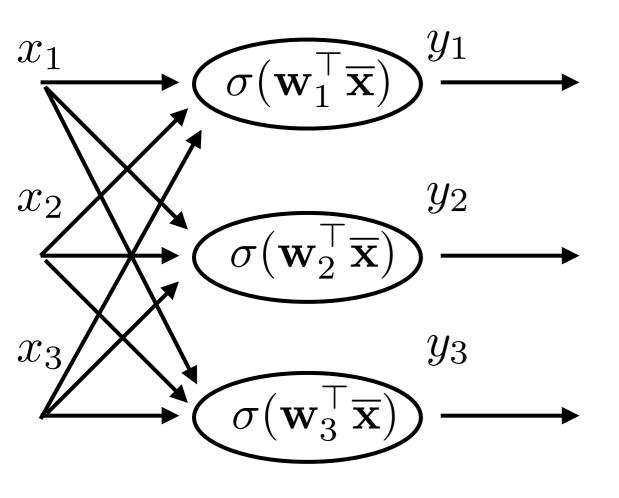




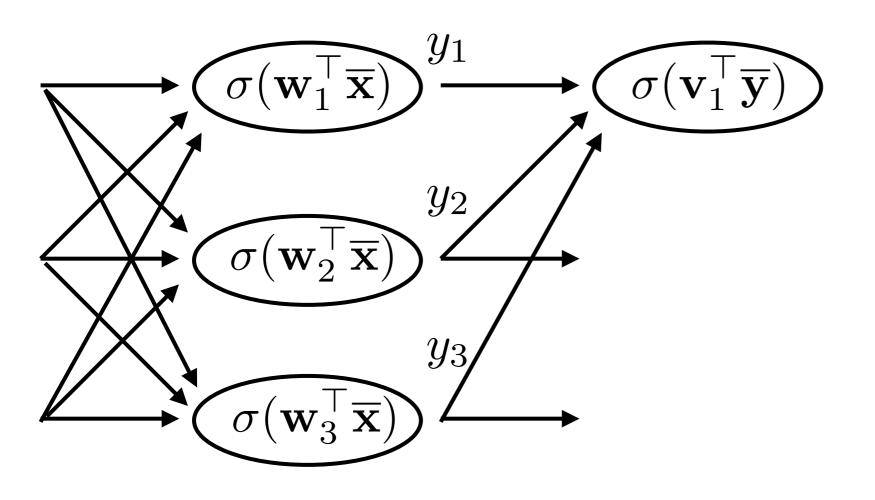




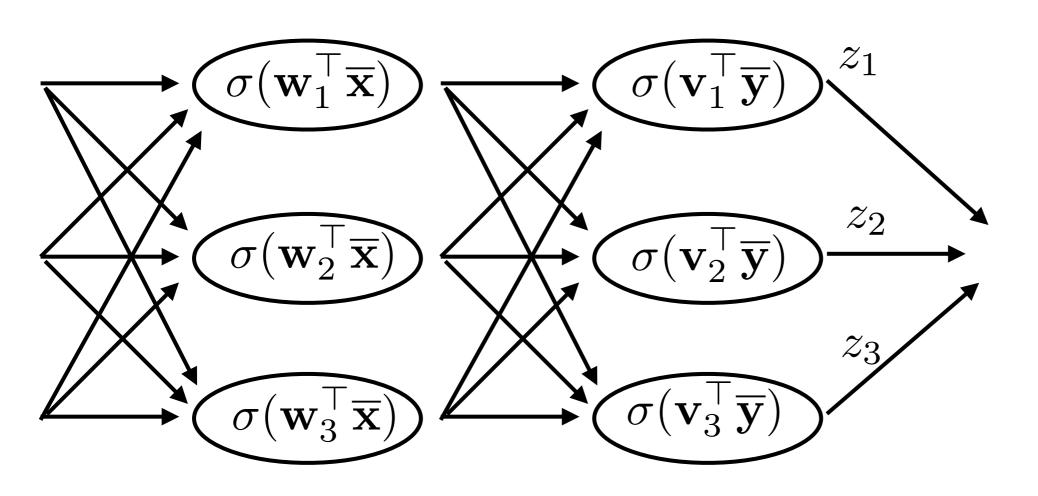




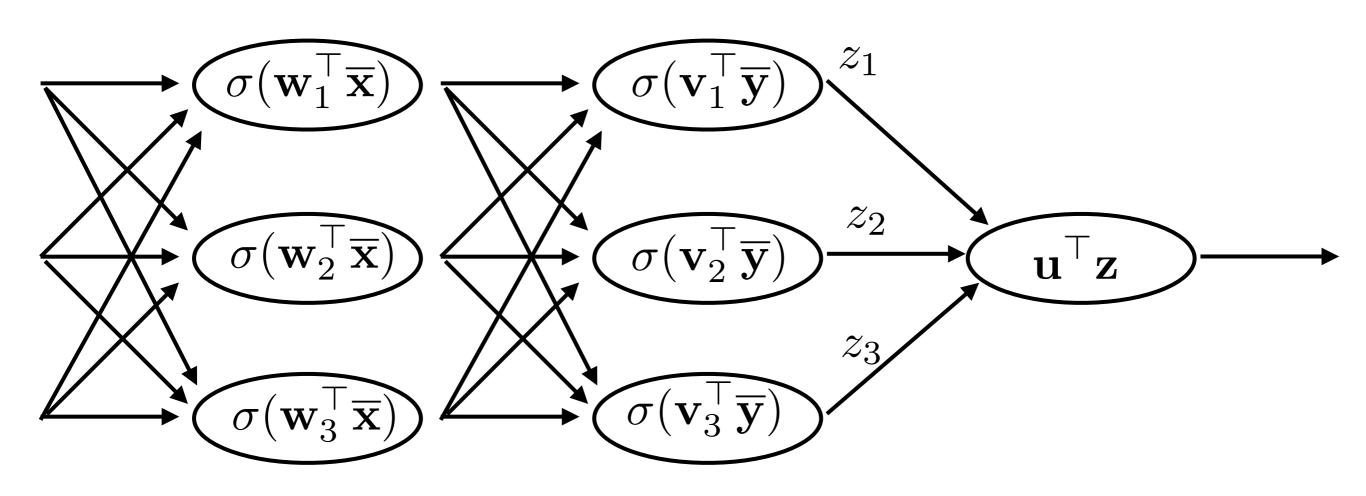




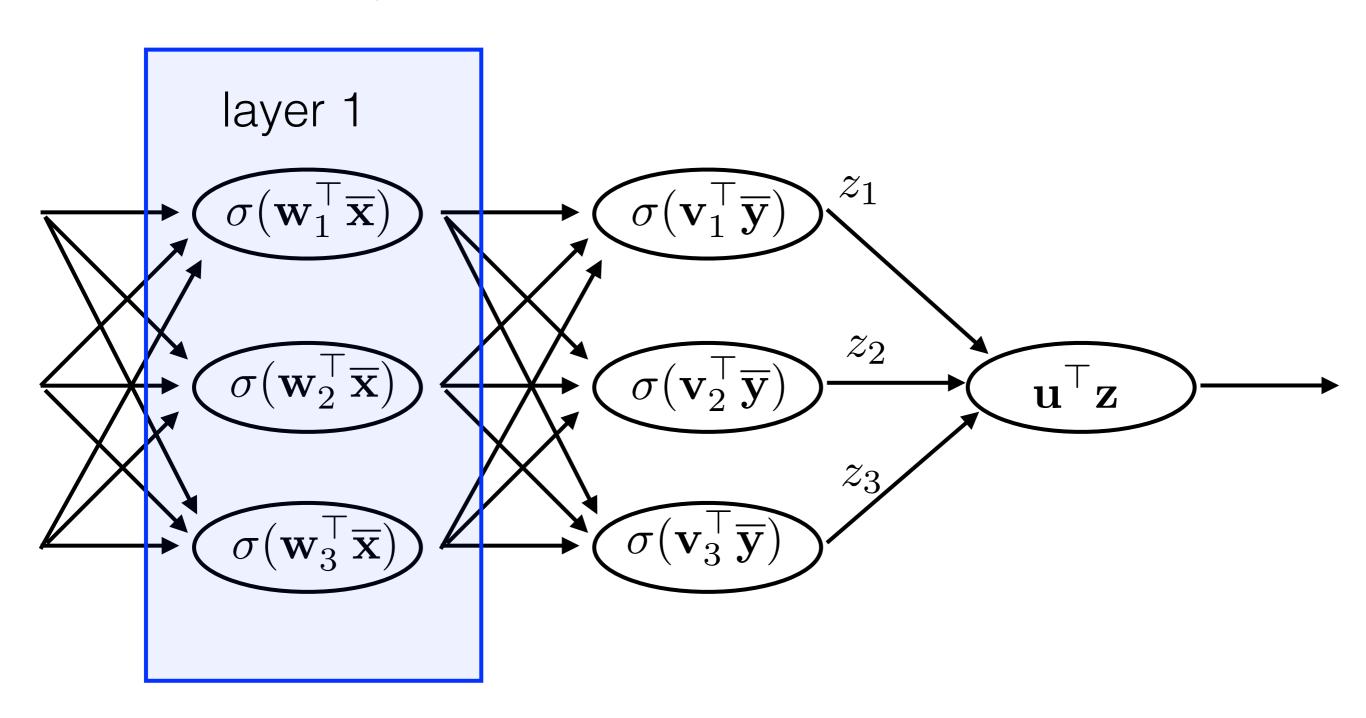




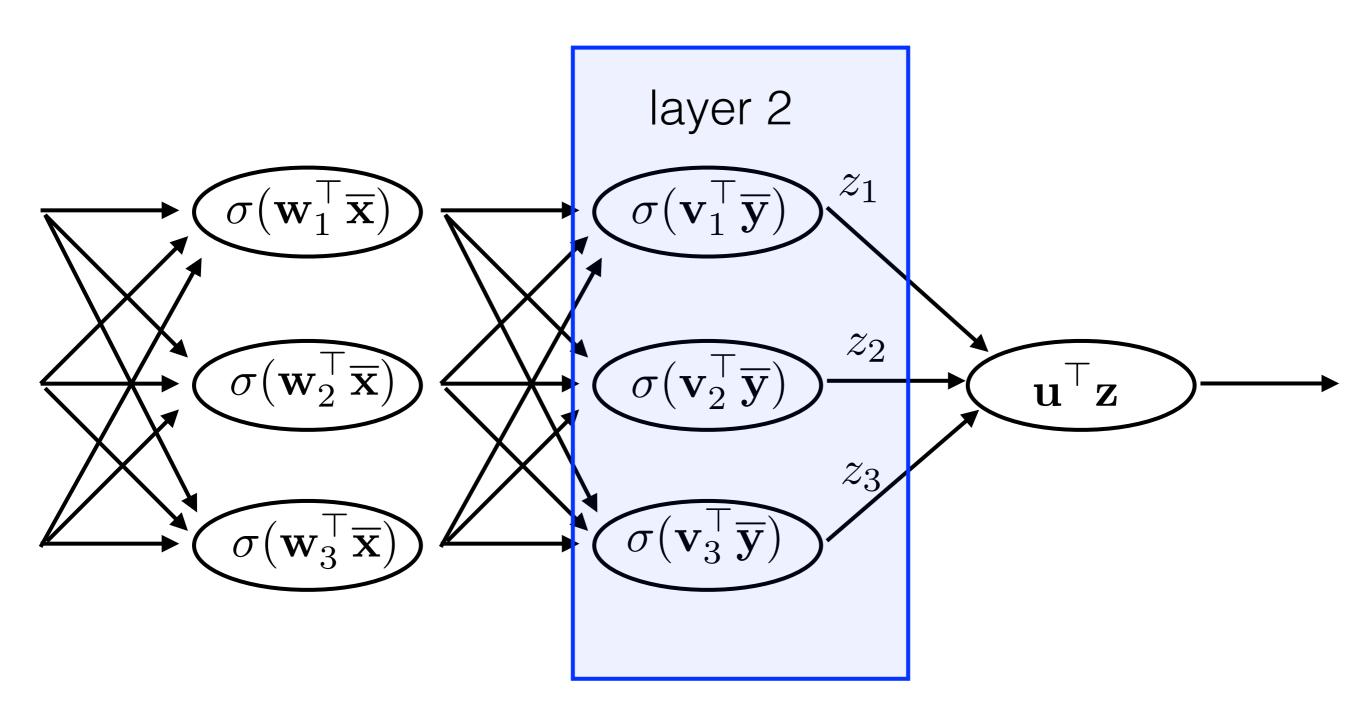




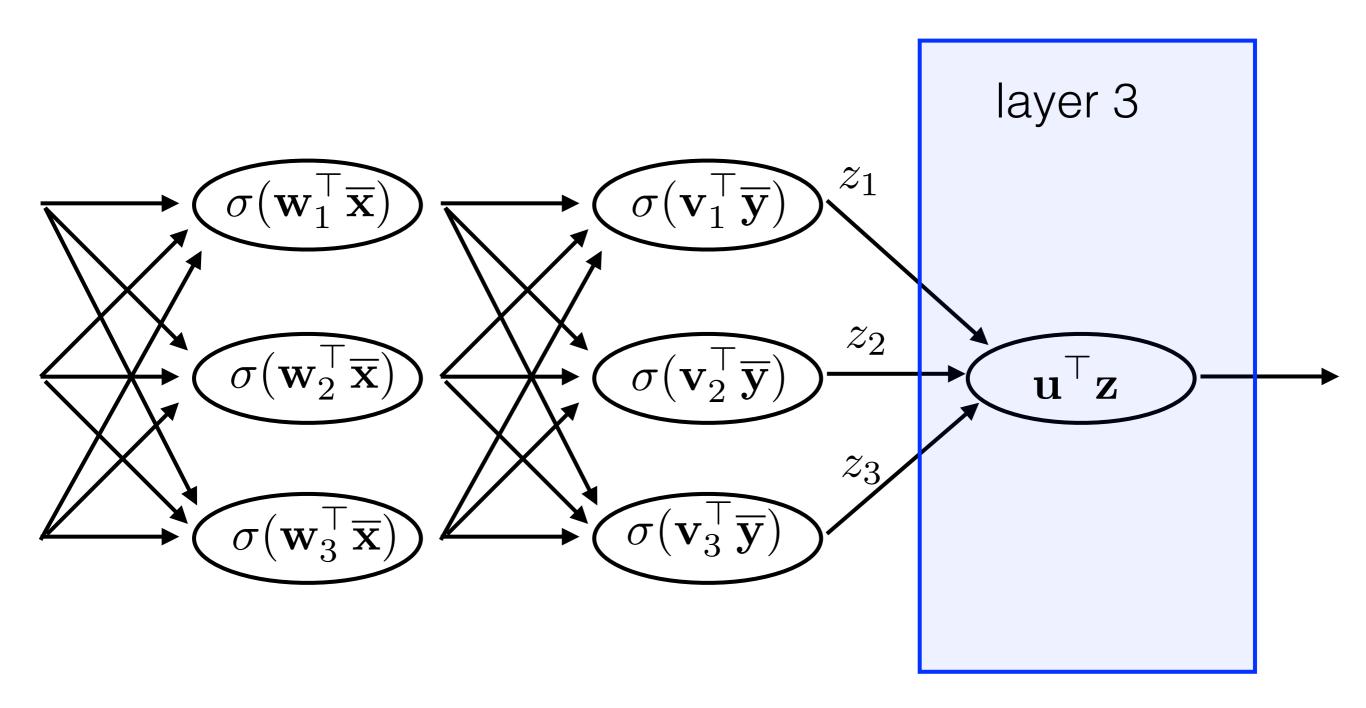




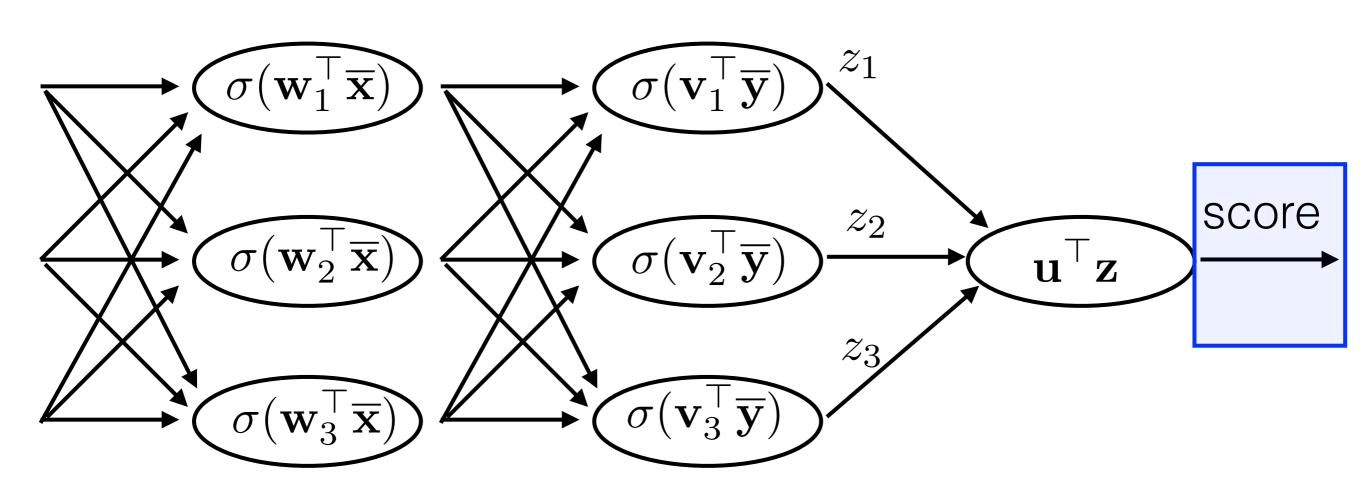




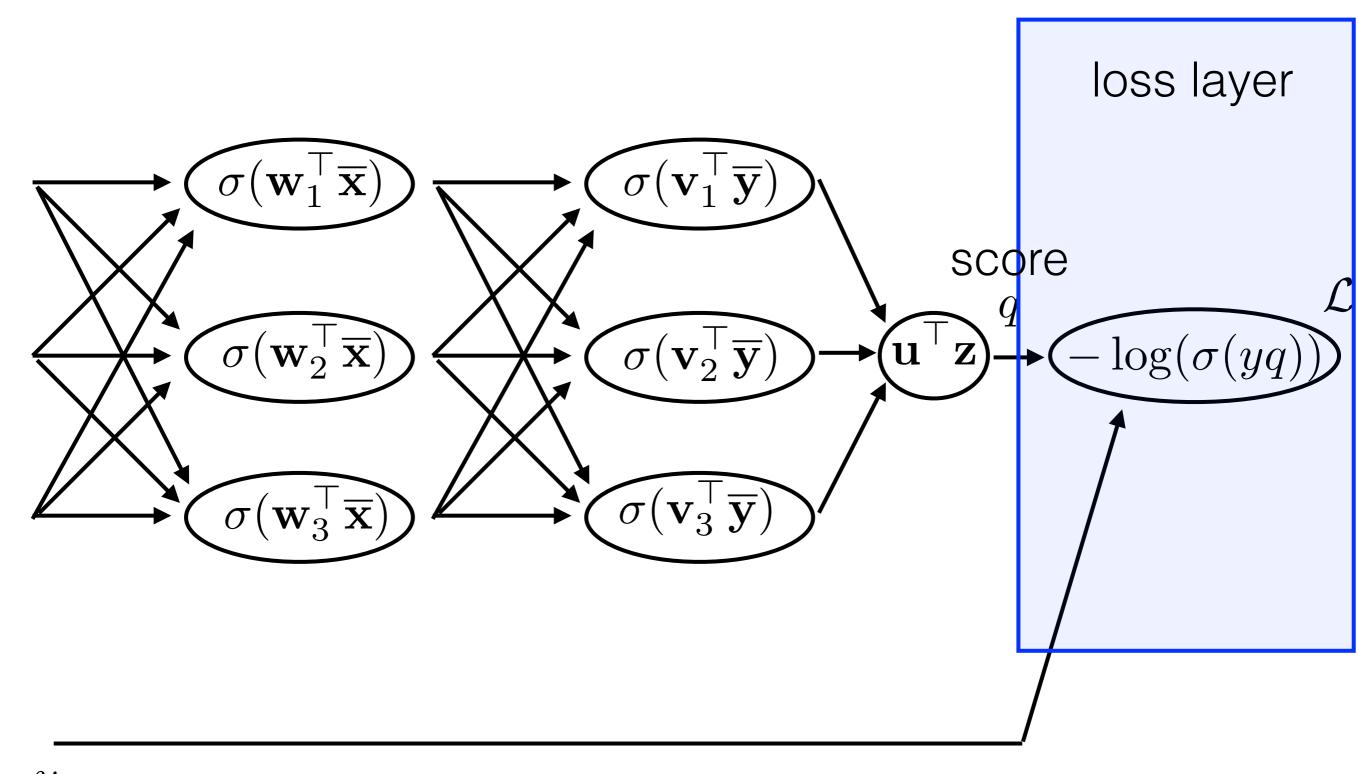




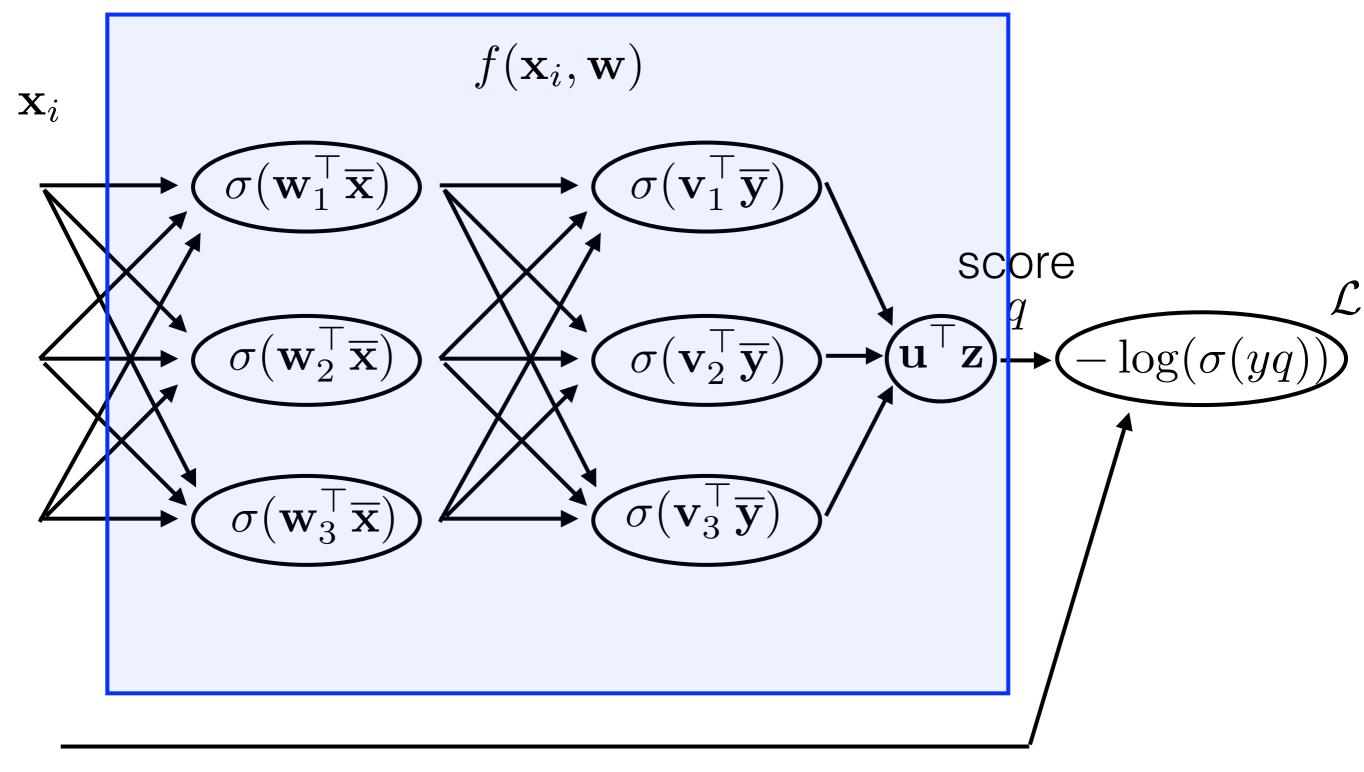




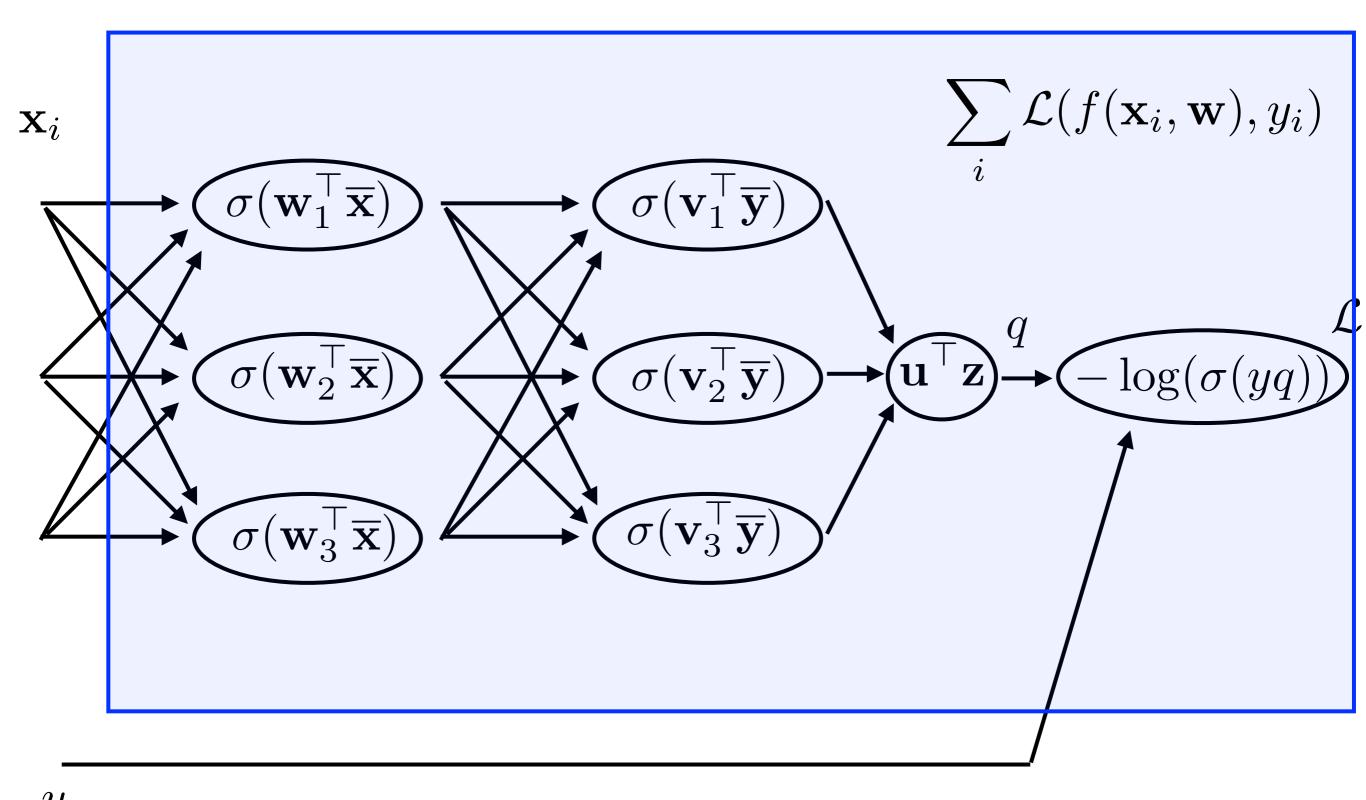














1. Estimate gradient

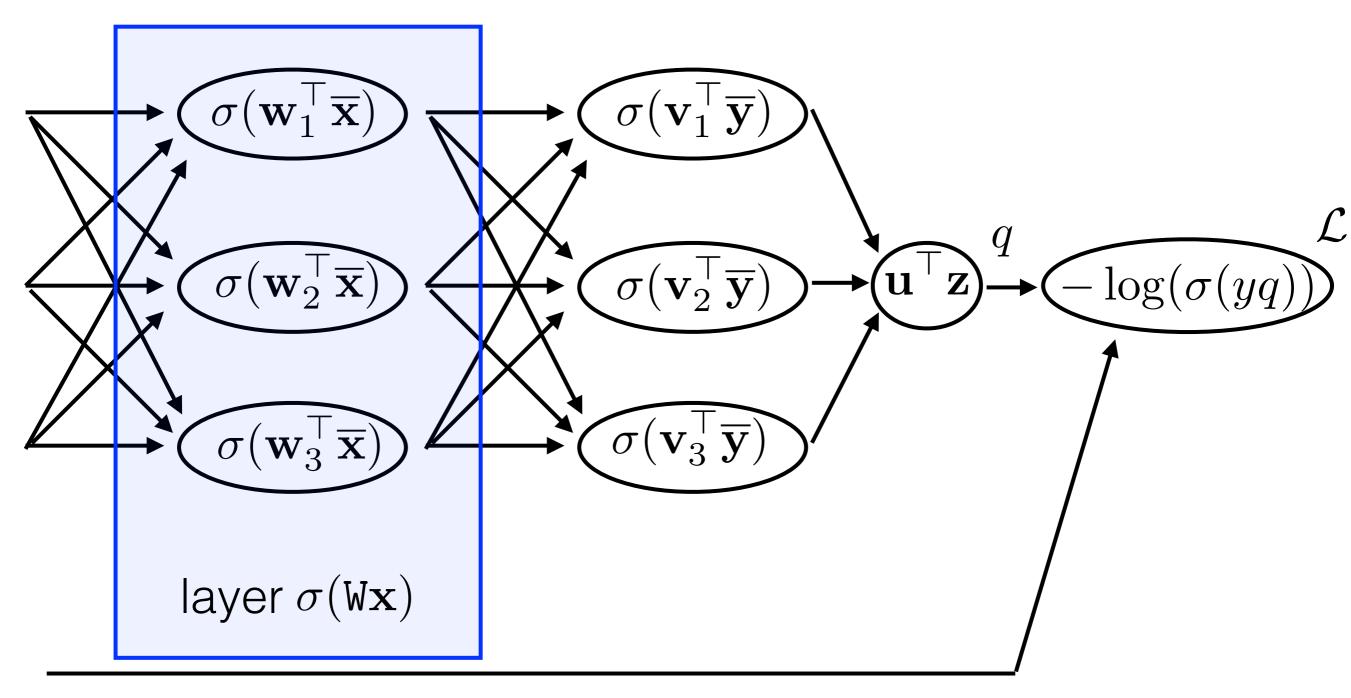
$$\sum_{i} \frac{\partial \mathcal{L}(f(\mathbf{x}_{i}, \mathbf{w}), y_{i})}{\partial \mathbf{w}}$$

2. Update weights:

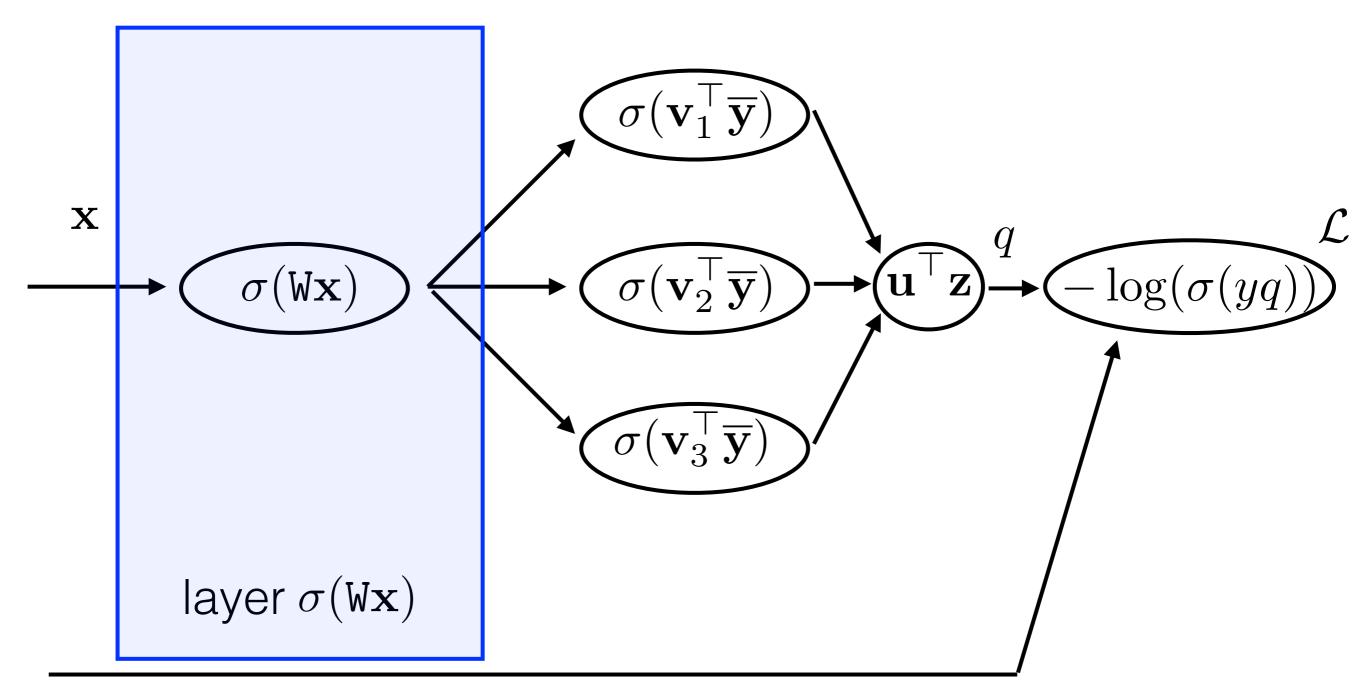
$$\mathbf{w} = \mathbf{w} - \alpha \sum_{i} \frac{\partial \mathcal{L}(f(\mathbf{x}_{i}, \mathbf{w}), y_{i})}{\partial \mathbf{w}}$$

- 3. Optionally update learning rate α
- 4. Repeat until convergence

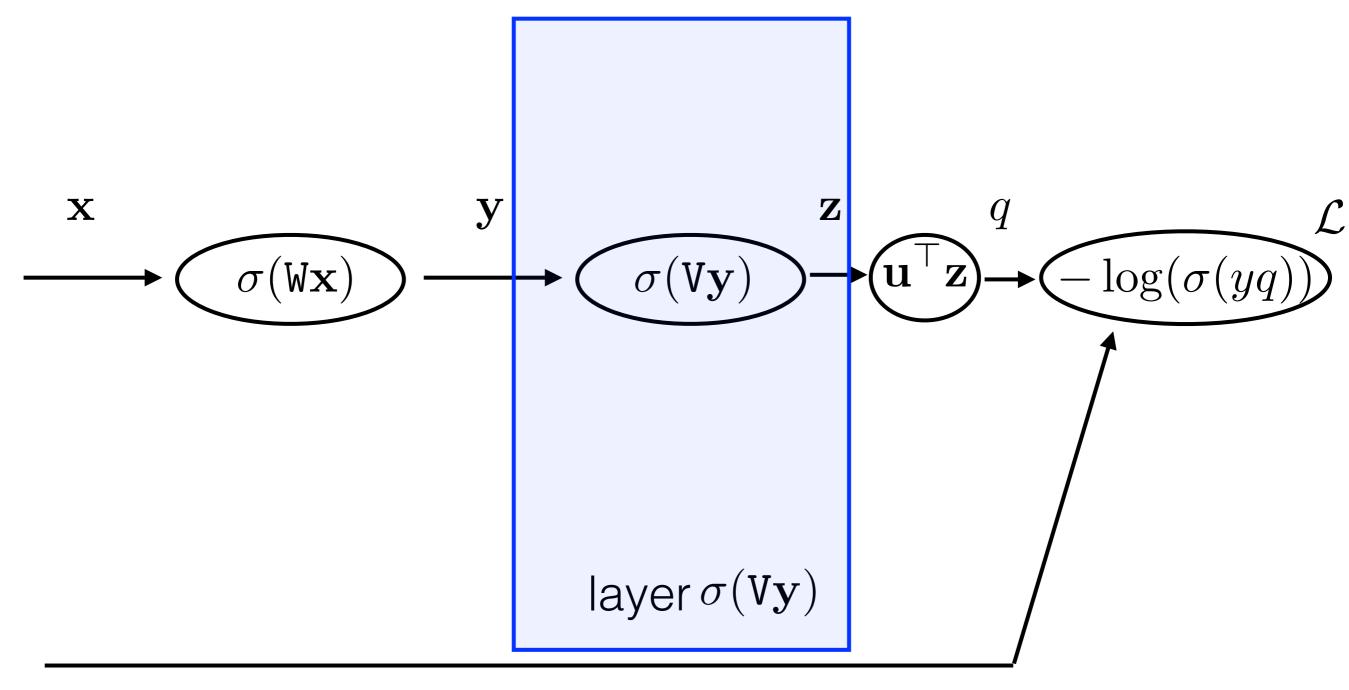






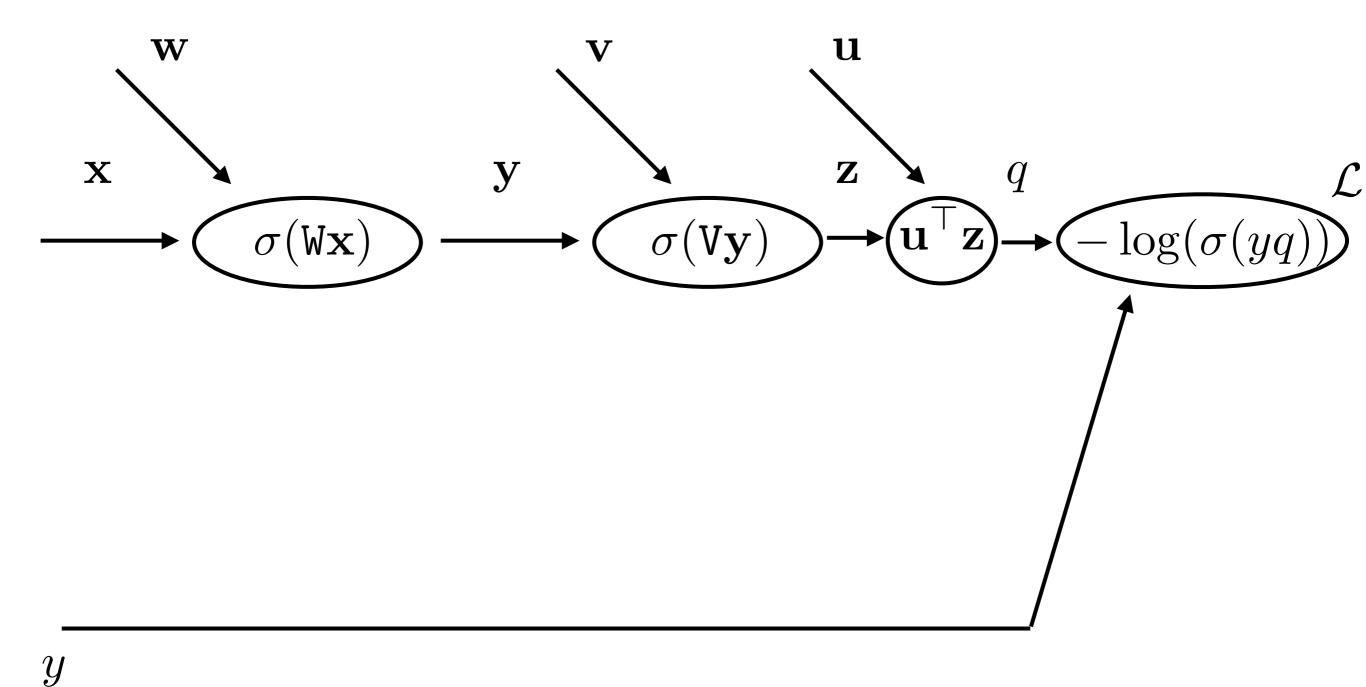






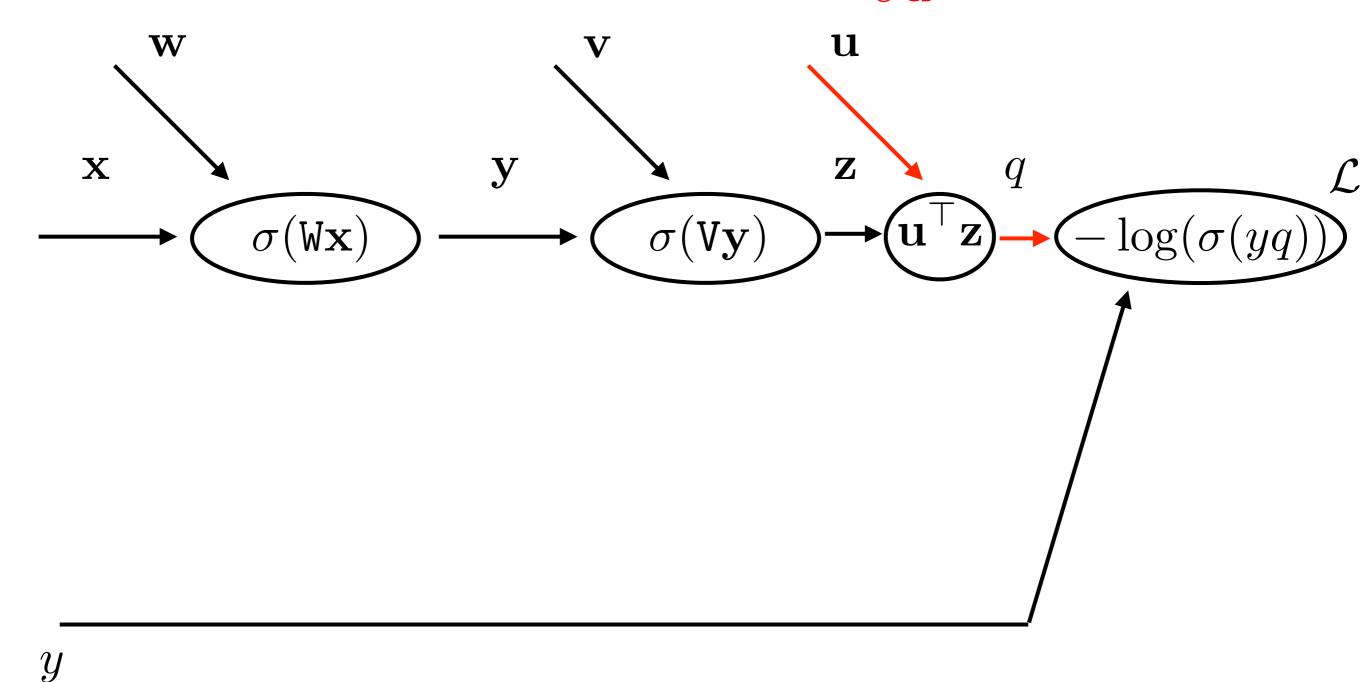


$$\mathbf{w} = \operatorname{vec}(V)$$
 $\mathbf{v} = \operatorname{vec}(V)$



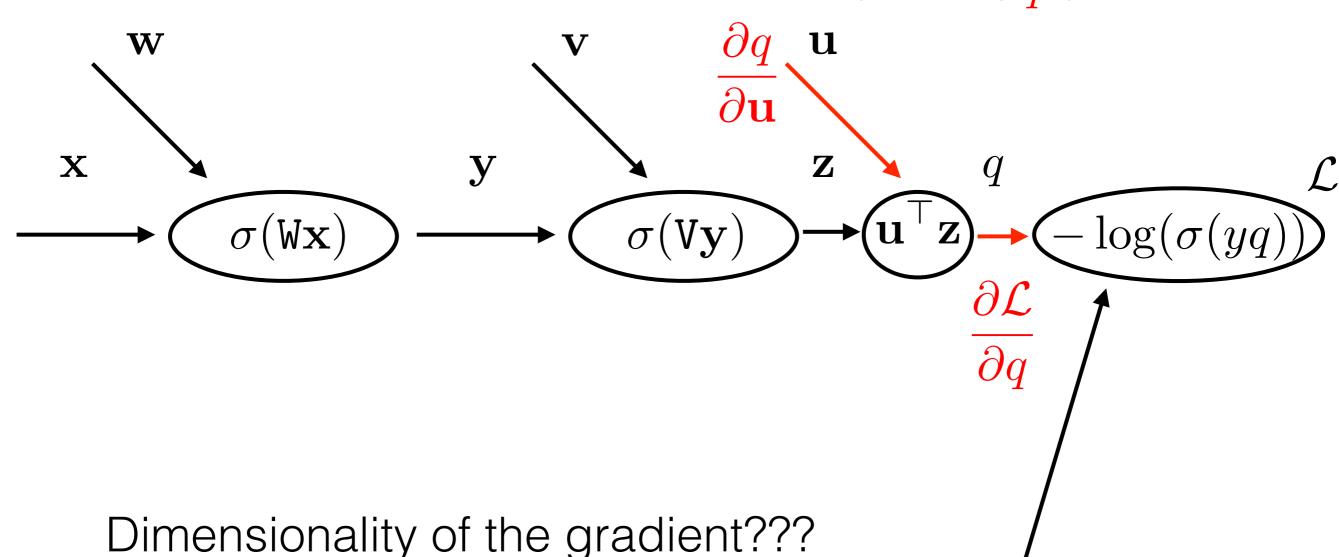


Derivative wrt
$$\mathbf{u}$$
 : $\frac{\partial \mathcal{L}}{\partial \mathbf{u}} = ?$

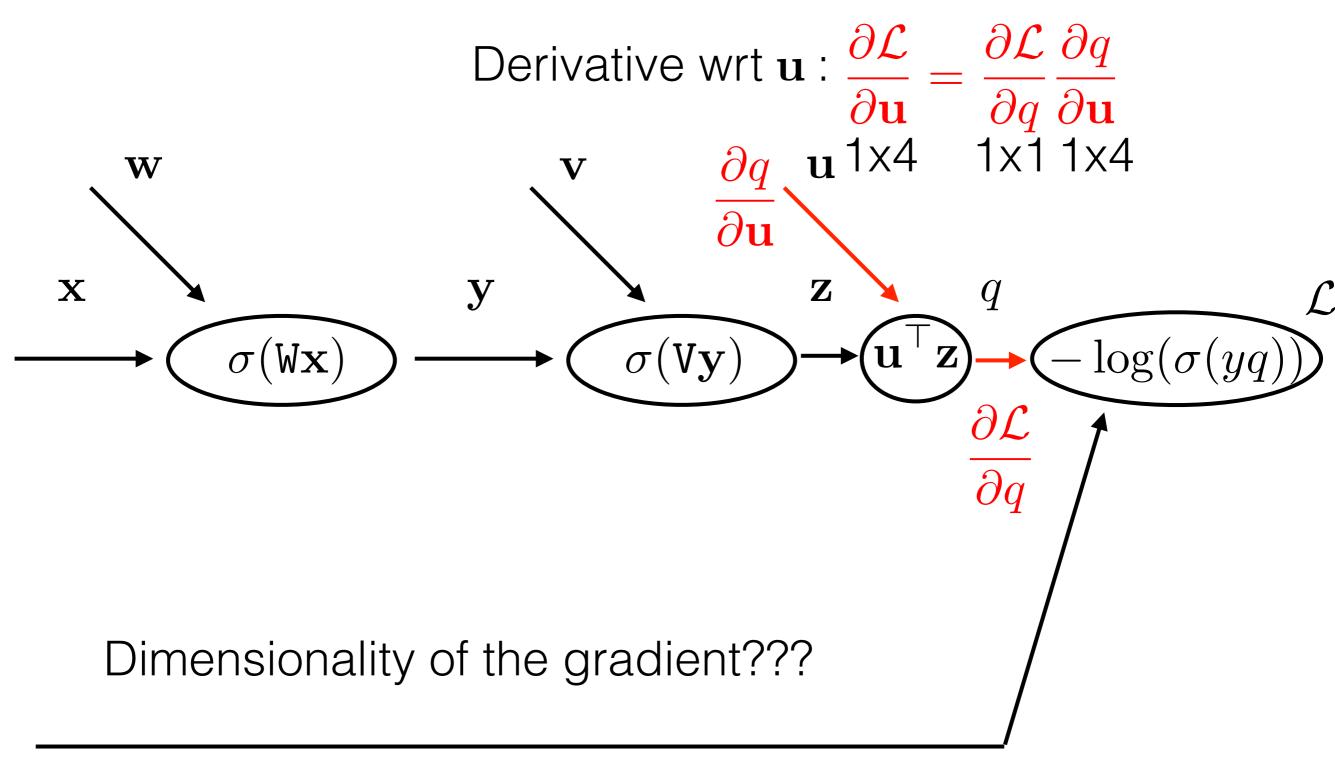




Derivative wrt
$$\mathbf{u}$$
: $\frac{\partial \mathcal{L}}{\partial \mathbf{u}} = \frac{\partial \mathcal{L}}{\partial q} \frac{\partial q}{\partial \mathbf{u}}$





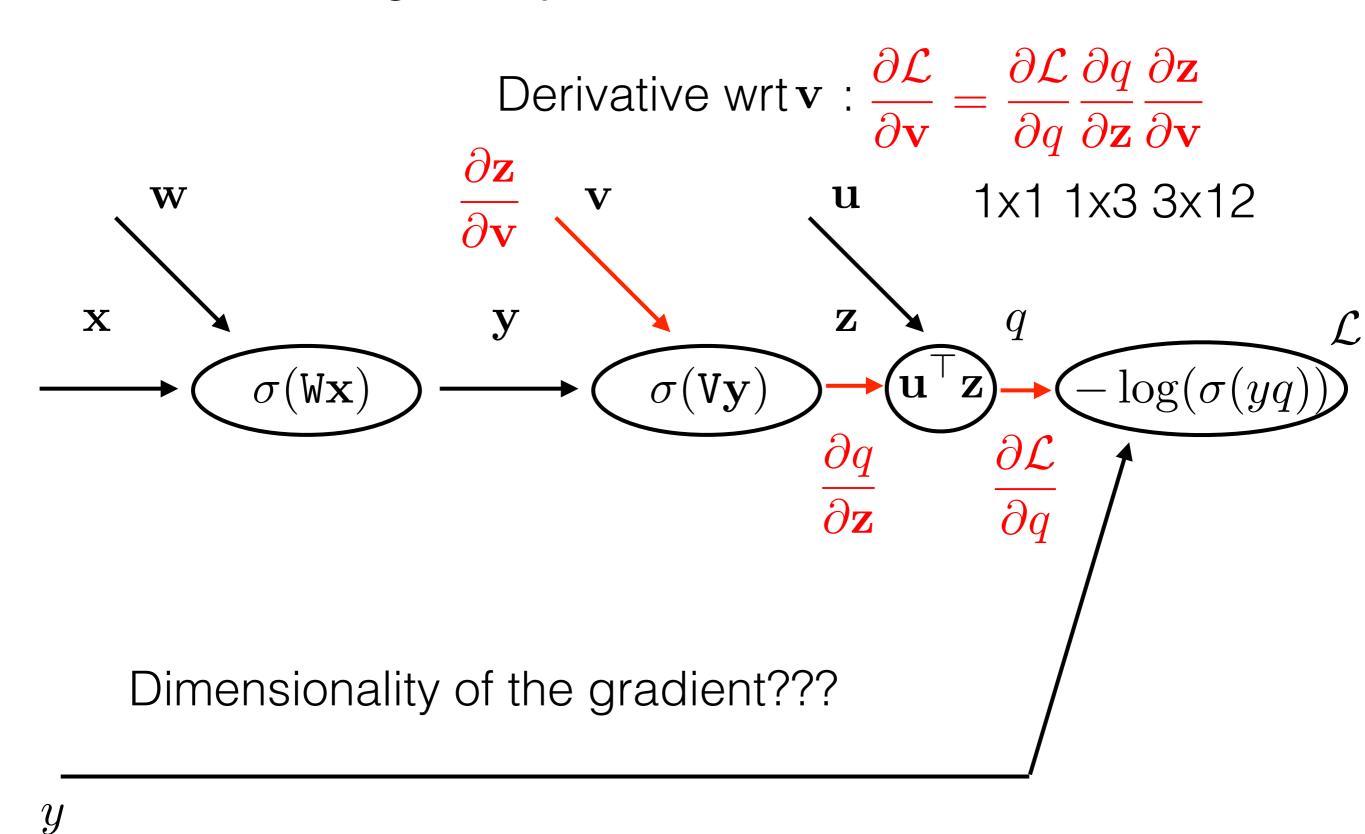




Derivative wrt \mathbf{v} : $\frac{\partial \mathcal{L}}{\partial \mathbf{v}} = \frac{\partial \mathcal{L}}{\partial a} \frac{\partial q}{\partial \mathbf{z}} \frac{\partial \mathbf{z}}{\partial \mathbf{v}}$ \mathbf{W} u \mathbf{Z} \mathbf{X} $\log(\sigma(yq))$ $\sigma(\mathtt{W}\mathbf{x})$ \mathbf{u}

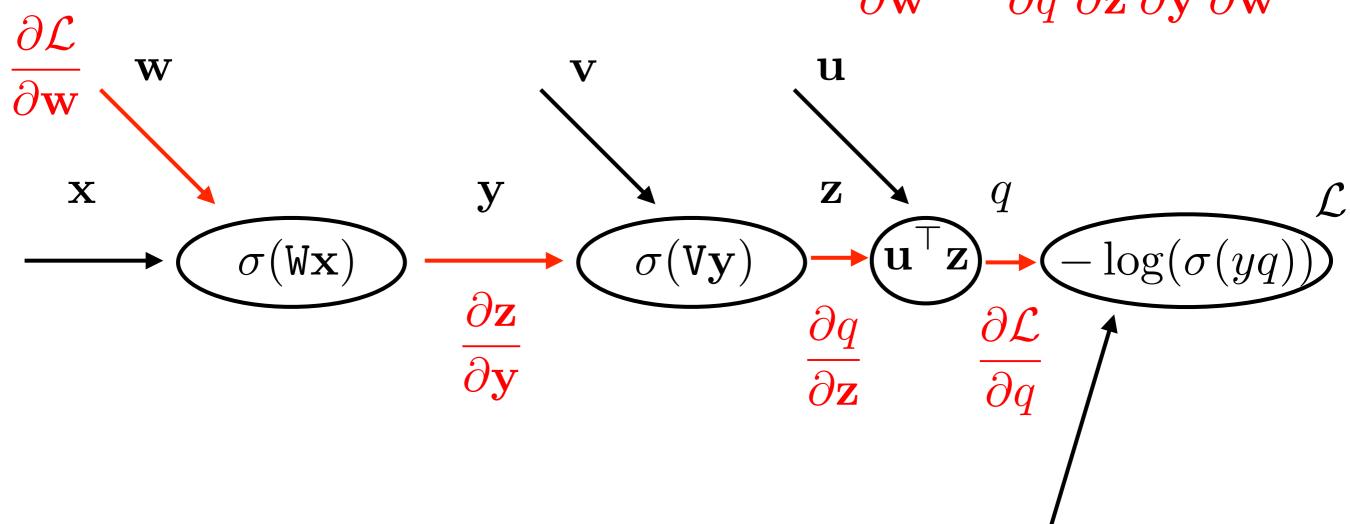
Dimensionality of the gradient???





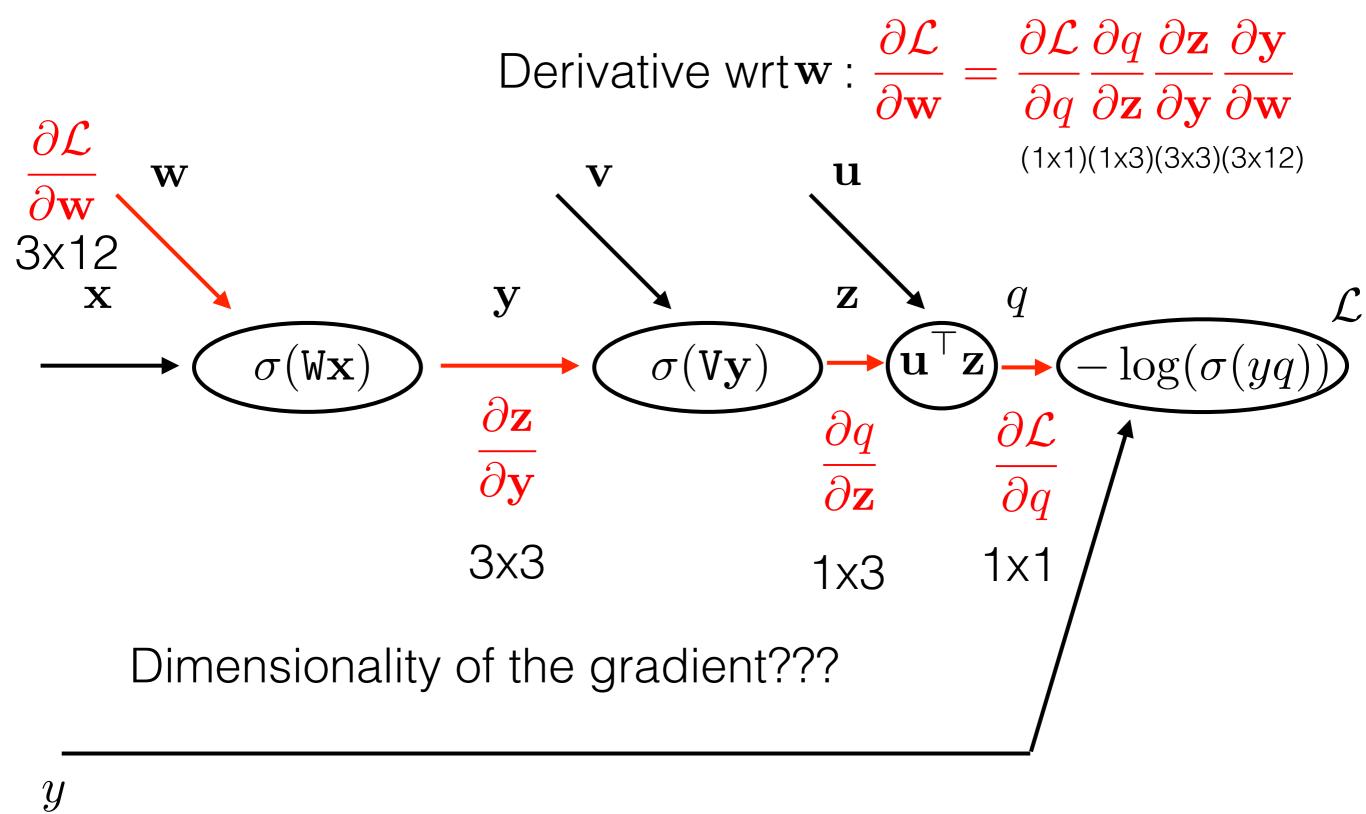


Derivative wrt
$$\mathbf{w}$$
: $\frac{\partial \mathcal{L}}{\partial \mathbf{w}} = \frac{\partial \mathcal{L}}{\partial q} \frac{\partial q}{\partial \mathbf{z}} \frac{\partial \mathbf{z}}{\partial \mathbf{y}} \frac{\partial \mathbf{y}}{\partial \mathbf{w}}$



Dimensionality of the gradient???







- 1. Estimate all required local gradients
- 2. Update weights:

$$\frac{\partial \mathcal{L}}{\partial \mathbf{u}} = \frac{\partial \mathcal{L}}{\partial q} \frac{\partial q}{\partial \mathbf{u}} \qquad \mathbf{u} = \mathbf{u} - \alpha \left[\frac{\partial \mathcal{L}}{\partial \mathbf{u}} \right]^{\top}
\frac{\partial \mathcal{L}}{\partial \mathbf{v}} = \frac{\partial \mathcal{L}}{\partial q} \frac{\partial q}{\partial \mathbf{z}} \frac{\partial \mathbf{z}}{\partial \mathbf{v}} \qquad \mathbf{v} = \mathbf{v} - \alpha \left[\frac{\partial \mathcal{L}}{\partial \mathbf{v}} \right]^{\top}
\frac{\partial \mathcal{L}}{\partial \mathbf{w}} = \frac{\partial \mathcal{L}}{\partial q} \frac{\partial q}{\partial \mathbf{z}} \frac{\partial \mathbf{z}}{\partial \mathbf{y}} \frac{\partial \mathbf{y}}{\partial \mathbf{w}} \qquad \mathbf{w} = \mathbf{w} - \alpha \left[\frac{\partial \mathcal{L}}{\partial \mathbf{w}} \right]^{\top}$$

- 3. Optionally update learning rate α
- 4. Repeat until convergence



Neural nets summary

- Neural net is a function created as concatenation of simplier functions (e.g. neurons or layers of neurons)
- Gradient optimization of the neural net is called backpropagation
- Neural net frameworks has many predefined layers
- Spoiler alert: It does not work (on images) at all why?



$$\mathbf{w}^* = \arg\min_{\mathbf{w}} \left(\sum_{i} -\log(p(y_i|\mathbf{x}_i, \mathbf{w})) \right) + (-\log p(\mathbf{w}))$$

loss function

prior/regulariser

- Class of function represented by a NN is too general.
- Naive regulariser helps a bit, but dimensionality/wildness is huge => curse-of-dimensionality, overfitting,...
- What is number of weights between two 1000-neuron layers?
 - **Next lecture:** study animal cortex to find a stronger prior on the class of suitable functions.
- Spoiler alert 2:

reduce very general class of functions "neuron layer" to very specific sub-class of functions "convolution layer"

