

Learning for vision II

Neural networks

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Vision for Robotics and Autonomous Systems

<https://cyber.felk.cvut.cz/vras/>



Center for Machine Perception

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Czech Technical University in Prague



Linear classifier and neuron

Labels



RGB images

+1

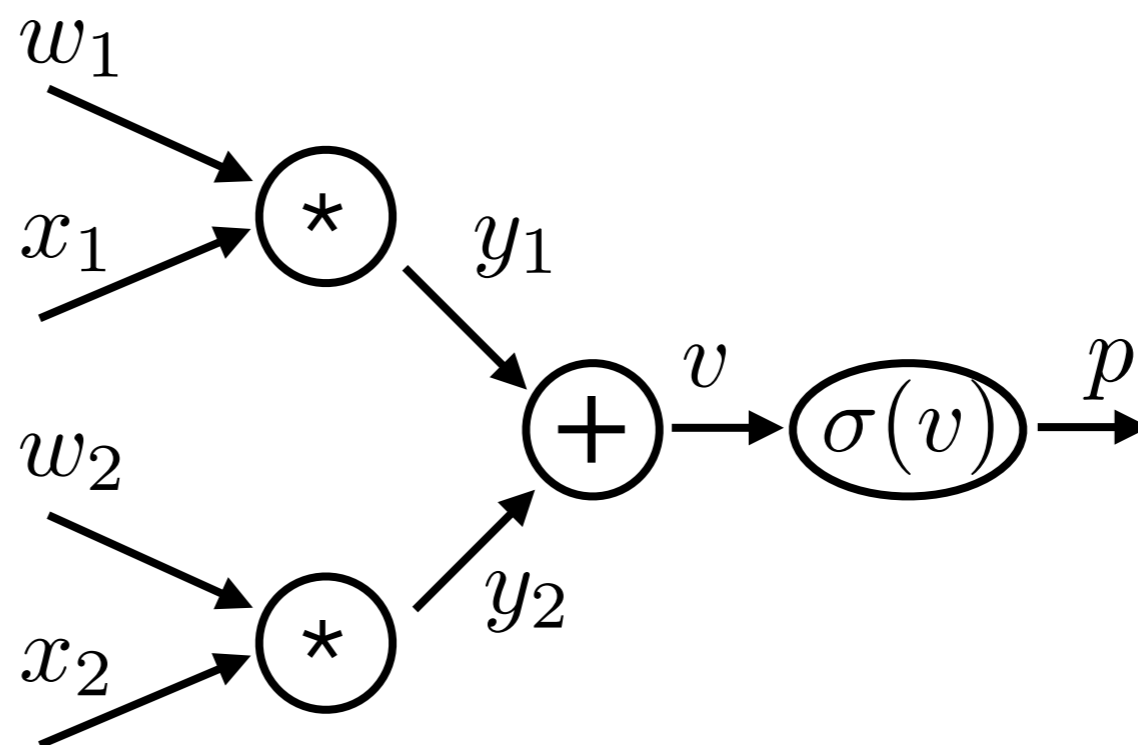


-1

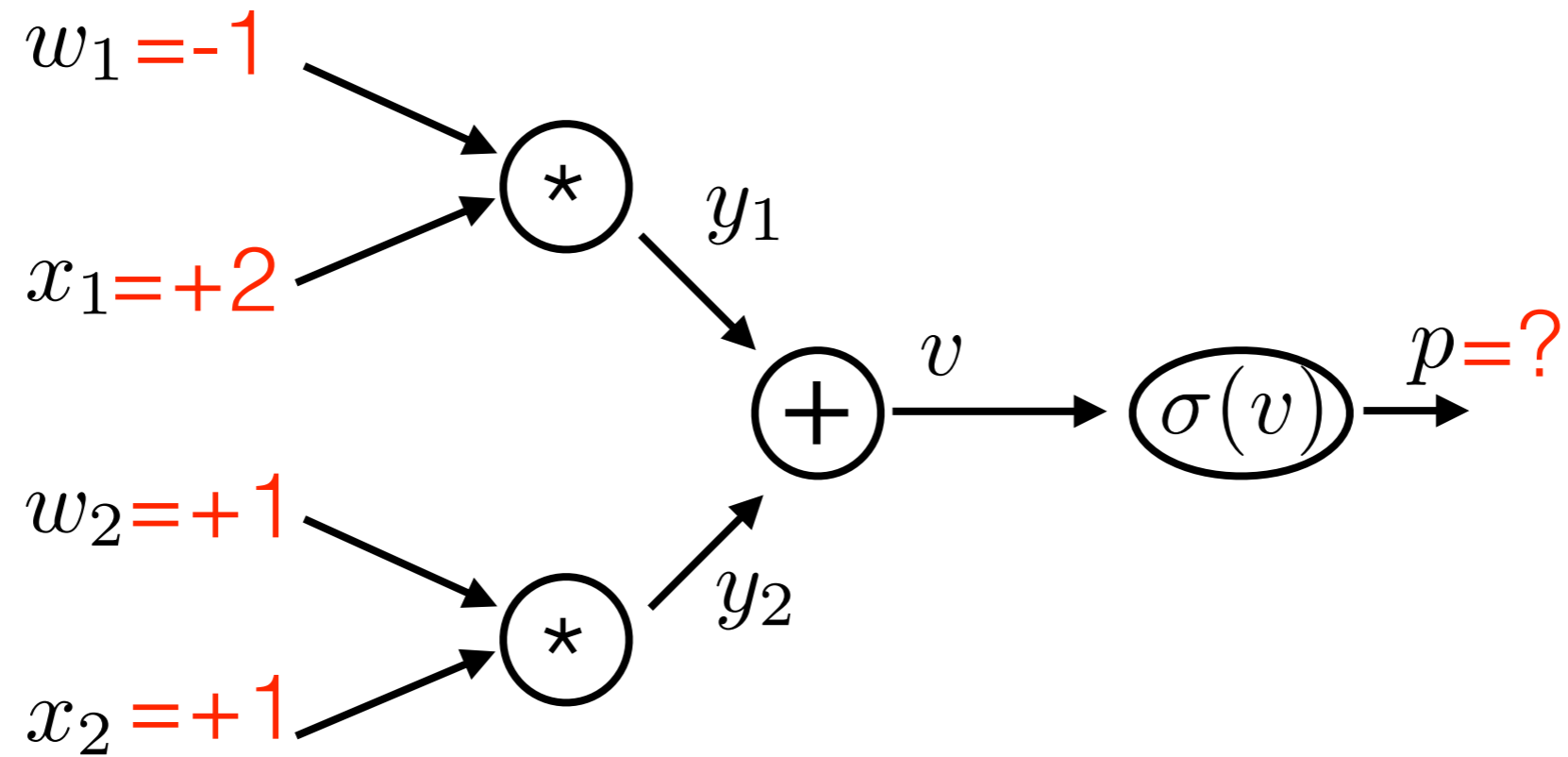


```
def classify():  
    # Linear classifier  
     $\mathbf{x} = \text{vec}(\text{$ )  
     $p = \sigma(\mathbf{w}^\top \mathbf{x})$   
    return  $p$ 
```

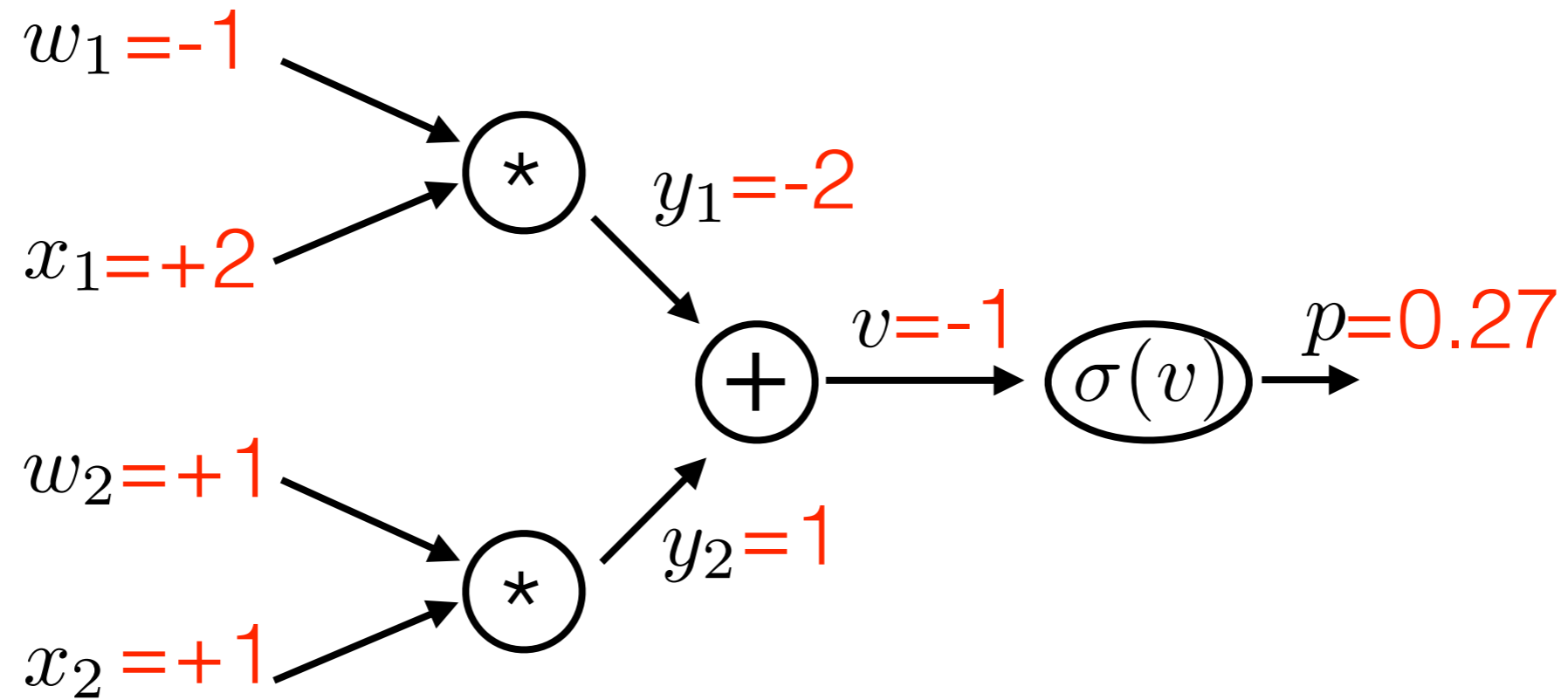
Computational graph of linear classifier



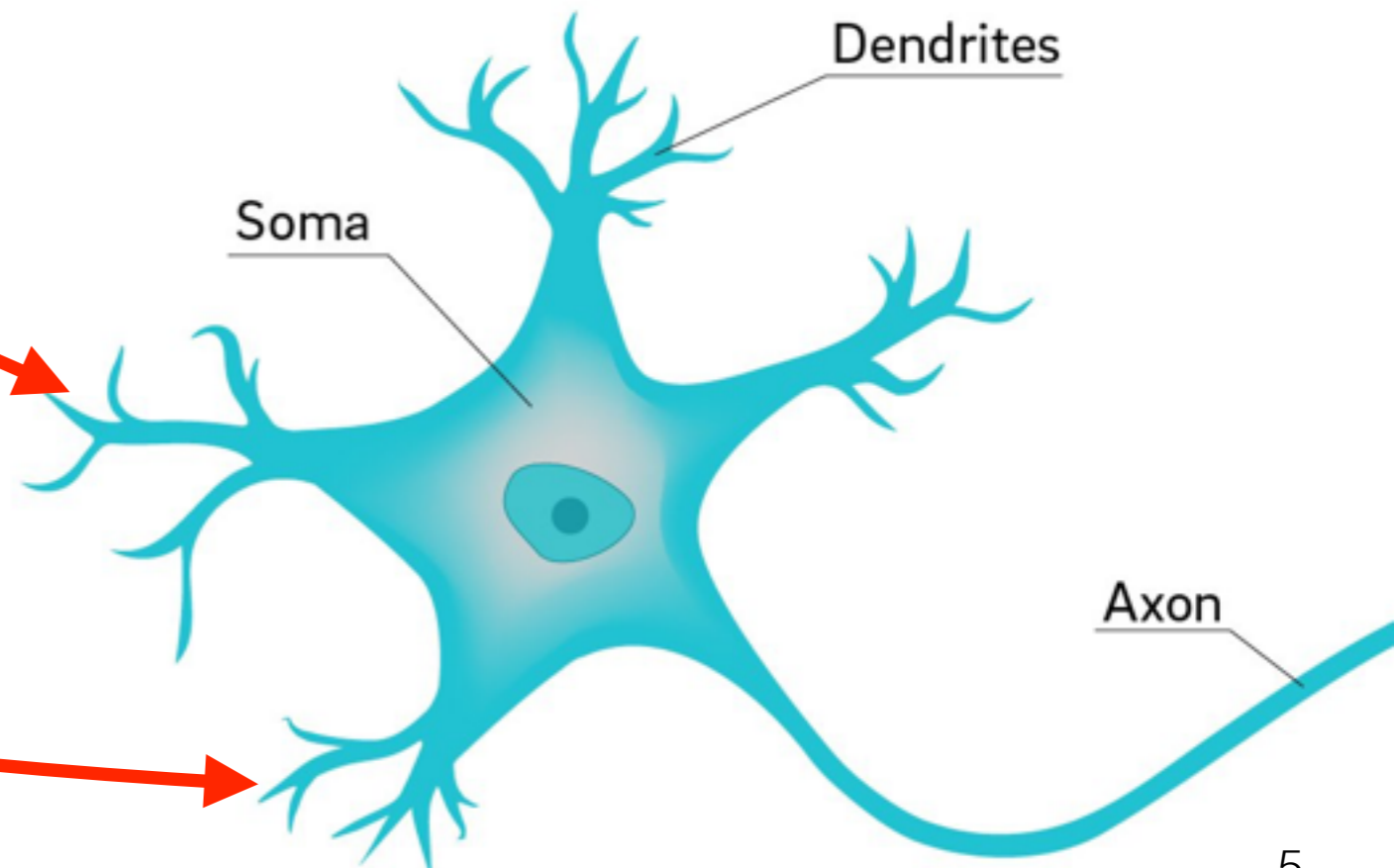
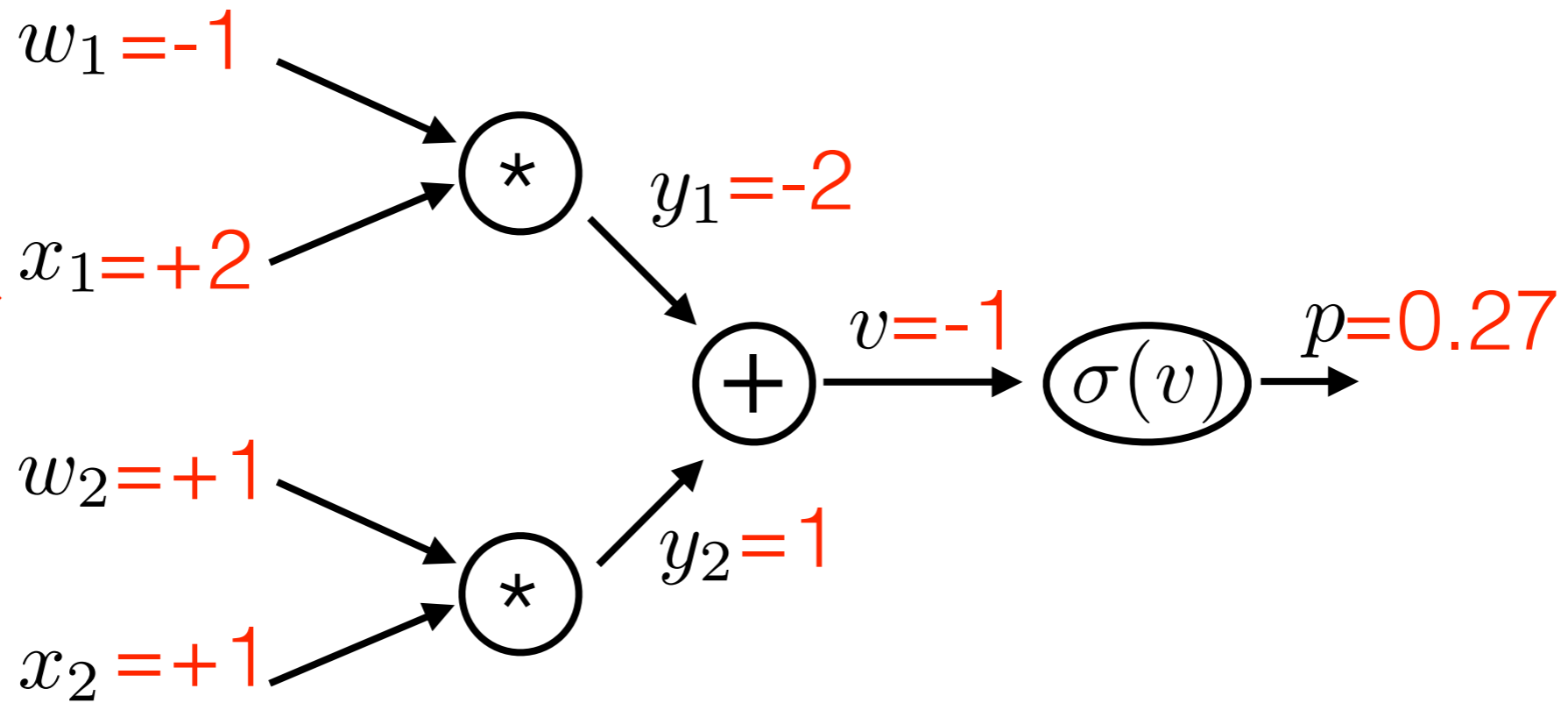
Example I: given trained neuron, and input, what is output?



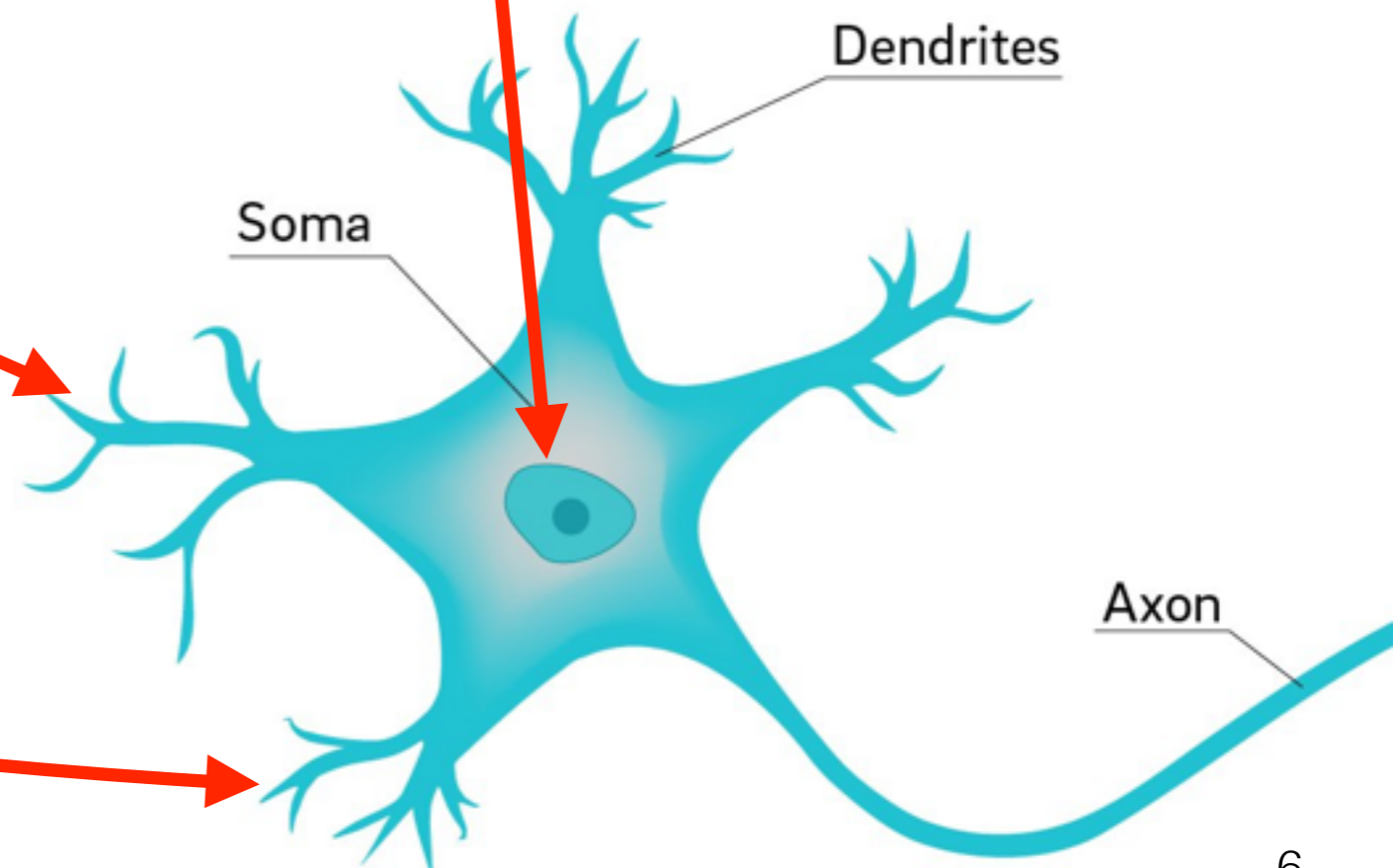
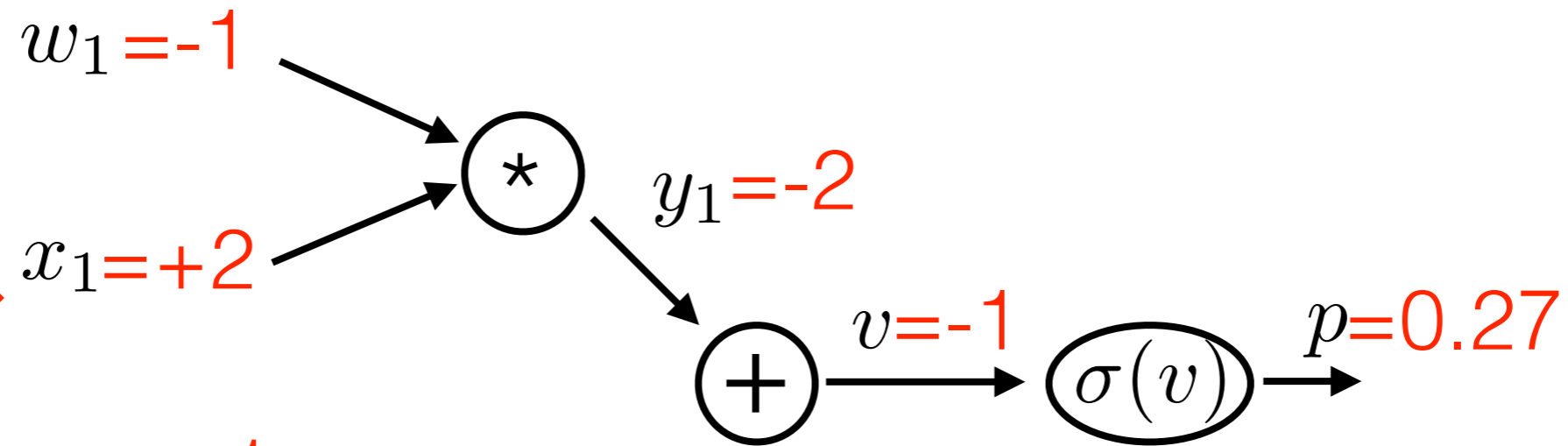
Example I: given trained classifier, and input, what is output?



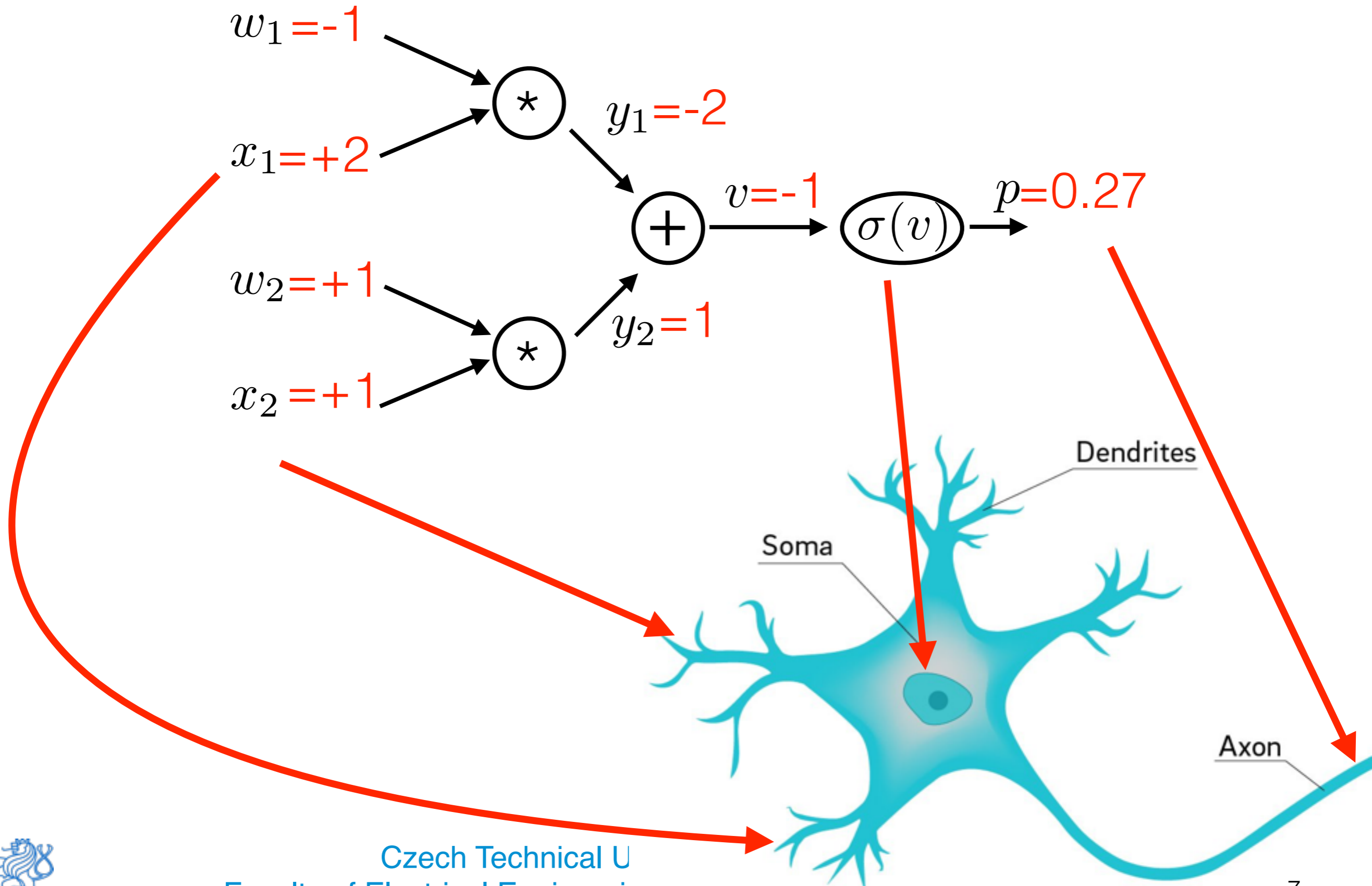
Relation to biological neuron



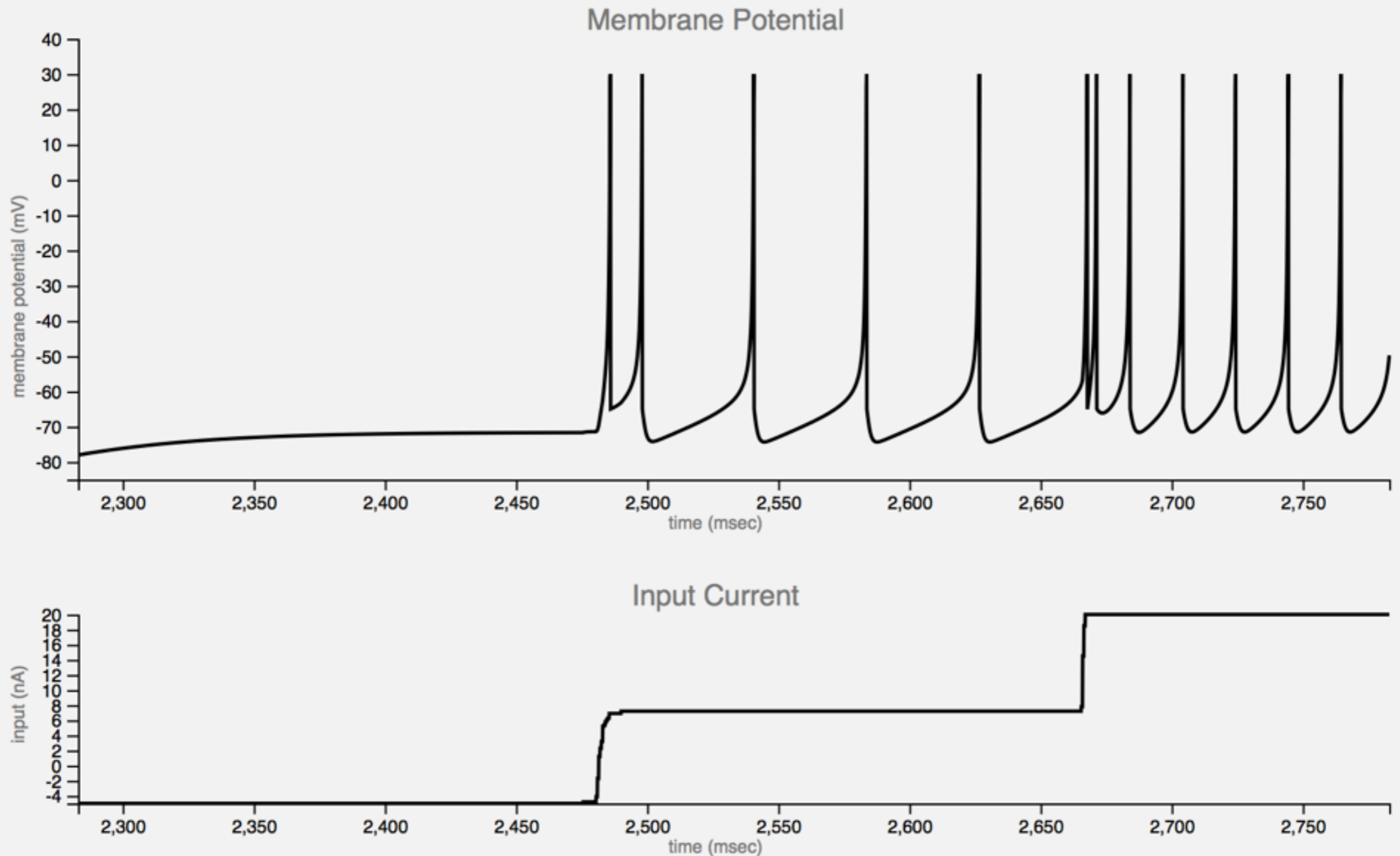
Relation to biological neuron



Relation to biological neuron



Modeling dynamic neuron behaviour

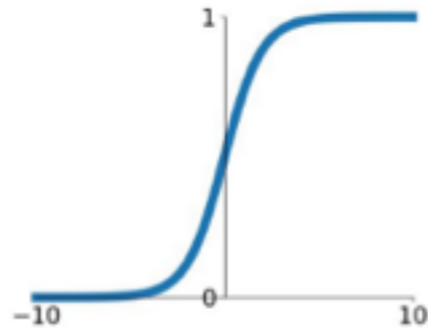


<http://jackterwilliger.com/biological-neural-networks-part-i-spiking-neurons/>

Activation functions $\sigma(v)$

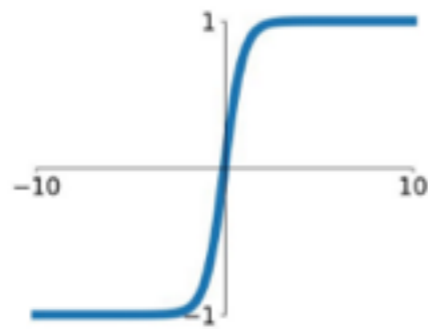
Sigmoid

$$\sigma(x) = \frac{1}{1+e^{-x}}$$



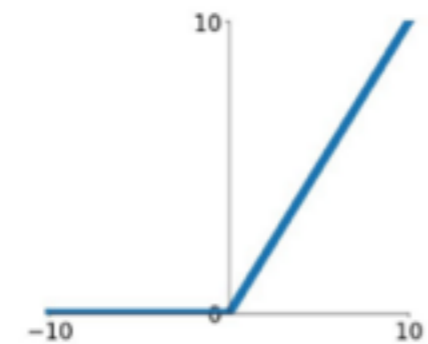
tanh

$$\tanh(x)$$



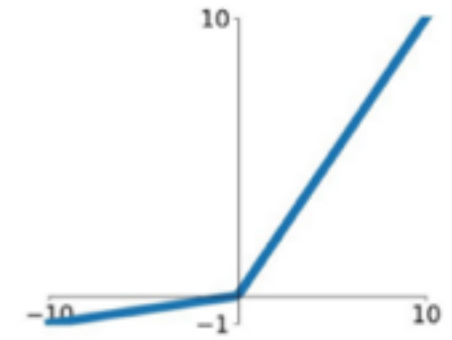
ReLU

$$\max(0, x)$$



Leaky ReLU

$$\max(0.1x, x)$$

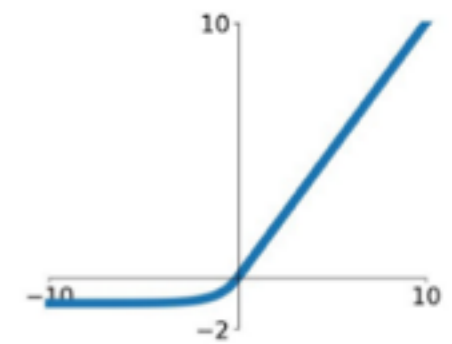


Maxout

$$\max(w_1^T x + b_1, w_2^T x + b_2)$$

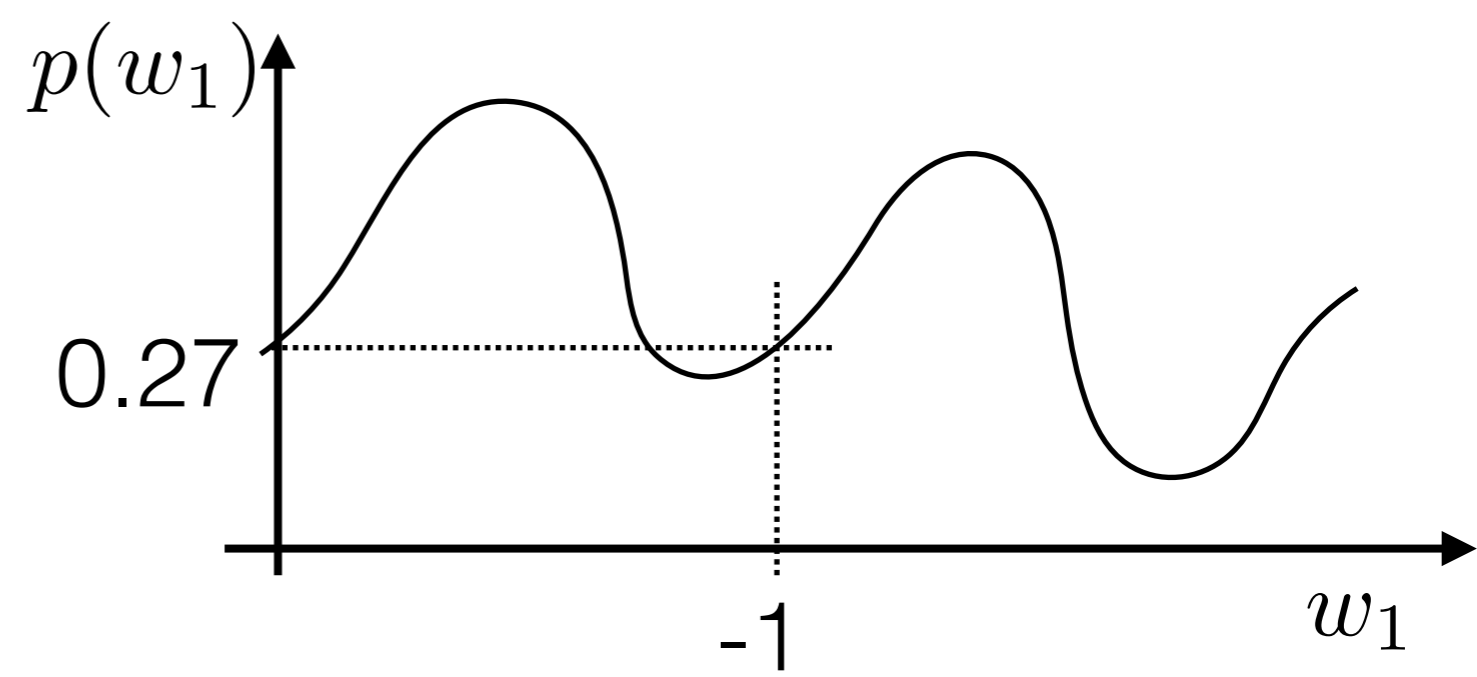
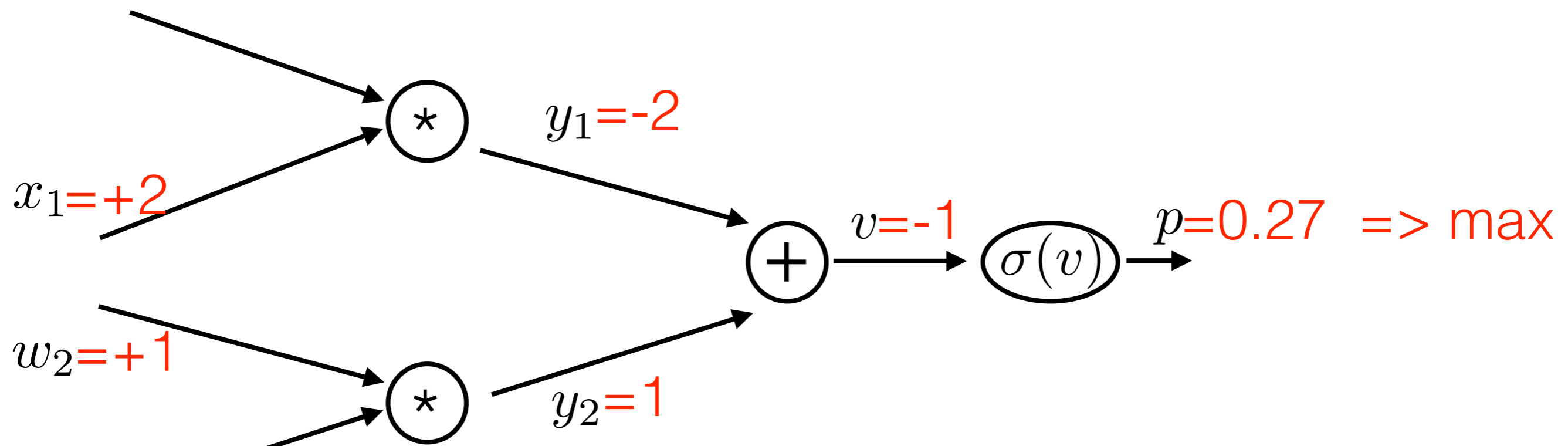
ELU

$$\begin{cases} x & x \geq 0 \\ \alpha(e^x - 1) & x < 0 \end{cases}$$



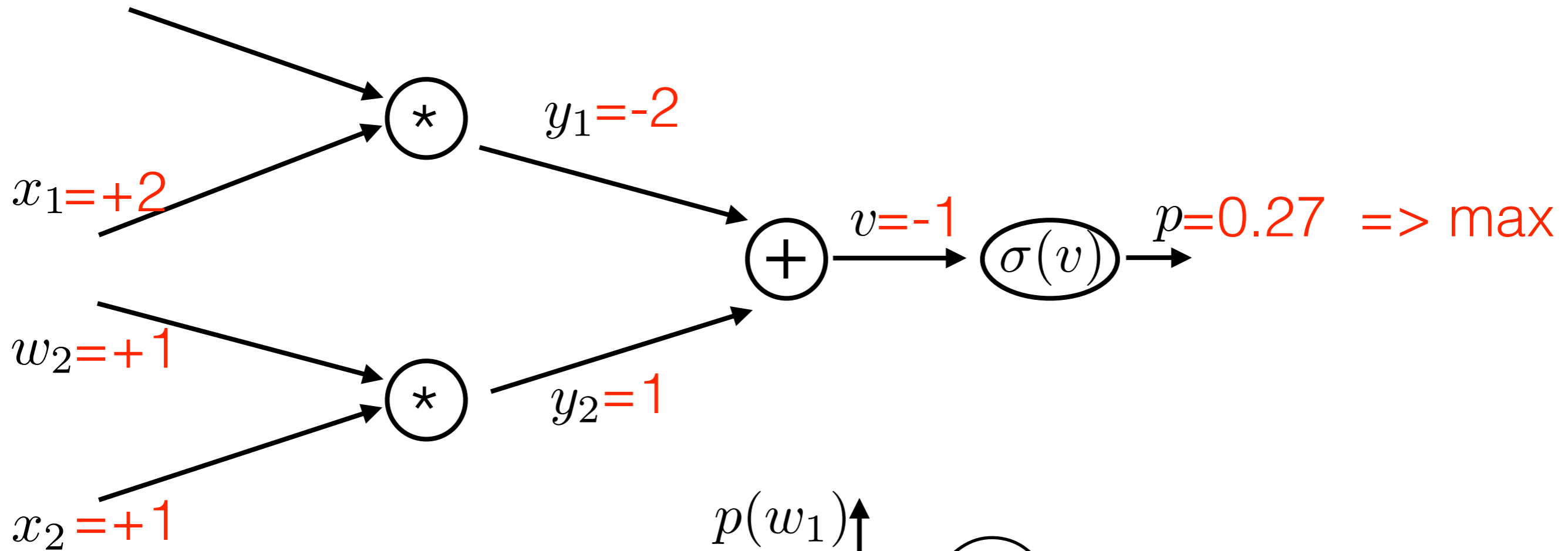
Example II: given x_1, x_2, w_1, w_2 , change weight w_1 to increase p

$w_1 = -1 + ??$

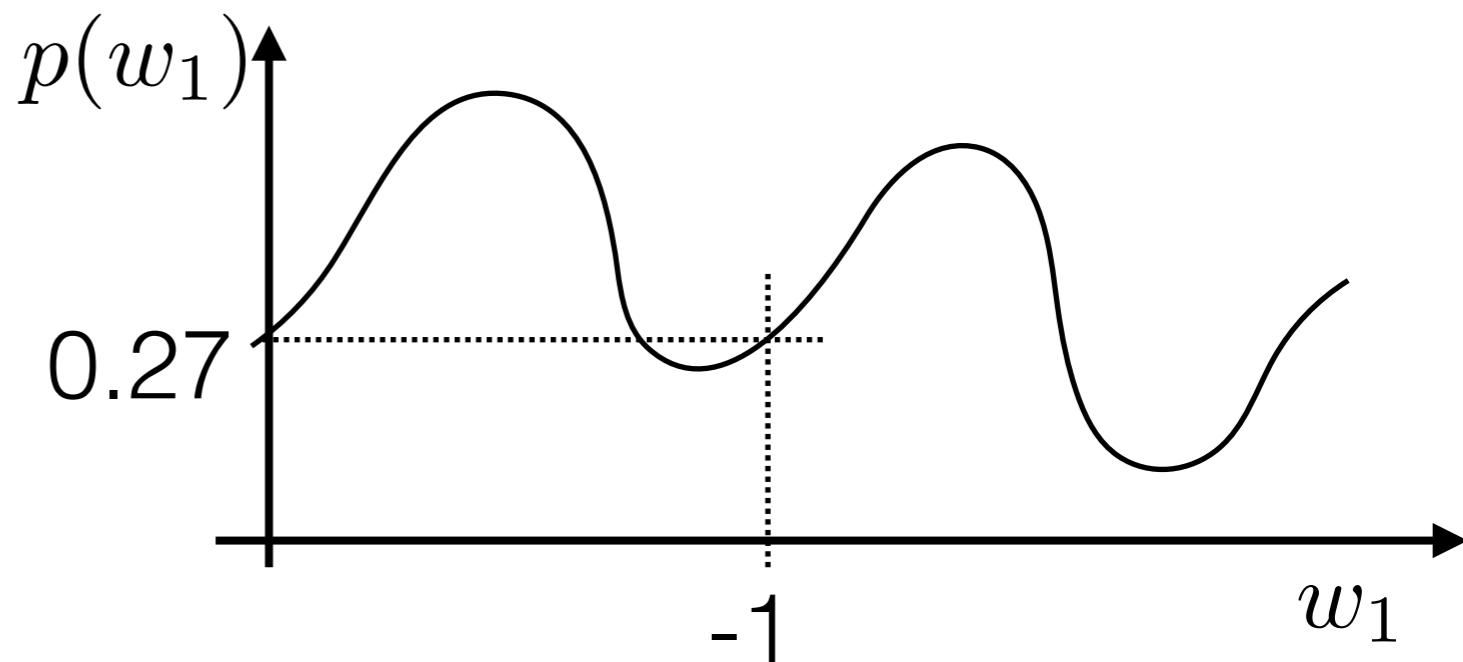


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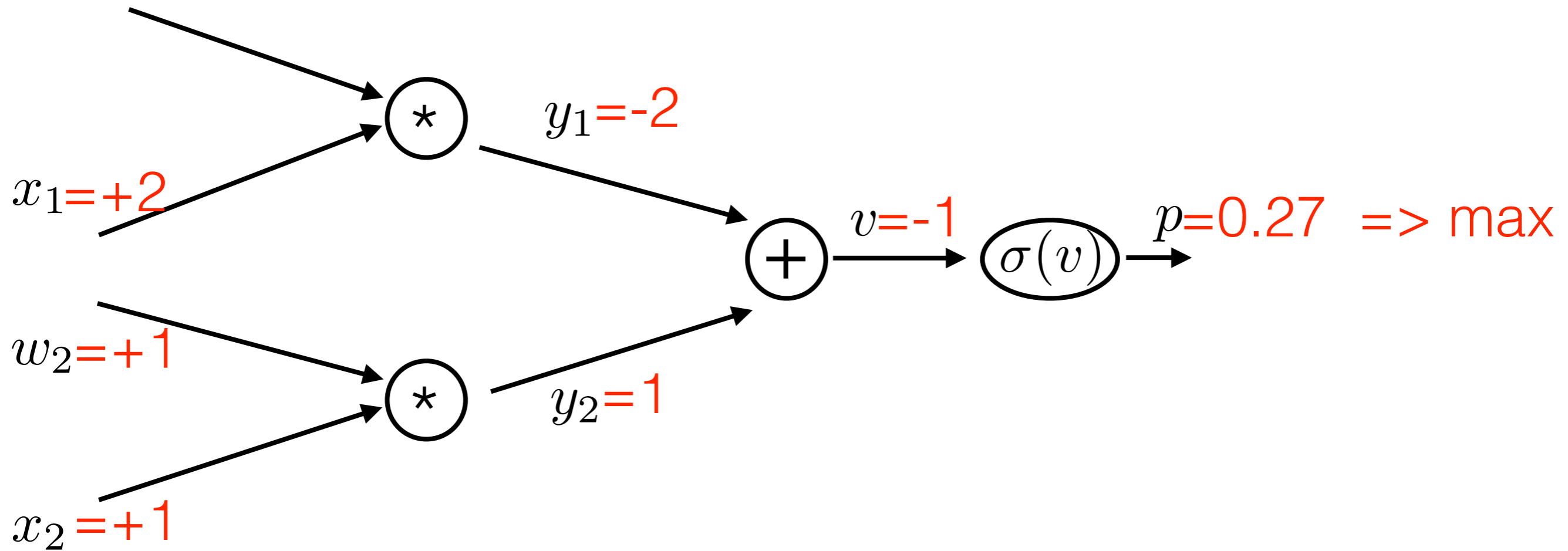


$$w_1 = w_1 + \frac{\partial p}{\partial w_1}$$



Example II: given x_1, x_2, w_1, w_2 , change weight w_1 to increase p

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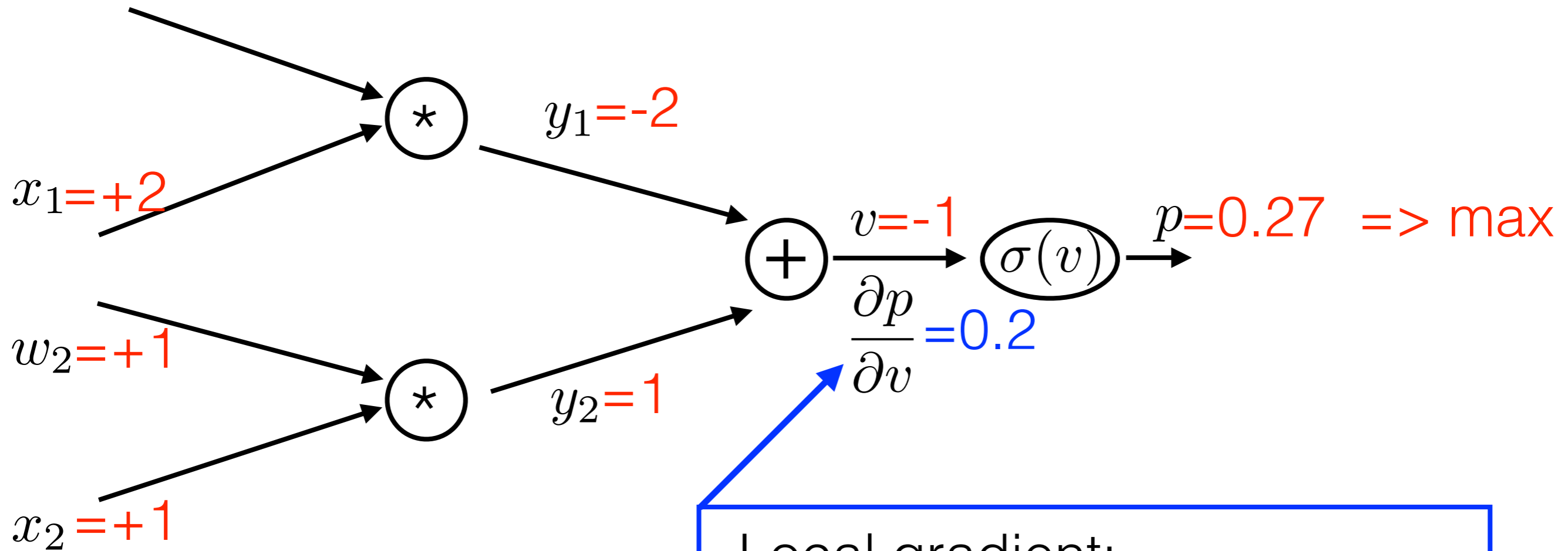
$$w_1 = w_1 + \frac{\partial p}{\partial w_1}$$

Chain-rule in computational graph $\frac{\partial p}{\partial w_1} = \frac{\partial p}{\partial v} \frac{\partial v}{\partial y_1} \frac{\partial y_1}{\partial w_1}$



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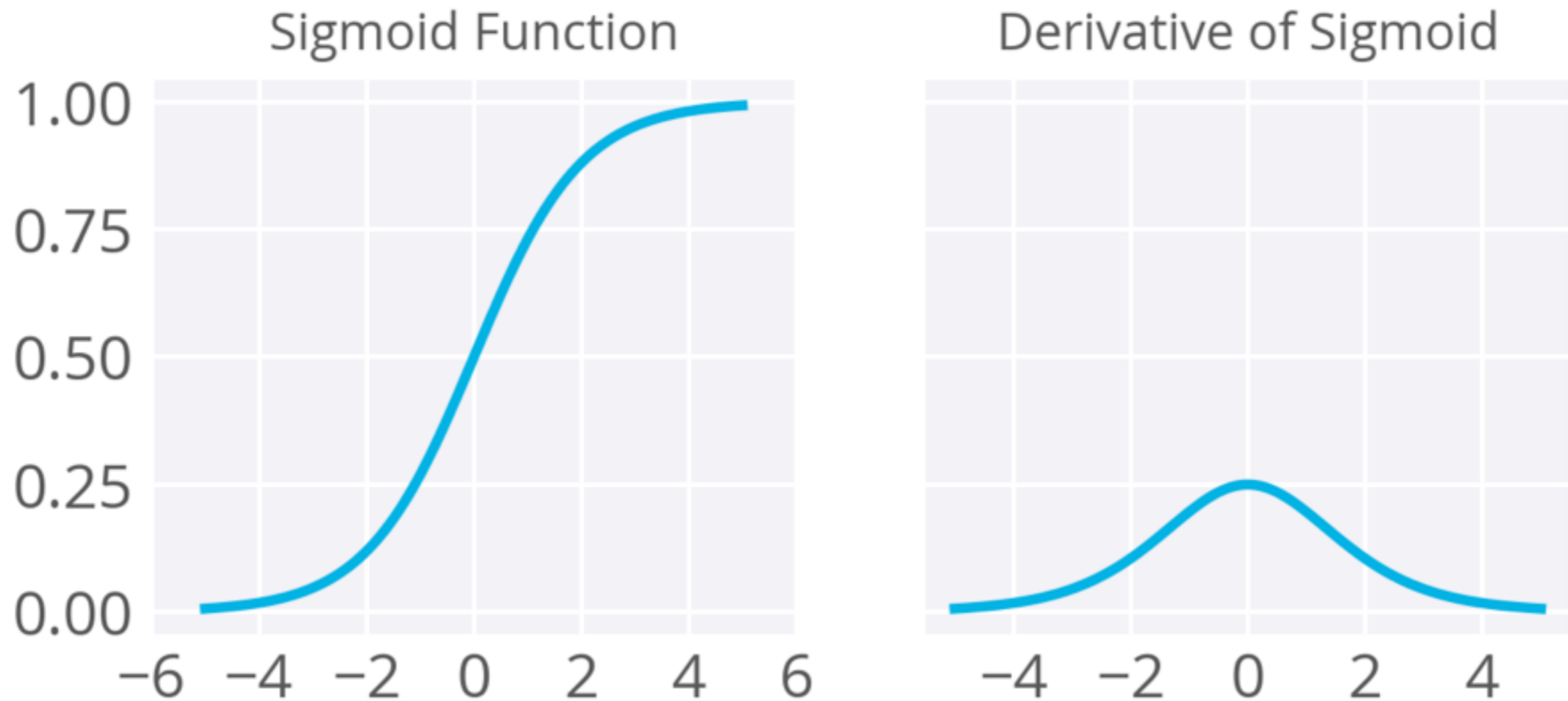
Local gradient:

$$\frac{\partial p}{\partial v} = \frac{\partial \sigma(v)}{\partial v} = \sigma(v)(1 - \sigma(v))$$

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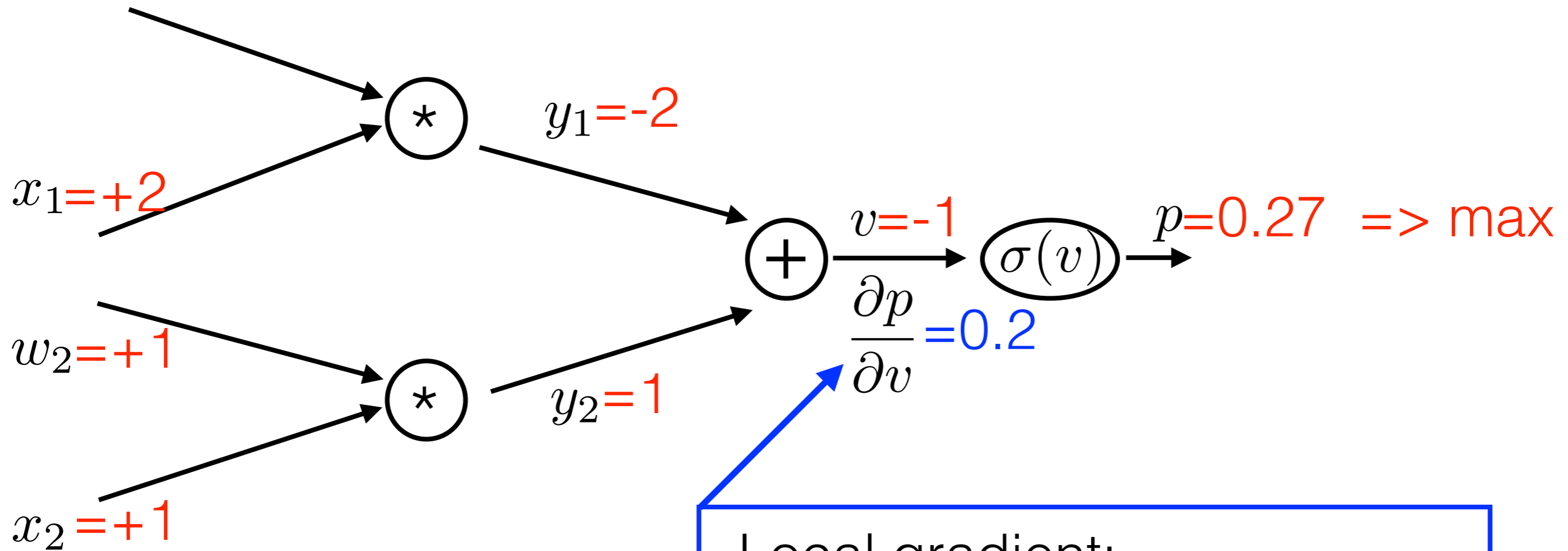
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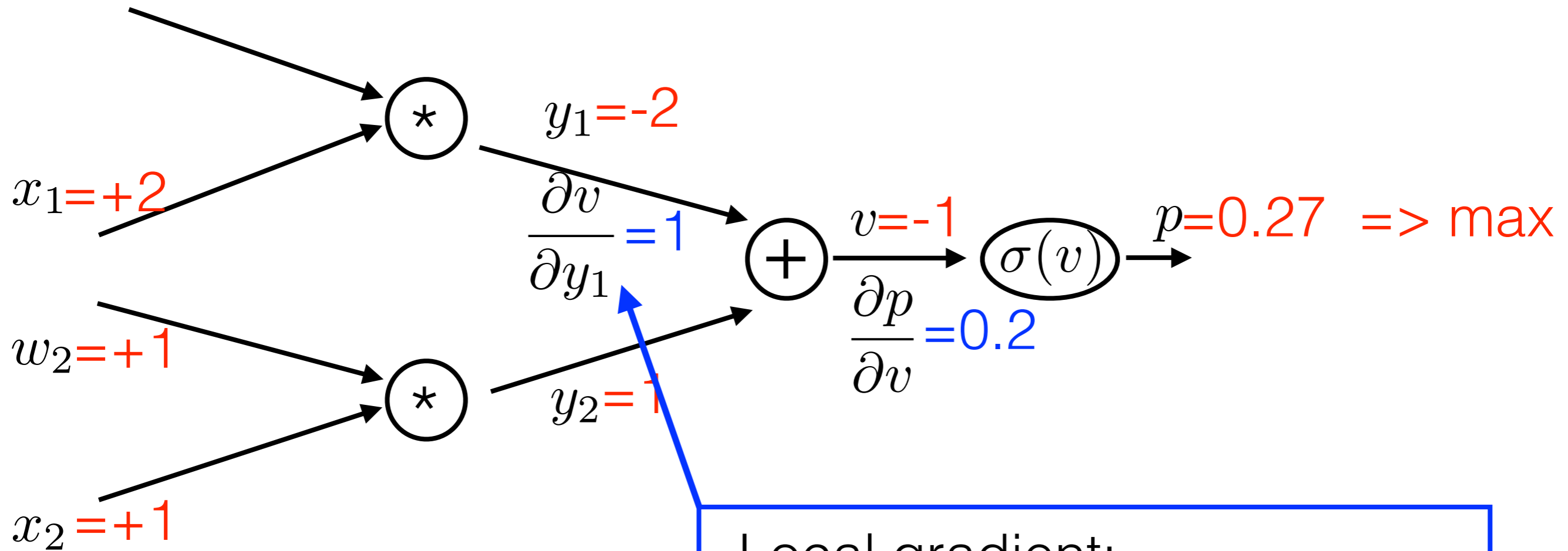
$$w_1 = w_1 + \frac{\partial p}{\partial w_1}$$

Chain-rule in computational graph $\frac{\partial p}{\partial w_1} = \frac{\partial p}{\partial v} \frac{\partial v}{\partial y_1} \frac{\partial y_1}{\partial w_1}$



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Local gradient:

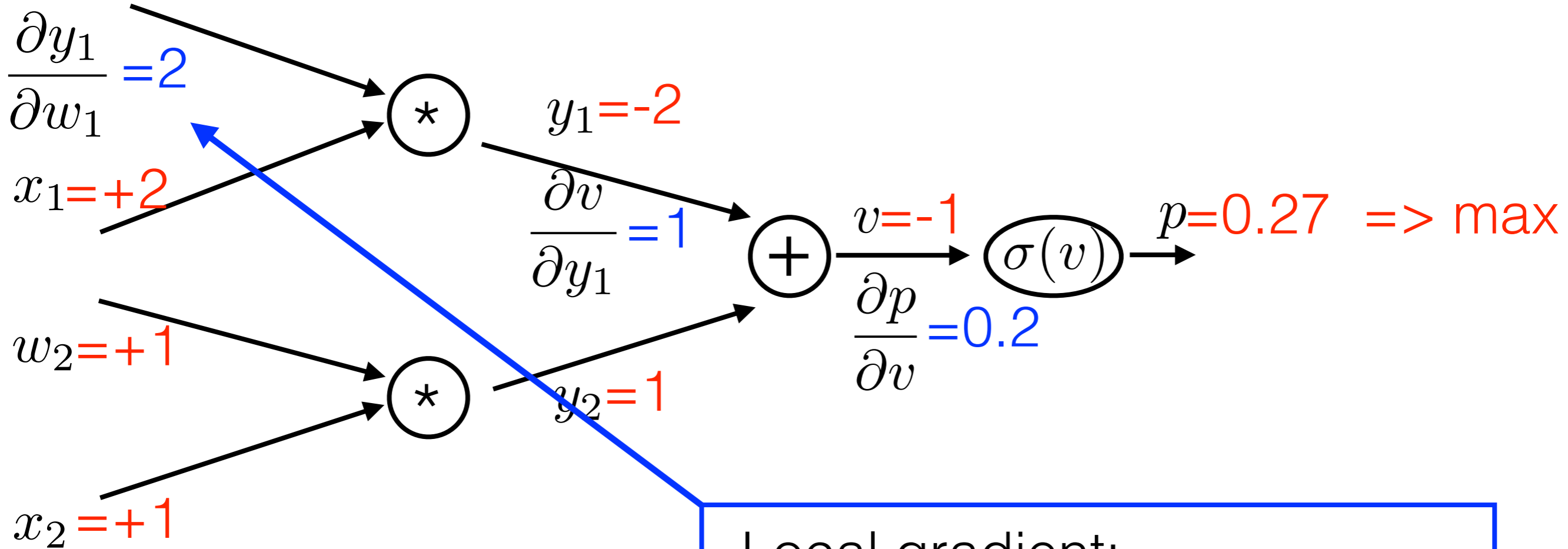
$$\frac{\partial v}{\partial y_1} = \frac{\partial(y_1 + y_2)}{\partial y_1} = 1$$

Chain-rule in computational graph $\frac{\partial p}{\partial w_1} = \frac{\partial p}{\partial v} \frac{\partial v}{\partial y_1} \frac{\partial y_1}{\partial w_1}$



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Local gradient:

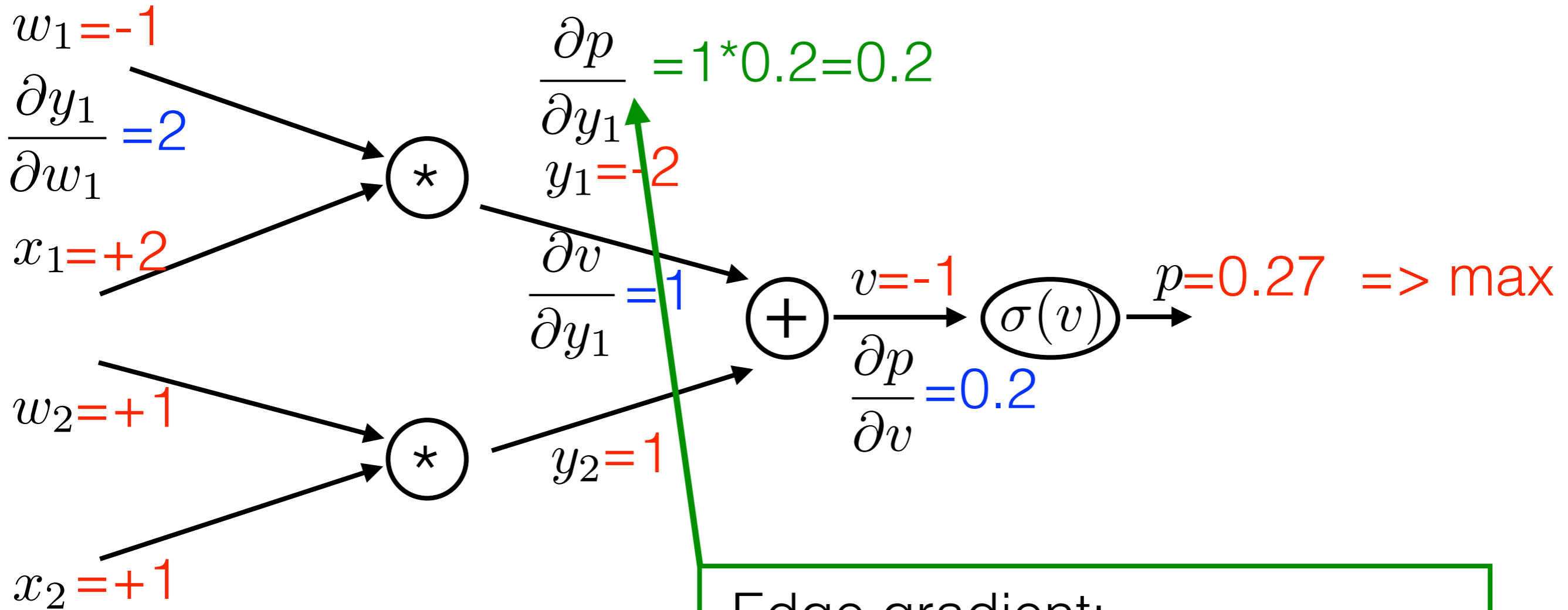
$$\frac{\partial y_1}{\partial w_1} = \frac{\partial(w_1 x_1)}{\partial w_1} = x_1$$

$$w_1 = w_1 + \frac{\partial p}{\partial w_1}$$

Chain-rule in computational graph $\frac{\partial p}{\partial w_1} = \frac{\partial p}{\partial v} \frac{\partial v}{\partial y_1} \frac{\partial y_1}{\partial w_1}$



Example II: given x_1, x_2, w_1, w_2 , change weight w_1 to increase p



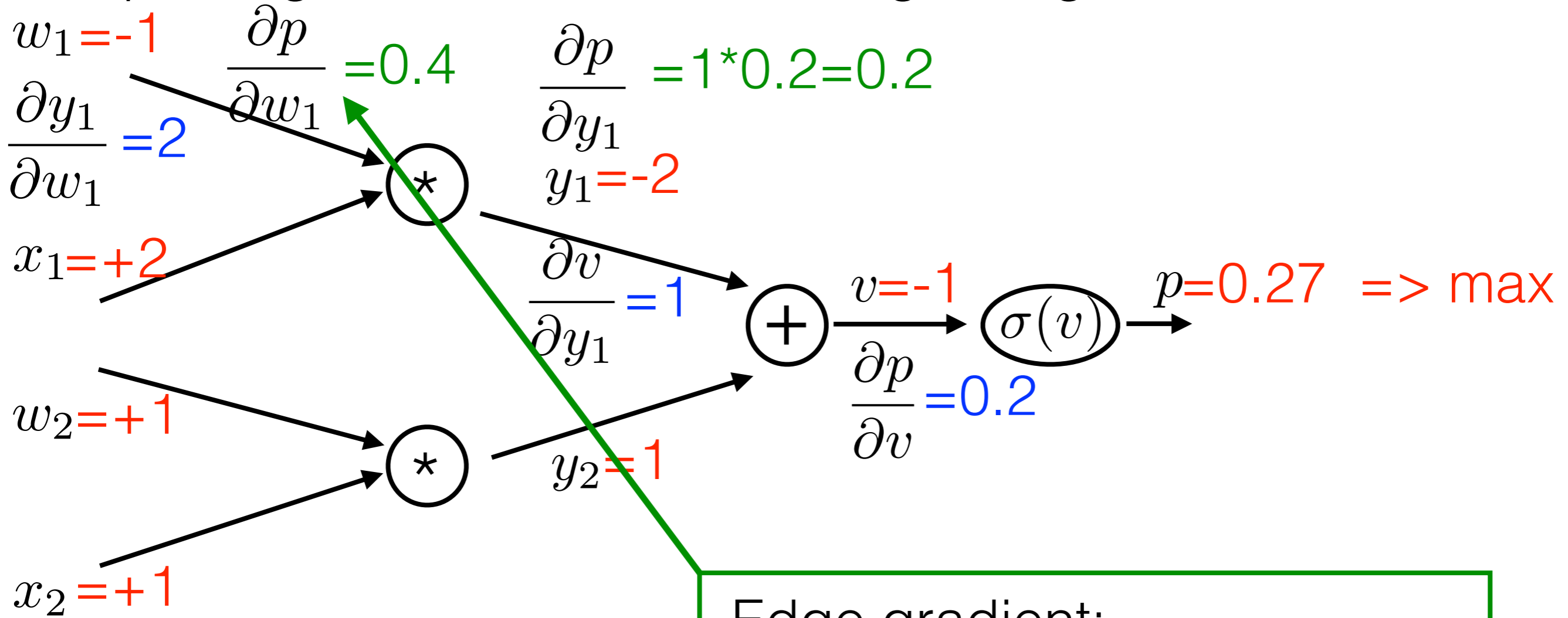
Edge gradient:

$$\frac{\partial p}{\partial y_1} = \frac{\partial p}{\partial v} \frac{\partial v}{\partial y_1}$$

Chain-rule in computational graph $\frac{\partial p}{\partial w_1} = \frac{\partial p}{\partial v} \frac{\partial v}{\partial y_1} \frac{\partial y_1}{\partial w_1}$



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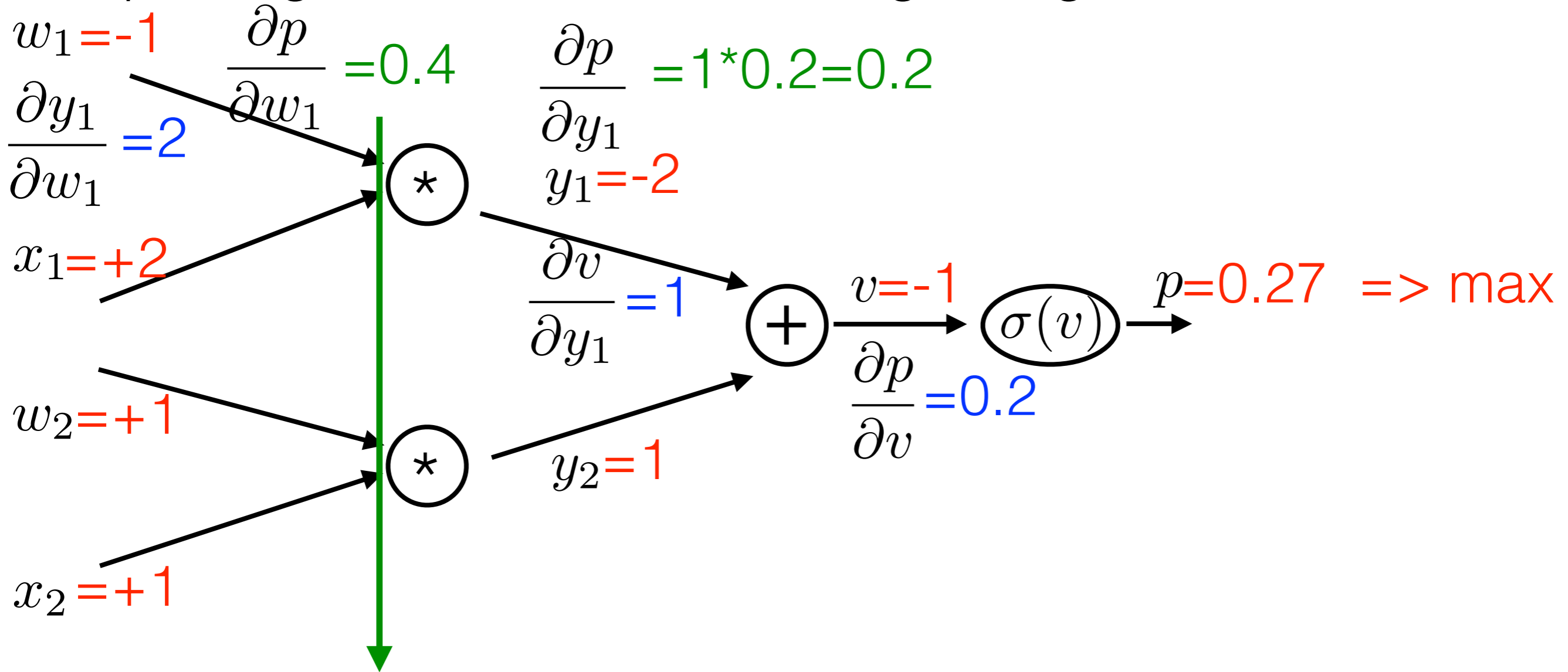
Edge gradient:

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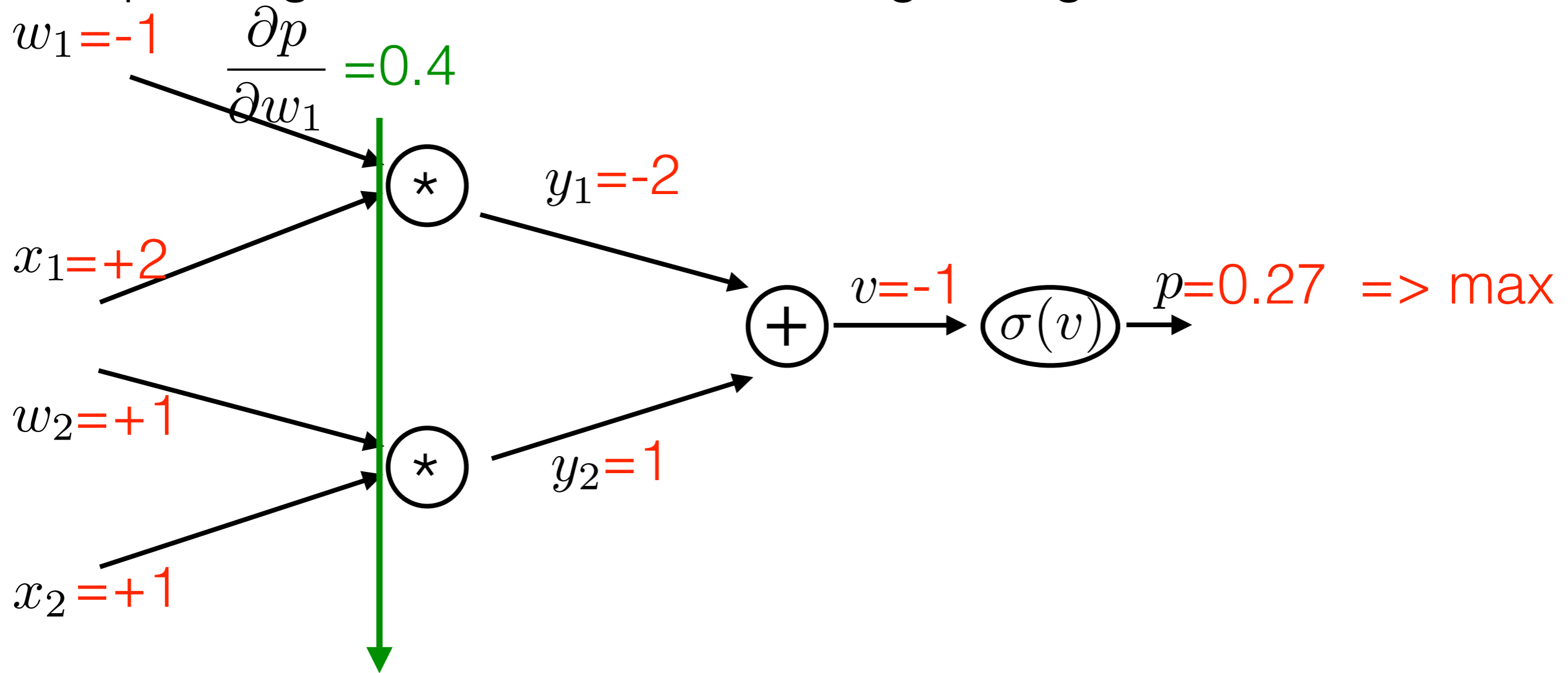


$$w_1 = w_1 + \frac{\partial p}{\partial w_1}$$

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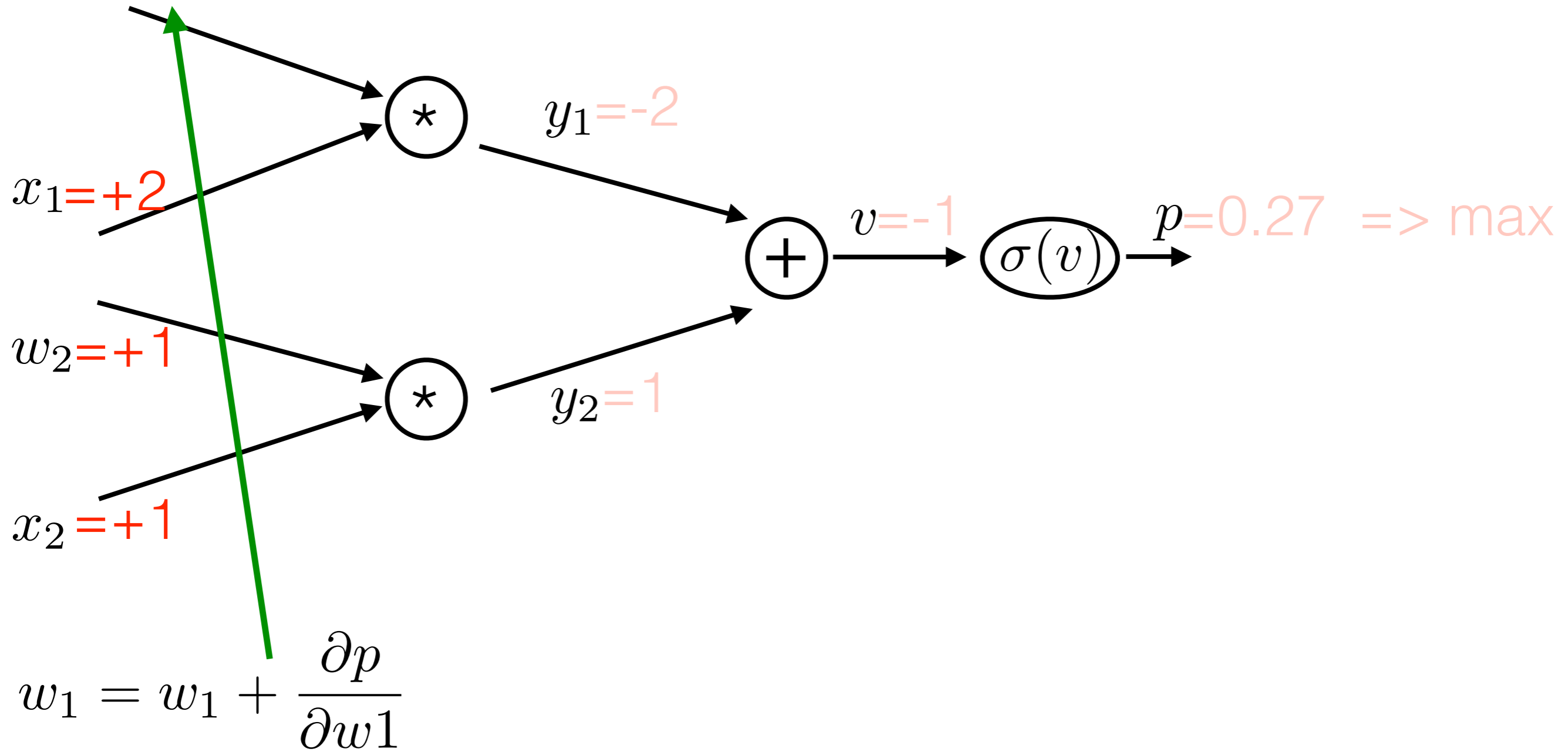
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Example II: given x_1, x_2, w_1, w_2 , change weight w_1 to increase p

$$w_1 = -0.6$$

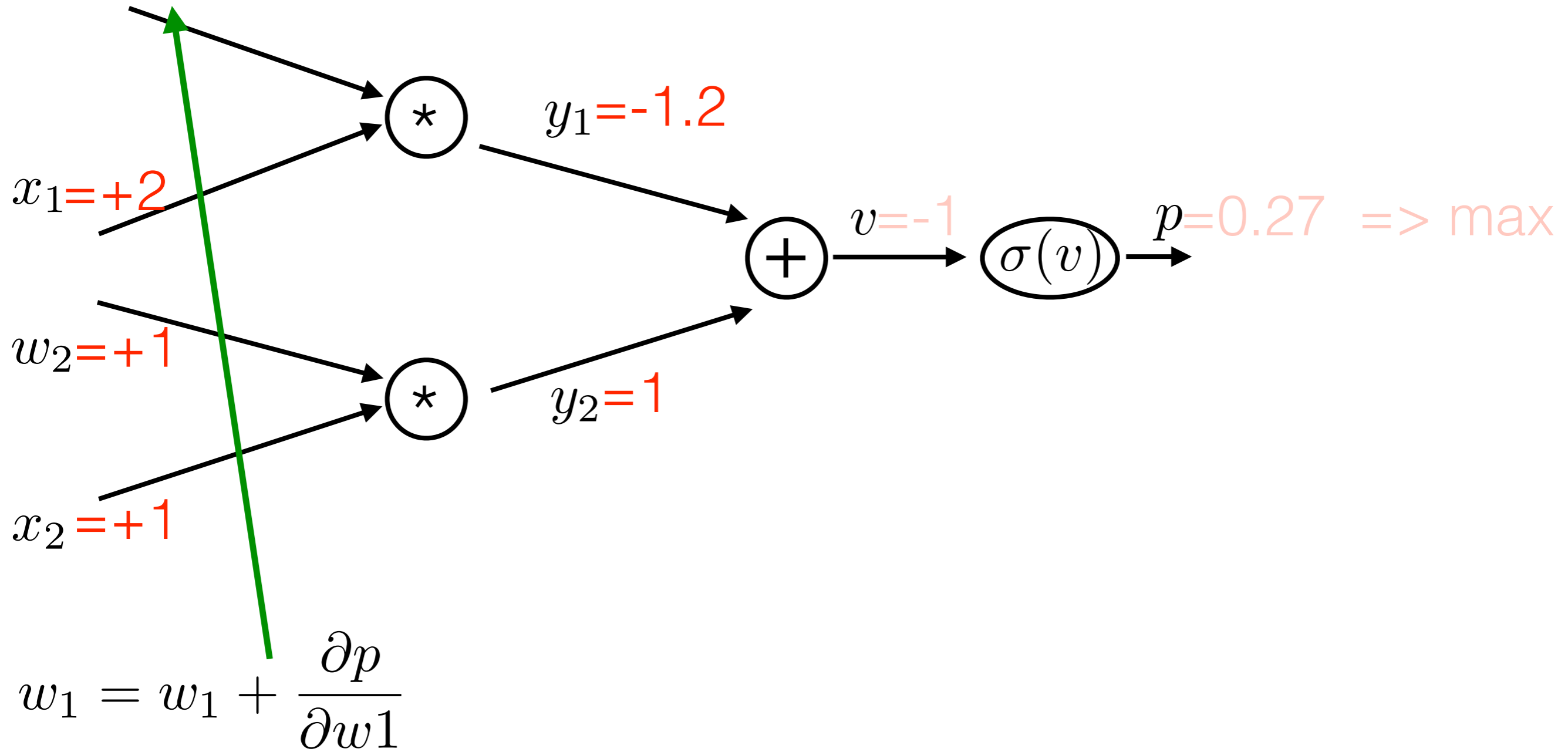


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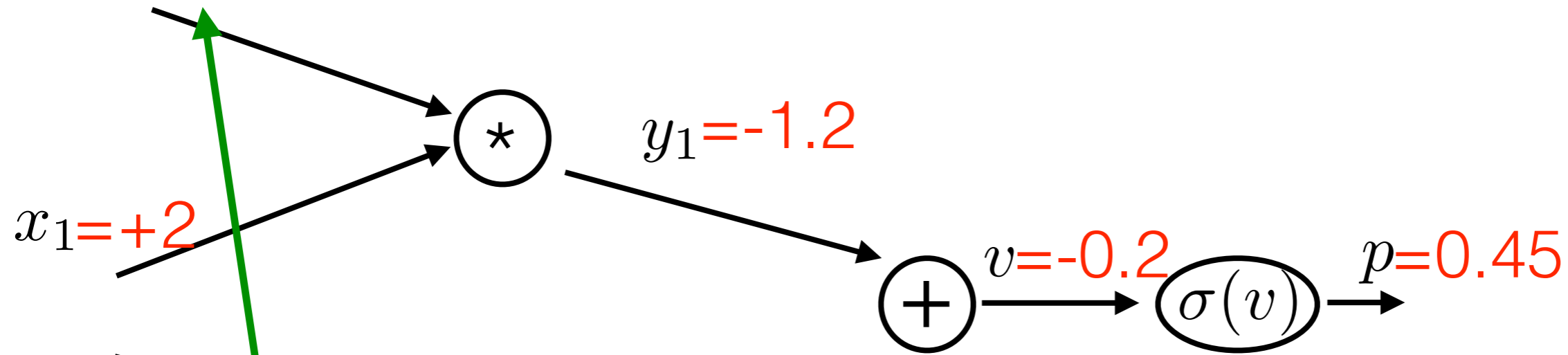


Chain-rule in computational graph $\frac{\partial p}{\partial w_1} = \frac{\partial p}{\partial v} \frac{\partial v}{\partial y_1} \frac{\partial y_1}{\partial w_1}$



Example II: given x_1, x_2, w_1, w_2 , change weight w_1 to increase p

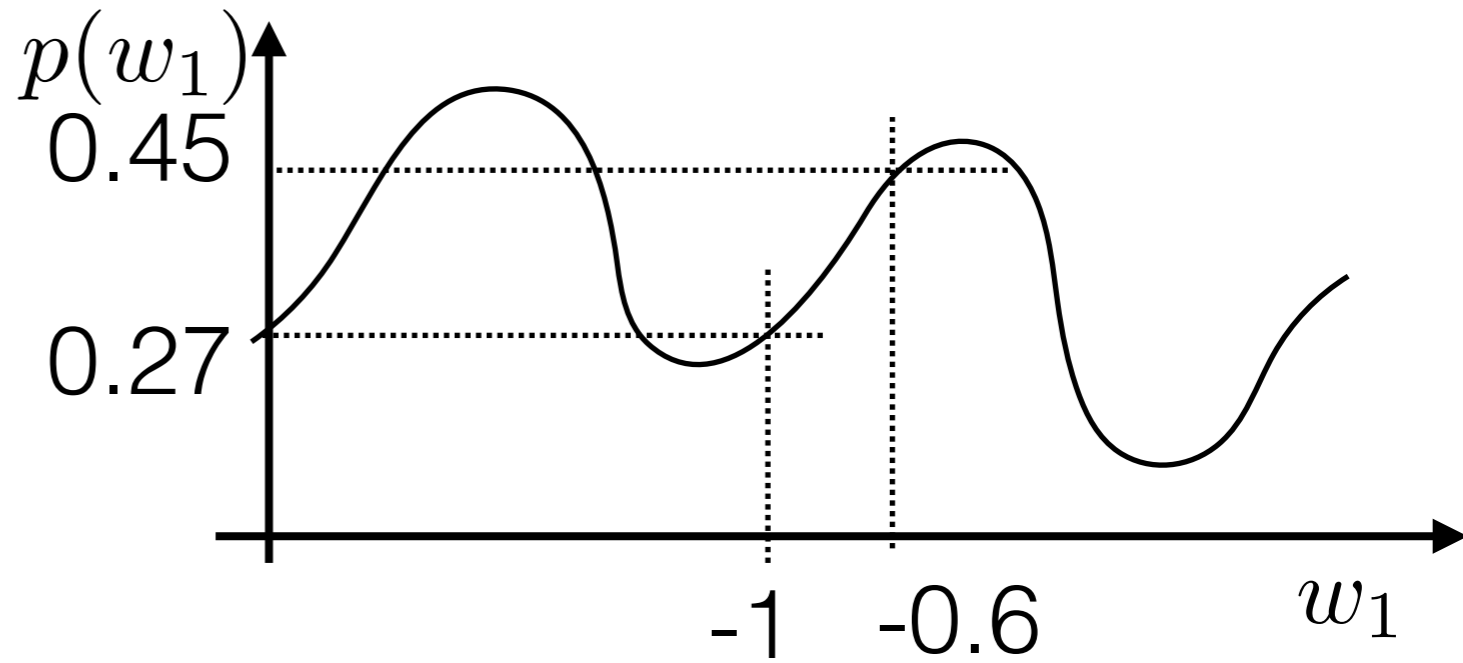
$$w_1 = -0.6$$



$$w_2 = +1$$

$$x_2 = +1$$

$$w_1 = w_1 + \frac{\partial p}{\partial w_1}$$

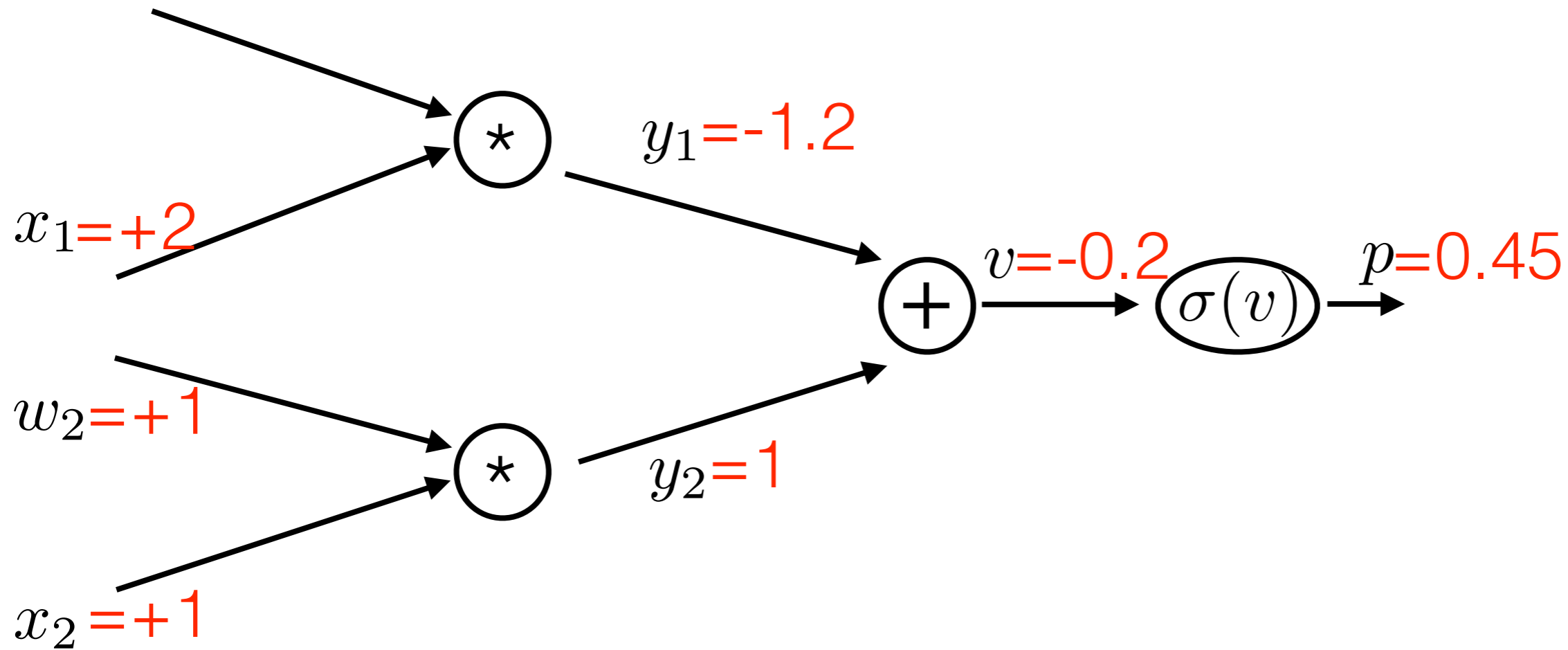


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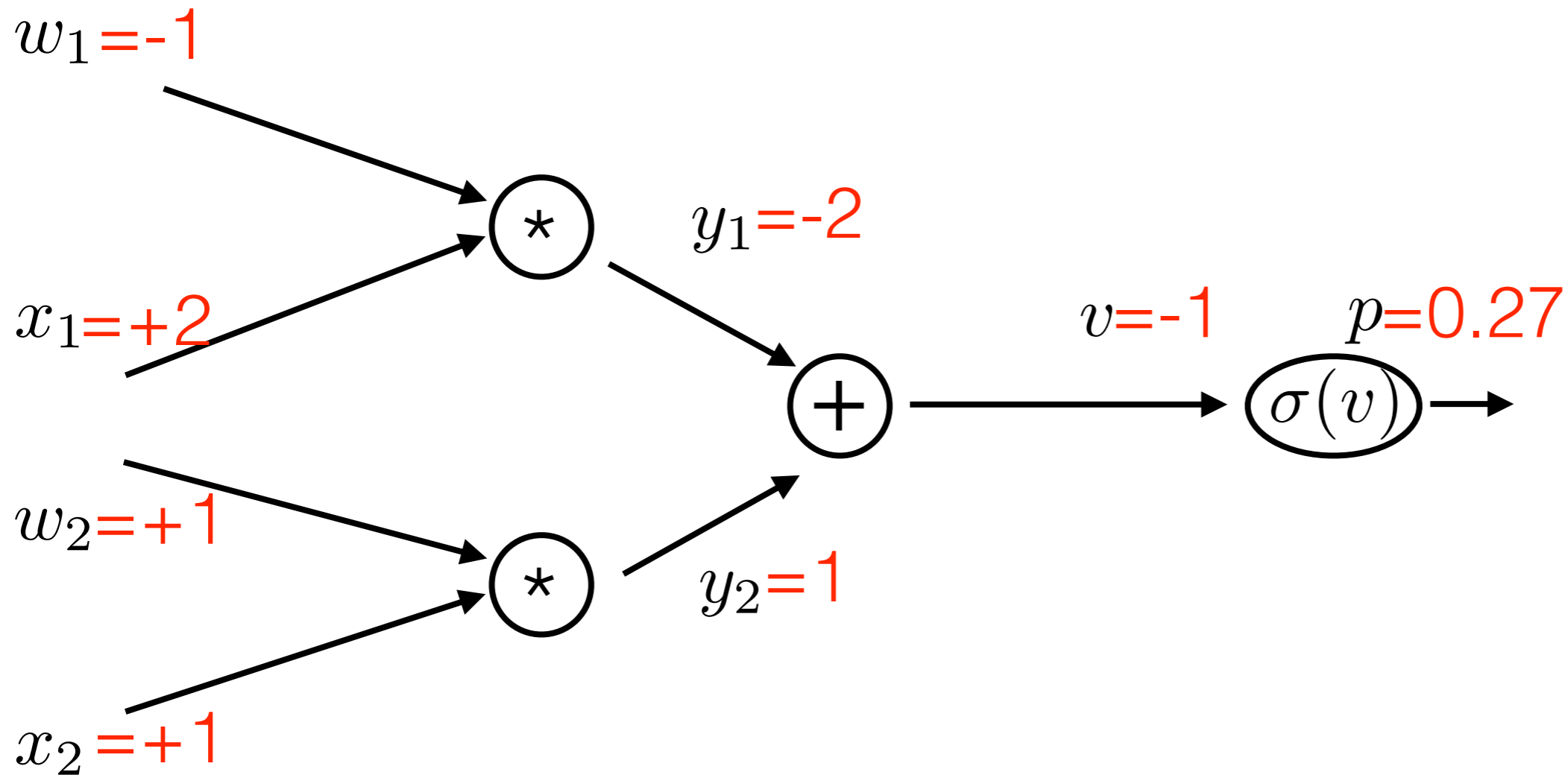


Discussion:

- edge_gradient = upstream_gradient * local_gradient
- what is maximum p (bounds)? can I also update x_1 ?
- relation to learning (max p for positive samples)



Computational graph of the learning- **adding loss layer**

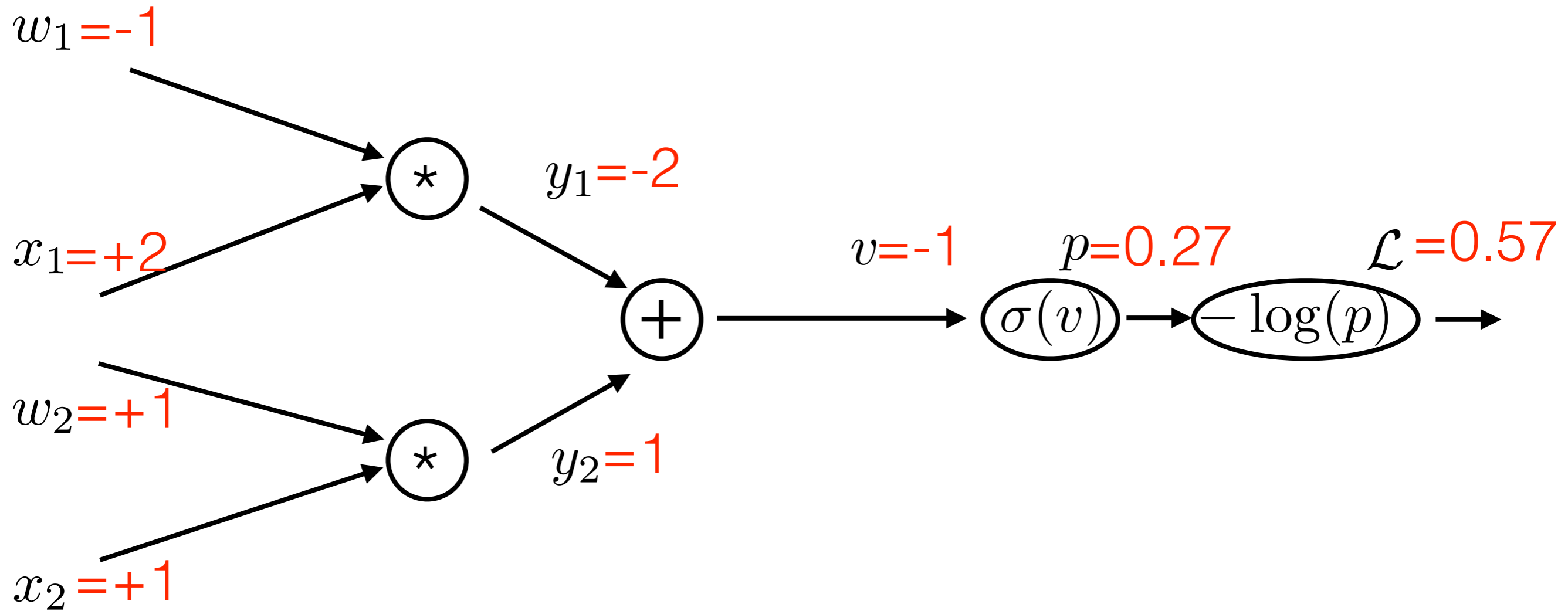


MAP estimate actually says:

Positive sample \Rightarrow p should be huge \Rightarrow minimize $-\log(p)$



Computational graph of the learning from a **positive** sample

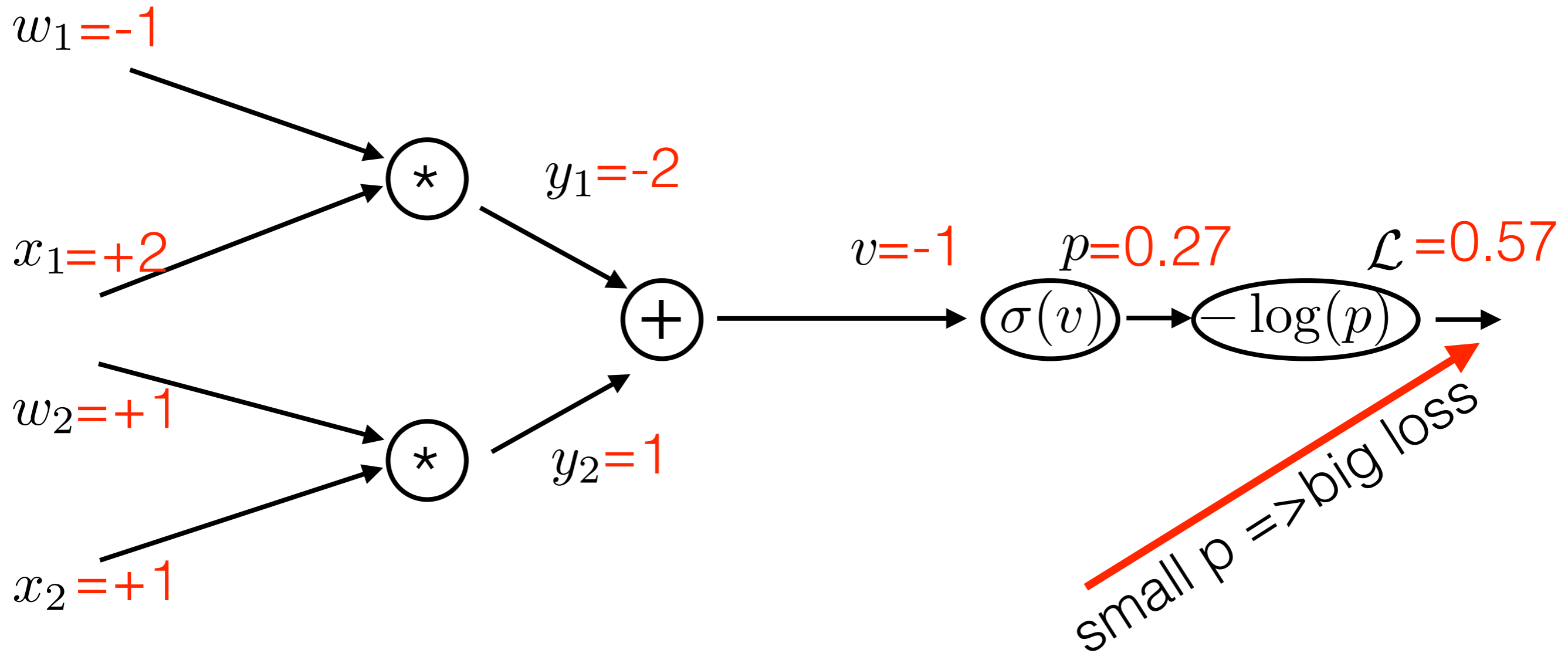


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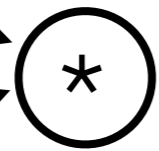
Computational graph of the learning from a **negative** sample

$$w_1 = -1$$

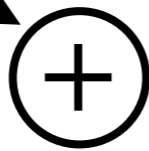
$$x_1 = +2$$

$$w_2 = +1$$

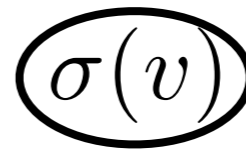
$$x_2 = +1$$



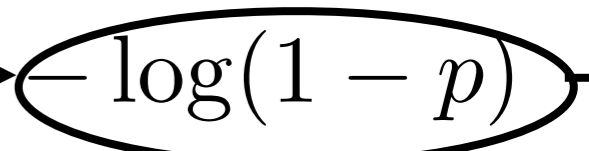
$$y_1 = -2$$



$$v = -1$$



$$p = 0.27$$



$$\mathcal{L} = 0.13$$

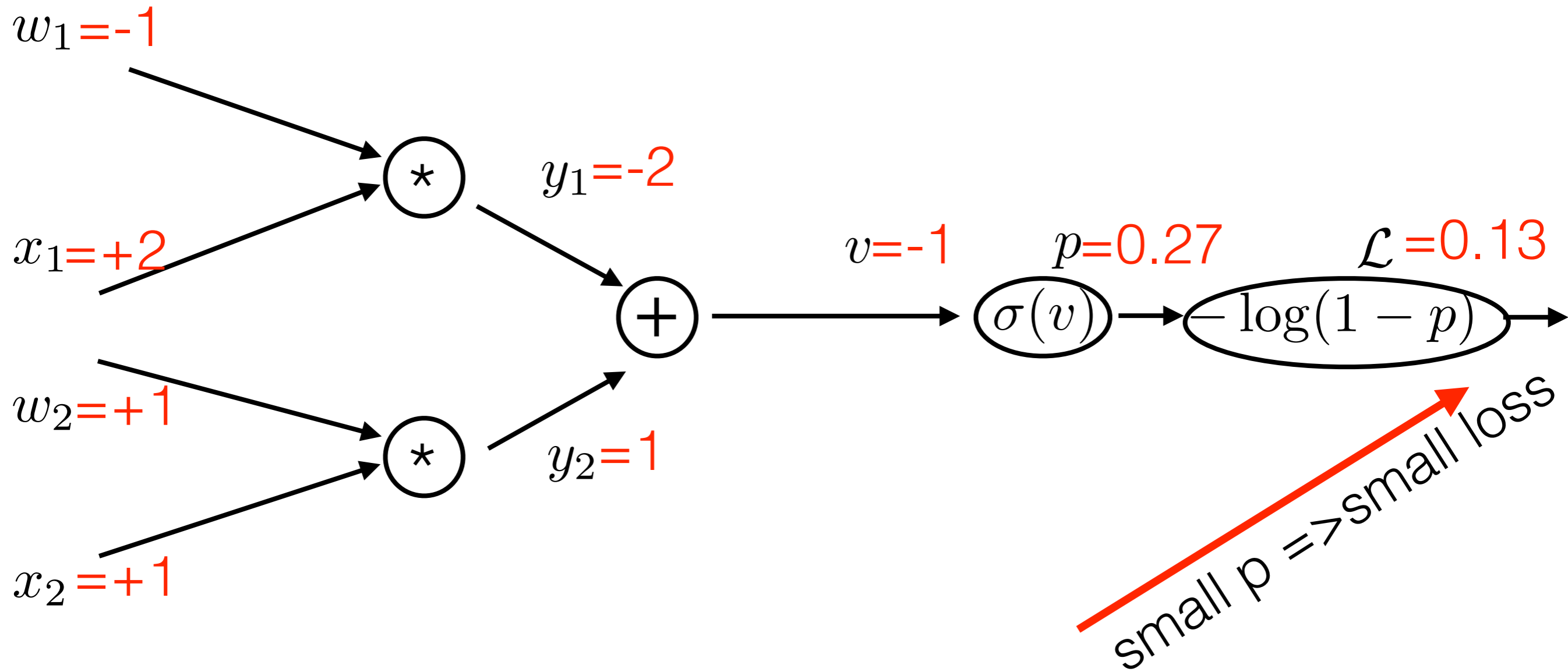
MAP estimate actually says:

Positive sample => p should be huge => minimize $-\log(p)$

Negative sample => p should be small => minimize $-\log(1-p)$



Computational graph of the learning from a **positive** sample



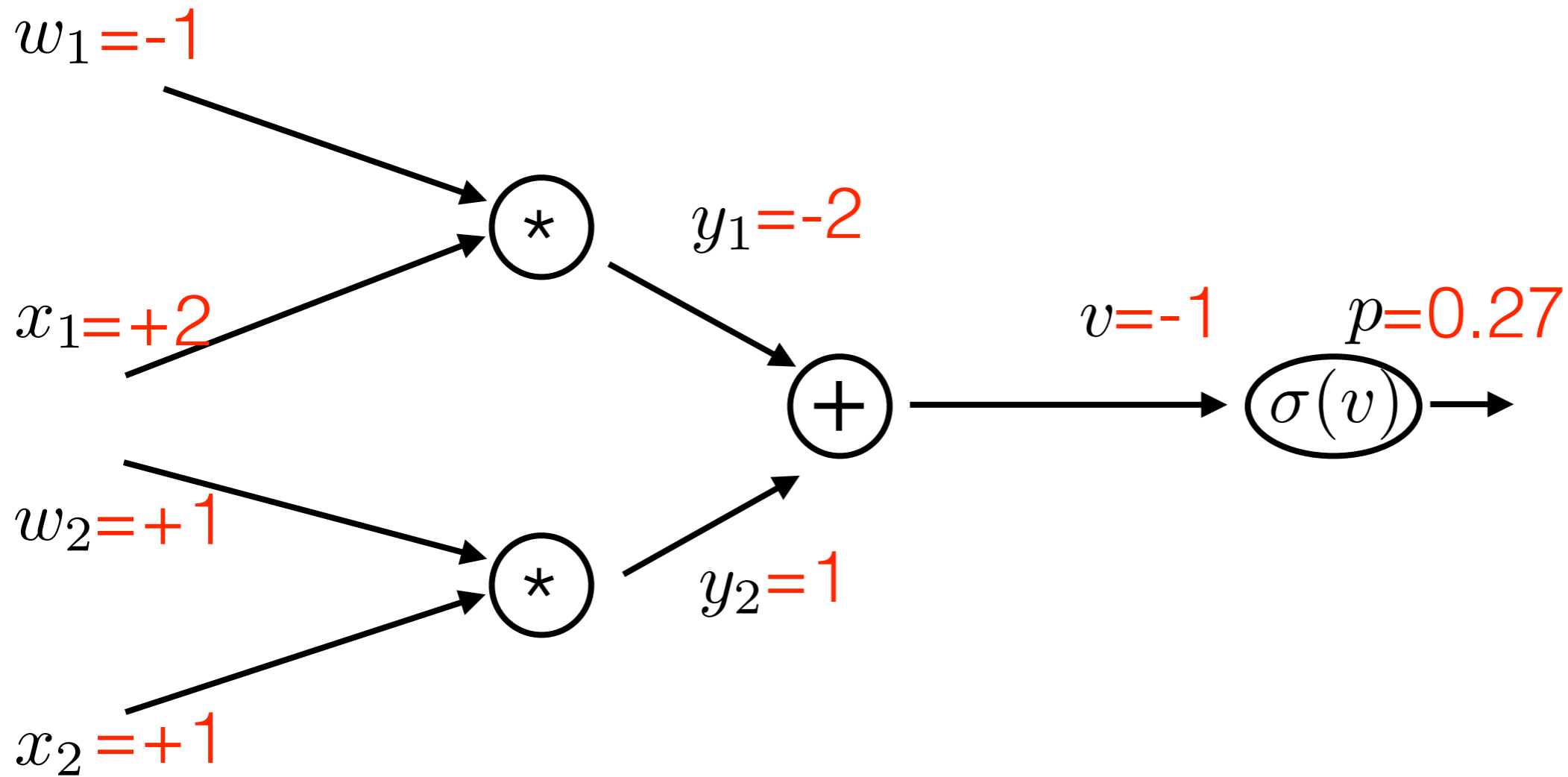
MAP estimate actually says:

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Computational graph of the learning- adding loss layer



MAP estimate actually says:

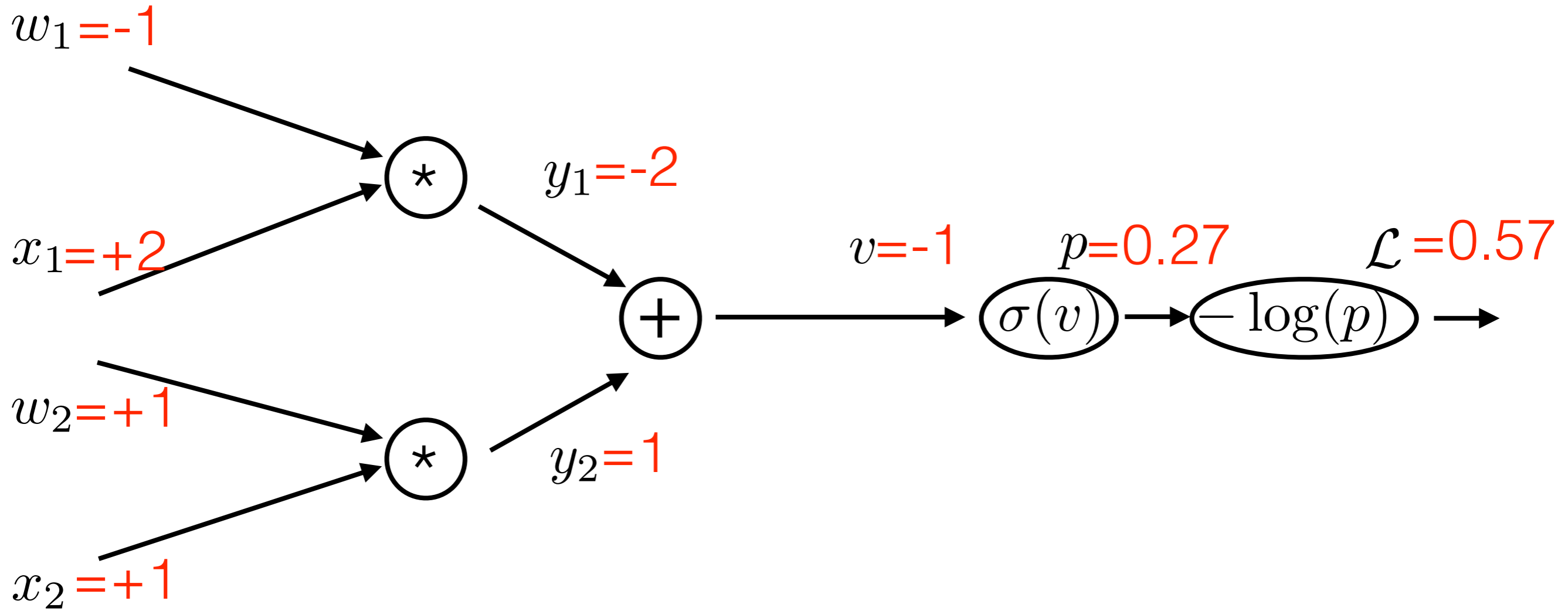
Positive sample \Rightarrow p should be huge \Rightarrow minimize $-\log(p)$

Negative sample \Rightarrow p should be small \Rightarrow minimize $-\log(1 - p)$

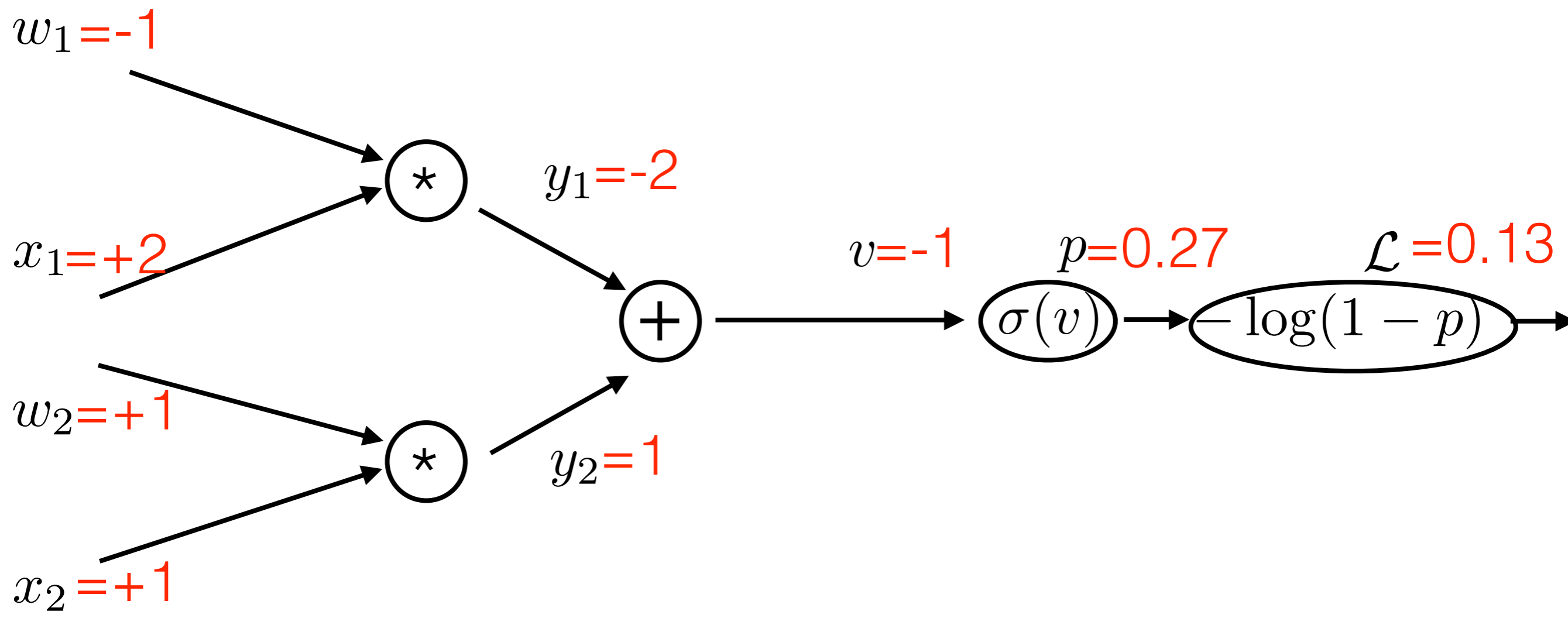
We will unify computational graph for both cases as follows.



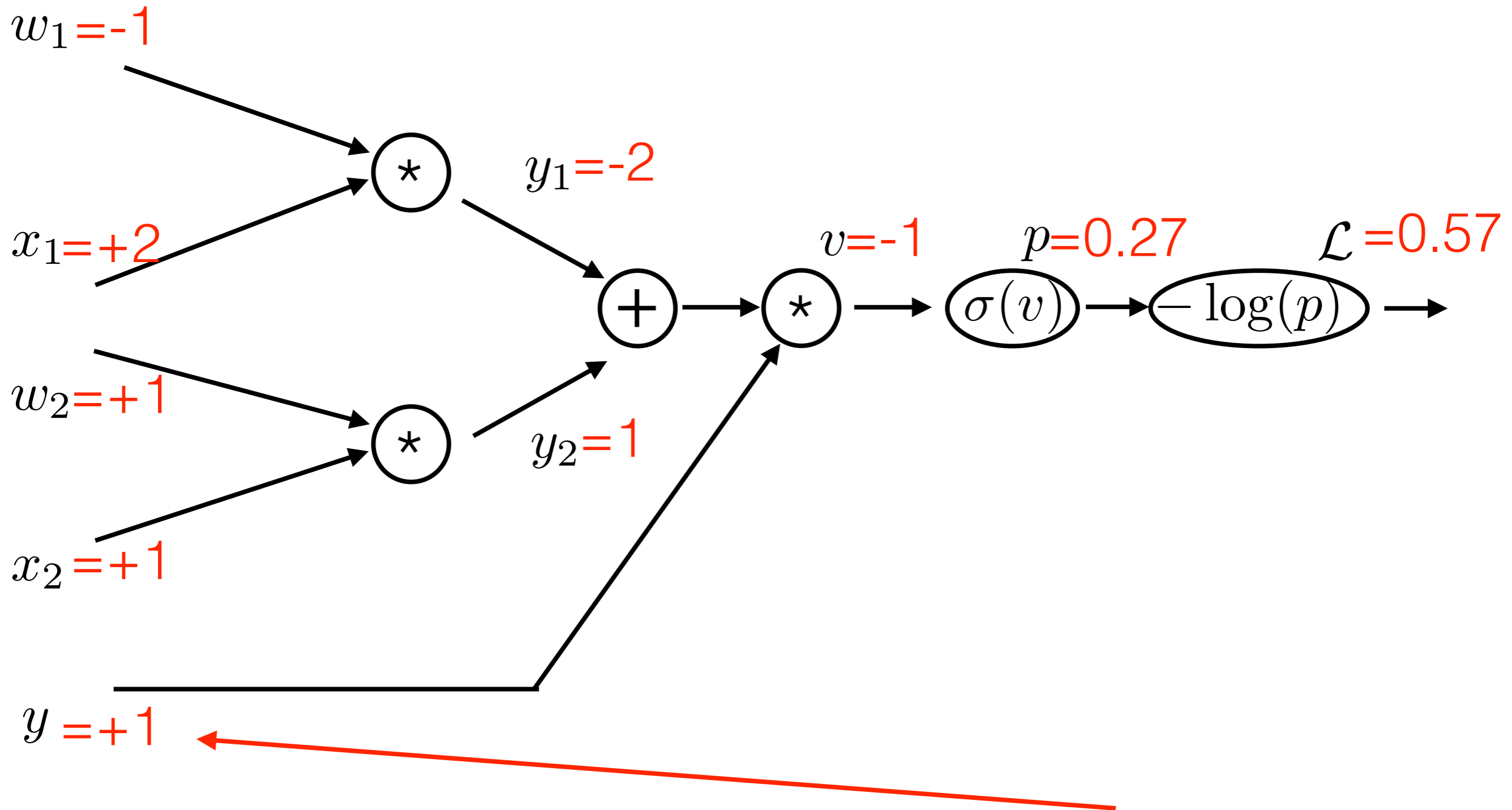
Computational graph of the learning from a **positive** sample



Computational graph of the learning from a **negative** sample



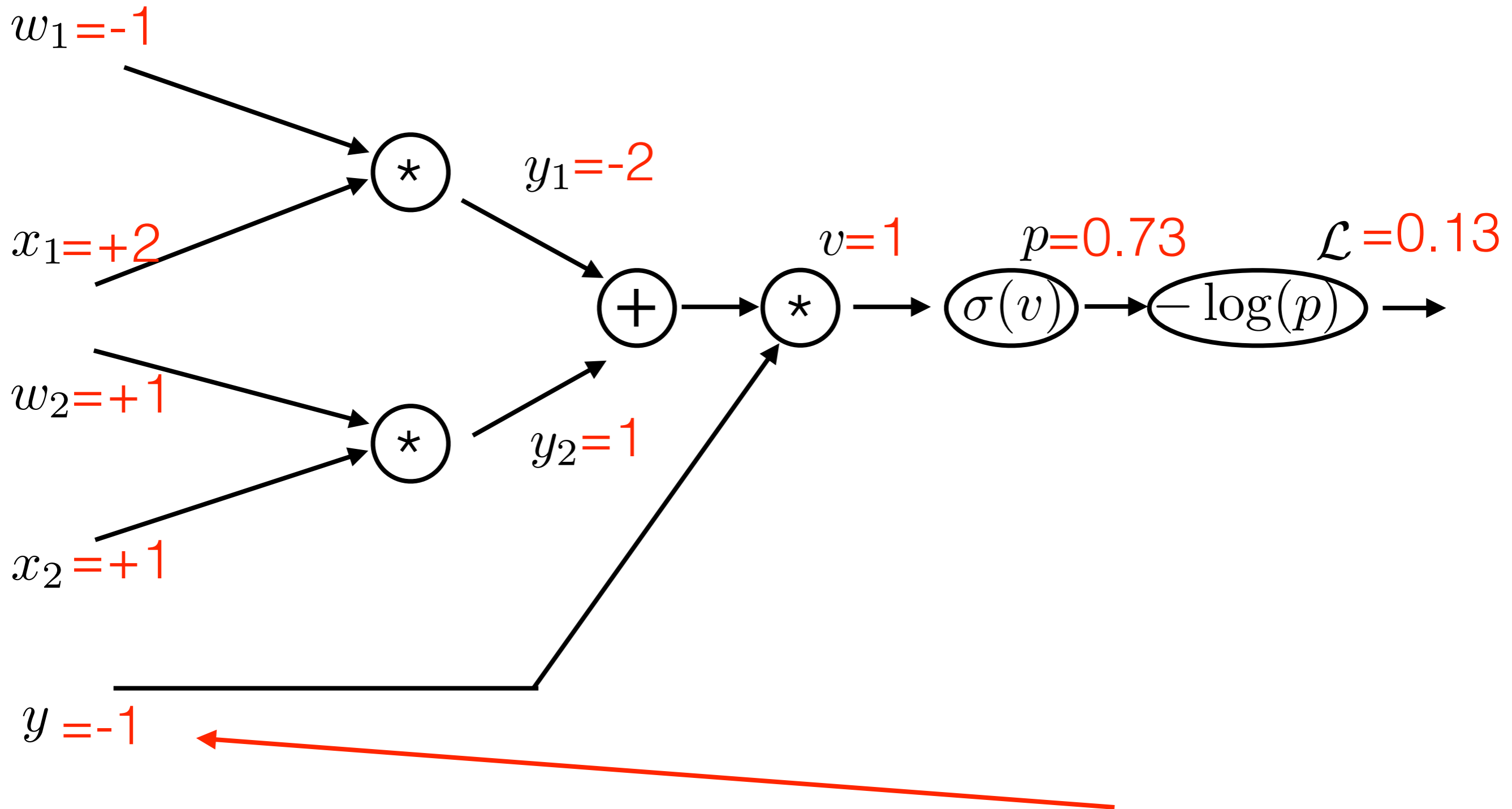
Computational graph of the learning



Computational graph for training on a **positive** sample



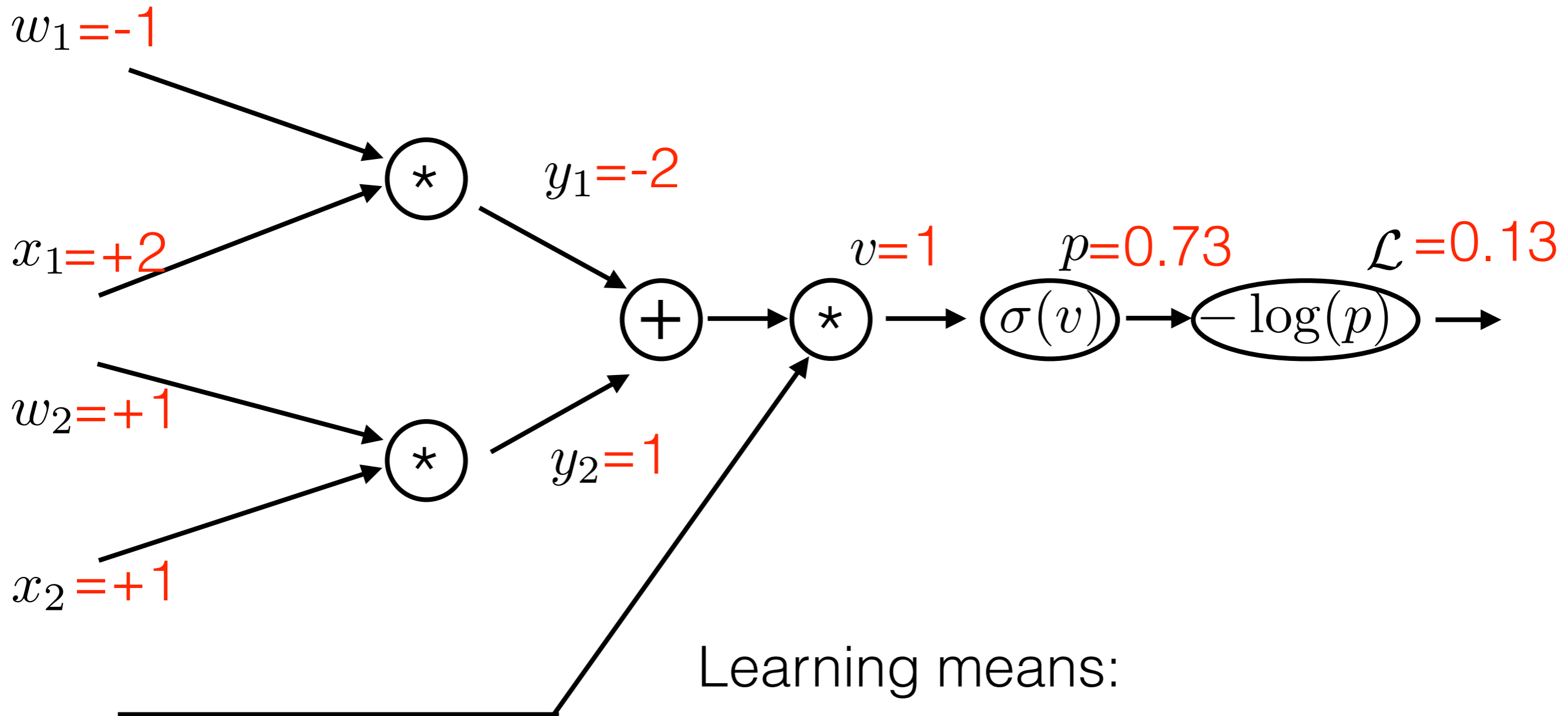
Computational graph of the learning



Computational graph for training on a **negative** sample



Computational graph of the learning

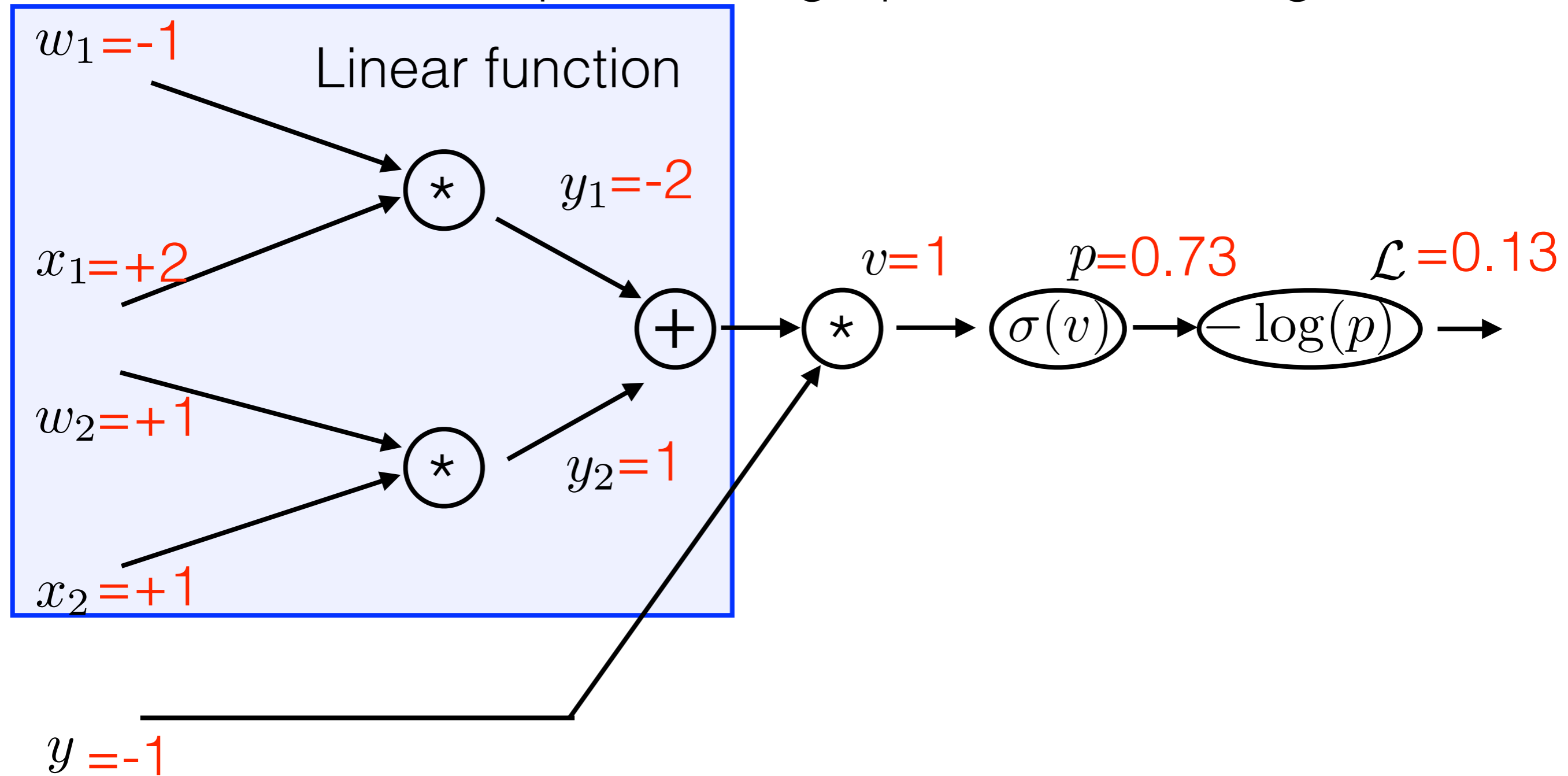


Iteratively change all weights \mathbf{w} to minimize \mathcal{L}

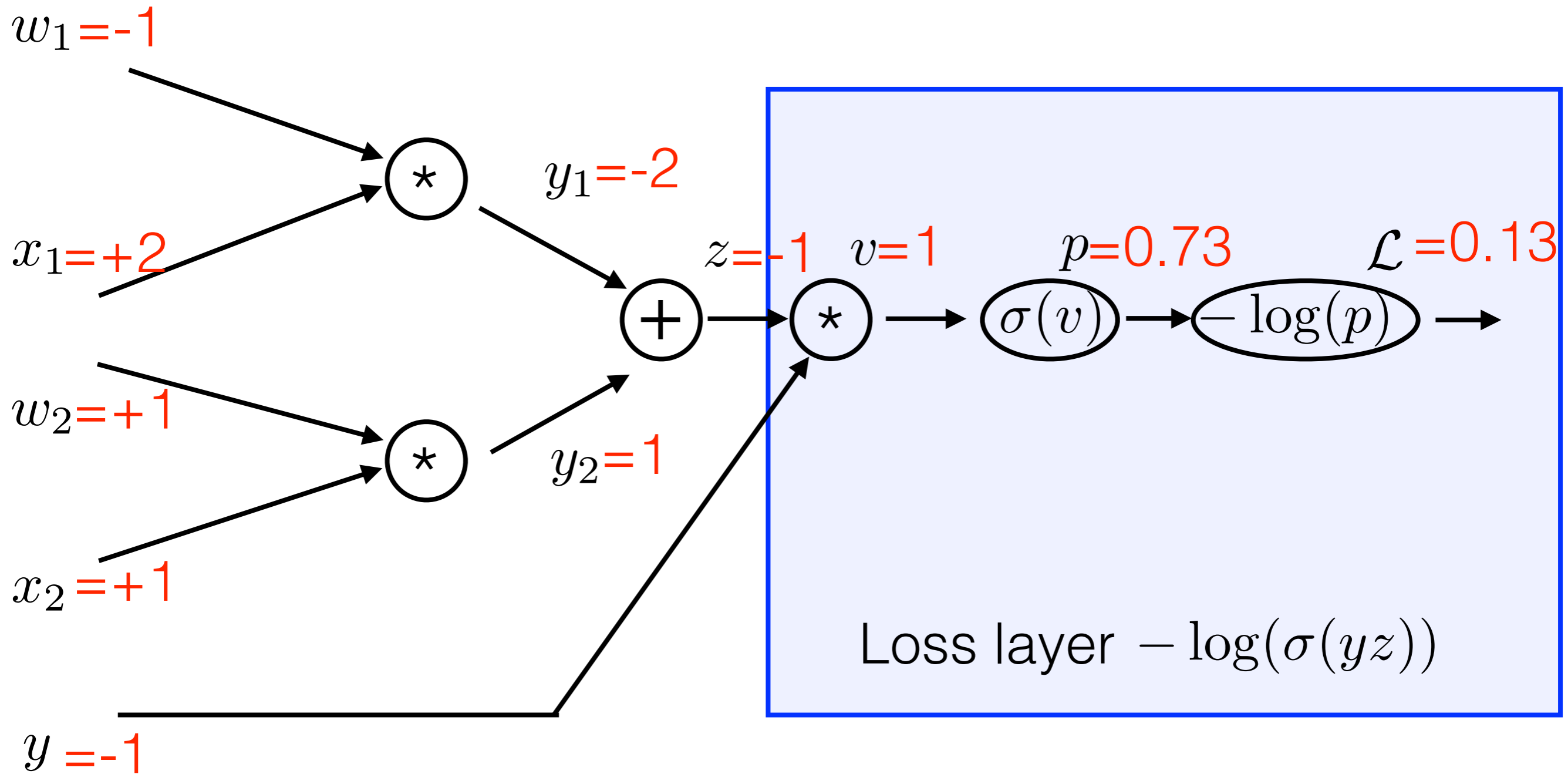
$$\mathbf{w} = \mathbf{w} - \alpha \left[\frac{\partial \mathcal{L}(\mathbf{w})}{\partial \mathbf{w}} \right]^\top \quad \text{where} \quad \frac{\partial \mathcal{L}}{\partial \mathbf{w}} = \left[\frac{\partial \mathcal{L}}{\partial w_1}, \frac{\partial \mathcal{L}}{\partial w_2}, \dots \right]$$



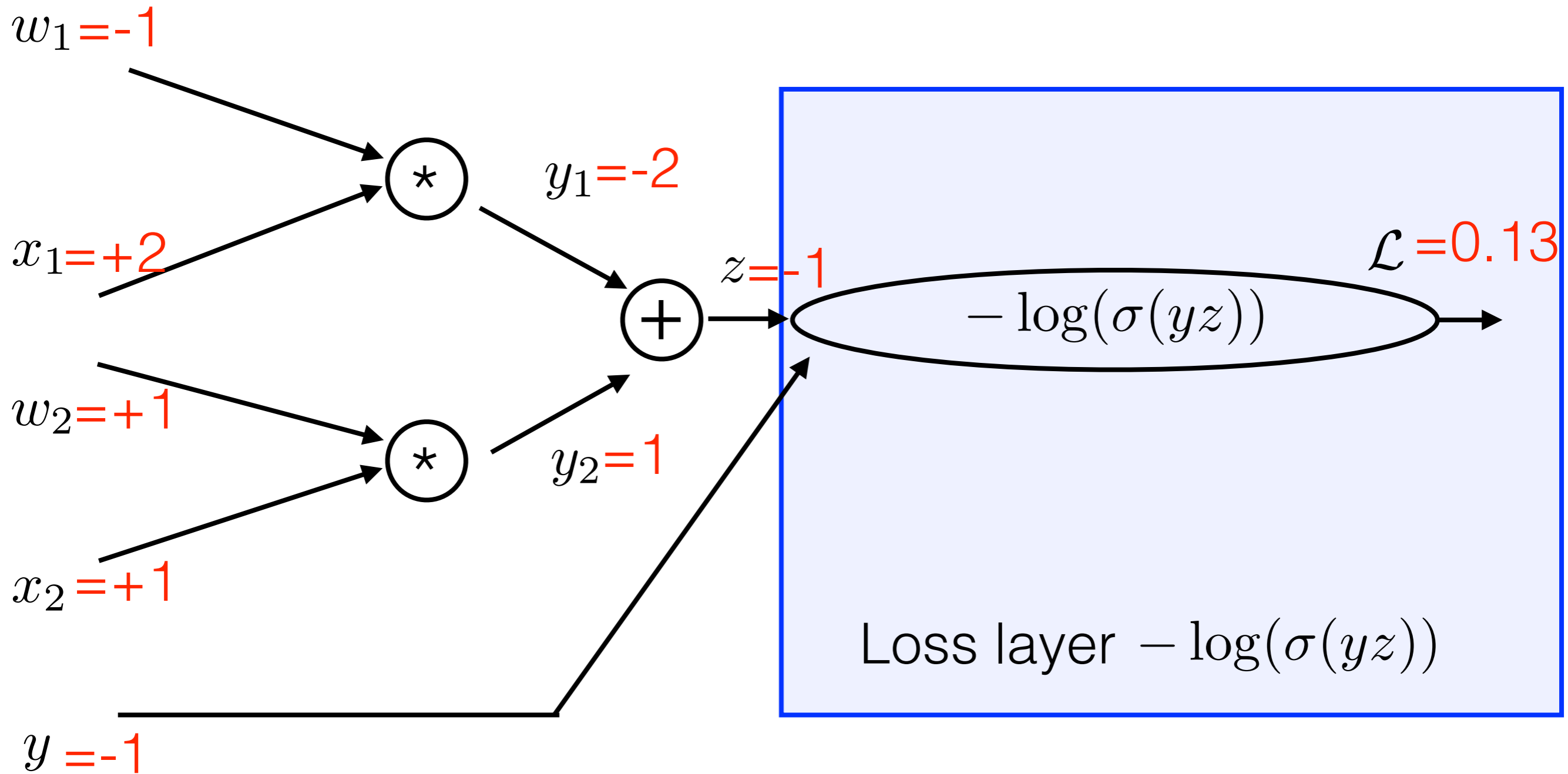
Computational graph of the learning



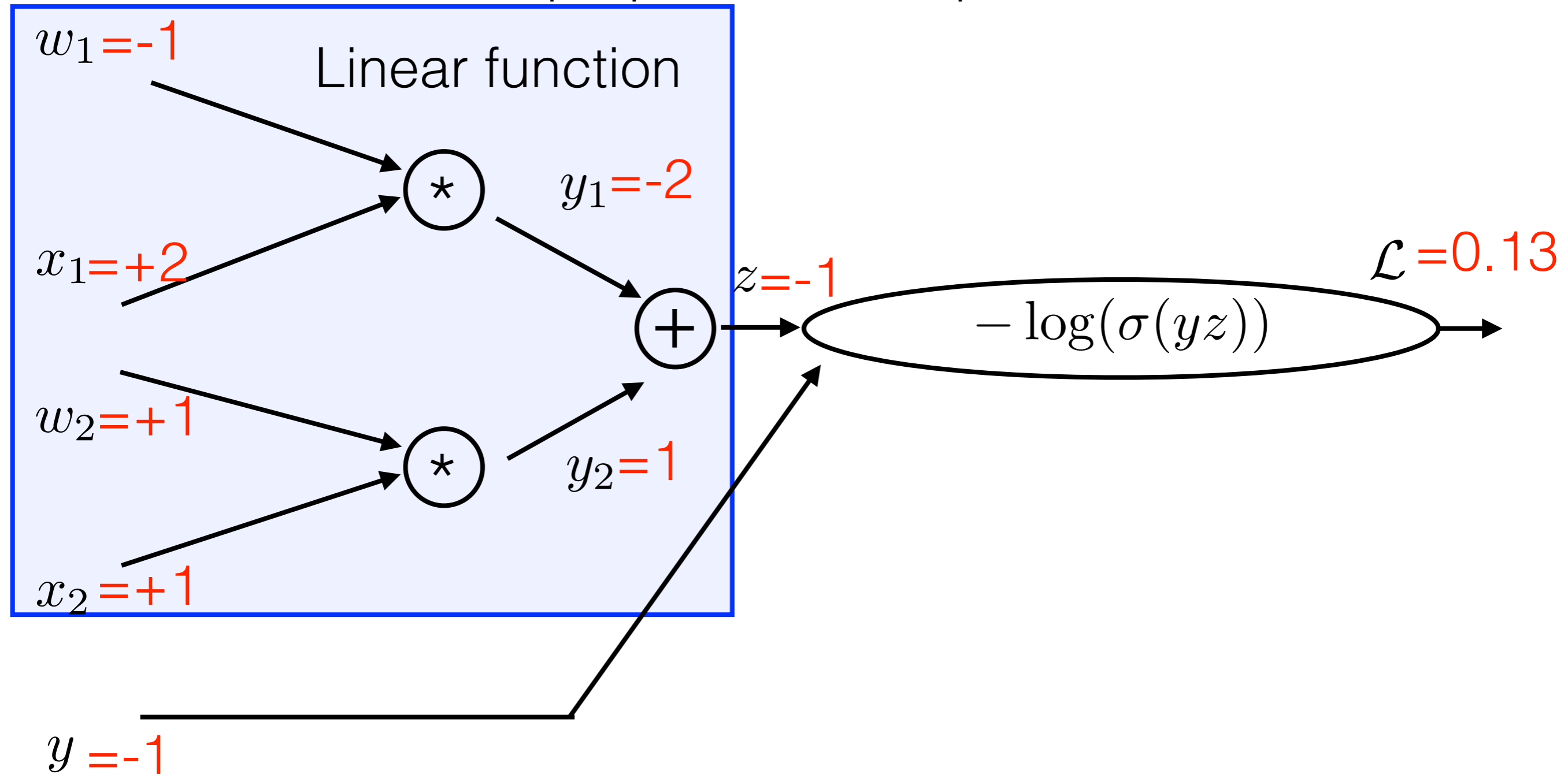
Computational graph of the learning



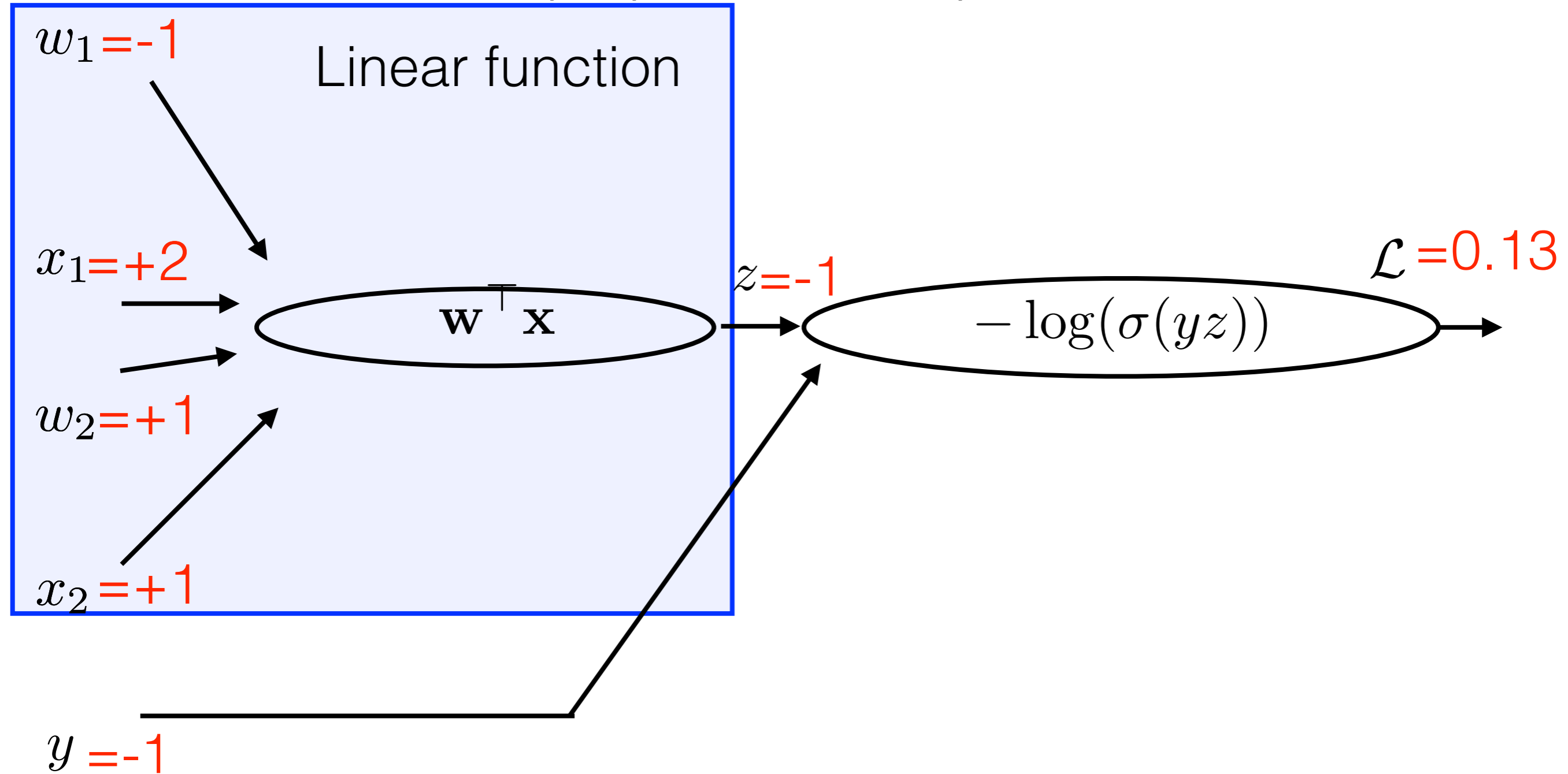
Backprop in vector representation



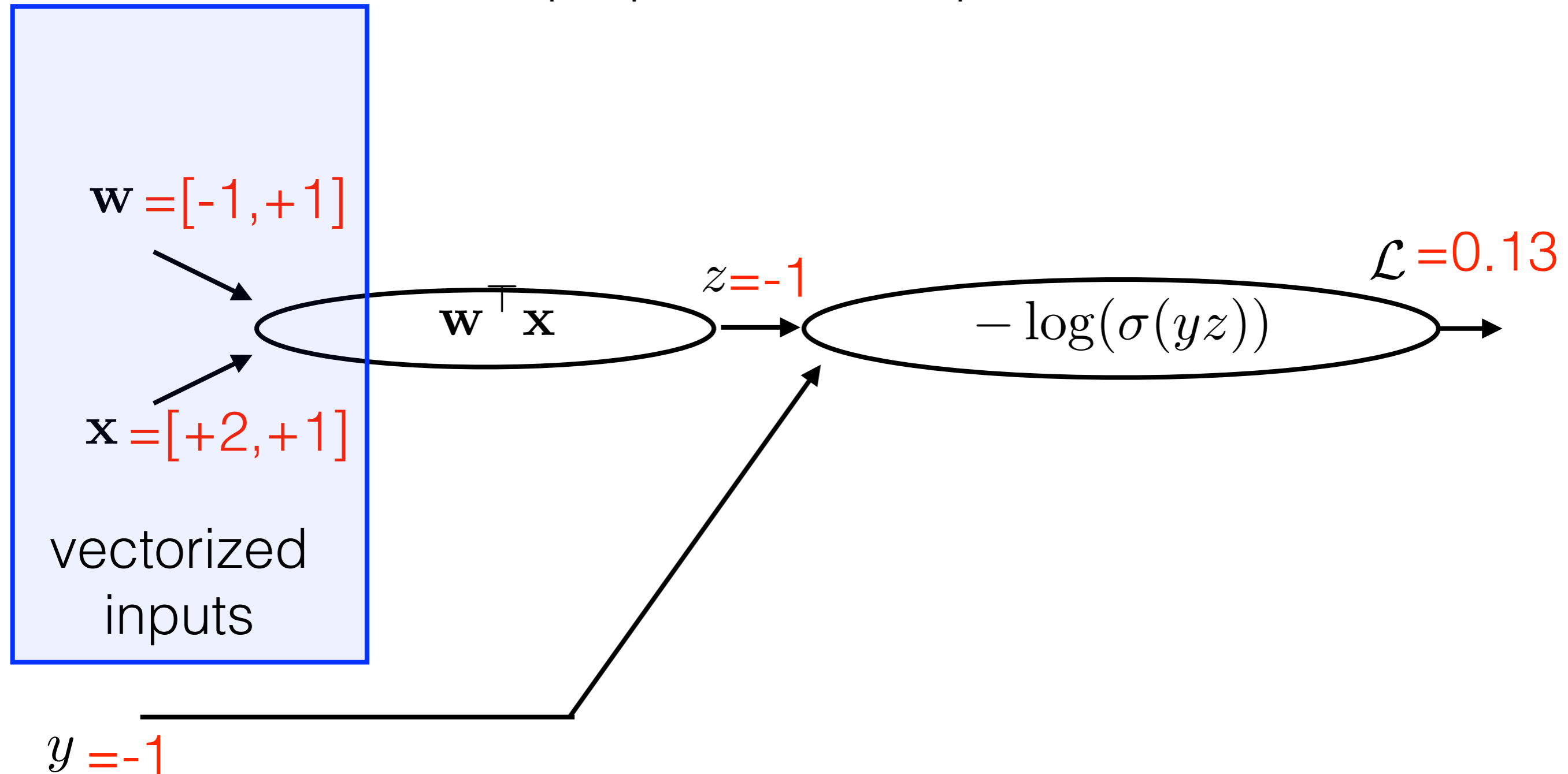
Backprop in vector representation



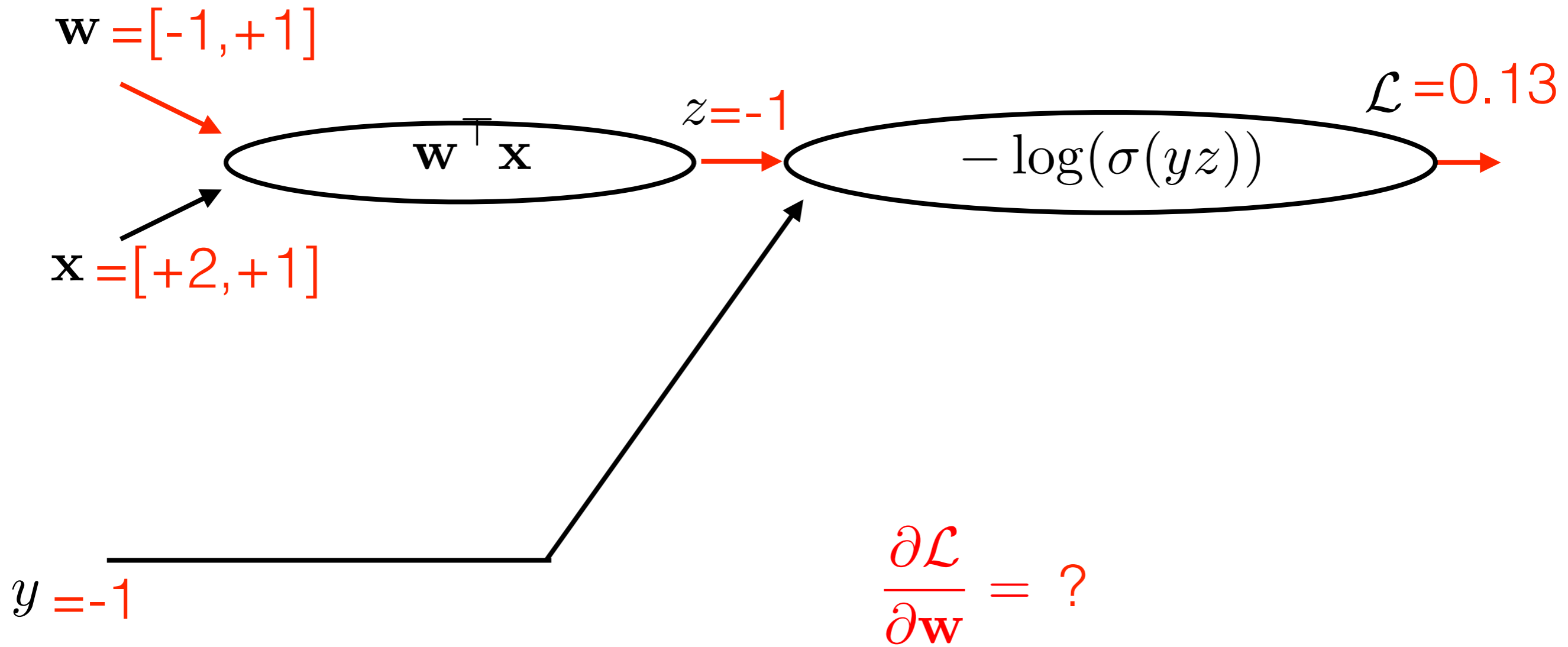
Backprop in vector representation



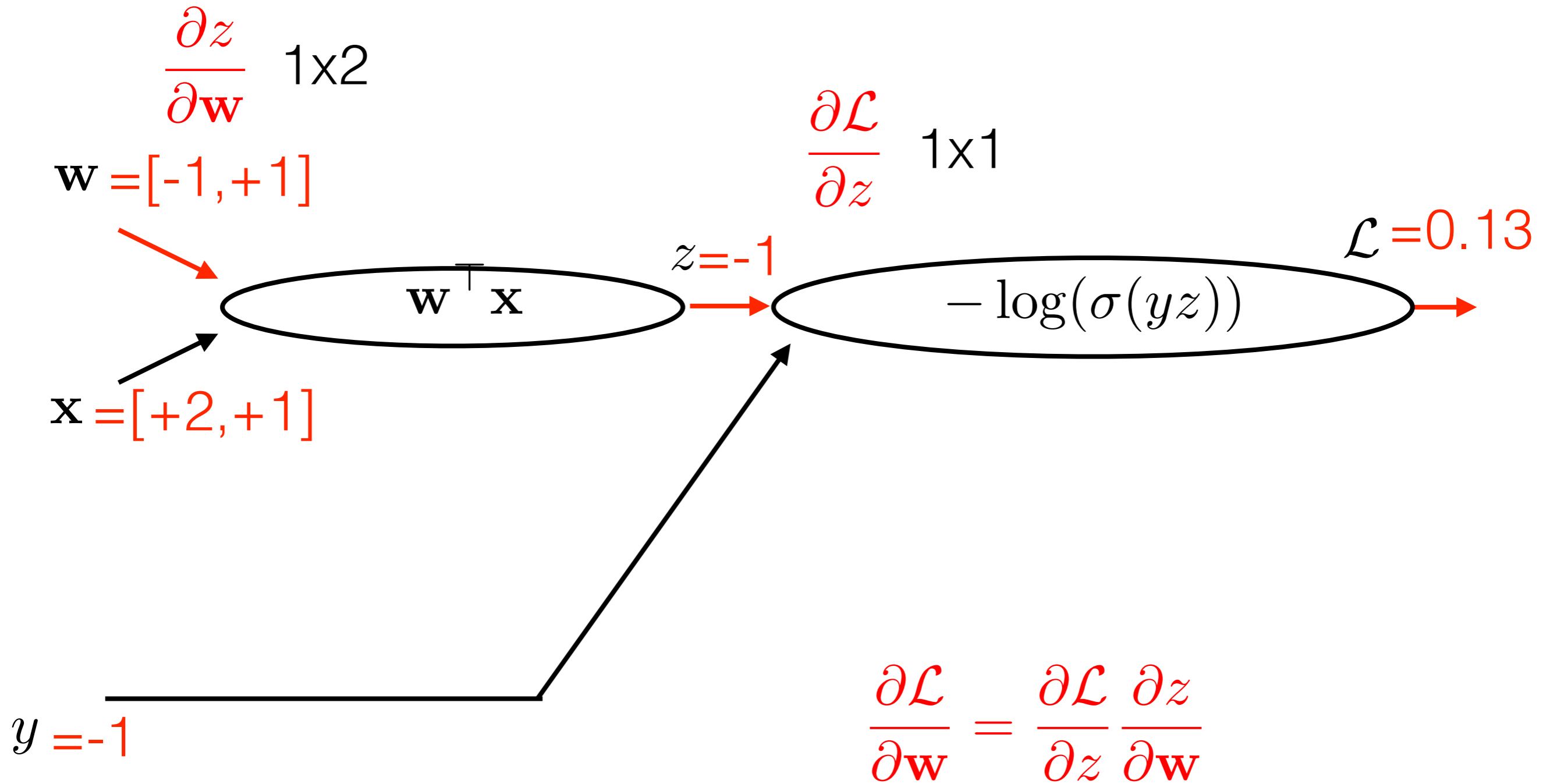
Backprop in vector representation



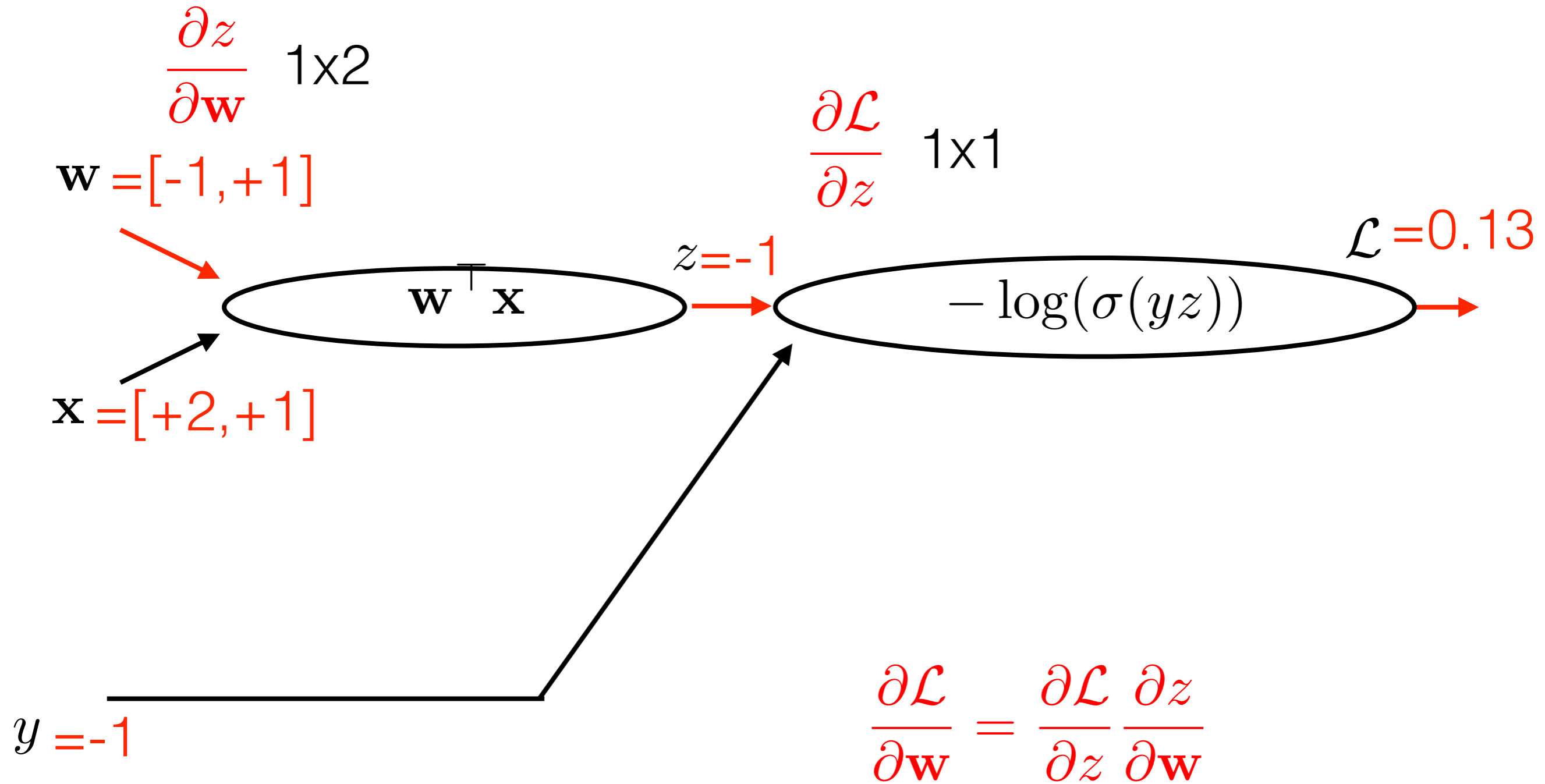
Backprop in vector representation



Backprop in vector representation



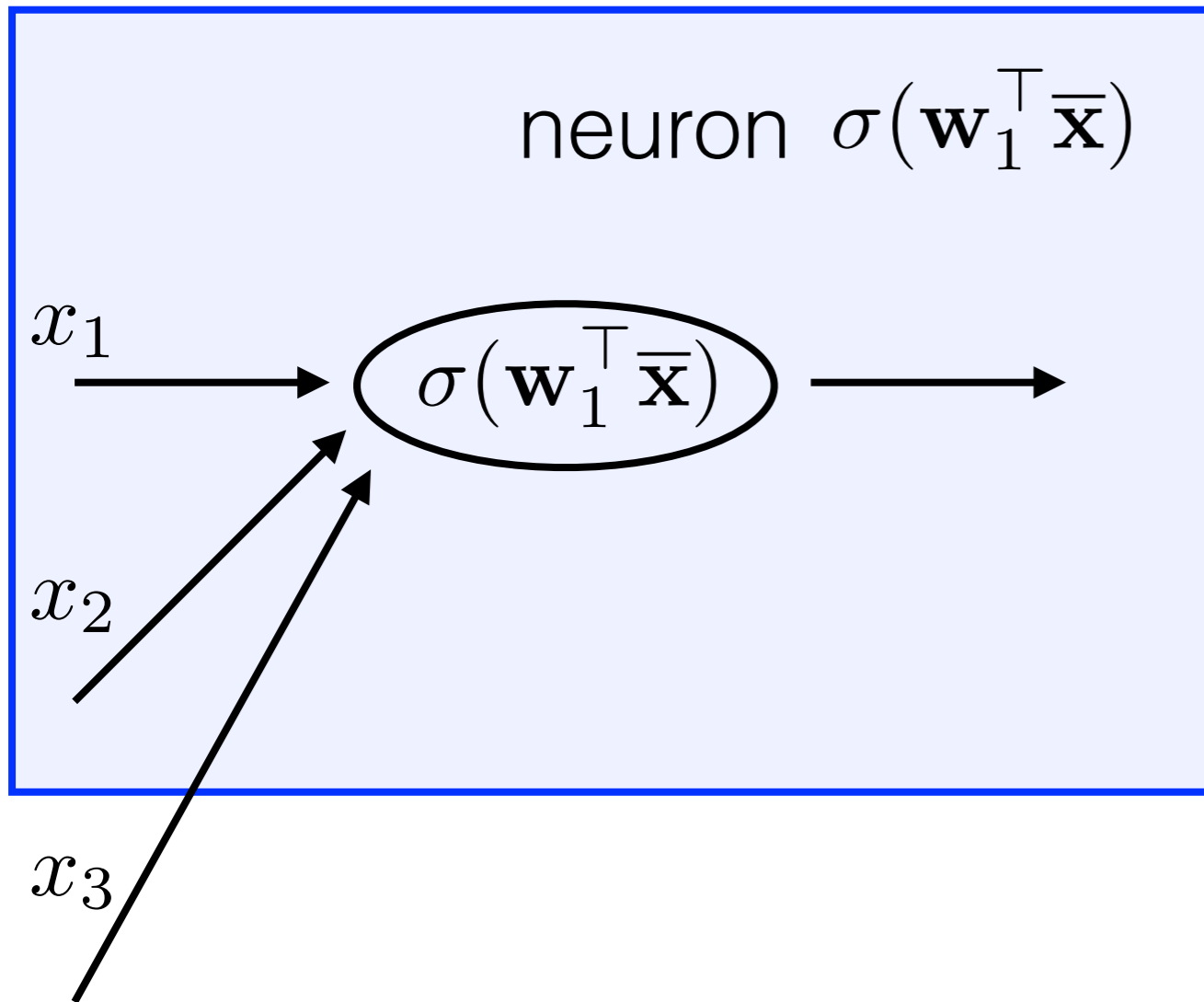
Backprop in vector representation



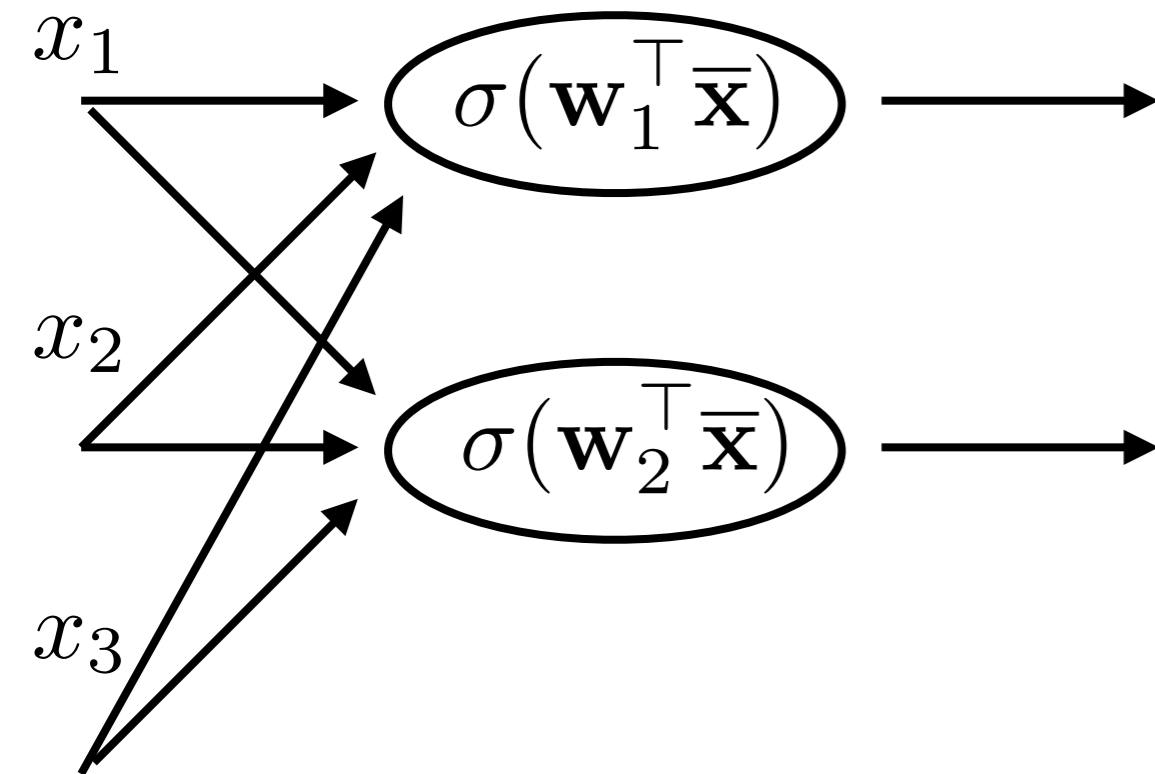
Learning from multiple training samples means summing up the gradient over all samples



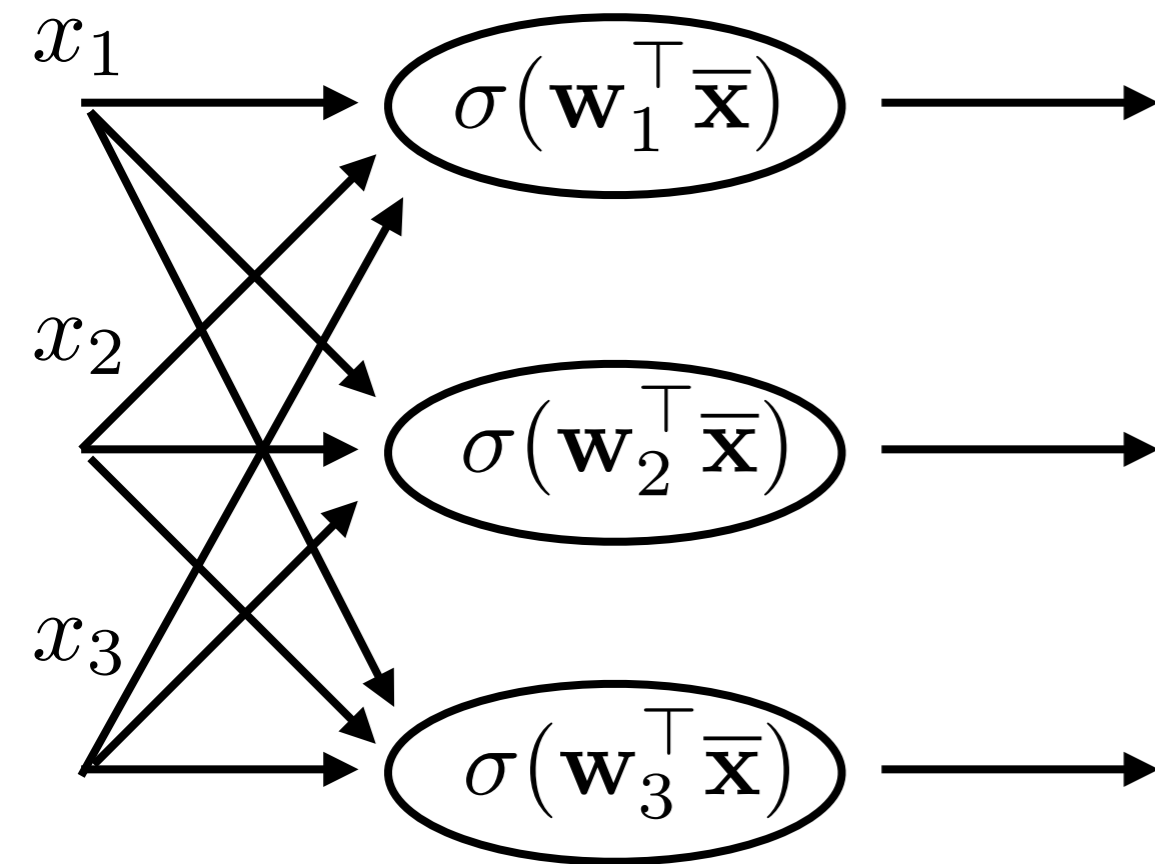
Multiple neurons and layers



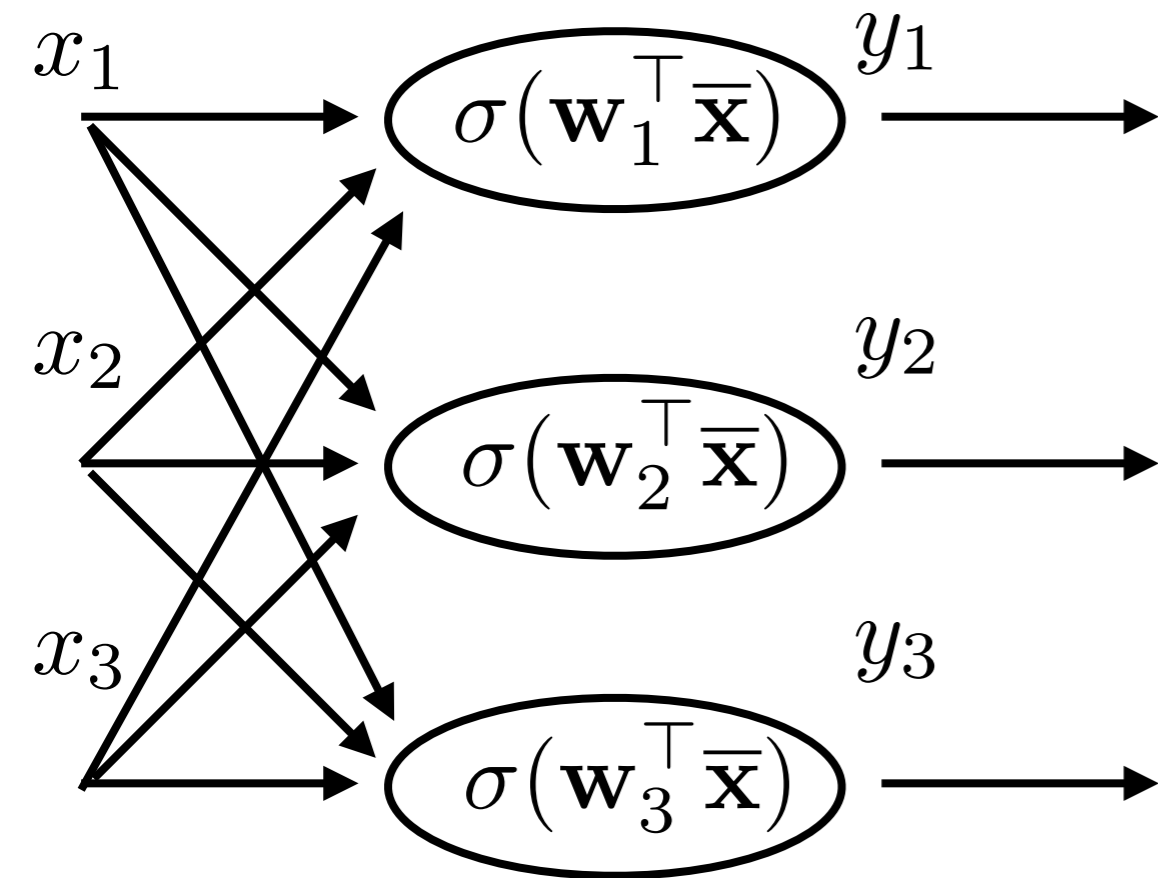
Multiple neurons and layers



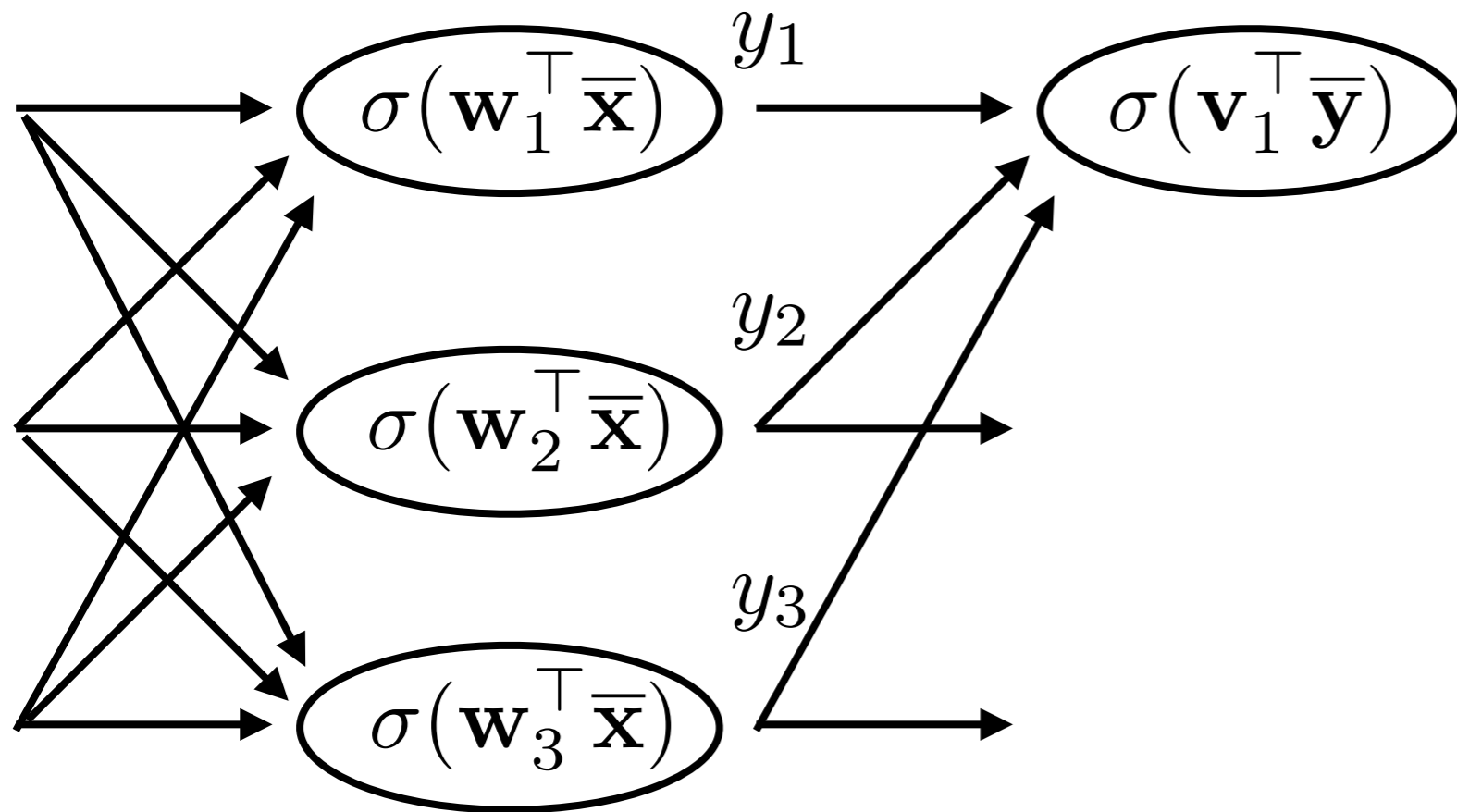
Multiple neurons and layers



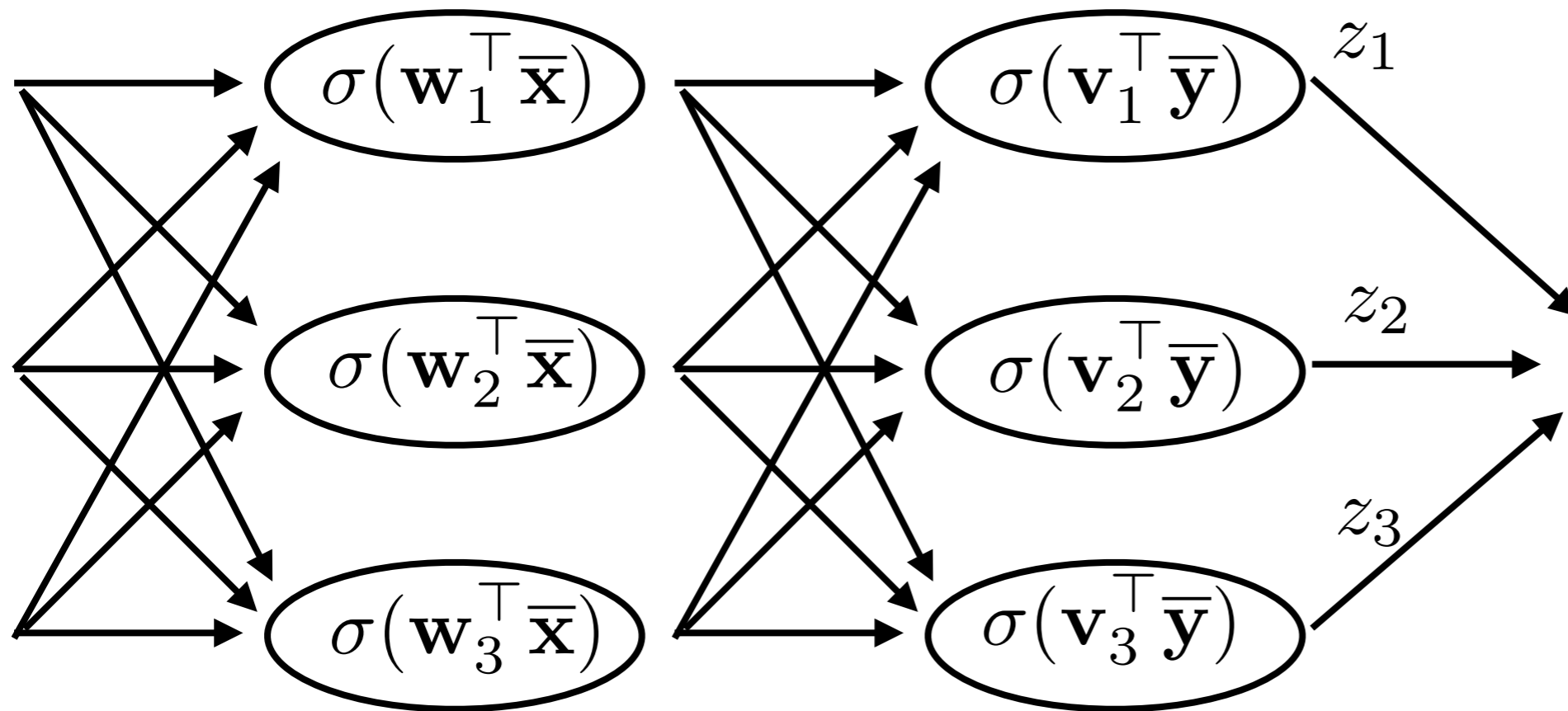
Multiple neurons and layers



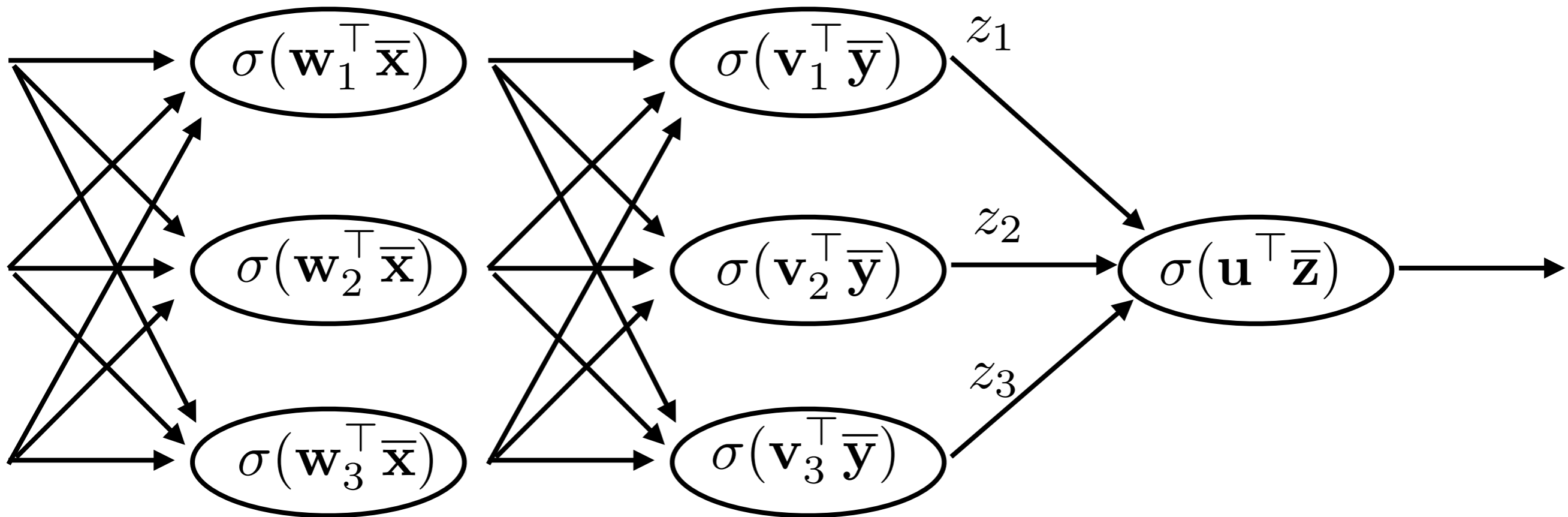
Multiple neurons and layers



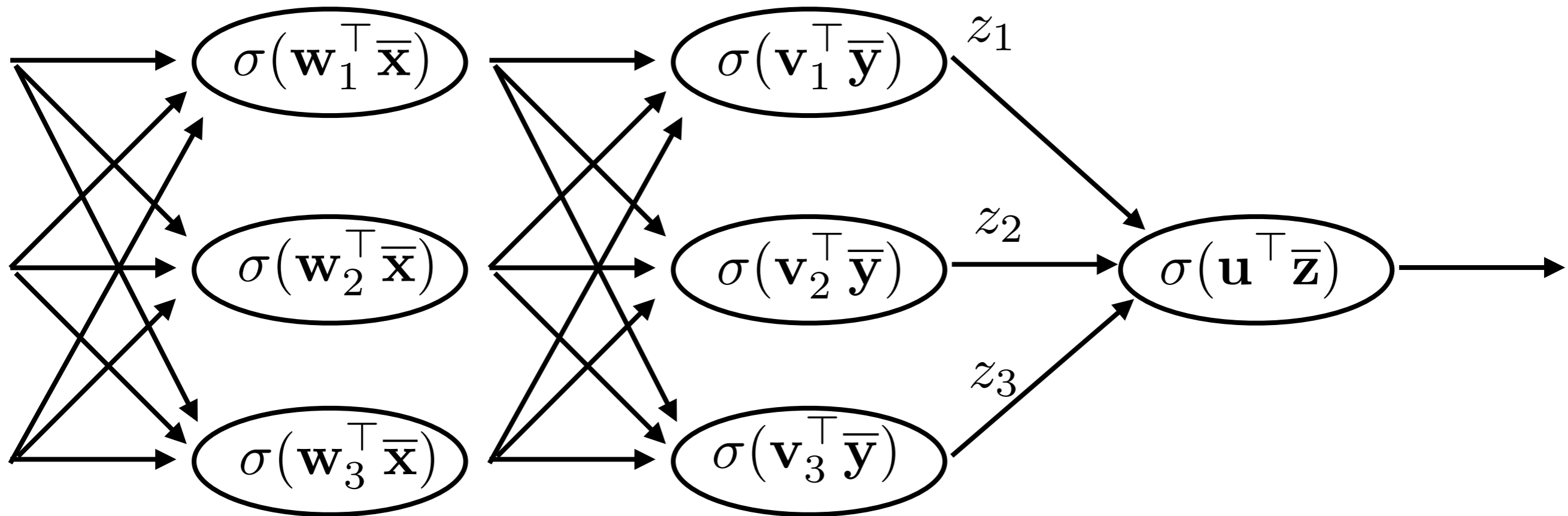
Multiple neurons and layers



Multiple neurons and layers



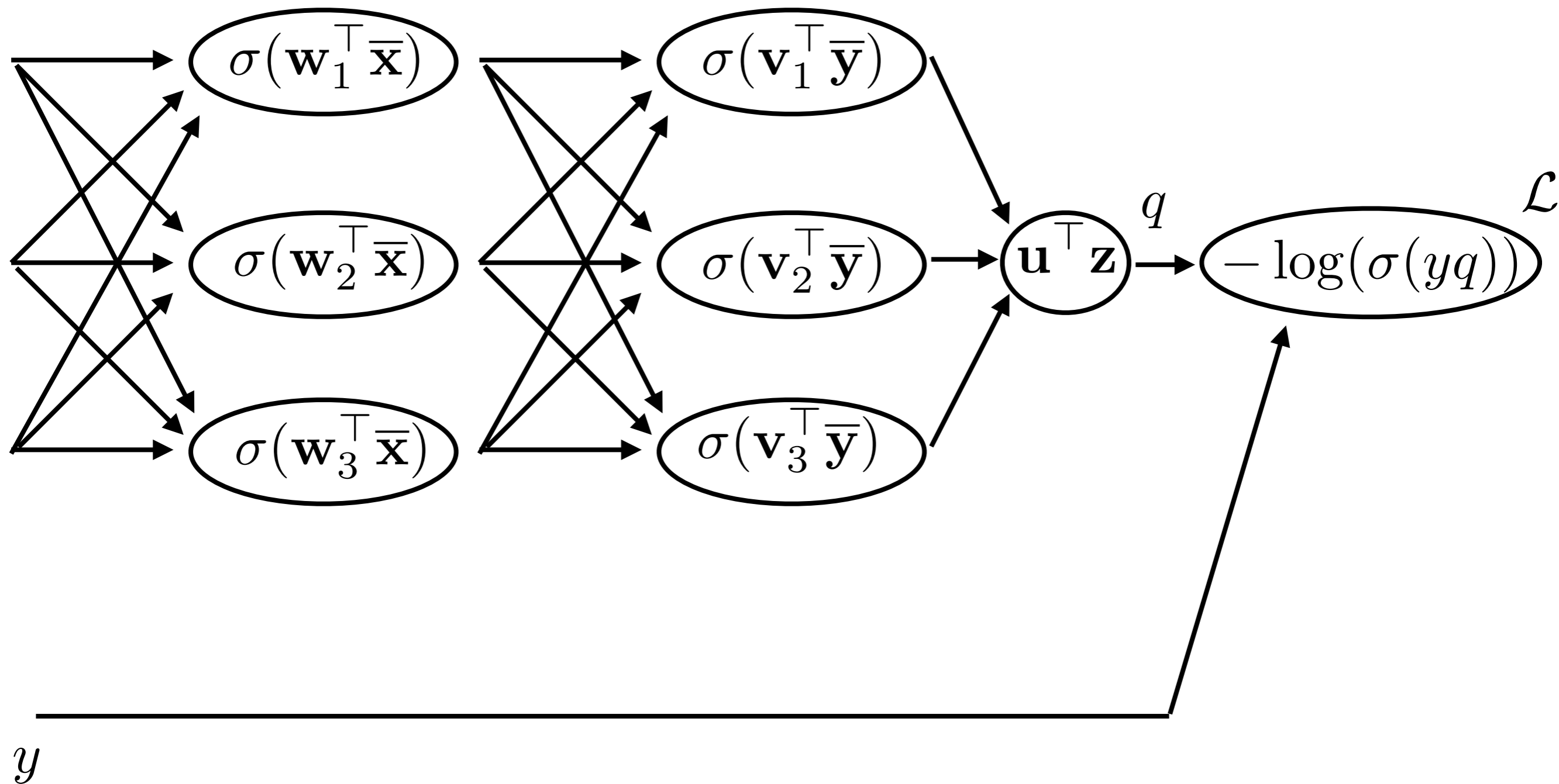
Multiple neurons and layers



- What is dimensionality of weights?



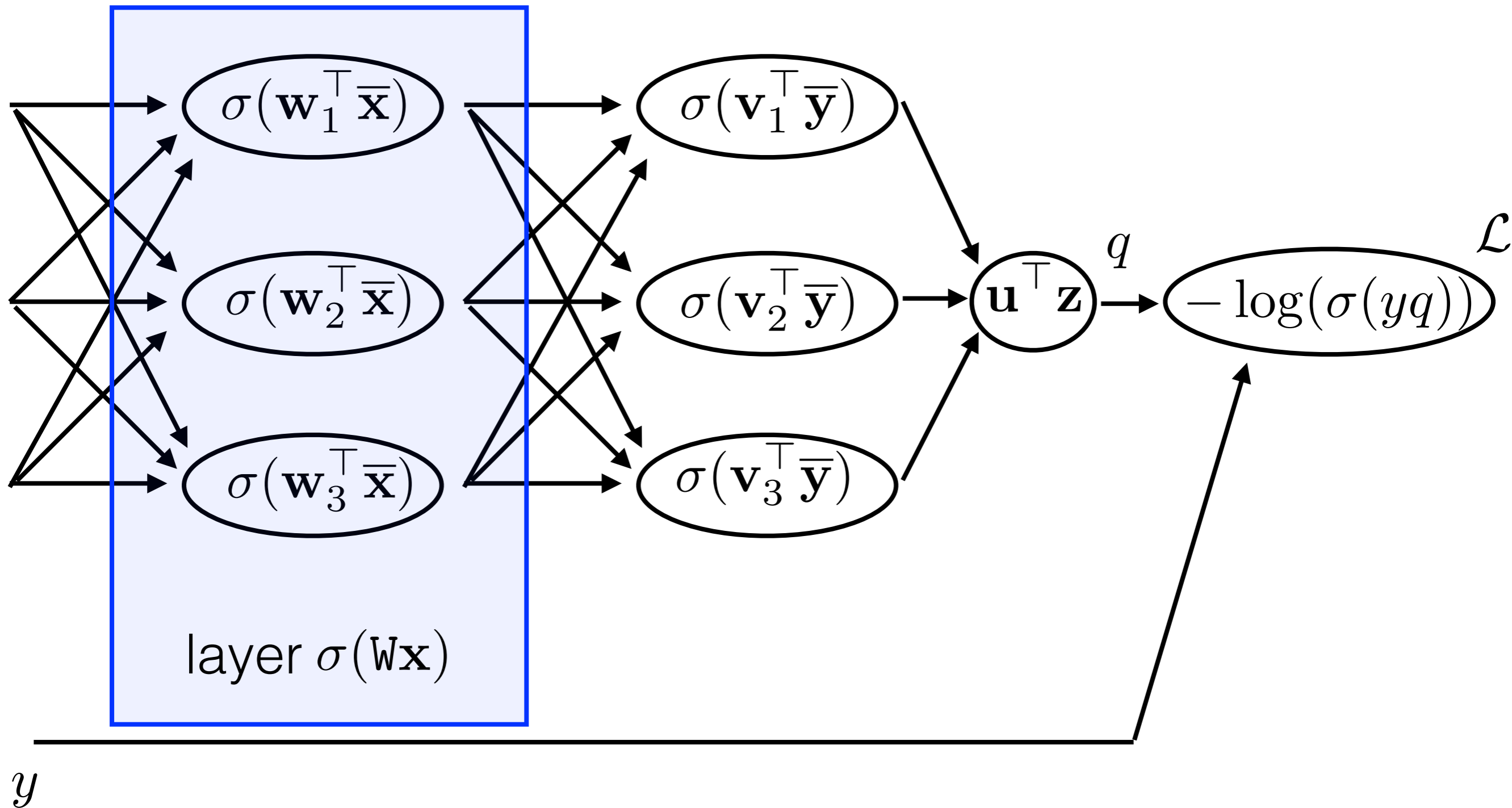
Learning of fully connected neural network



y



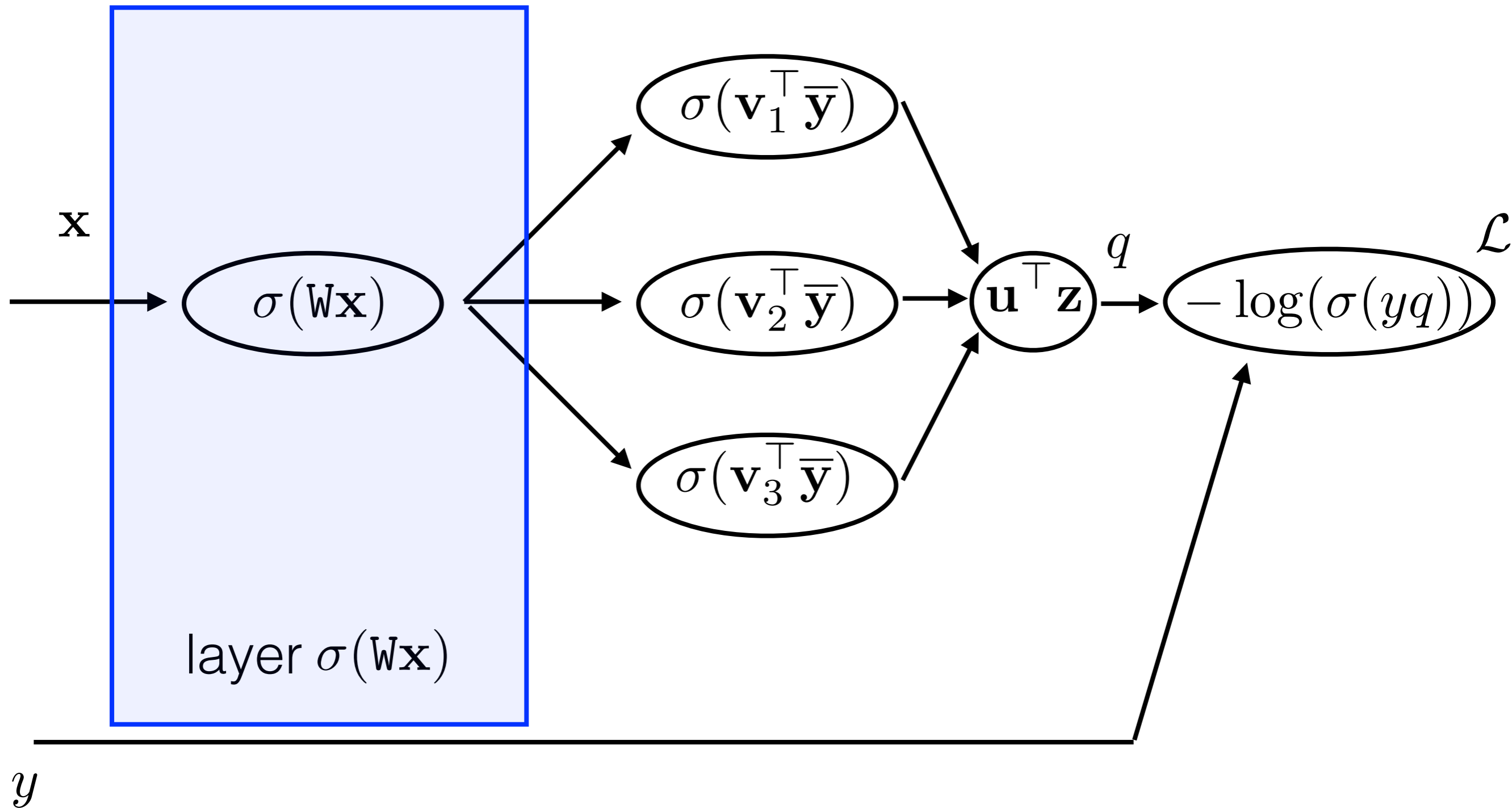
Learning of fully connected neural network



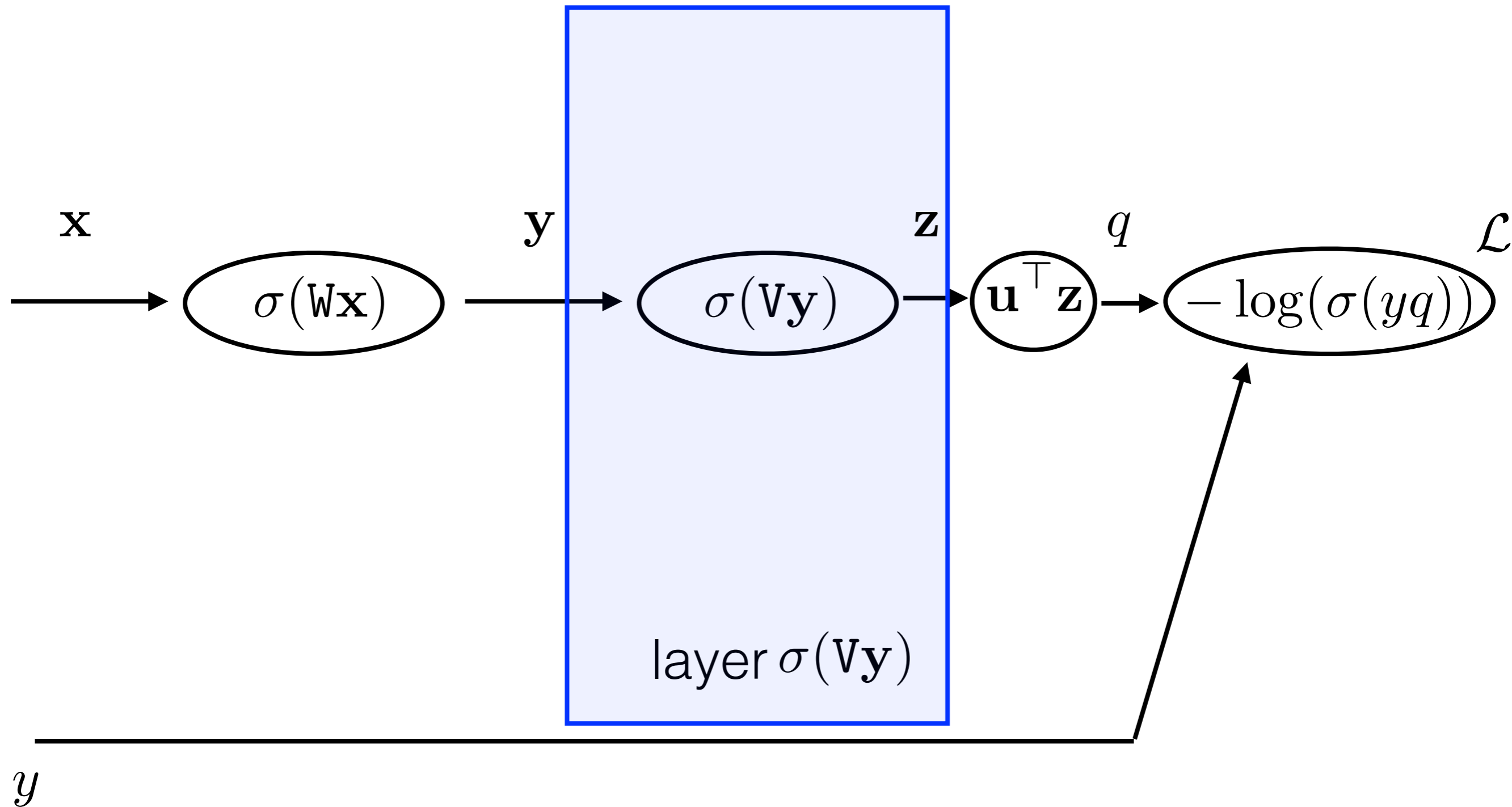
y



Learning of fully connected neural network



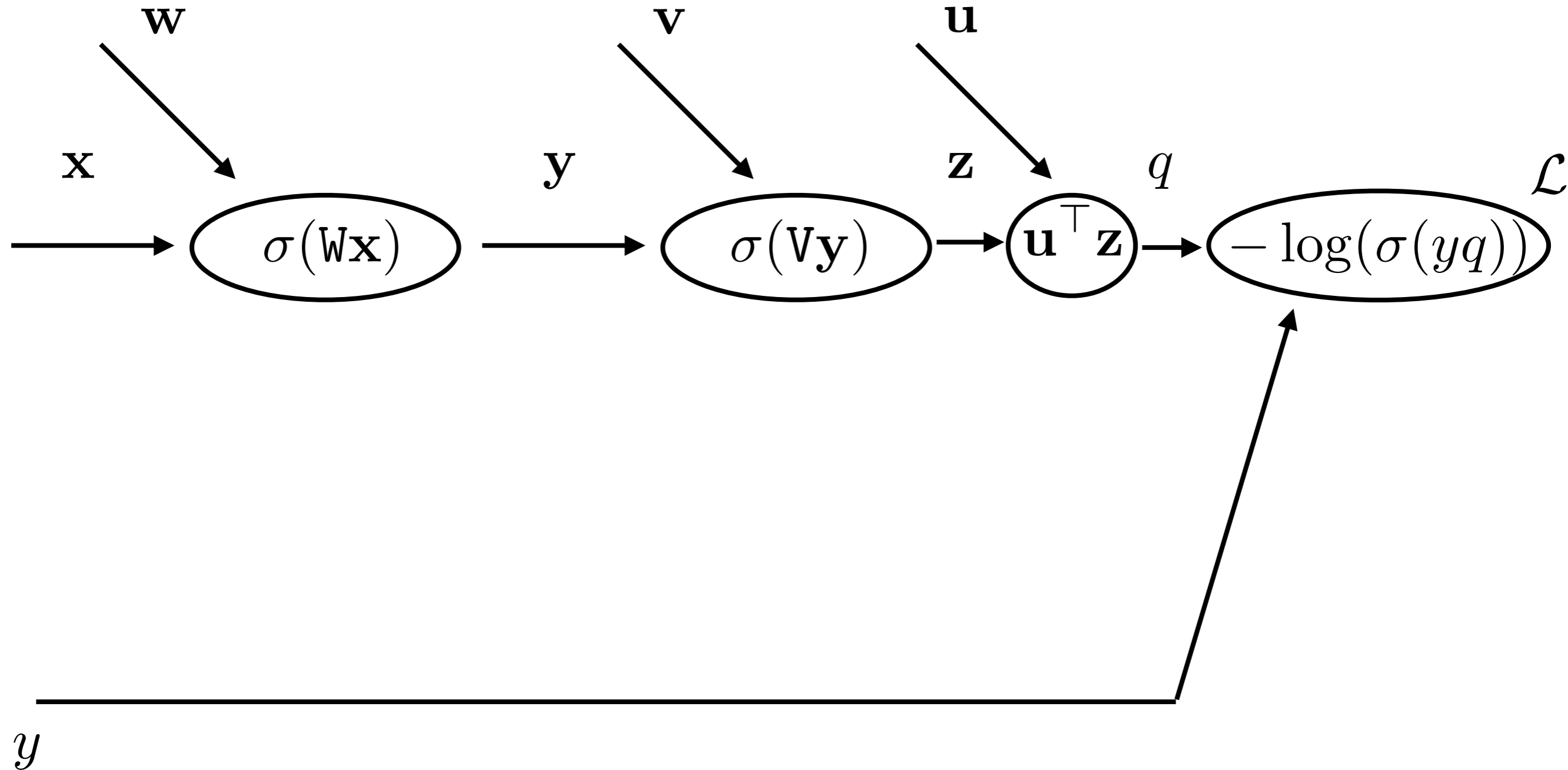
Learning of fully connected neural network



Learning of fully connected neural network

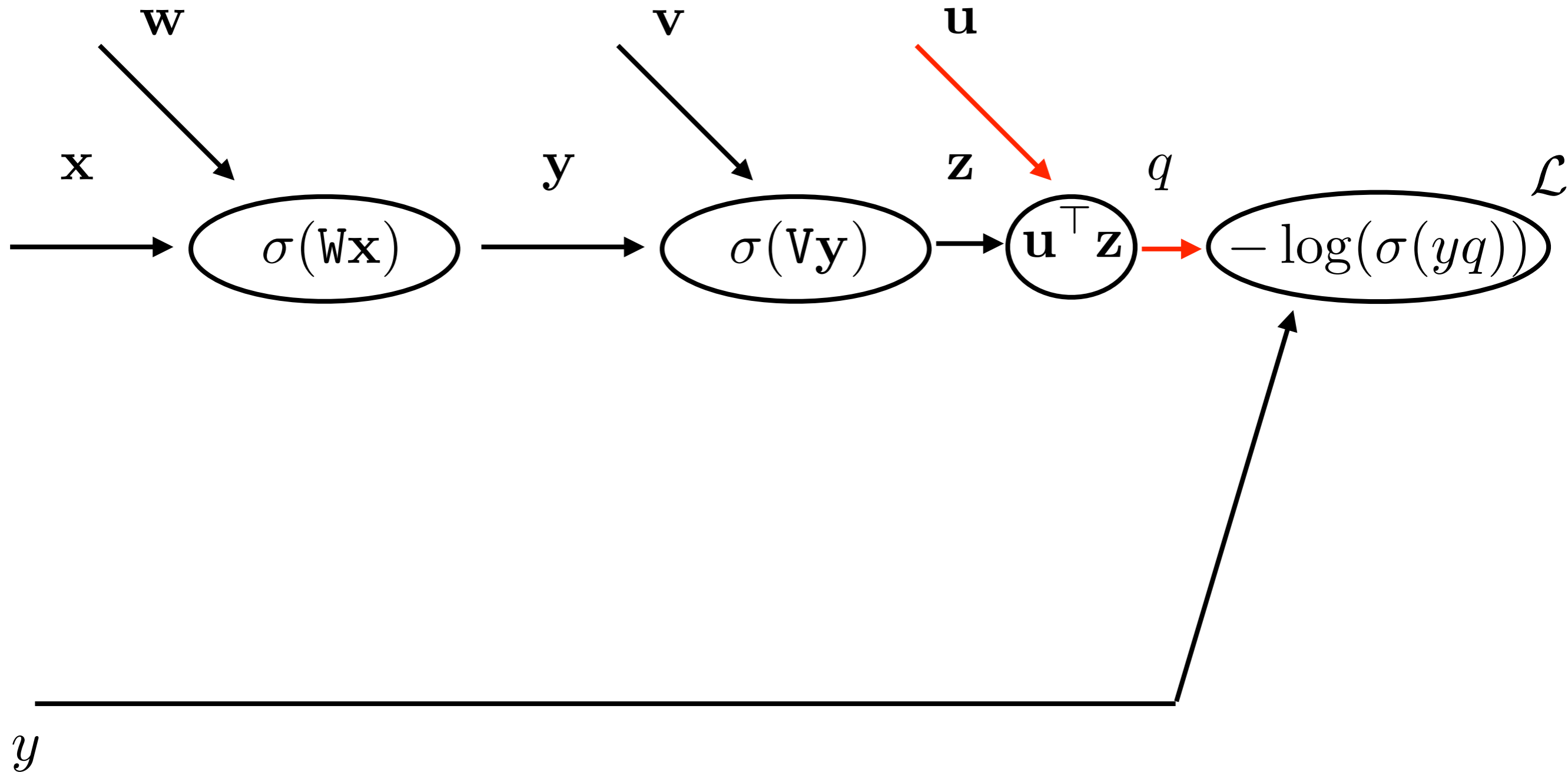
$$\mathbf{w} = \text{vec}(W)$$

$$\mathbf{v} = \text{vec}(V)$$



Learning of fully connected neural network

Derivative wrt \mathbf{u} : $\frac{\partial \mathcal{L}}{\partial \mathbf{u}} = ?$

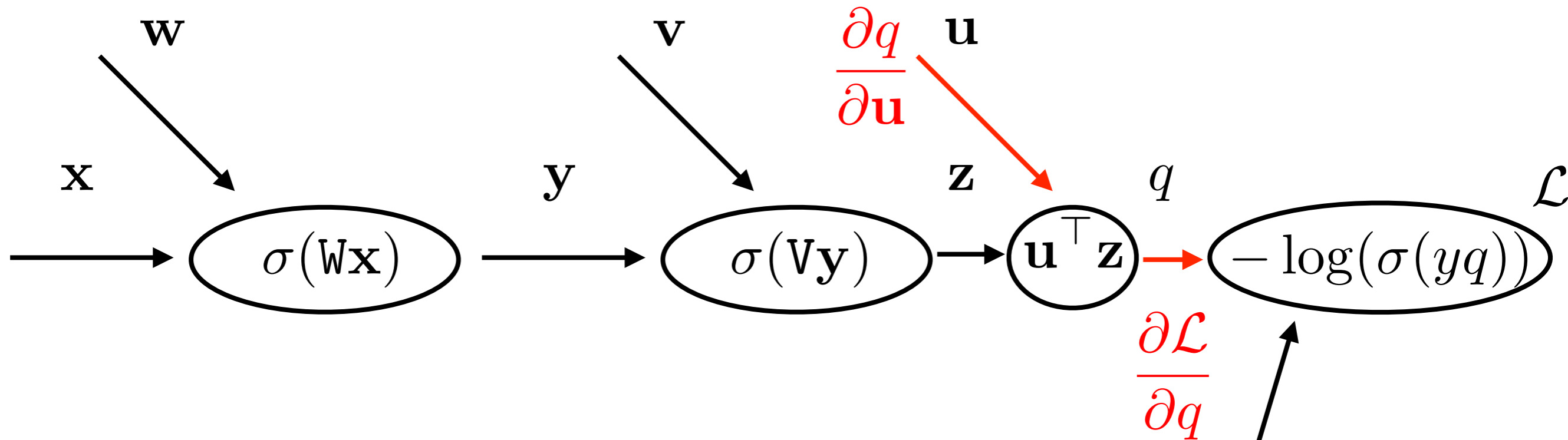


y



Learning of fully connected neural network

$$\text{Derivative wrt } \mathbf{u} : \frac{\partial \mathcal{L}}{\partial \mathbf{u}} = \frac{\partial \mathcal{L}}{\partial q} \frac{\partial q}{\partial \mathbf{u}}$$

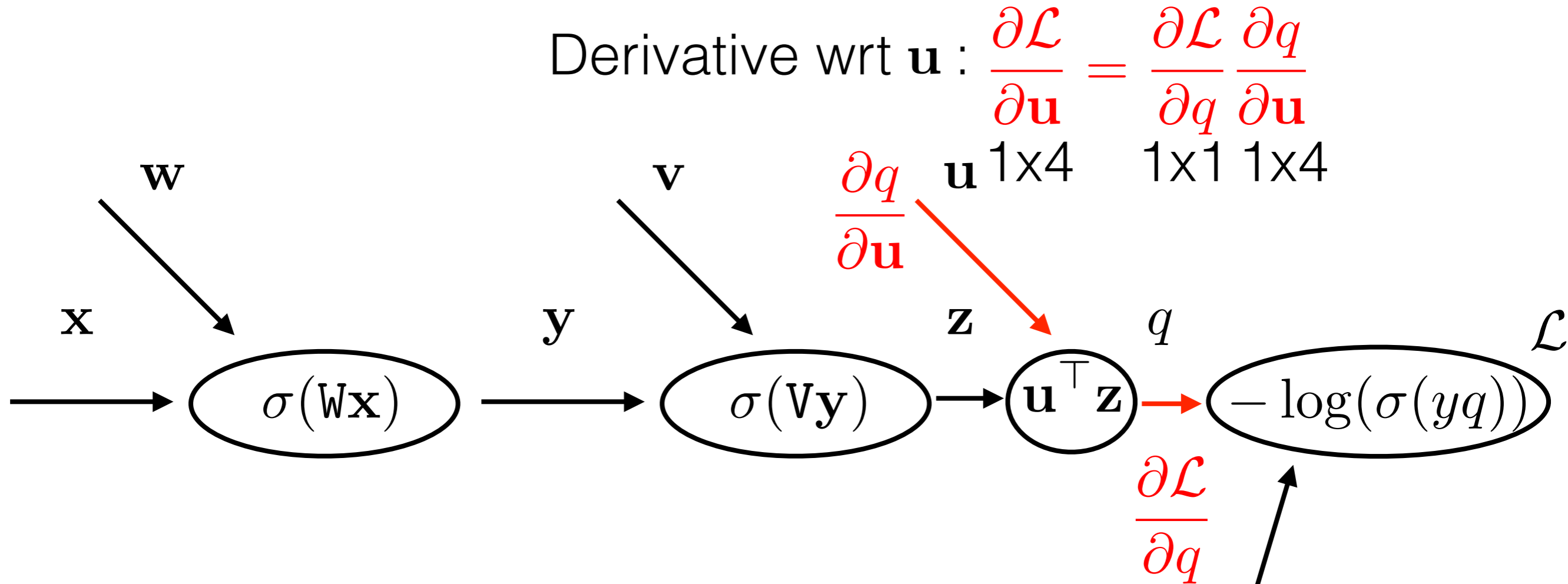


Dimensionality of the gradient???

y



Learning of fully connected neural network



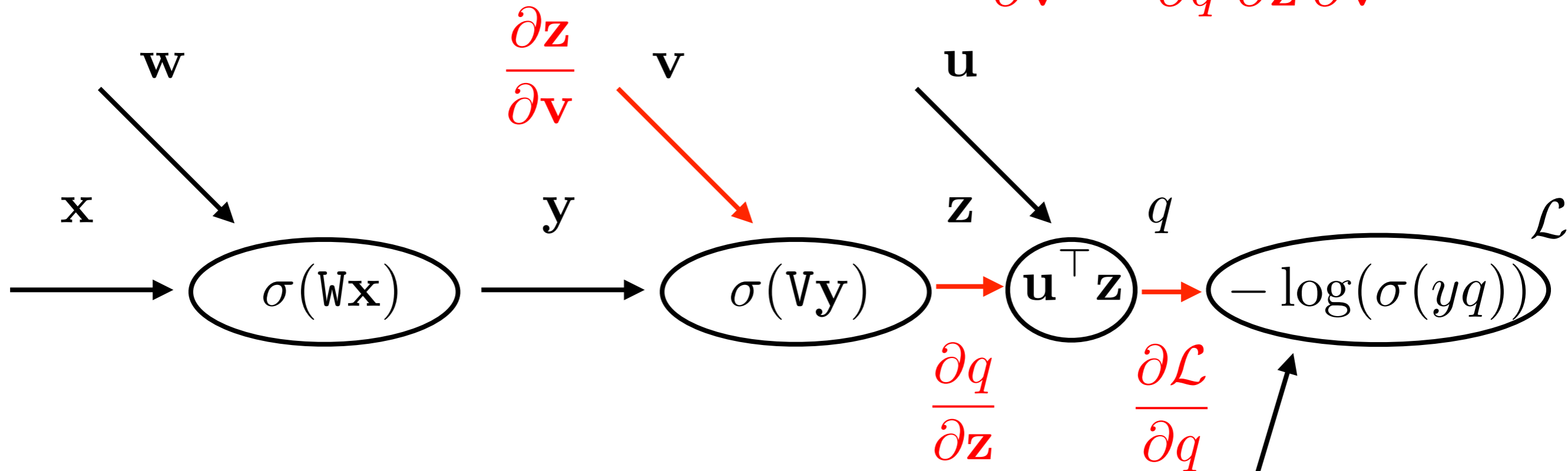
Dimensionality of the gradient???

y



Learning of fully connected neural network

$$\text{Derivative wrt } \mathbf{v} : \frac{\partial \mathcal{L}}{\partial \mathbf{v}} = \frac{\partial \mathcal{L}}{\partial q} \frac{\partial q}{\partial \mathbf{z}} \frac{\partial \mathbf{z}}{\partial \mathbf{v}}$$



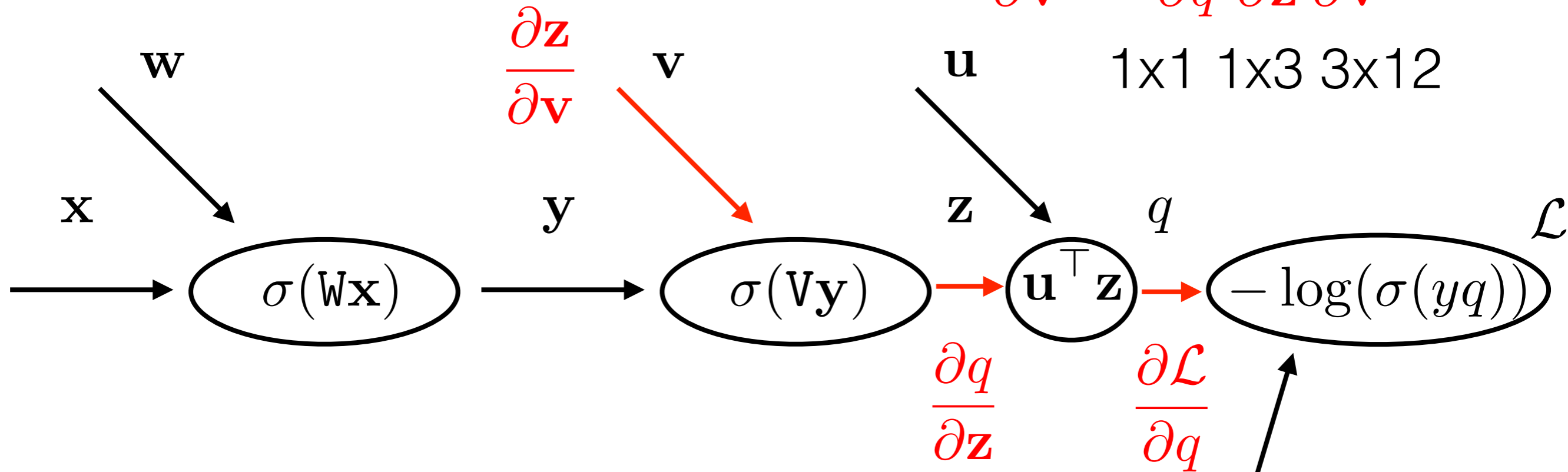
Dimensionality of the gradient???

y



Learning of fully connected neural network

Derivative wrt \mathbf{v} : $\frac{\partial \mathcal{L}}{\partial \mathbf{v}} = \frac{\partial \mathcal{L}}{\partial q} \frac{\partial q}{\partial \mathbf{z}} \frac{\partial \mathbf{z}}{\partial \mathbf{v}}$



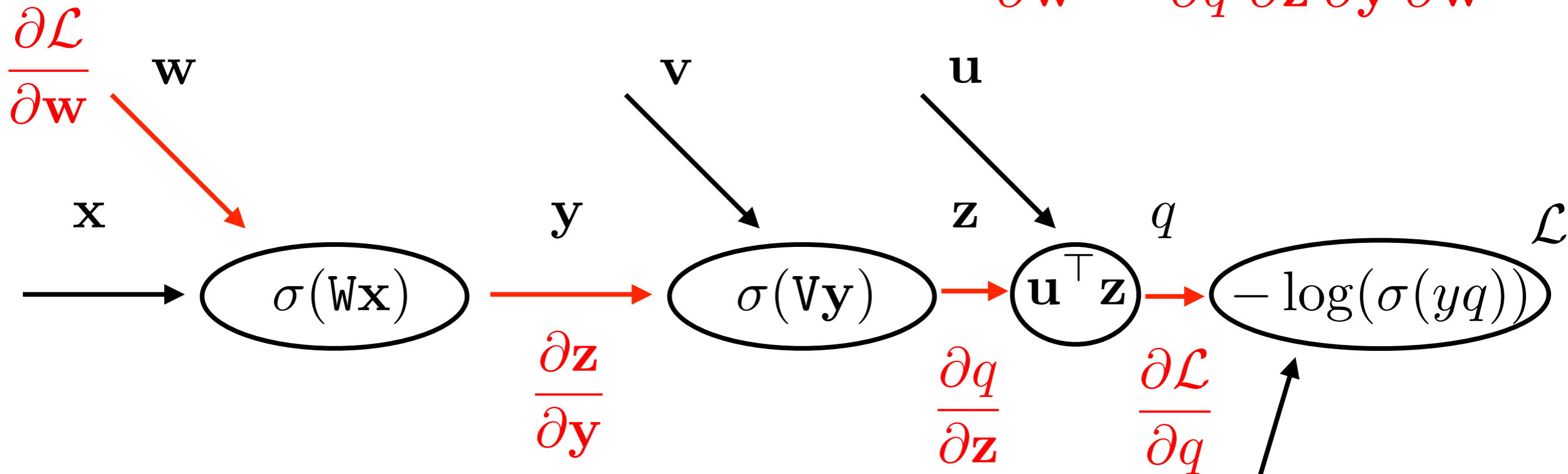
Dimensionality of the gradient???

y



Learning of fully connected neural network

Derivative wrt \mathbf{w} : $\frac{\partial \mathcal{L}}{\partial \mathbf{w}} = \frac{\partial \mathcal{L}}{\partial q} \frac{\partial q}{\partial \mathbf{z}} \frac{\partial \mathbf{z}}{\partial \mathbf{y}} \frac{\partial \mathbf{y}}{\partial \mathbf{w}}$



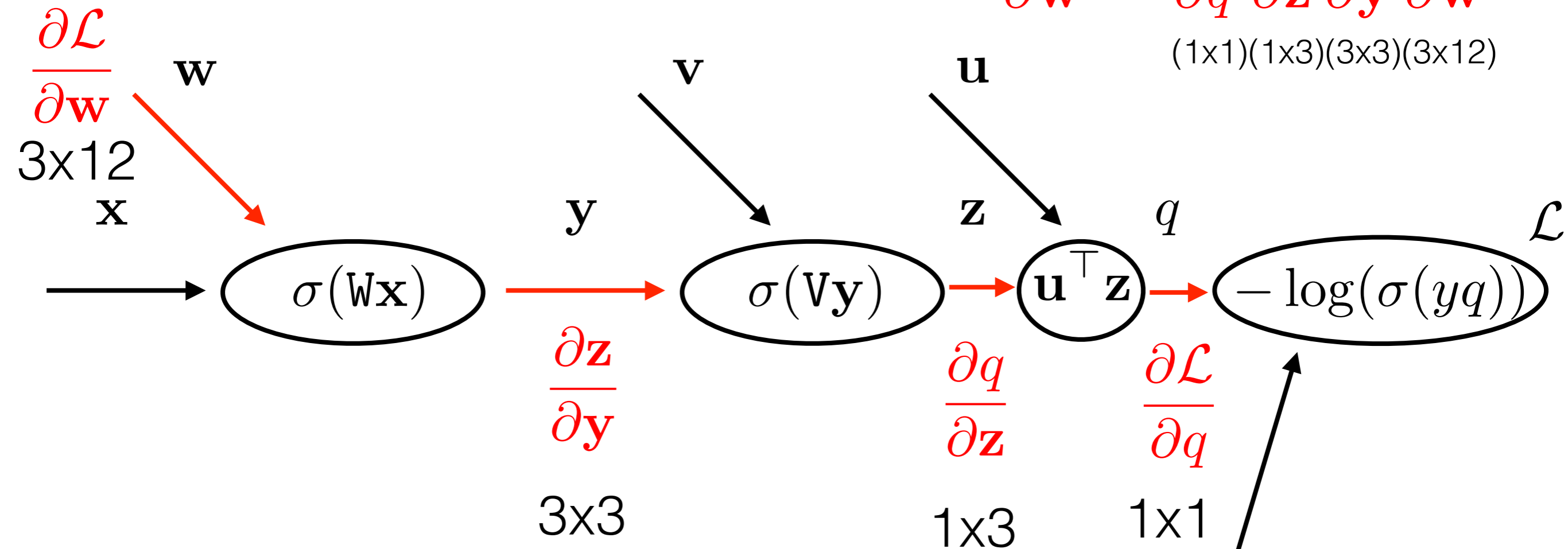
Dimensionality of the gradient???

y



Learning of fully connected neural network

Derivative wrt \mathbf{w} : $\frac{\partial \mathcal{L}}{\partial \mathbf{w}} = \frac{\partial \mathcal{L}}{\partial q} \frac{\partial q}{\partial \mathbf{z}} \frac{\partial \mathbf{z}}{\partial \mathbf{y}} \frac{\partial \mathbf{y}}{\partial \mathbf{w}}$
 (1x1)(1x3)(3x3)(3x12)



Dimensionality of the gradient???

y



Learning of fully connected neural network

1. Estimate all required local gradients
2. Update weights:

$$\frac{\partial \mathcal{L}}{\partial \mathbf{u}} = \frac{\partial \mathcal{L}}{\partial q} \frac{\partial q}{\partial \mathbf{u}} \quad \mathbf{u} = \mathbf{u} - \alpha \left[\frac{\partial \mathcal{L}}{\partial \mathbf{u}} \right]^\top$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{v}} = \frac{\partial \mathcal{L}}{\partial q} \frac{\partial q}{\partial \mathbf{z}} \frac{\partial \mathbf{z}}{\partial \mathbf{v}} \quad \mathbf{v} = \mathbf{v} - \alpha \left[\frac{\partial \mathcal{L}}{\partial \mathbf{v}} \right]^\top$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{w}} = \frac{\partial \mathcal{L}}{\partial q} \frac{\partial q}{\partial \mathbf{z}} \frac{\partial \mathbf{z}}{\partial \mathbf{y}} \frac{\partial \mathbf{y}}{\partial \mathbf{w}} \quad \mathbf{w} = \mathbf{w} - \alpha \left[\frac{\partial \mathcal{L}}{\partial \mathbf{w}} \right]^\top$$

3. Optionally update learning rate α
4. Repeat until convergence



Neural nets summary

- Neural net is a function created as concatenation of simpler functions (e.g. neurons or layers of neurons)
- Gradient optimization of the neural net is called backpropagation
- Neural net frameworks has many predefined layers
- **Spoiler alert:** It does not work (on images) at all - why?



$$\mathbf{w}^* = \arg \min_{\mathbf{w}} \left(\sum_i -\log(p(y_i | \mathbf{x}_i, \mathbf{w})) \right) + (-\log p(\mathbf{w}))$$

loss function prior/regulariser

- Class of function represented by a NN is too general.
- Naive regulariser helps a bit, but dimensionality/wildness is huge => curse-of-dimensionality, overfitting,...
- What is number of weights between two 1000-neuron layers?
- **Next lecture:** study animal cortex to find a stronger prior on the class of suitable functions.
- **Spoiler alert 2:**
reduce very general class of functions "neuron layer" to very specific sub-class of functions "convolution layer"

