Object Oriented Programming in C++

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Lecture 11

B3B36PRG - C Programming Language



Overview of the Lecture

■ Part 1 – Object Oriented Programming (in C++)

Objects and Methods in C++

Relationship

Inheritance

Polymorphism

Inheritance and Composition

■ Part 2 – Standard Template Library (in C++)

Templates

Standard Template Library (STL)



Part 1 – Object Oriented Programming



Outline

Objects and Methods in C++

Relationship

Inheritance

Polymorphism

Inheritance and Composition



Example of Encapsulation

Class Matrix encapsulates 2D matrix of double values

Relationship

```
class Matrix {
   public:
      Matrix(int rows, int cols);
      Matrix(const Matrix &m);
      ~Matrix();
      inline int rows(void) const { return ROWS; }
      inline int cols(void) const { return COLS; }
      double getValueAt(int r, int c) const;
      void setValueAt(double v, int r, int c);
      void fillRandom(void);
      Matrix sum(const Matrix &m2);
      Matrix operator+(const Matrix &m2);
      Matrix& operator=(const Matrix &m);
   private:
      inline double& at(int r, int c) const { return vals[COLS * r + c]; }
   private:
      const int ROWS:
      const int COLS:
      double *vals;
};
std::ostream& operator<<(std::ostream& out, const Matrix& m);</pre>
```



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lec11/matrix.h

- For a convenient access to matrix cells, we can implement operator
 - () with two arguments r and c denoting the cell row and column

```
class Matrix {
   public:
      double& operator()(int r, int c);
      double operator()(int r, int c) const;
};
// use the reference for modification of the cell value
double& Matrix::operator()(int r, int c)
   return at(r, c);
// copy the value for the const operator
double Matrix::operator()(int r, int c) const
   return at(r, c);
```

For simplicity and better readability, we do not check range of arguments.



Example Matrix – Identity Matrix

Implementation of the function set the matrix to the identity using the matrix subscripting operator

```
void setIdentity(Matrix& matrix)
   for (int r = 0; r < matrix.rows(); ++r) {
      for (int c = 0; c < matrix.cols(); ++c) {</pre>
         matrix(r, c) = (r == c) ? 1.0 : 0.0:
Matrix m1(2, 2);
std::cout << "Matrix m1 -- init values: " << std::endl << m1;</pre>
setIdentity(m1);
std::cout << "Matrix m1 -- identity: " << std::endl << m1;
```

Example of output

```
Matrix m1 -- init values:
0.0 0.0
0.0 0.0
Matrix m1 -- identity:
1.0 0.0
0.0 1.0
```



lec11/demo-matrix.cc

Relationship

Outline

Relationship



Relationship between Objects

- Objects can be in relationship based on the
 - Inheritance is the relationship of the type is

Object of descendant class is also the ancestor class

One class is derived from the ancestor class

Objects of the derived class extends the based class

Derived class contains all the field of the ancestor class

However, some of the fields may be hidden

New methods can be implemented in the derived class

New implementation override the previous one

- Derived class (objects) are specialization of a more general ancestor (super) class
- An object can be part of the other objects it is the has relation
 - Similarly to compound structures that contain other struct data types as their data fields, objects can also compound of other objects
 - We can further distinguish
 - Aggregation an object is a part of other object
 - Composition inner object exists only within the compound object



- Aggregation relationship of the type "has" or "it is composed
 - Let **A** be aggregation of **B C**, then objects **B** and **C** are contained in A
 - It results that B and C cannot survive without A In such a case, we call the relationship as composition

Example of implementation

```
class GraphComp { // composition
                                                struct Edge {
   private:
                                                    Node v1;
      std::vector<Edge> edges;
                                                    Node v2;
};
                                                };
class GraphComp { // aggregation
                                                struct Node {
   public:
                                                    Data data;
      GraphComp(std::vector<<u>Edge</u>>& edges)
                                                };
      : edges(edges) {}
   private:
      const std::vector<Edge>& edges;
};
```



Relationship

Inheritance



Inheritance

- Founding definition and implementation of one class on another existing class(es)
- Let class **B** be inherited from the class **A**, then
 - Class B is subclass or the derived class of A
- Class A is superclass or the base class of B ■ The subclass **B** has two parts in general:
 - Derived part is inherited from A
 - New incremental part contains definitions and implementation added by the class **B**
- The inheritance is relationship of the type is-a
 - Object of the type B is also an instance of the object of the type A
- Properties of B inherited from the A can be redefined
 - Change of field visibility (protected, public, private)
 - Overriding of the method implementation
- Using inheritance we can create hierarchies of objects

Implement general function in superclasses or creating abstract classes that are further specialized in the derived classes.



Example MatrixExt - Extension of the Matrix

- We will extend the existing class Matrix to have identity method and also multiplication operator
- We refer the superclass as the Base class using typedef
- We need to provide a constructor for the MatrixExt; however, we used the existing constructor in the base class



Example MatrixExt – Identity and Multiplication Operator

■ We can use only the public (or protected) methods of Matrix class

```
#include "matrix ext.h"
                                   Matrix does not have any protected members
void MatrixExt::setIdentity(void)
   for (int r = 0; r < rows(); ++r) {
      for (int c = 0; c < cols(); ++c) {
         (*this)(r, c) = (r == c) ? 1.0 : 0.0;
   }
Matrix MatrixExt::operator*(const Matrix &m2)
   Matrix m3(rows(). m2.cols()):
   for (int r = 0; r < rows(); ++r) {
      for (int c = 0; c < m2.cols(); ++c) {
         m3(r, c) = 0.0:
         for (int k = 0; k < cols(); ++k) {</pre>
            m3(r, c) += (*this)(r, k) * m2(k, c);
      }
   return m3;
```



lec11/matrix ext.cc

Example MatrixExt – Example of Usage 1/2

Objects of the class MatrixExt also have the methods of the Matrix

```
#include <iostream>
                                                 clang++ matrix.cc matrix_ext.
                                                      cc demo-matrix ext.cc &&
#include "matrix ext.h"
                                                          ./a.out
                                                 Matrix m1:
using std::cout;
                                                  3.0
int main(void)
                                                  5.0
   int ret = 0:
                                                 Matrix m2:
   MatrixExt m1(2, 1);
                                                  1.0 2.0
   m1(0, 0) = 3; m1(1, 0) = 5;
                                                 m1 * m2 =
   MatrixExt m2(1, 2);
                                                  13.0
   m2(0, 0) = 1; m2(0, 1) = 2;
                                                 m2 * m1 =
   cout << "Matrix m1:\n" << m1 << std::endl; 3.0 6.0
   cout << "Matrix m2:\n" << m2 << std::endl:</pre>
                                                  5.0 10.0
   cout << m1 * m2 = n' << m2 * m1 << std::endl;
   cout << "m2 * m1 = \n" << m1 * m2 << std::endl:
   return ret;
                                                 lec11/demo-matrix ext.cc
```



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Example MatrixExt – Example of Usage 2/2

- We may use objects of MatrixExt anywhere objects of Matrix can be applied.
- This is a result of the inheritance

And a first step towards polymorphism

```
void setIdentity(Matrix& matrix)
   for (int r = 0; r < matrix.rows(); ++r) {
      for (int c = 0; c < matrix.cols(); ++c) {</pre>
         matrix(r, c) = (r == c) ? 1.0 : 0.0;
MatrixExt m1(2, 1);
cout << "Using setIdentity for Matrix" << std::endl;</pre>
setIdentity(m1);
cout << "Matrix m1:\n" << m1 << std::endl:</pre>
```

lec11/demo-matrix ext.cc



Categories of the Inheritance

- Strict inheritance derived class takes all of the superclass and adds own methods and attributes. All members of the superclass are available in the derived class. It strictly follows the is-a hierarchy
- Nonstrict inheritance the subclass derives from the a superclass only certain attributes or methods that can be further redefined
- Multiple inheritance a class is derived from several superclasses



Inheritance - Summary

- Inheritance is a mechanism that allows
 - Extend data field of the class and modify them
 - Extend or modify methods of the class
- Inheritance allows to
 - Create hierarchies of classes
 - "Pass" data fields and methods for further extension and modification
 - Specialize (specify) classes
- The main advantages of inheritance are
 - It contributes essentially to the code reusability

Together with encapsulation!

■ Inheritance is foundation for the polymorphism



Polymorphism

Relationship

Outline

Polymorphism



Objects and Methods in C++

Polymorphism

Polymorphism can be expressed as the ability to refer in a same way to different objects

We can call the same method names on different objects

- We work with an object whose actual content is determined at the runtime
- \blacksquare Polymorphism of objects Let the class **B** be a subclass of **A**, then the object of the **B** can be used wherever it is expected to be an object of the class A
- Polymorphism of methods requires dynamic binding, i.e., static vs. dynamic type of the class
 - Let the class B be a subclass of A and redefines the method m()
 - \blacksquare A variable x is of the static type **B**, but its dynamic type can be **A** or B
 - Which method is actually called for x.m() depends on the dynamic type



In MatrixExt, we may override a method implemented in the base class Matrix, e.g., fillRandom() will also use negative values.

```
class MatrixExt : public Matrix {
   void fillRandom(void);
void MatrixExt::fillRandom(void)
   for (int r = 0; r < rows(); ++r) {</pre>
      for (int c = 0; c < cols(); ++c) {</pre>
         (*this)(r, c) = (rand() \% 100) / 10.0;
         if (rand() % 100 > 50) {
             (*this)(r, c) *= -1.0; // change the sign
                              lec11/matrix_ext.h, lec11/matrix_ext.cc
```

■ We can call the method fillRandom() of the MatrixExt

```
MatrixExt *m1 = new MatrixExt(3, 3);
Matrix *m2 = new MatrixExt(3, 3);
m1->fillRandom(); m2->fillRandom();
cout << "m1: MatrixExt as MatrixExt:\n" << *m1 << std::endl;</pre>
cout << "m2: MatrixExt as Matrix:\n" << *m2 << std::endl;</pre>
delete m1; delete m2;
                                            lec11/demo-matrix_ext.cc
```

■ However, in the case of m2 the Matrix::fillRandom() is called m1: MatrixExt as MatrixExt:

```
-1.3 9.8 1.2
8.7 -9.8 -7.9
-3.6 - 7.3 - 0.6
m2: MatrixExt as Matrix:
7.9 2.3 0.5
9.0 7.0 6.6
7.2 1.8 9.7
```

We need a dynamic way to identity the object type at runtime for the polymorphism of the methods



Virtual Methods – Polymorphism and Inheritance

- We need a dynamic binding for polymorphism of the methods
- It is usually implemented as a virtual method in object oriented programming languages
- Override methods that are marked as virtual has a dynamic binding to the particular dynamic type



Polymorphism

Example – Overriding without Virtual Method 1/2 #include <iostream> clang++ demo-novirtual.cc

```
using namespace std;
                                                  ./a.out
class A {
                                                  Object of the class A
   public:
                                                  Object of the class B
      void info()
                                                  Object of the class A
         cout << "Object of the class A" << endl;</pre>
};
class B : public A {
   public:
      void info()
         cout << "Object of the class B" << endl;
};
A* a = new A(): B* b = new B():
A* ta = a; // backup of a pointer
a->info(); // calling method info() of the class A
b->info(); // calling method info() of the class B
a = b; // use the polymorphism of objects
a->info(); // without the dynamic binding, method of the class A is called
delete ta; delete b:
                                                  lec11/demo-novirtual.cc
```

Example – Overriding with Virtual Method 2/2

```
#include <iostream>
                                                  clang++ demo-virtual.cc
using namespace std;
                                                  ./a.out
class A {
                                                  Object of the class A
   public:
                                                  Object of the class B
      virtual void info() // Virtual !!!
                                                  Object of the class B
      {
         cout << "Object of the class A" << endl;</pre>
};
class B : public A {
   public:
      void info()
         cout << "Object of the class B" << endl;
};
A* a = new A(): B* b = new B():
A* ta = a; // backup of a pointer
a->info(); // calling method info() of the class A
b->info(); // calling method info() of the class B
a = b; // use the polymorphism of objects
a->info(); // the dynamic binding exists, method of the class B is called
delete ta; delete b;
                                                    lec11/demo-virtual.cc
```

Derived Classes, Polymorphism, and Practical Implications

- Derived class inherits the methods and data fields of the superclass, but it can also add new methods and data fields
 - It can extend and specialize the class
 - It can modify the implementation of the methods
- An object of the derived class can be used instead of the object of the superclass, e.g.,
 - We can implement more efficient matrix multiplication without modification of the whole program

We may further need a mechanism to create new object based on the dynamic type, i.e., using the newInstance virtual method

- Virtual methods are important for the polymorphism
 - It is crucial to use a virtual destructor for a proper destruction of the object

E.g., when a derived class allocate additional memory



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Example – Virtual Destructor 1/4

```
#include <iostream>
using namespace std;
class Base {
   public:
      Base(int capacity) {
         cout << "Base::Base -- allocate data" << endl;</pre>
         int *data = new int[capacity];
      }
      virtual ~Base() { // virtual destructor is important
         cout << "Base::~Base -- release data" << endl;</pre>
   protected:
      int *data;
};
```



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lec11/demo-virtual_destructor.cc

Example – Virtual Destructor 2/4

```
class Derived : public Base {
   public:
      Derived(int capacity) : Base(capacity) {
         cout << "Derived::Derived -- allocate data2" << endl;</pre>
         int *data2 = new int[capacity];
      ~Derived() {
         cout << "Derived::~Derived -- release data2" << endl;</pre>
         int *data2;
   protected:
      int *data2;
```

lec11/demo-virtual destructor.cc



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};

Example – Virtual Destructor 3/4

Using virtual destructor all allocated data are properly released

```
cout << "Using Derived " << endl;</pre>
Derived *object = new Derived(1000000);
delete object;
cout << endl;</pre>
cout << "Using Base" << endl;</pre>
Base *object = new Derived(1000000);
delete object;
                                            lec11/demo-virtual destructor.cc
    clang++ demo-virtual_destructor.cc && ./a.out
    Using Derived
    Base::Base -- allocate data
    Derived::Derived -- allocate data2
    Derived:: "Derived -- release data2
    Base:: "Base -- release data
    Using Base
    Base::Base -- allocate data
    Derived::Derived -- allocate data2
    Derived:: "Derived -- release data2
```



Both desctructors Derived and Base are called

Base::~Base -- release data

Example – Virtual Destructor 4/4

■ Without virtual destructor, e.g.,

```
class Base {
   "Base(): // without virtualdestructor
};
Derived *object = new Derived(1000000);
delete object;
Base *object = new Derived(1000000);
delete object;
```

 Only both constructors are called, but only destructor of the Base class in the second case Base *object = new Derived(1000000);

```
Using Derived
```

```
Base::Base -- allocate data
Derived::Derived -- allocate data2
Derived::~Derived -- release data2
```

Base:: "Base -- release data

```
Using Base
```

Base::Base -- allocate data Derived::Derived -- allocate data2

Base:: "Base -- release data

Only the desctructor of Base is called

Relationship

Outline

Inheritance and Composition



Objects and Methods in C++

- A part of the object oriented programming is the object oriented design (OOD)
 - It aims to provide "a plan" how to solve the problem using objects and their relationship
 - An important part of the design is identification of the particular objects
 - their generalization to the classes
 - and also designing a class hierarchy
- Sometimes, it may be difficult to decides
 - What is the common (general) object and what is the specialization, which is important step for class hierarchy and applying the inheritance
 - It may also be questionable when to use composition
- Let show the inheritance on an example of geometrical objects



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```
class Rectangle {
   public:
      Rectangle(double w, double h) : width(w), height(h) {}
      inline double getWidth(void) const { return width; }
      inline double getHeight(void) const { return height; }
      inline double getDiagonal(void) const
      {
         return sqrt(width*width + height*height);
   protected:
      double width;
      double height;
```



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};

```
class <u>Cuboid</u> : public <u>Rectangle</u> {
   public:
      Cuboid(double w, double h, double d) :
         Rectangle(w, h), depth(d) {}
      inline double getDepth(void) const { return depth; }
      inline double getDiagonal(void) const
         const double tmp = Rectangle::getDiagonal();
         return sqrt(tmp * tmp + depth * depth);
      }
   protected:
      double depth;
};
```



- Class Cuboid extends the class Rectangle by the depth
 - Cuboid inherits data fields width a height
 - Cuboid also inherits "getters" getWidth() and getHeight()
 - Constructor of the Rectangle is called from the Cuboid constructor
- The descendant class Cuboid extends (override) the getDiagonal() methods

```
It actually uses the method getDiagonal() of the ancestor
Rectangle::getDiagonal()
```

■ We create a "specialization" of the Rectangle as an extension Cuboid class

Is it really a suitable extension?

What is the cuboid area? What is the cuboid circumference?



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Objects and Methods in C++

Example – Inheritance Cuboid Extend Rectangle

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Example – Inheritance Cuboid Extend Rectangle

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Is it really a suitable extension?

What is the cuboid area? What is the cuboid circumference?



Example – Inheritance – Rectangle is a Special Cuboid 1/2

Rectangle is a cuboid with zero depth

```
class Cuboid {
  public:
      Cuboid(double w, double h, double d) :
         width(w), height(h), depth(d) {}
      inline double getWidth(void) const { return width; }
      inline double getHeight(void) const { return height; }
      inline double getDepth(void) const { return depth; }
      inline double getDiagonal(void) const
         return sqrt(width*width + height*height + depth*depth);
   protected:
      double width:
      double height;
      double depth;
```



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};

```
class Rectangle : public Cuboid {
   public:
          Rectangle(double w, double h) : Cuboid(w, h, 0.0) {}
};
```

- Rectangle is a "cuboid" with zero depth
- Rectangle inherits all data fields: with, height, and depth
- It also inherits all methods of the ancestor

Accessible can be only particular ones

- The constructor of the Cuboid class is accessible and it used to set data fields with the zero depth
- Objects of the class Rectangle can use all variable and methods of the Cuboid class



Should be Rectangle Descendant of Cuboid or Cuboid be Descendant of Rectangle?

- 1. Cuboid is descendant of the rectangle
 - "Logical" addition of the depth dimensions, but methods valid for the rectangle do not work of the cuboid

E.g., area of the rectangle

- Rectangle as a descendant of the cuboid
 - Logically correct reasoning on specialization "All what work for the cuboid also work for the cuboid with zero depth"
 - Inefficient implementation every rectangle is represented by 3 dimensions



Should be Rectangle Descendant of Cuboid or Cuboid be Descendant of Rectangle?

- 1. Cuboid is descendant of the rectangle
 - "Logical" addition of the depth dimensions, but methods valid for the rectangle do not work of the cuboid

E.g., area of the rectangle

- 2. Rectangle as a descendant of the cuboid
 - Logically correct reasoning on specialization "All what work for the cuboid also work for the cuboid with zero depth"
 - Inefficient implementation every rectangle is represented by 3 dimensions

Specialization is correct

Everything what hold for the ancestor have to be valid for the descendant



- 1. Cuboid is descendant of the rectangle
 - "Logical" addition of the depth dimensions, but methods valid for the rectangle do not work of the cuboid

E.g., area of the rectangle

- 2. Rectangle as a descendant of the cuboid
 - Logically correct reasoning on specialization "All what work for the cuboid also work for the cuboid with zero depth"
 - Inefficient implementation every rectangle is represented by 3 dimensions

Specialization is correct

Everything what hold for the ancestor have to be valid for the descendant

However, in this particular case, usage of the inheritance is questionable.



Relationship of the Ancestor and Descendant is of the type "is-a"

- Is a straight line segment descendant of the point?
 - Straight line segment does not use any method of a point is-a?: segment is a point $? \to NO \to \text{segment}$ is not descendant of the point
- Is rectangle descendant of the straight line segment? is-a?: NO
- Is rectangle descendant of the square, or vice versa?
 - Rectangle "extends" square by one dimension, but it is not a square
 - Square is a rectangle with the width same as the height

Set the width and height in the constructor!



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Substitution Principle

- Relationship between two derived classes
- Policy
 - Derived class is a specialization of the superclass

There is the is-a relationship

- Wherever it is possible to sue a class, it must be possible to use the descendant in such a way that a user cannot see any difference Polymorphism
- Relationship is-a must be permanent



Composition of Objects

- If a class contains data fields of other object type, the relationship is called composition
- Composition creates a hierarchy of objects, but not by inheritance
 Inheritance creates hierarchy of relationship in the sense of descendant / ancestor
- Composition is a relationship of the objects aggregation consists / is compound
- It is a relationship of the type "has"



Example – Composition 1/3

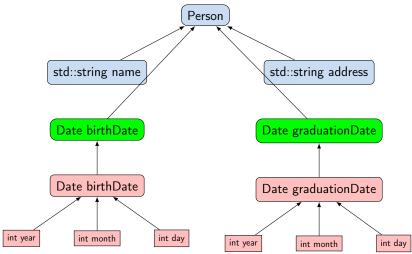
- Each person is characterized by attributes of the Person class
 - name (string)
 - address (string)
 - birthDate (date)
 - graduationDate (date)
- Date is characterized by three attributes Datum (class Date)
 - day (int)
 - month (int)
 - year (int)



```
#include <string>
                                  class Date {
                                     public:
class Person {
                                        int day;
   public:
                                        int month;
   std::string name;
                                        int year;
                                  };
   std::string address;
   Date birthDate;
   Date graduationDate;
};
```



Example - Composition 3/3





Inheritance vs Composition

- Inheritance objects:
 - Creating a derived class (descendant, subclass, derived class)
 - Derived class is a specialization of the superclass
 - May add variables (data fields) Or overlapping variables (names)
 - Add or modify methods
 - Unlike composition, inheritance changes the properties of the objects
 - New or modified methods
 - Access to variables and methods of the ancestor (base class, superclass)

If access is allowed (public/protected)

Composition of objects is made of attributes (data fields) of the object type

It consists of objects

- A distinction between composition an inheritance
 - ".ls" test a symptom of inheritance (is-a)
 - "Has" test a symptom of composition (has)



Inheritance and Composition - Pitfalls

- Excessive usage of composition and also inheritance in cases it is not needed leads to complicated design
- Watch on literal interpretations of the relationship is-a and has, sometimes it is not even about the inheritance, or composition

 $E.g.,\ Point 2D\ and\ Point 3D\ or\ Circle\ and\ Ellipse$

- Prefer composition and not the inheritance
 - One of the advantages of inheritance is the polymorphism
- Using inheritance violates the encapsulation

Especially with the access rights set to the protected



Part II

Part 2 – Standard Template Library (STL)



Outline

Templates

Standard Template Library (STL)



Templates

- Class definition may contain specific data fields of a particular type
- The data type itself does not change the behavior of the object, e.g., typically as in
 - Linked list or double linked list
 - Queue, Stack, etc.
 - data containers
- Definition of the class for specific type would be identical except the data type
- We can use templates for later specification of the particular data type, when the instance of the class is created
- Templates provides compile-time polymorphism

In constrast to the run-time polymorphism realized by virtual methods.



Example – Template Class

 The template class is defined by the template keyword with specification of the type name

```
template <typename T>
class Stack {
  public:
     bool push(T *data);
     T* pop(void);
};
```

 An object of the template class is declared with the specified particular type

```
Stack<int> intStack;
Stack<double> doubleStack;
```



Example - Template Function

 Templates can also be used for functions to specify particular type and use type safety and typed operators

```
template <typename T>
int T const & max(T const &a, T const &b)
{
   return a < b ? b : a;
}

double da, db;
int ia, ib;
std::cout << "max double: " << max(da, db) << std::endl;
std::cout << "max int: " << max(ia, ib) << std::endl;
//not allowed such a function is not defined
std::cout << "max mixed " << max(da, ib) << std::endl;</pre>
```



Outline

Templates

Standard Template Library (STL)



STL

- Standard Template Library (STL) is a library of the standard C++ that provides efficient implementations of the data containers, algorithms, functions, and iterators
- High efficiency of the implementation is achieved by templates with compile-type polymorphism
- Standard Template Library Programmer's Guide https://www.sgi.com/tech/stl/



std::vector - Dynamic "C" like array

 One of the very useful data containers in STL is vector which behaves like C array but allows to add and remove elements

```
#include <iostream>
#include <vector>
int main(void)
   std::vector<int> a:
   for (int i = 0; i < 10; ++i) {
      a.push_back(i);
   for (int i = 0; i < a.size(); ++i) {</pre>
      std::cout << "a[" << i << "] = " << a[i] << std::endl;
   std::cout << "Add one more element" << std::endl;</pre>
   a.push_back(0);
   for (int i = 5; i < a.size(); ++i) {</pre>
      std::cout << "a[" << i << "] = " << a[i] << std::endl:
   return 0:
                                                 lec11/stl-vector.cc
```



Summary of the Lecture



Topics Discussed

- Objects and Methods in C++ example of 2D matrix encapsulation
 - Subscripting operator
- Relationship between objects
 - Aggregation
 - Composition
- Inheritance properties and usage in C++
- Polymorphism dynamic binding and virtual methods
- Inheritance and Composition
- Templates and STL

