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Homework 5 for the Physics for OI

This homework is focused on coordinate systems, center of mass and moment of inertia.

Your tasks:

- a) To calculate coordinates (especially z-coordinate) of a center of mass of hemisphere of radius R with its bottom in the xy plane and centered around z-axis (see the picture).
- b) To calculate the moment of inertia of the hemisphere from the a) if the axis of rotation would be the z-axis.
- c) To calculate the moment of inertia of a sphere with its center at the origin of the coordinate system if the axis of rotation would be the z-axis (the hemisphere from the a) was completed to a sphere).
- d) To calculate the moment of inertia of a quarter of cylinder (see the picture) of radius R and height H if the axis of rotation is "o".
- e) To calculate the moment of inertia of a cylinder (the quarter of cylinder was completed to a cylinder) of radius R and height H if the axis of rotation is "o".



Hemisphere

Quarter of cylinder

Additional instructions and hints:

The density of each body is constant and equal to ρ . Evaluate each result both in the pure format (as a function of the ρ , R, or H) and also divided by the mass of the body (the result will be just a function of radius R)

Use triple integration in cylindrical coordinates for the d) and e). Assume that the "o" axis is identical with the z-axis.

Recalculation between Cartesian and cylindrical coordinates: $x = r \sin \phi$

$$x = r \sin \phi$$
$$y = r \cos \phi$$

$$z = z$$

Mass of a cylinder calculated in cylindrical coordinates, "o" axis is z-axis.

$$m = \rho V = \rho \int_{0}^{H} \int_{0}^{2\pi R} r dr d\phi dz$$

Use triple integration in spherical coordinates for the a), b) and c).

Recalculation between Cartesian and spherical coordinates:

 $x = r \sin \theta \cos \varphi$ $y = r \sin \theta \sin \varphi$ $z = r \cos \theta$

Mass of a sphere with its center at the origin of coordinate system calculated in spherical coordinates

$$m = \rho V = \rho \int_{0}^{\pi} \int_{0}^{2\pi R} \int_{0}^{R} r^{2} \sin \theta dr d\varphi d\theta$$

You can use either *Integrate* function from the Mathematica or chained application of the direct integration sign.







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