

Statistical Machine Learning (BE4M33SSU)

Lecture 10: Structured Output Support Vector Machines

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V. Franc

- ◆ Generic linear classifier.
- ◆ Structured Output Perceptron.
- ◆ Structured Output Support Vector Machines.
- ◆ Cutting Plane Algorithm.

Linear classifier

Two-class linear classifier:

- ◆ \mathcal{X} is a set of observations and $\mathcal{Y} = \{+1, -1\}$ is a set of hidden labels
- ◆ $\phi: \mathcal{X} \rightarrow \mathbb{R}^n$ feature map embedding observations from \mathcal{X} to \mathbb{R}^n
- ◆ Two-class linear classifier $h: \mathcal{X} \rightarrow \mathcal{Y}$

$$h(x; \mathbf{w}, b) = \text{sign}(\langle \mathbf{w}, \phi(x) \rangle + b) = \begin{cases} +1 & \text{if } \langle \mathbf{w}, \phi(x) \rangle + b \geq 0 \\ -1 & \text{if } \langle \mathbf{w}, \phi(x) \rangle + b < 0 \end{cases}$$

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A generic linear classifier:

- ◆ \mathcal{X} is a set of observations and \mathcal{Y} is a finite set of hidden states
- ◆ $\phi: \mathcal{X} \times \mathcal{Y} \rightarrow \mathbb{R}^n$ feature map embedding $\mathcal{X} \times \mathcal{Y}$ to \mathbb{R}^n
- ◆ Generic linear classifier $h: \mathcal{X} \rightarrow \mathcal{Y}$

$$h(x; \mathbf{w}) \in \underset{y \in \mathcal{Y}}{\text{Argmax}} \langle \mathbf{w}, \phi(x, y) \rangle$$

Example: multi-class linear classifier

- ◆ \mathcal{X} is a set of observations and $\mathcal{Y} = \{1, \dots, Y\}$ is a set of class labels
- ◆ Multi-class linear classifier $h: \mathcal{X} \rightarrow \mathcal{Y}$

$$h(x; \mathbf{w}) \in \underset{y \in \mathcal{Y}}{\text{Argmax}} \langle \mathbf{w}_y, \phi(x) \rangle$$

where $\phi: \mathcal{X} \rightarrow \mathbb{R}^d$ is a feature map $\mathbf{w} = (\mathbf{w}_1, \dots, \mathbf{w}_Y) \in \mathbb{R}^{d \cdot Y}$ are parameters.

- ◆ We can write the score function as

$$\langle \mathbf{w}_y, \phi(x) \rangle = \langle \mathbf{w}, \phi(x, y) \rangle$$

where $\phi: \mathcal{X} \times \mathcal{Y} \rightarrow \mathbb{R}^{d \cdot Y}$ is

$$\phi(x, y) = (\mathbf{0}; \dots; \underbrace{\phi(x)}_{y\text{-th slot}}; \dots; \mathbf{0})$$

Example: sequence classifier for OCR

- ◆ $\mathbf{x} = (x_1, \dots, x_L) \in \mathcal{I}^L$ sequence of L images with characters
- ◆ $\mathbf{y} = (y_1, \dots, y_L) \in \mathcal{A}^L$ sequence of L chars. from $\mathcal{A} = \{A, \dots, Z\}$

For example:

$$\mathbf{x} = (x_1, x_2, x_3, x_4) \quad \mathbf{y} = (y_1, y_2, y_3, y_4)$$

JOHN

JOHN

BILL

BILL

⋮

⋮

DANA

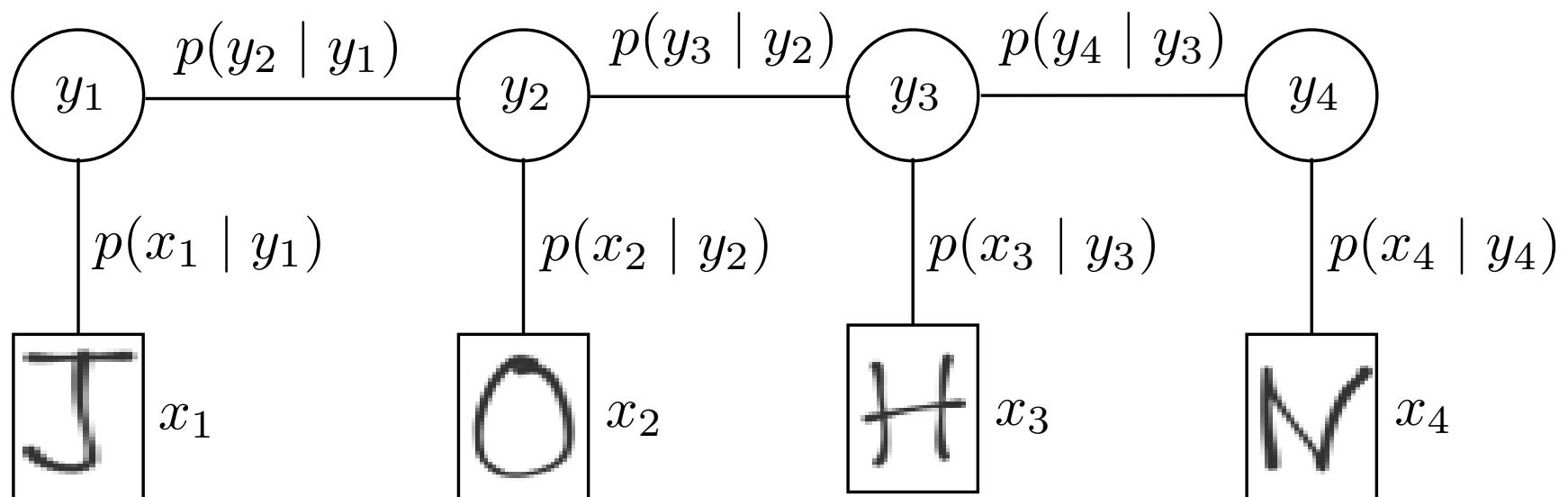
DANA

Example: sequence classifier for OCR

Hidden Markov Chain model:

- ◆ $\mathbf{x} = (x_1, \dots, x_L) \in \mathcal{I}^L$ sequence of L images with characters
- ◆ $\mathbf{y} = (y_1, \dots, y_L) \in \mathcal{A}^L$ sequence of L chars. from $\mathcal{A} = \{A, \dots, Z\}$
- ◆ $p(x_i | y_i)$ appearance model for characters
- ◆ $p(y_i | y_{i-1})$ language model

$$p(\mathbf{x}, \mathbf{y}) = p(y_1) \prod_{i=2}^L p(y_i | y_{i-1}) \prod_{i=1}^L p(x_i | y_i)$$



Example: sequence classifier for OCR

- ◆ The MAP estimate from HMM:

$$\hat{\mathbf{y}} \in \underset{\mathbf{y} \in \mathcal{A}^L}{\text{Argmax}} \left(\log p(y_1) + \sum_{i=2}^L \log p(y_i | y_{i-1}) + \sum_{i=1}^L \log p(x_i | y_i) \right)$$

- ◆ Let us assume the following parametrization:

$$\begin{aligned} \log p(y_1) &= \langle \mathbf{w}, \phi(y_1) \rangle \\ \log p(y_i | y_{i-1}) &= \langle \mathbf{w}, \phi(y_{i-1}, y_i) \rangle \\ \log p(x_i | y_i) &= \langle \mathbf{w}, \phi(x_i, y_i) \rangle \end{aligned}$$

- ◆ The MAP estimate becomes a linear classifier:

$$\hat{\mathbf{y}} = \underset{(y_1, \dots, y_L) \in \mathcal{A}^L}{\text{Argmax}} \left\langle \mathbf{w}, \underbrace{\phi(y_1) + \sum_{i=2}^L \phi(y_{i-1}, y_i) + \sum_{i=1}^L \phi(x_i, y_i)}_{\phi(\mathbf{x}, \mathbf{y})} \right\rangle$$

Learning by Empirical Risk Minimization

- ◆ $\ell: \mathcal{Y} \times \mathcal{Y} \rightarrow [0, \infty)$ - loss such that $\ell(y, y') = 0$ iff $y = y'$.
- ◆ Find parameters \mathbf{w} of $h(x; \mathbf{w})$ which minimize the expected risk

$$R(\mathbf{w}) = \mathbb{E}_{(x,y) \sim p} \left(\ell(y, h(x; \mathbf{w})) \right)$$

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- ◆ The Empirical Risk Minimization principle leads to solving

$$\mathbf{w}^* \in \underset{\mathbf{w} \in \mathbb{R}^n}{\text{Argmin}} R_{\mathcal{T}^m}(\mathbf{w})$$

where the empirical risk is

$$R_{\mathcal{T}^m}(\mathbf{w}) = \frac{1}{m} \sum_{i=1}^m \ell(y^i, h(x^i; \mathbf{w}))$$

and $\mathcal{T}^m = \{(x^i, y^i) \in (\mathcal{X} \times \mathcal{Y}) \mid i = 1, \dots, m\}$ are training examples drawn from i.i.d. with distribution $p(x, y)$.

Learning linear classifier from separable examples

- ◆ A correctly classified example (x^i, y^i) , that is,

$$y^i = h(x^i; \mathbf{w}) = \underset{y \in \mathcal{Y}}{\text{Argmax}} \langle \mathbf{w}, \phi(x^i, y) \rangle$$

implies

$$\langle \phi(x^i, y^i), \mathbf{w} \rangle > \langle \phi(x^i, y), \mathbf{w} \rangle, \quad \forall y \in \mathcal{Y} \setminus \{y^i\}$$

Definition 1. *The examples $\mathcal{T}^m = \{(x^i, y^i) \in (\mathcal{X} \times \mathcal{Y}) \mid i = 1, \dots, m\}$ are linearly separable w.r.t. joint feature map $\phi: \mathcal{X} \times \mathcal{Y} \rightarrow \mathbb{R}^n$ if there exists $\mathbf{w} \in \mathbb{R}^n$ such that*

$$\langle \phi(x^i, y^i), \mathbf{w} \rangle > \langle \phi(x^i, y), \mathbf{w} \rangle, \quad \forall i \in \{1, \dots, m\}, y \in \mathcal{Y} \setminus \{y^i\}$$

Example: sequence classifier for OCR

$$\mathcal{T}^m = \{(\text{JOHN}, \text{JOHN}), (\text{BILL}, \text{BILL}), \dots\}$$

$$\left. \begin{array}{l} \langle \phi(\text{JOHN}, \text{JOHN}), \mathbf{w} \rangle > \langle \phi(\text{JOHN}, \text{AAAA}), \mathbf{w} \rangle \\ \langle \phi(\text{JOHN}, \text{JOHN}), \mathbf{w} \rangle > \langle \phi(\text{JOHN}, \text{AAAB}), \mathbf{w} \rangle \\ \vdots \\ \langle \phi(\text{JOHN}, \text{JOHN}), \mathbf{w} \rangle > \langle \phi(\text{JOHN}, \text{ZZZZ}), \mathbf{w} \rangle \end{array} \right\} \begin{array}{l} 26^4 - 1 \\ \text{inequalities} \end{array}$$

Example: sequence classifier for OCR

$$\mathcal{T}^m = \{(\text{JOHN}, \text{JOHN}), (\text{BILL}, \text{BILL}), \dots\}$$

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$$\left. \begin{aligned} \langle \phi(\text{BILL}, \text{BILL}), \mathbf{w} \rangle &> \langle \phi(\text{BILL}, \text{AAAA}), \mathbf{w} \rangle \\ \langle \phi(\text{BILL}, \text{BILL}), \mathbf{w} \rangle &> \langle \phi(\text{BILL}, \text{AAAB}), \mathbf{w} \rangle \\ &\vdots \\ \langle \phi(\text{BILL}, \text{BILL}), \mathbf{w} \rangle &> \langle \phi(\text{JOHN}, \text{ZZZZ}), \mathbf{w} \rangle \end{aligned} \right\} \begin{array}{l} 26^4 - 1 \\ \text{inequalities} \end{array}$$

(Generic) Perceptron algorithm

- ◆ **Task:** given a set of points $\{\mathbf{a}^i \in \mathbb{R}^n \mid i = 1, 2, \dots, K\}$ we want to find $\mathbf{w} \in \mathbb{R}^n$ such that

$$\langle \mathbf{w}, \mathbf{a}^i \rangle > 0, \quad \forall i \in \{1, 2, \dots, K\} \quad (1)$$

- ◆ **Perceptron:**

1. $\mathbf{w} \leftarrow \mathbf{0}$
2. Find a violating $\langle \mathbf{w}, \mathbf{a}^i \rangle \leq 0, i \in \{1, 2, \dots, K\}$
3. If there is no violating inequality return \mathbf{w} otherwise update

$$\mathbf{w} \leftarrow \mathbf{w} + \mathbf{a}^i$$

and go to step 2.

- ◆ If the set of inequalities (1) is solvable then the Perceptron algorithm exits in a finite number of steps which does not depend on m .

Structured Output Perceptron

- ◆ Learning $h(x; \mathbf{w}) \in \text{Argmax}_{y \in \mathcal{Y}} \langle \mathbf{w}, \phi(x, y) \rangle$ from examples $\mathcal{T}^m = \{(x^i, y^i) \in (\mathcal{X} \times \mathcal{Y}) \mid i = 1, \dots, m\}$ leads to solving

$$\langle \phi(x^i, y^i) - \phi(x^i, y), \mathbf{w} \rangle > 0, \quad \forall i \in \{1, \dots, m\}, y \in \mathcal{Y} \setminus \{y^i\}$$

- ◆ **Algorithm:**

1. $\mathbf{w} \leftarrow \mathbf{0}$
2. Find a misclassified example $(x^i, y^i) \in \mathcal{T}^m$ such that

$$y^i \neq \hat{y}^i \in \text{Argmax}_{y \in \mathcal{Y}} \langle \mathbf{w}, \phi(x^i, y) \rangle \quad \text{prediction problem}$$

3. If there is no misclassified example return \mathbf{w} otherwise update

$$\mathbf{w} \leftarrow \mathbf{w} + \phi(x^i, y^i) - \phi(x^i, \hat{y}^i) \quad \text{parameter update}$$

and go to step 2.

Structured Output SVM

- ◆ Learning $h(x; \mathbf{w}) \in \text{Argmax}_{y \in \mathcal{Y}} \langle \mathbf{w}, \phi(x, y) \rangle$ from examples $\mathcal{T}^m = \{(x^i, y^i) \in (\mathcal{X} \times \mathcal{Y}) \mid i = 1, \dots, m\}$ by ERM leads to

$$\mathbf{w}^* \in \underset{\mathbf{w} \in \mathbb{R}^n}{\text{Argmin}} R_{\mathcal{T}^m}(\mathbf{w}) \quad \text{where} \quad R_{\mathcal{T}^m}(\mathbf{w}) = \frac{1}{m} \sum_{i=1}^m \ell(y^i, h(x^i; \mathbf{w}))$$

Structured Output SVM

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- ◆ The SO-SVM approximates the ERM by a convex problem

$$\mathbf{w}^* \in \underset{\mathbf{w} \in \mathbb{R}^n}{\text{Argmin}} \left(\frac{\lambda}{2} \|\mathbf{w}\|^2 + R^\psi(\mathbf{w}) \right) \quad \text{where} \quad R^\psi(\mathbf{w}) = \frac{1}{m} \sum_{i=1}^m \psi(x^i, y^i, \mathbf{w})$$

Structured Output SVM

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- ◆ The surrogate loss $\psi: \mathcal{X} \times \mathcal{Y} \times \mathbb{R}^n \rightarrow \mathbb{R}$ is an upper bound:

$$\ell(y, h(x; \mathbf{w})) \leq \psi(x, y, \mathbf{w}), \quad \forall (x, y, \mathbf{w}) \in (\mathcal{X} \times \mathcal{Y} \times \mathbb{R}^n)$$

which is convex in \mathbf{w} for any (x, y) .

Margin rescaling loss

- ◆ We require the score of the correct label y^i to be higher than the score of any incorrect label y by margin proportional to the loss $\ell(y^i, y)$:

$$\langle \mathbf{w}, \phi(x^i, y^i) \rangle \geq \langle \mathbf{w}, \phi(x^i, y) \rangle + \ell(y^i, y), \quad \forall y \in \mathcal{Y} \setminus \{y^i\}$$

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- ◆ Example: Sequential OCR, Hamming distance $\ell(\mathbf{y}, \mathbf{y}') = \sum_{i=1}^L [y_i \neq y'_i]$

$$\begin{aligned} \langle \phi(\text{JOHN}, \text{JOHN}), \mathbf{w} \rangle &\geq \langle \phi(\text{JOHN}, \text{AAAA}), \mathbf{w} \rangle + 4 \\ \langle \phi(\text{JOHN}, \text{JOHN}), \mathbf{w} \rangle &\geq \langle \phi(\text{JOHN}, \text{JAAA}), \mathbf{w} \rangle + 3 \\ \langle \phi(\text{JOHN}, \text{JOHN}), \mathbf{w} \rangle &\geq \langle \phi(\text{JOHN}, \text{JOAA}), \mathbf{w} \rangle + 2 \\ \langle \phi(\text{JOHN}, \text{JOHN}), \mathbf{w} \rangle &\geq \langle \phi(\text{JOHN}, \text{JOHA}), \mathbf{w} \rangle + 1 \end{aligned}$$

⋮

Margin rescaling loss

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- ◆ The margin rescaling loss

$$\psi(x^i, y^i, \mathbf{w}) = \max \left\{ 0, \max_{y \in \mathcal{Y} \setminus \{y^i\}} \left(\ell(y^i, y) + \langle \mathbf{w}, \phi(x^i, y) \rangle - \langle \mathbf{w}, \phi(x^i, y^i) \rangle \right) \right\}$$

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- ◆ It upper bounds of the true loss:

$$y^i \neq \hat{y} = h(x^i; \mathbf{w}) \in \underset{y \in \mathcal{Y}}{\text{Argmax}} \langle \mathbf{w}, \phi(x^i, y) \rangle$$

implies $\langle \mathbf{w}, \phi(x^i, \hat{y}) \rangle - \langle \mathbf{w}, \phi(x^i, y^i) \rangle \geq 0$ and hence

$$\psi(x^i, y^i, \mathbf{w}) \geq \ell(y^i, h(x^i, \mathbf{w})), \quad \forall \mathbf{w} \in \mathbb{R}^n$$

Margin-rescaling loss

- ◆ Using shortcuts $\ell_i(y) = \ell(y^i, y)$ and $\phi_i(y) = \phi(x^i, y) - \phi(x^i, y^i)$ we can simplify the margin rescaling loss:

$$\begin{aligned}
 \psi(x^i, y^i, \mathbf{w}) &= \max\{0, \max_{y \in \mathcal{Y} \setminus \{y^i\}} (\ell(y^i, y) + \langle \mathbf{w}, \phi(x^i, y) \rangle - \langle \mathbf{w}, \phi(x^i, y^i) \rangle)\} \\
 &= \max_{y \in \mathcal{Y}} (\ell(y^i, y) + \langle \mathbf{w}, \phi(x^i, y) \rangle - \langle \mathbf{w}, \phi(x^i, y^i) \rangle) \\
 &= \max_{y \in \mathcal{Y}} (\ell_i(y) + \langle \mathbf{w}, \phi_i(y) \rangle)
 \end{aligned}$$

- ◆ The margin-rescaling loss is a point-wise maximum over $|\mathcal{Y}|$ linear terms, hence, it is convex.

SO-SVM leads to a convex QP

- ◆ The SO-SVM with margin-rescaling loss:

$$\mathbf{w}^* \in \underset{\mathbf{w} \in \mathbb{R}^n}{\text{Argmin}} \left(\underbrace{\frac{\lambda}{2} \|\mathbf{w}\|^2 + \frac{1}{m} \sum_{i=1}^m \max_{y \in \mathcal{Y}} \{ \ell_i(y) + \langle \mathbf{w}, \phi_i(y) \rangle \}}_{R^\psi(\mathbf{w})} \right)$$

- ◆ By using slack variables it can be rewritten as a Quadratic Program:

$$\mathbf{w}^* = \underset{\mathbf{w} \in \mathbb{R}^n, \boldsymbol{\xi} \in \mathbb{R}^m}{\text{argmin}} \left(\frac{\lambda}{2} \|\mathbf{w}\|^2 + \frac{1}{m} \sum_{i=1}^m \xi_i \right)$$

subject to

$$\xi_i \geq \ell_i(y) + \langle \mathbf{w}, \phi_i(y) \rangle, \quad \forall i \in \{1, \dots, m\}, \forall y \in \mathcal{Y}$$

- ◆ Note that the QP has $m|\mathcal{Y}|$ linear constraints !

Cutting Plane Algorithm

- ◆ The SO-SVM problem

$$\mathbf{w}^* \in \underset{\mathbf{w} \in \mathbb{R}^n}{\text{Argmin}} \left(\frac{\lambda}{2} \|\mathbf{w}\|^2 + R^\psi(\mathbf{w}) \right)$$

- ◆ Equivalent formulation: for any $\lambda > 0$ there exists $r > 0$ such that

$$\mathbf{w}^* \in \underset{\mathbf{w} \in \mathcal{W}}{\text{Argmin}} R^\psi(\mathbf{w}) \quad (2)$$

where $\mathcal{W} = \{\mathbf{w} \in \mathbb{R}^n \mid \|\mathbf{w}\| \leq r\}$ is a ball of radius r .

Cutting Plane Algorithm

- ◆ The SO-SVM problem

$$\mathbf{w}^* \in \underset{\mathbf{w} \in \mathbb{R}^n}{\text{Argmin}} \left(\frac{\lambda}{2} \|\mathbf{w}\|^2 + R^\psi(\mathbf{w}) \right)$$

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where $\mathcal{W} = \{\mathbf{w} \in \mathbb{R}^n \mid \|\mathbf{w}\| \leq r\}$ is a ball of radius r .

- ◆ CP algorithm: approximate (2) by a series of simpler problems

$$\mathbf{w}_t \in \underset{\mathbf{w} \in \mathcal{W}}{\text{Argmin}} R_t^\psi(\mathbf{w}), \quad t = 1, 2, \dots$$

where $R_t^\psi(\mathbf{w})$ is a successively tighter lower bound of $R^\psi(\mathbf{w})$.

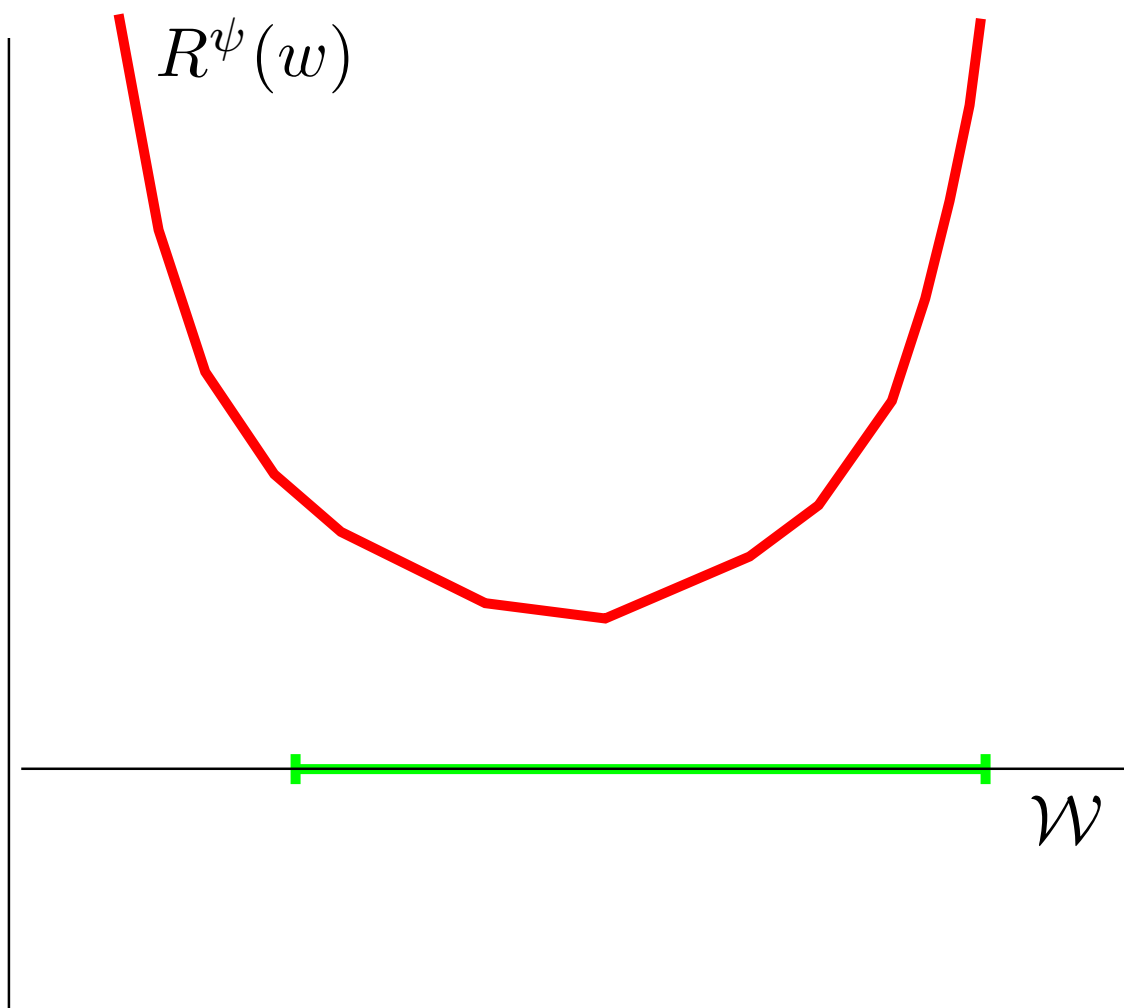
Cutting Plane Algorithm



$$R^\psi(\mathbf{w}) = \frac{1}{m} \sum_{i=1}^m \max_{\hat{y}^i \in \mathcal{Y}} (\ell_i(\hat{y}^i) + \langle \phi_i(\hat{y}^i), \mathbf{w} \rangle) = \max_{\substack{\hat{y}^1 \in \mathcal{Y} \\ \vdots \\ \hat{y}^m \in \mathcal{Y}}} \frac{1}{m} \sum_{i=1}^m (\ell_i(\hat{y}^i) + \langle \phi_i(\hat{y}^i), \mathbf{w} \rangle)$$

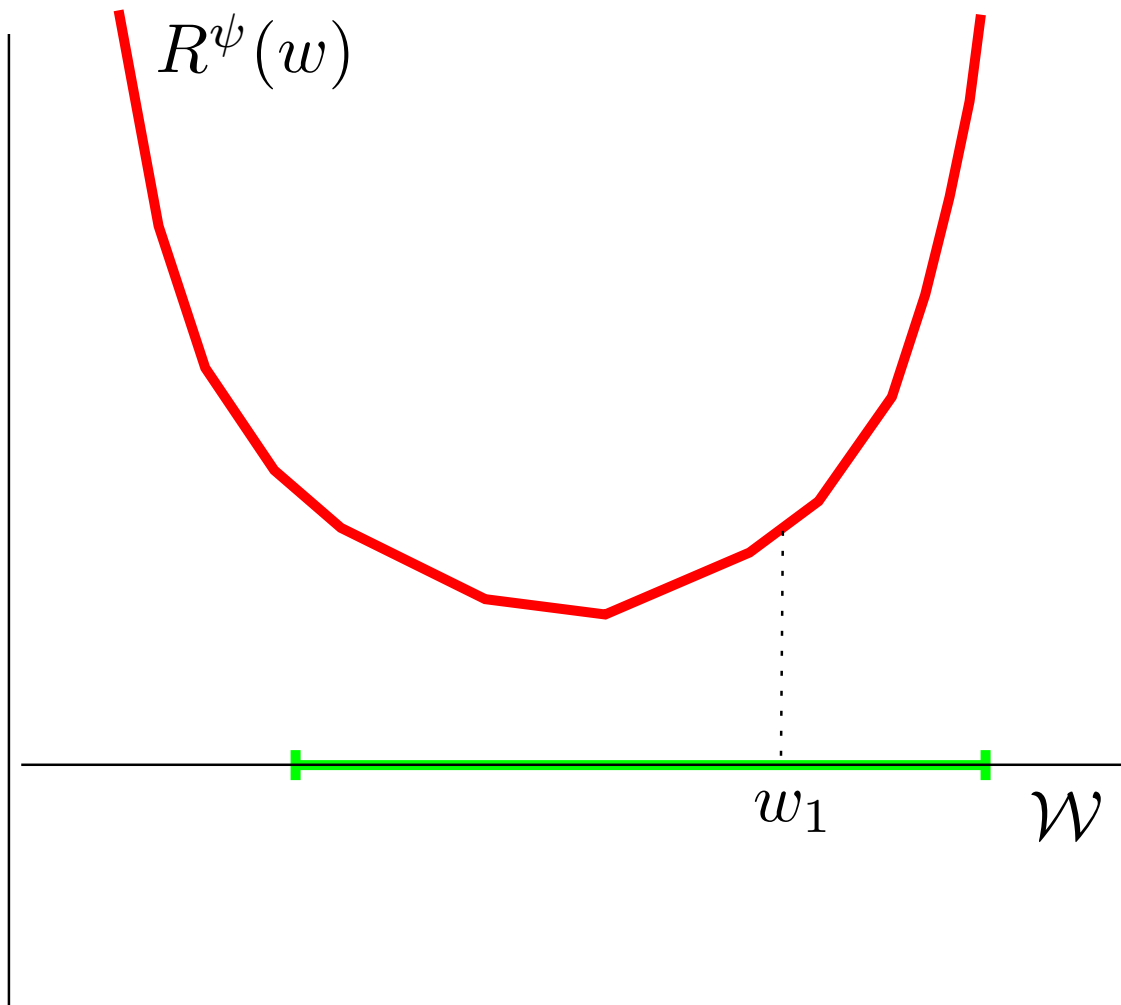
Cutting Plane Algorithm

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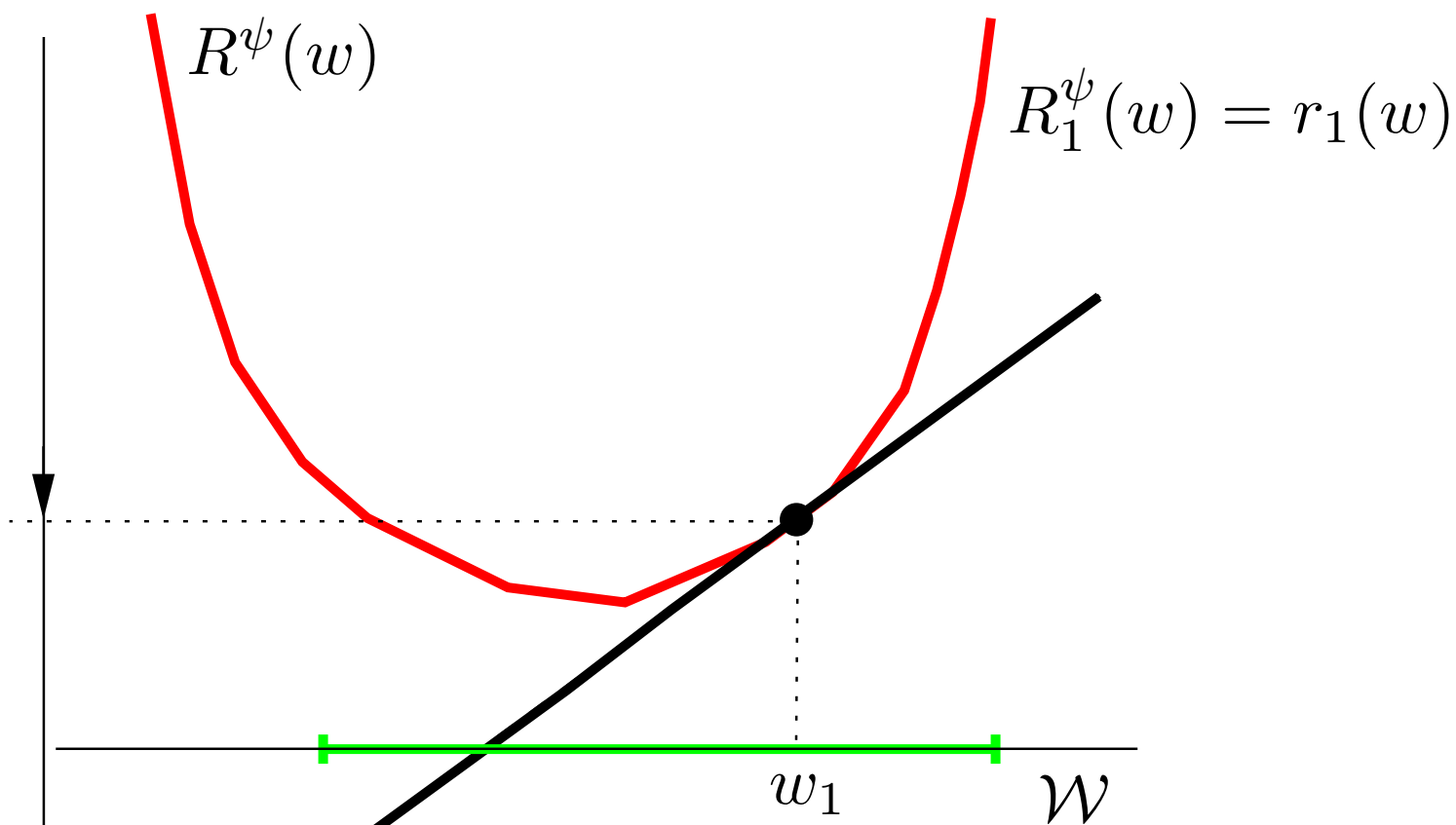
Cutting Plane Algorithm

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Cutting Plane Algorithm

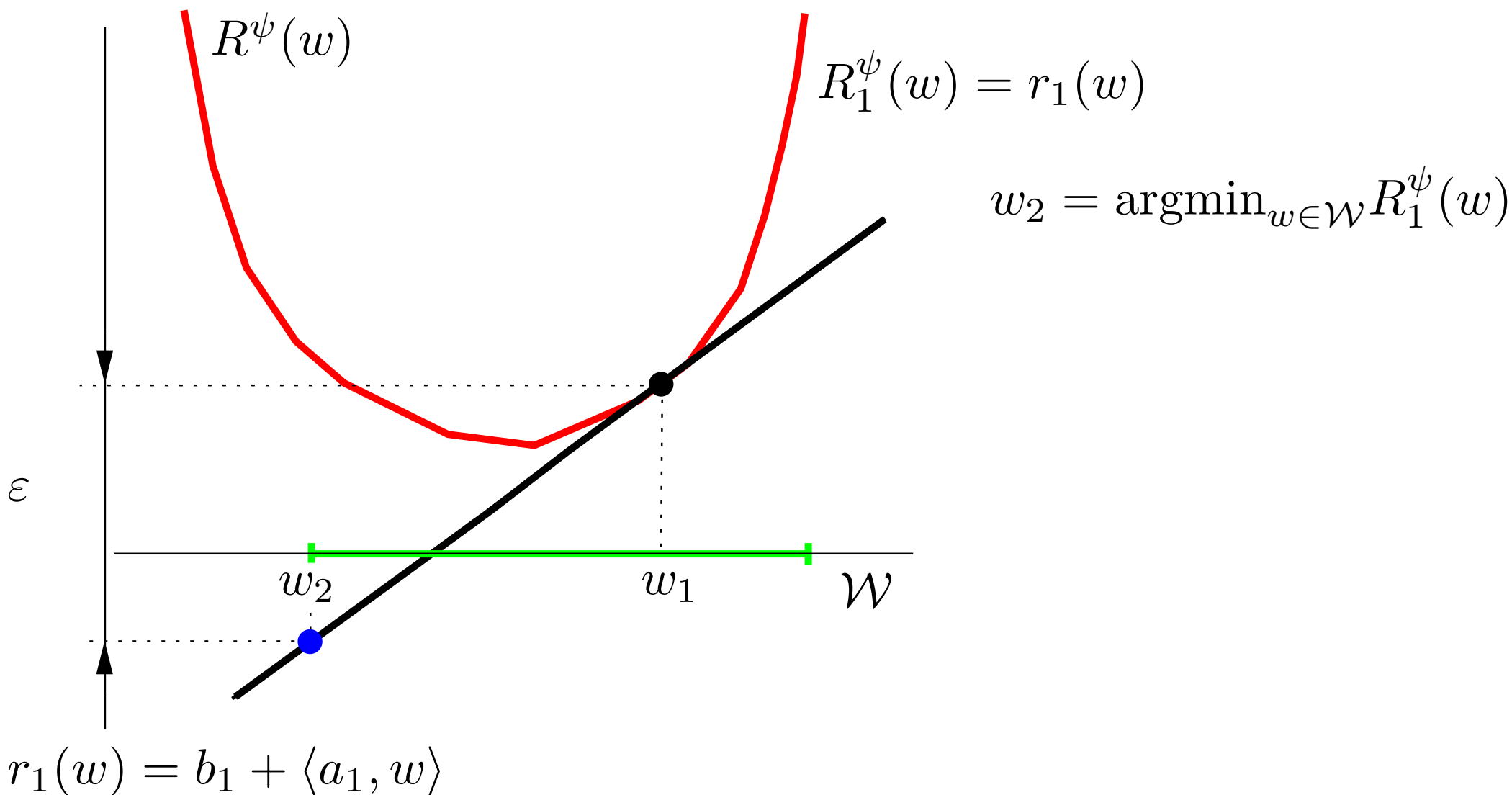
$$R^\psi(w) = \frac{1}{m} \sum_{i=1}^m \max_{\hat{y}^i \in \mathcal{Y}} (\ell_i(\hat{y}^i) + \langle \phi_i(\hat{y}^i), w \rangle) = \max_{\substack{\hat{y}^1 \in \mathcal{Y} \\ \vdots \\ \hat{y}^m \in \mathcal{Y}}} \frac{1}{m} \sum_{i=1}^m (\ell_i(\hat{y}^i) + \langle \phi_i(\hat{y}^i), w \rangle)$$



$$r_1(w) = b_1 + \langle a_1, w \rangle$$

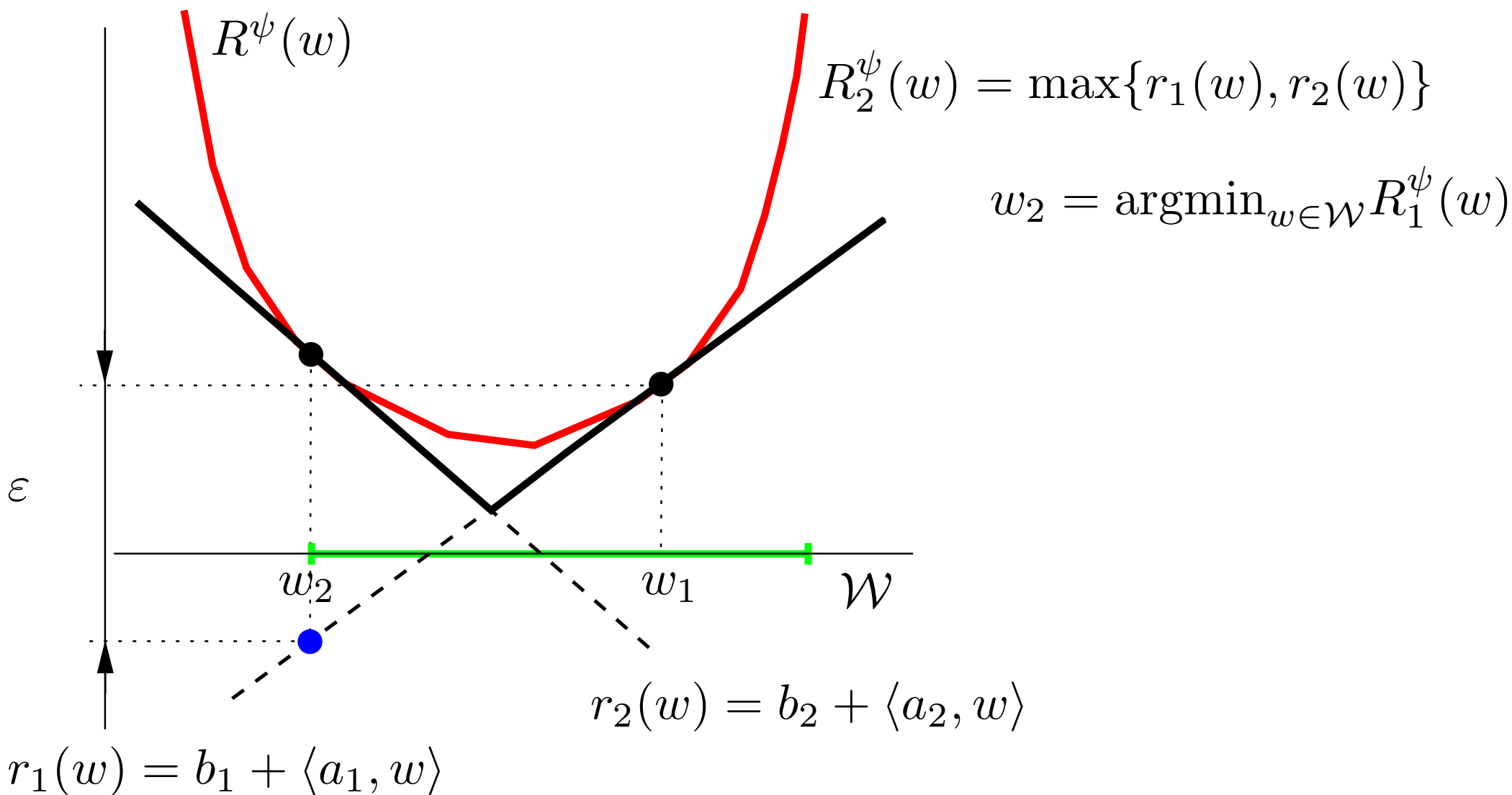
Cutting Plane Algorithm

$$R^\psi(w) = \frac{1}{m} \sum_{i=1}^m \max_{\hat{y}^i \in \mathcal{Y}} (\ell_i(\hat{y}^i) + \langle \phi_i(\hat{y}^i), w \rangle) = \max_{\substack{\hat{y}^1 \in \mathcal{Y} \\ \vdots \\ \hat{y}^m \in \mathcal{Y}}} \frac{1}{m} \sum_{i=1}^m (\ell_i(\hat{y}^i) + \langle \phi_i(\hat{y}^i), w \rangle)$$



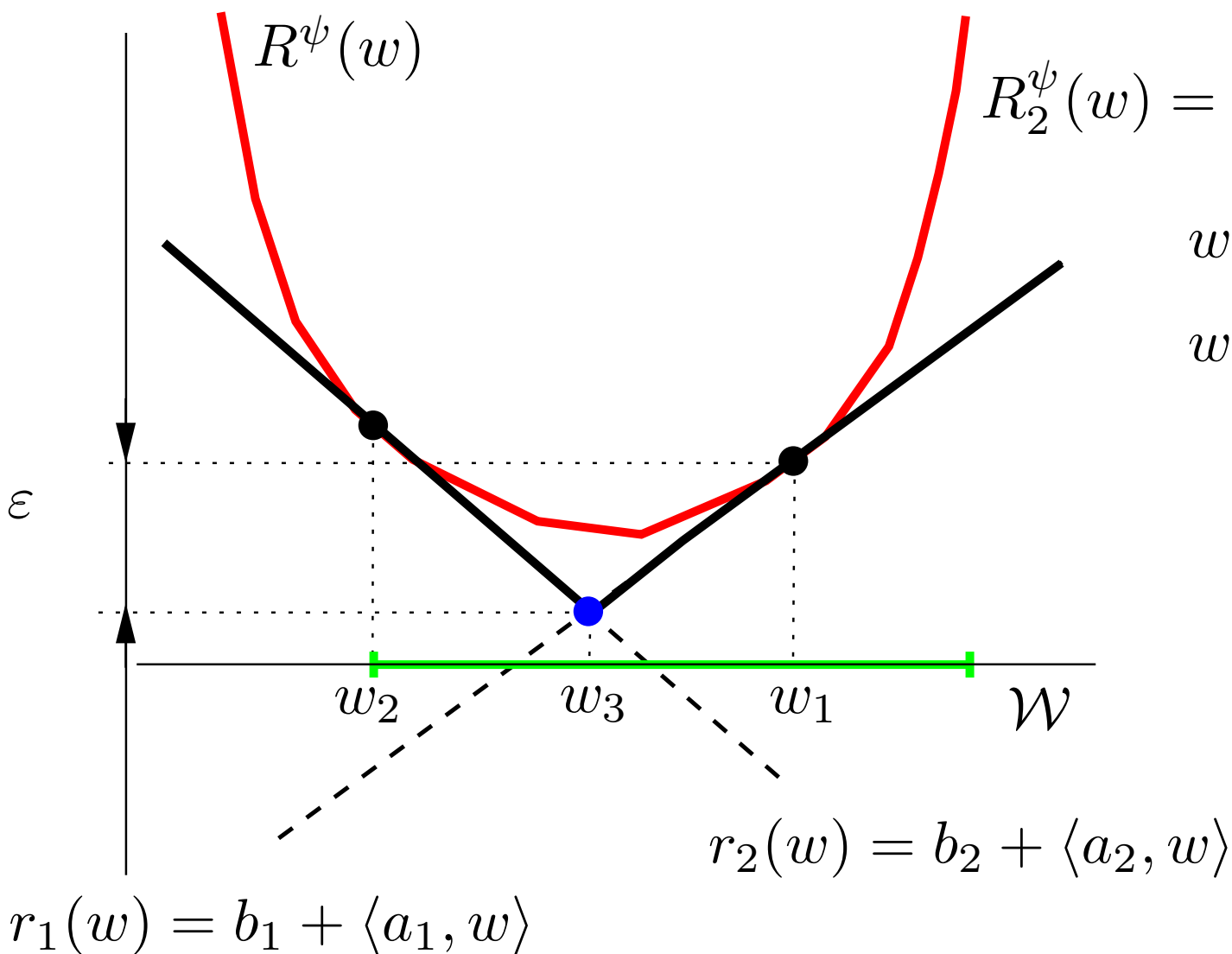
Cutting Plane Algorithm

$$R^\psi(w) = \frac{1}{m} \sum_{i=1}^m \max_{\hat{y}^i \in \mathcal{Y}} (\ell_i(\hat{y}^i) + \langle \phi_i(\hat{y}^i), w \rangle) = \max_{\substack{\hat{y}^1 \in \mathcal{Y} \\ \vdots \\ \hat{y}^m \in \mathcal{Y}}} \frac{1}{m} \sum_{i=1}^m (\ell_i(\hat{y}^i) + \langle \phi_i(\hat{y}^i), w \rangle)$$



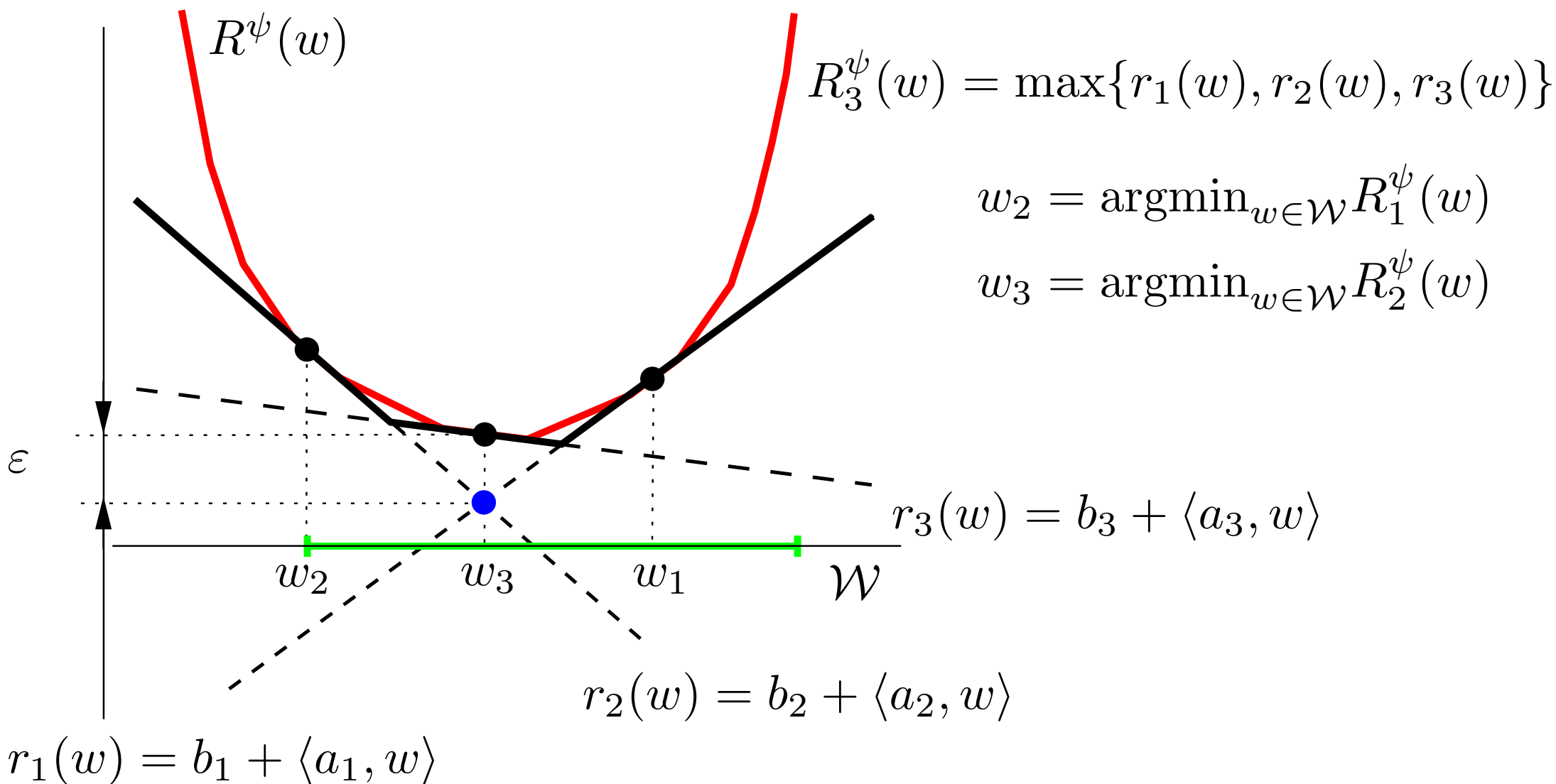
Cutting Plane Algorithm

$$R^\psi(w) = \frac{1}{m} \sum_{i=1}^m \max_{\hat{y}^i \in \mathcal{Y}} (\ell_i(\hat{y}^i) + \langle \phi_i(\hat{y}^i), w \rangle) = \max_{\substack{\hat{y}^1 \in \mathcal{Y} \\ \vdots \\ \hat{y}^m \in \mathcal{Y}}} \frac{1}{m} \sum_{i=1}^m (\ell_i(\hat{y}^i) + \langle \phi_i(\hat{y}^i), w \rangle)$$



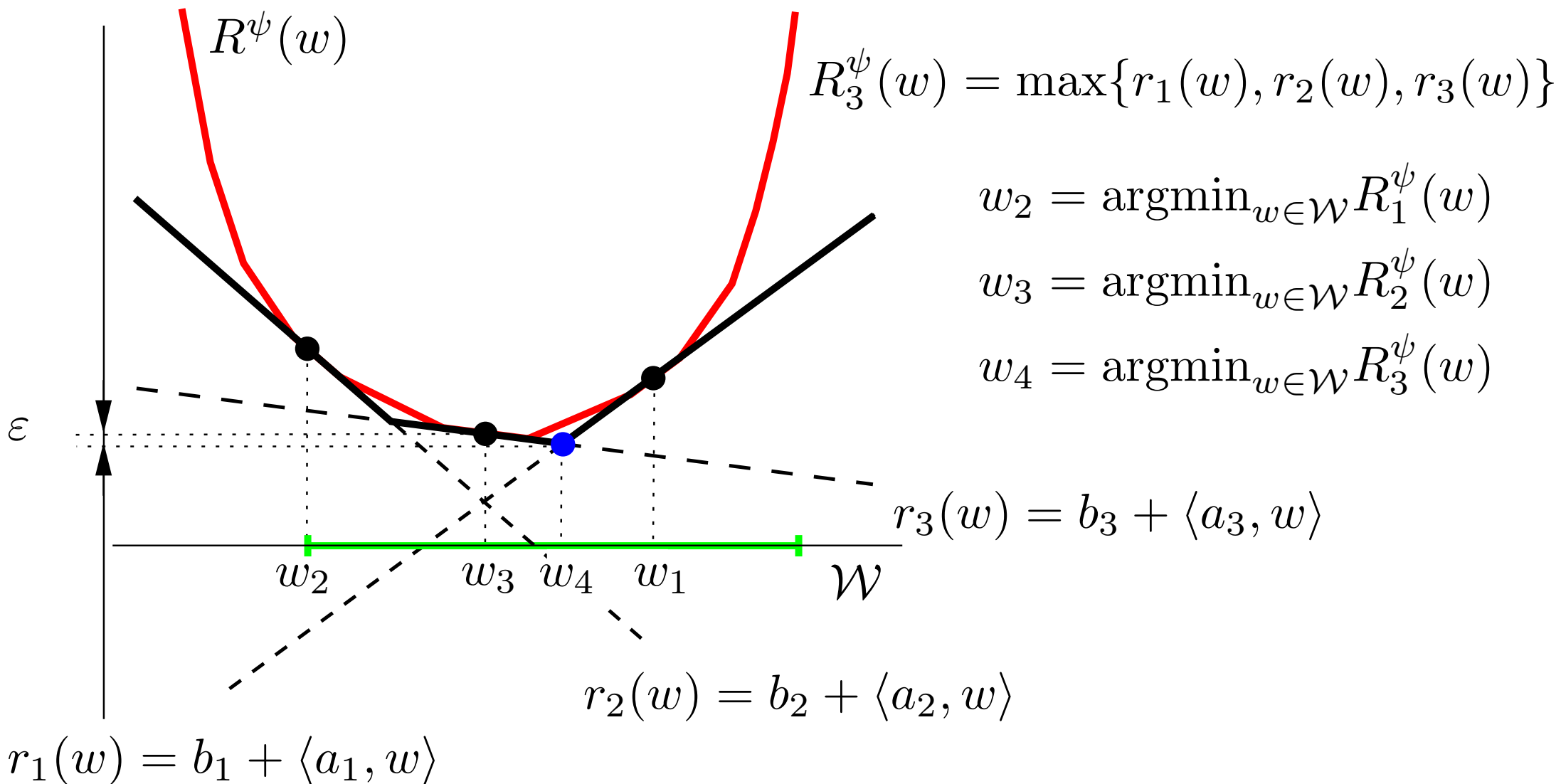
Cutting Plane Algorithm

$$R^\psi(w) = \frac{1}{m} \sum_{i=1}^m \max_{\hat{y}^i \in \mathcal{Y}} (\ell_i(\hat{y}^i) + \langle \phi_i(\hat{y}^i), w \rangle) = \max_{\substack{\hat{y}^1 \in \mathcal{Y} \\ \vdots \\ \hat{y}^m \in \mathcal{Y}}} \frac{1}{m} \sum_{i=1}^m (\ell_i(\hat{y}^i) + \langle \phi_i(\hat{y}^i), w \rangle)$$



Cutting Plane Algorithm

$$R^\psi(w) = \frac{1}{m} \sum_{i=1}^m \max_{\hat{y}^i \in \mathcal{Y}} (\ell_i(\hat{y}^i) + \langle \phi_i(\hat{y}^i), w \rangle) = \max_{\substack{\hat{y}^1 \in \mathcal{Y} \\ \vdots \\ \hat{y}^m \in \mathcal{Y}}} \frac{1}{m} \sum_{i=1}^m (\ell_i(\hat{y}^i) + \langle \phi_i(\hat{y}^i), w \rangle)$$



Cutting plane algorithm (version 1)

1. $\mathbf{w}_1 \in \mathcal{W}$, $t \leftarrow 1$
2. Compute a new cutting plane and the objective value:

$$\mathbf{a}_t = \frac{1}{m} \sum_{i=1}^m \phi_i(\hat{y}^i), \quad b_t = \frac{1}{m} \sum_{i=1}^m \ell_i(\hat{y}^i), \quad R^\psi(\mathbf{w}_t) = b_t + \langle \mathbf{w}_t, \mathbf{a}_t \rangle$$

where \hat{y}^i is a solutions of **loss augmented prediction** problem:

$$\hat{y}^i = \operatorname{argmax}_{y \in \mathcal{Y}} (\ell_i(y) + \langle \mathbf{w}, \phi_i(y) \rangle) = \operatorname{argmax}_{y \in \mathcal{Y}} (\ell(y^i, y) + \langle \mathbf{w}, \phi(x^i, y) \rangle)$$

3. Solve a reduced problem

$$\mathbf{w}_{t+1} = \operatorname{argmin}_{\mathbf{w} \in \mathcal{W}} R_t^\psi(\mathbf{w}) \quad \text{where} \quad R_t^\psi(\mathbf{w}) = \max_{i=1, \dots, t} (b_i + \langle \mathbf{w}, \mathbf{a}_i \rangle)$$

4. If $\min_{i=1, \dots, t+1} R(\mathbf{w}_t) - R^\psi(\mathbf{w}_{t+1}) \leq \varepsilon$ exit else $t \leftarrow t + 1$ and go to 2.

Cutting plane algorithm (version 2)

1. $\mathbf{w}_1 \in \mathbb{R}^n$, $t \leftarrow 1$
2. Compute a new cutting plane and the objective value:

$$\mathbf{a}_t = \frac{1}{m} \sum_{i=1}^m \phi_i(\hat{y}^i), \quad b_t = \frac{1}{m} \sum_{i=1}^m \ell_i(\hat{y}^i), \quad R^\psi(\mathbf{w}_t) = b_t + \langle \mathbf{w}_t, \mathbf{a}_t \rangle$$

where \hat{y}^i is a solutions of **loss augmented prediction** problem:

$$\hat{y}^i = \operatorname{argmax}_{y \in \mathcal{Y}} (\ell_i(y) + \langle \mathbf{w}, \phi_i(y) \rangle) = \operatorname{argmax}_{y \in \mathcal{Y}} (\ell(y^i, y) + \langle \mathbf{w}, \phi(x^i, y) \rangle)$$

3. Solve a reduced problem

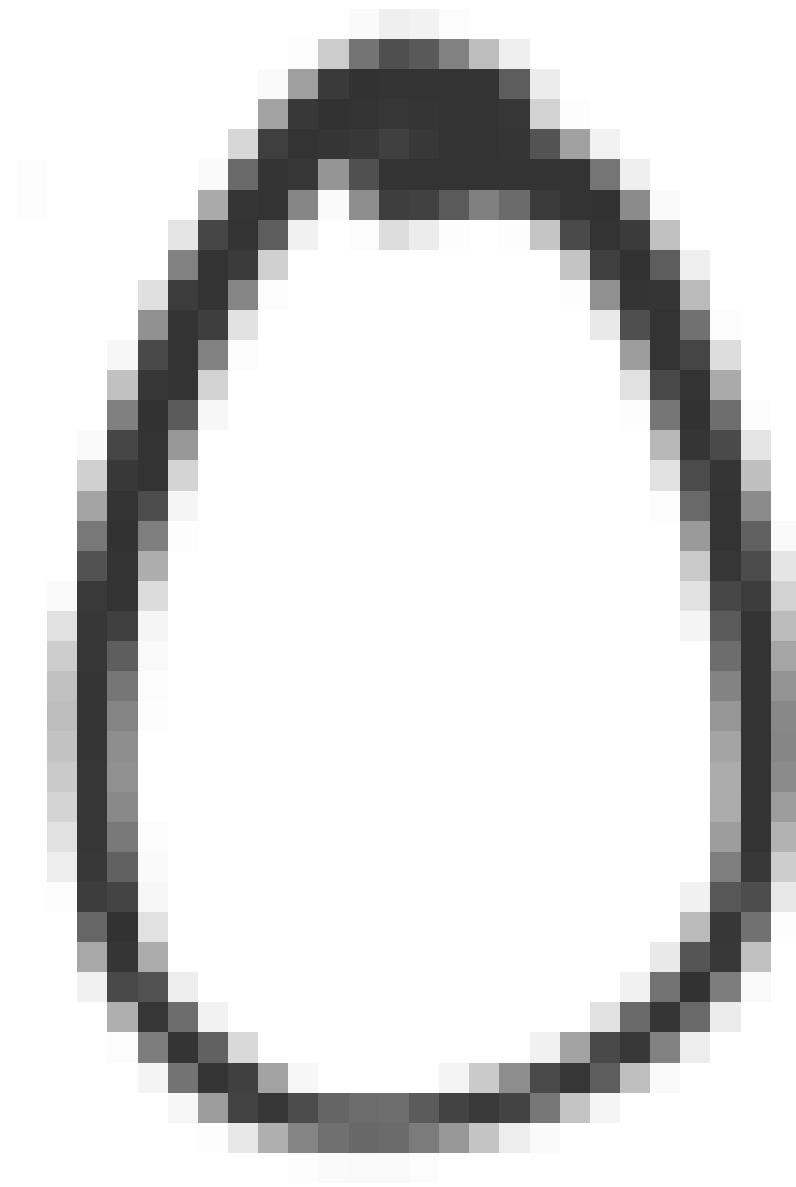
$$\mathbf{w}_{t+1} = \operatorname{argmin}_{\mathbf{w} \in \mathbb{R}^n} \left(\frac{\lambda}{2} \|\mathbf{w}\|^2 + R_t^\psi(\mathbf{w}) \right) \quad \text{where} \quad R_t^\psi(\mathbf{w}) = \max_{i=1, \dots, t} (b_i + \langle \mathbf{w}, \mathbf{a}_i \rangle)$$

4. If $\min_{i=1, \dots, t+1} R(\mathbf{w}_t) - R^\psi(\mathbf{w}_{t+1}) \leq \varepsilon$ exit else $t \leftarrow t + 1$ and go to 2.

Summary

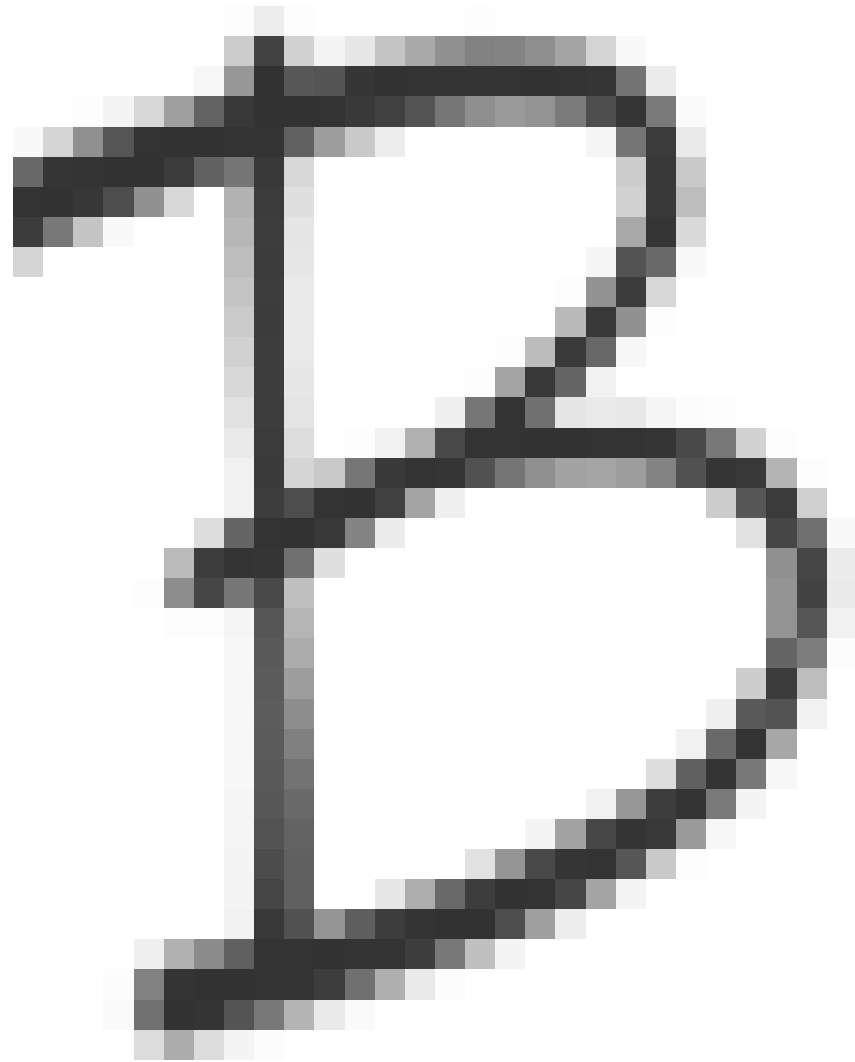
- ◆ Generic linear classifier
- ◆ Structured Output Perceptron
- ◆ Structured Output Support Vector Machines
- ◆ Cutting Plane Algorithm

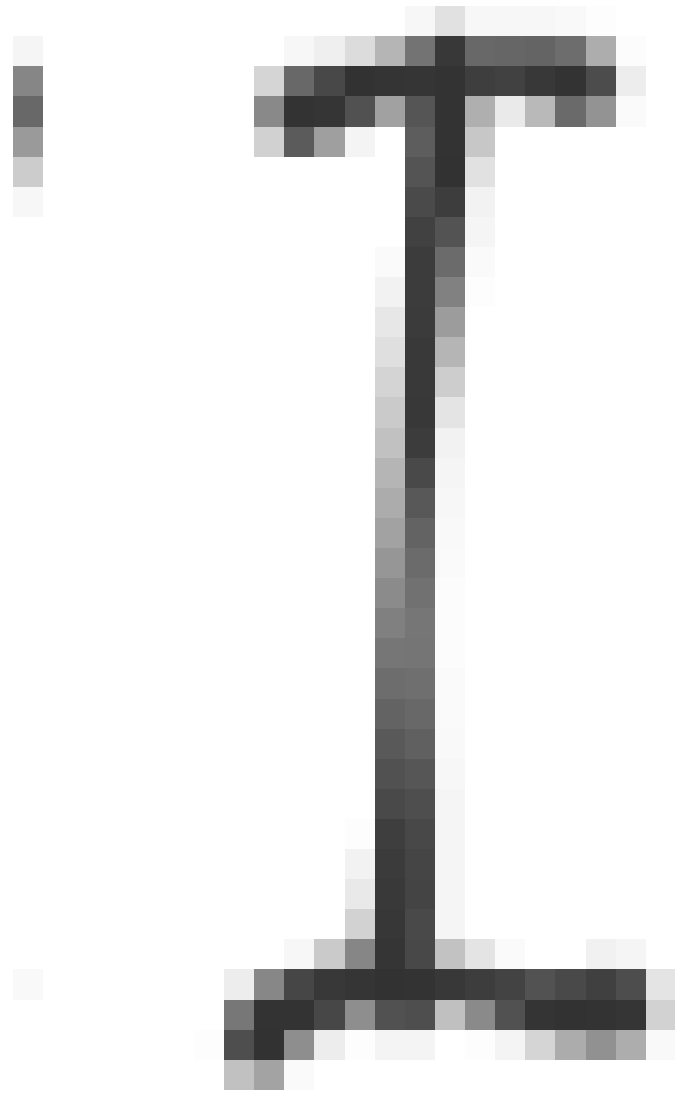


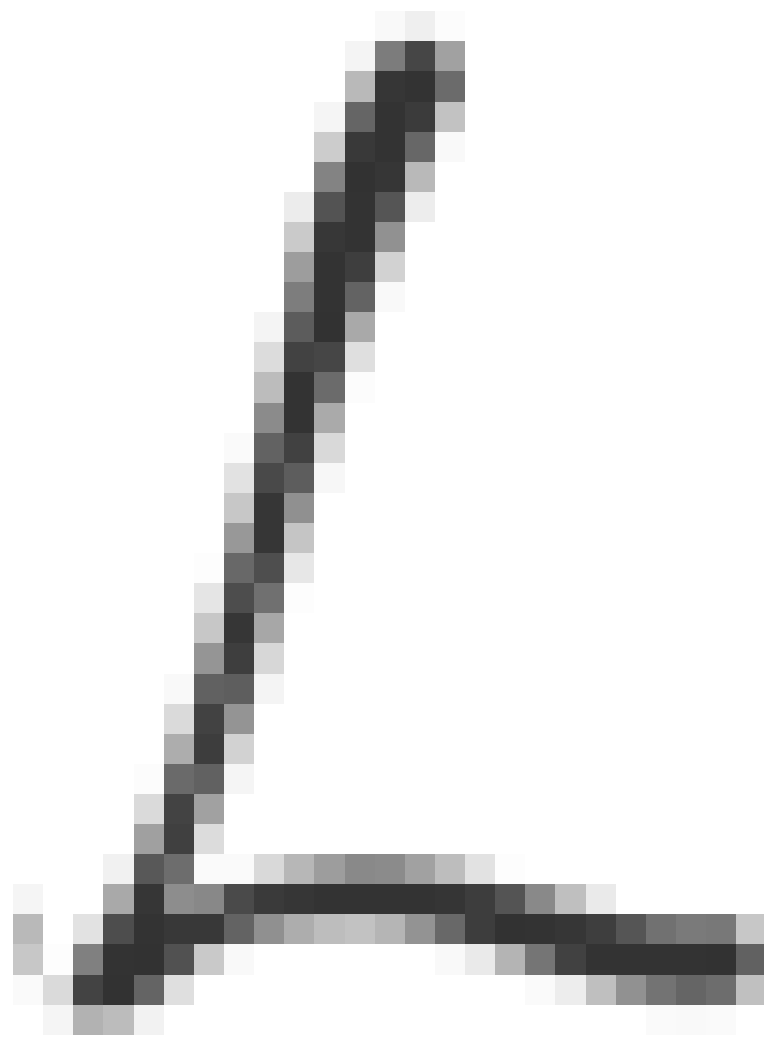


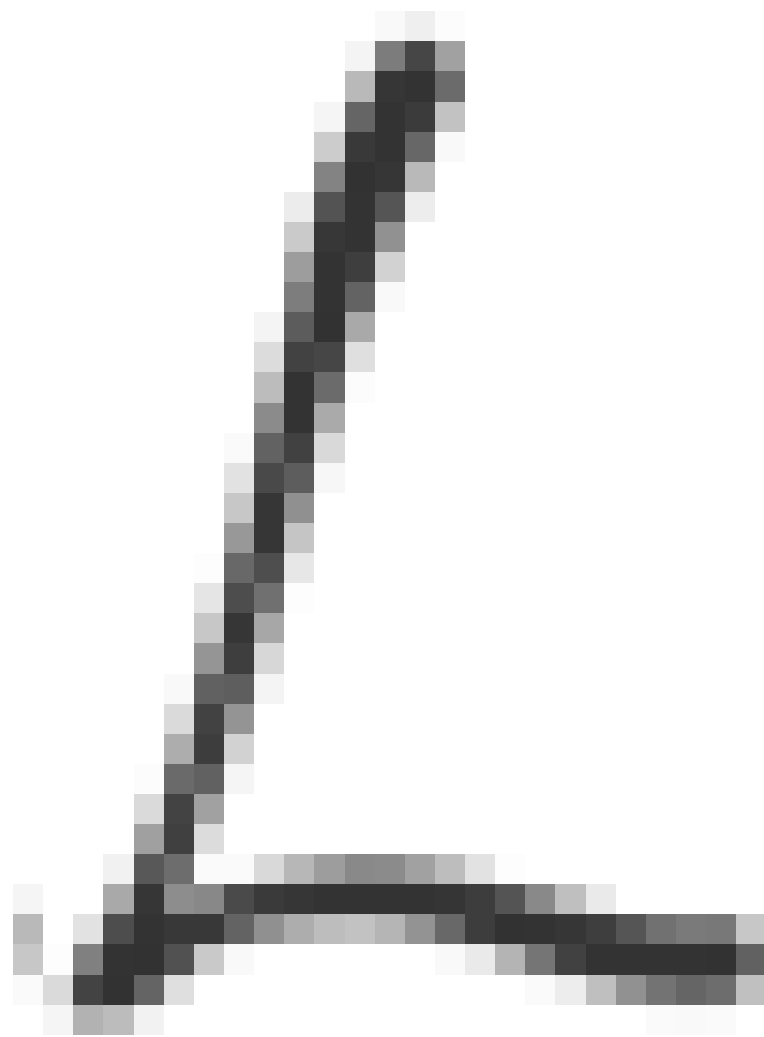


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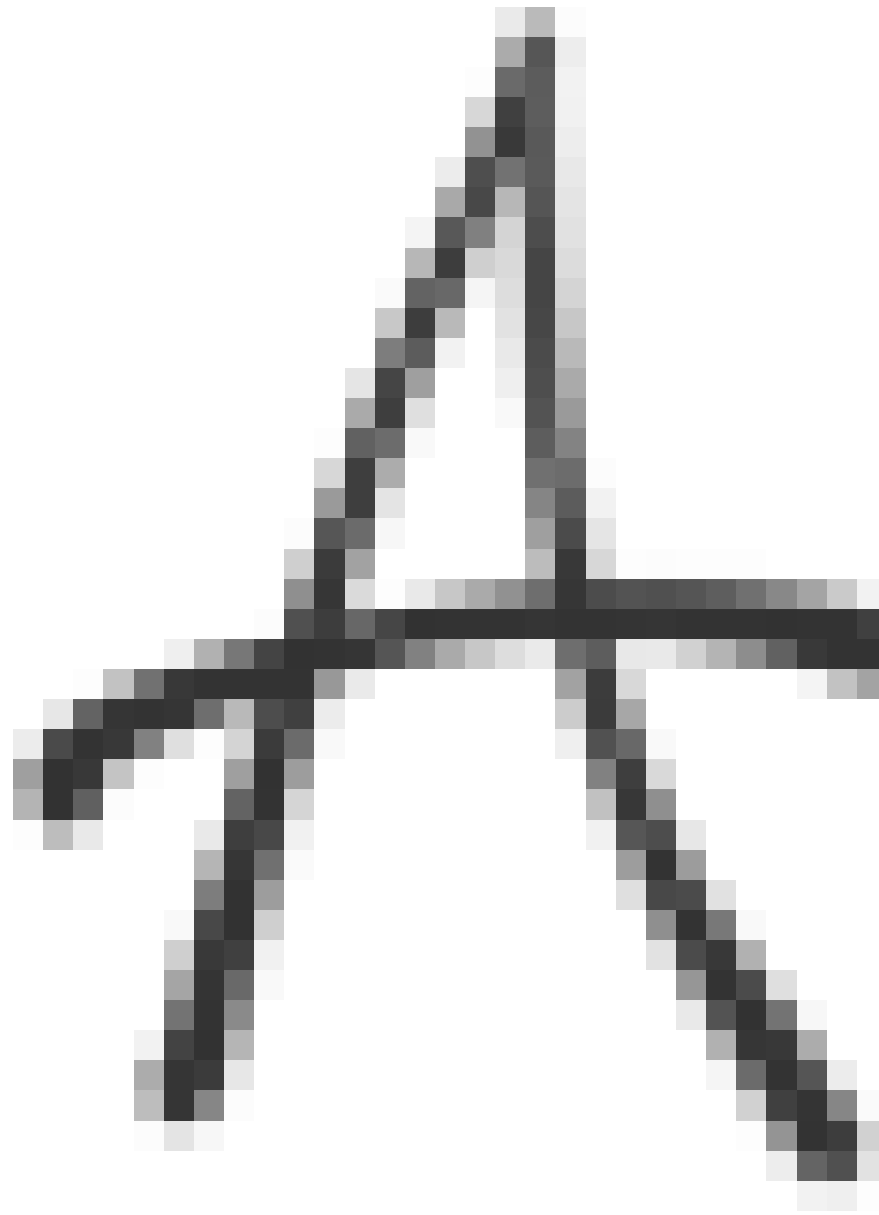




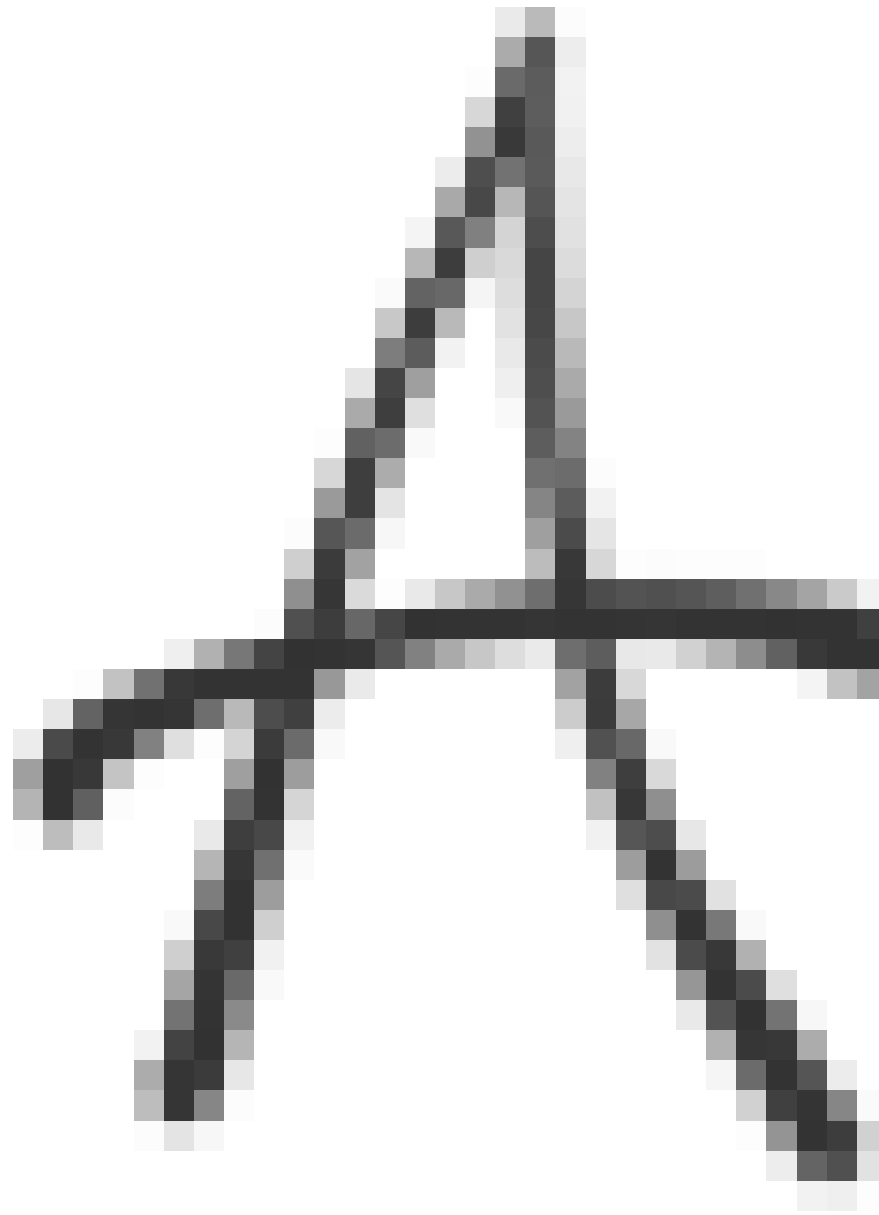


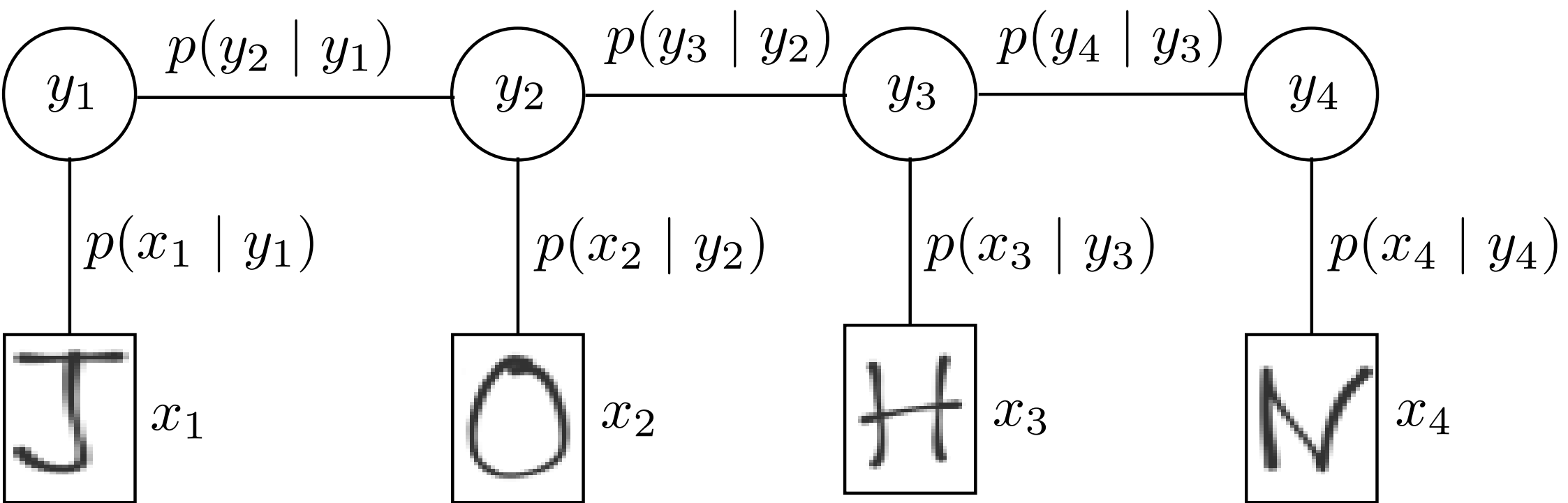


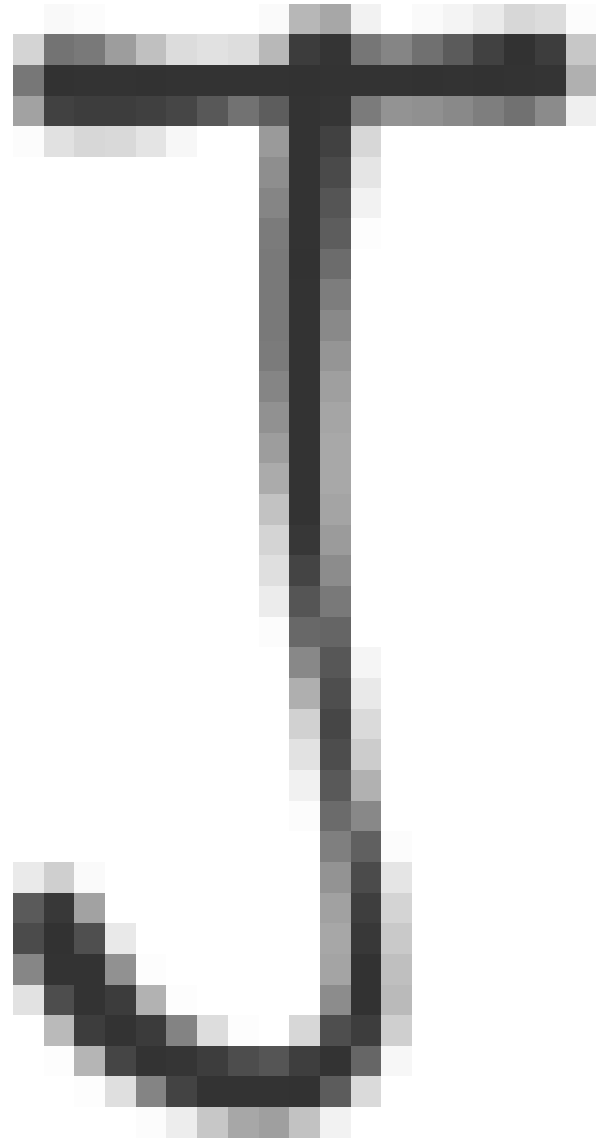


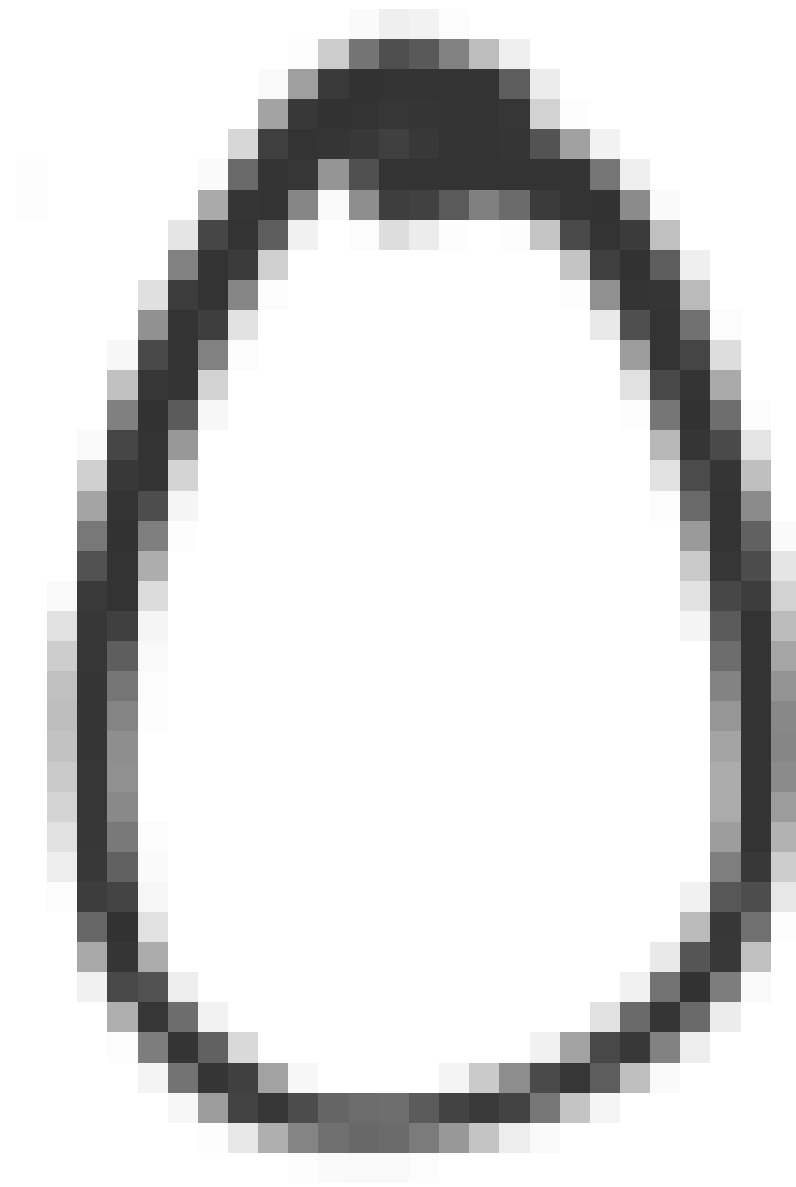


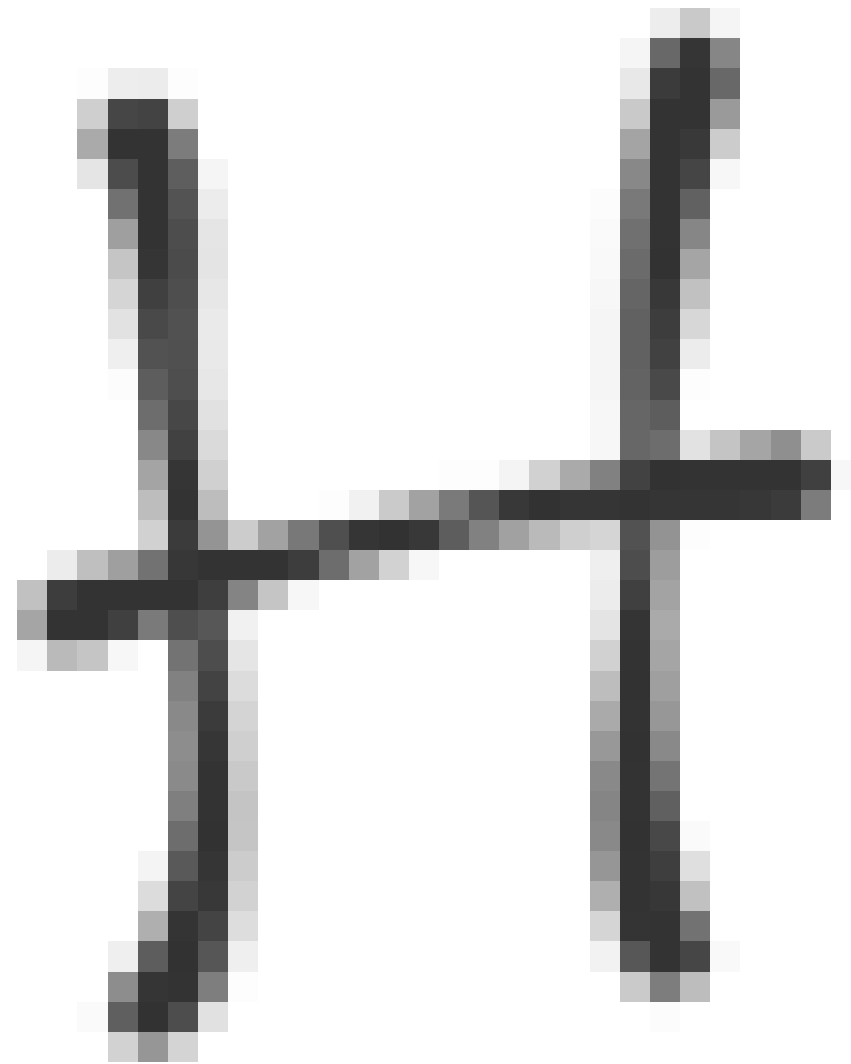
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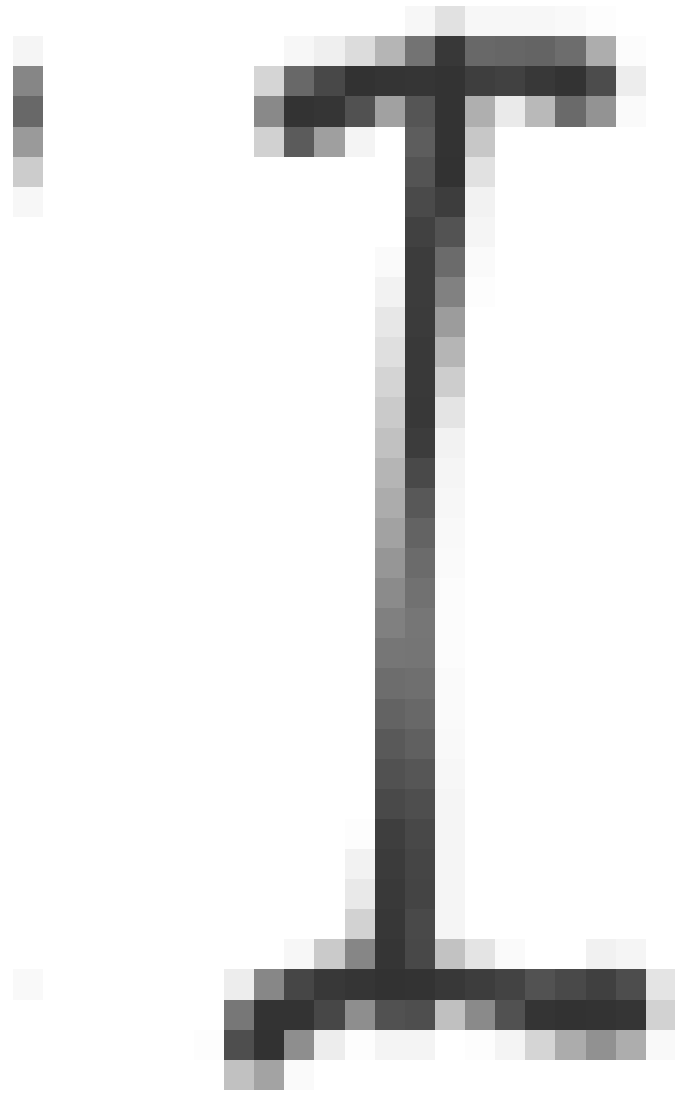


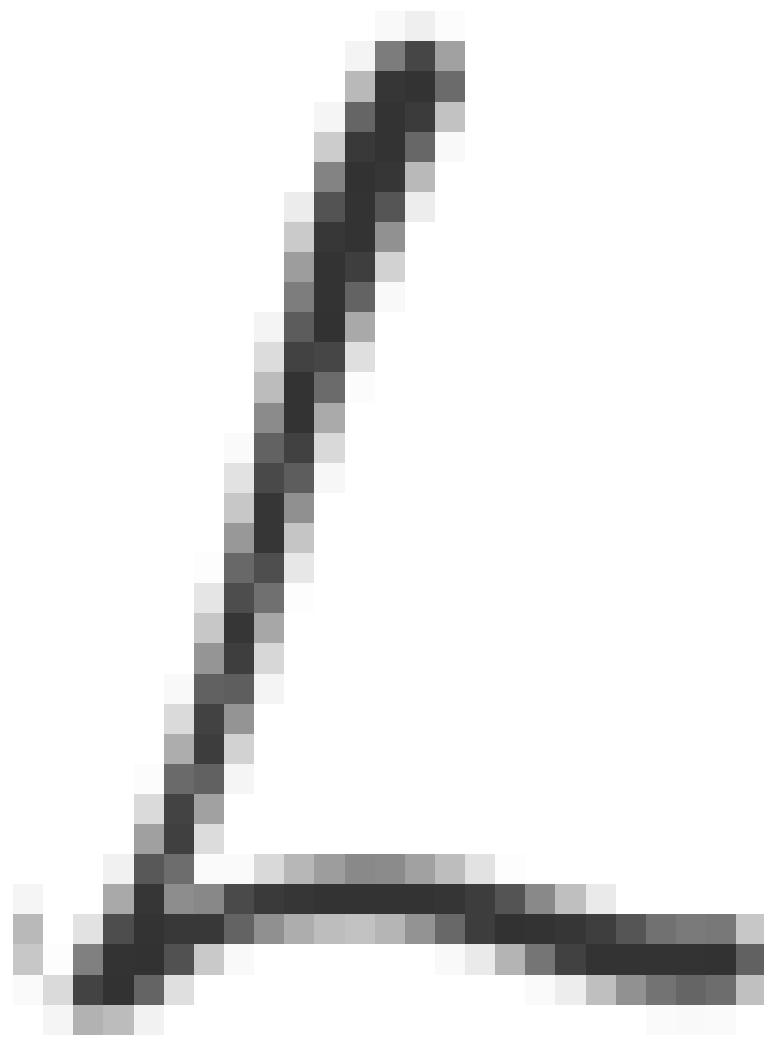


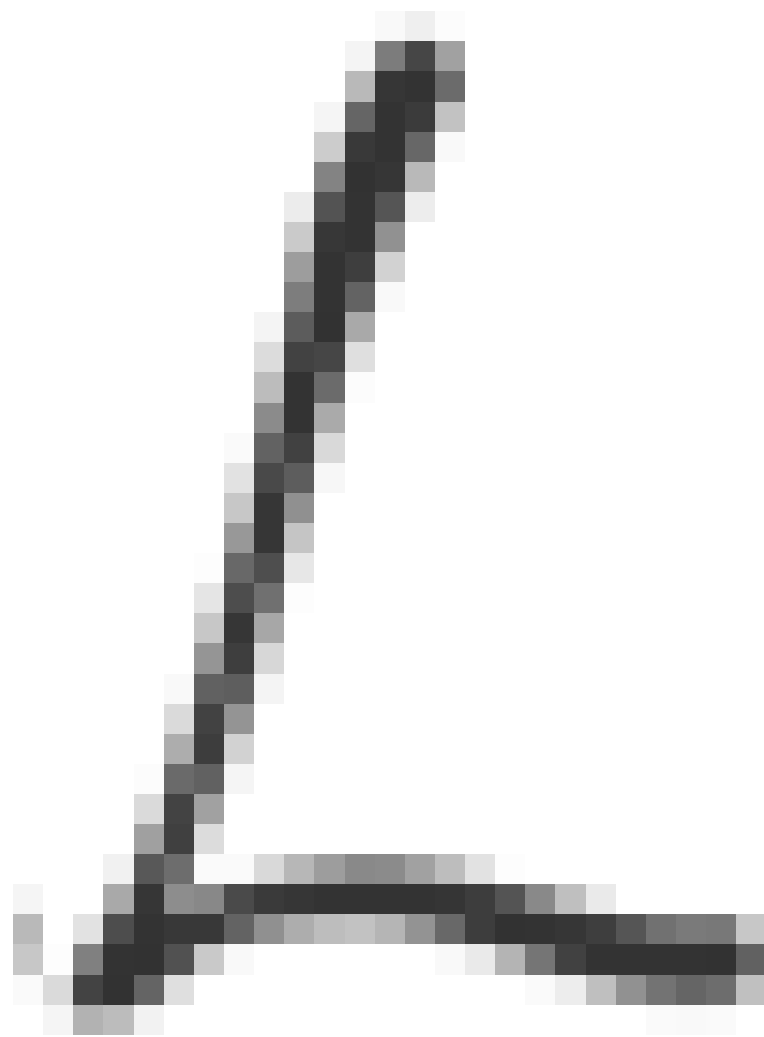


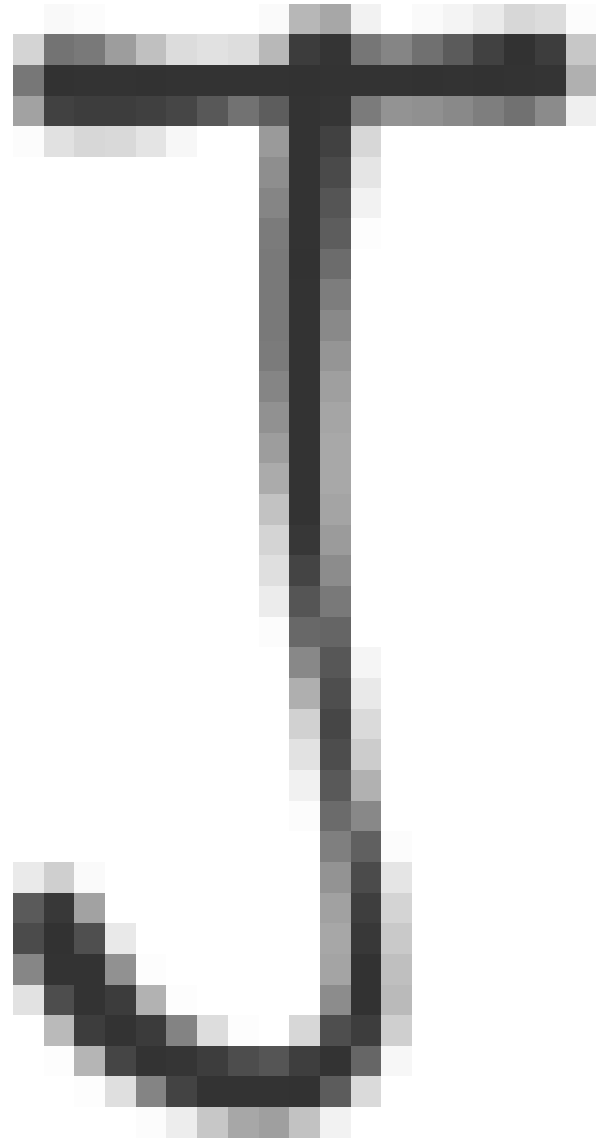
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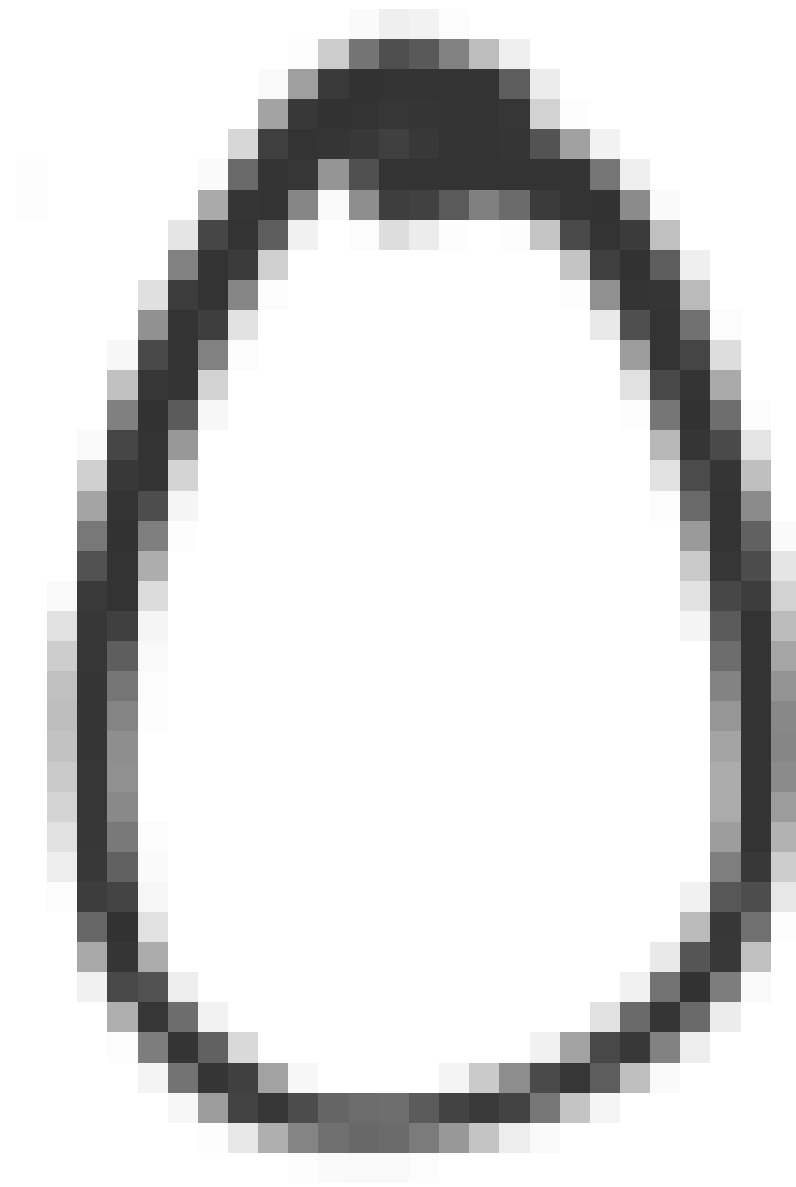


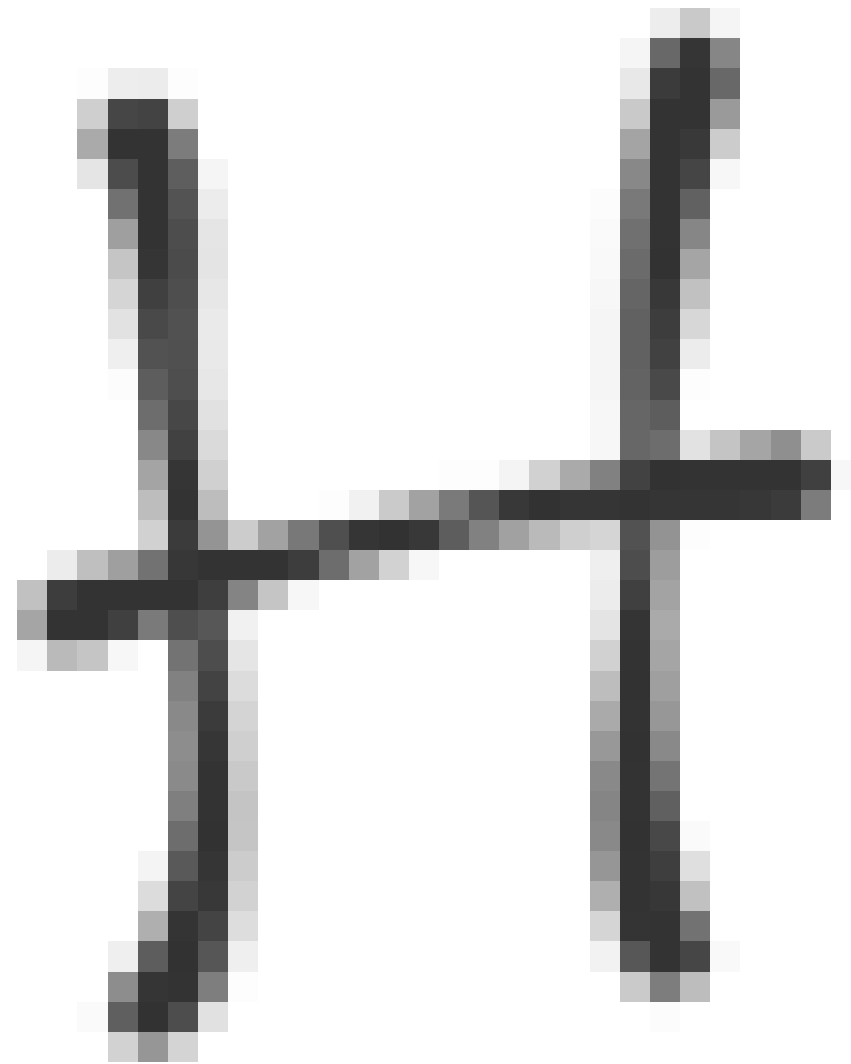




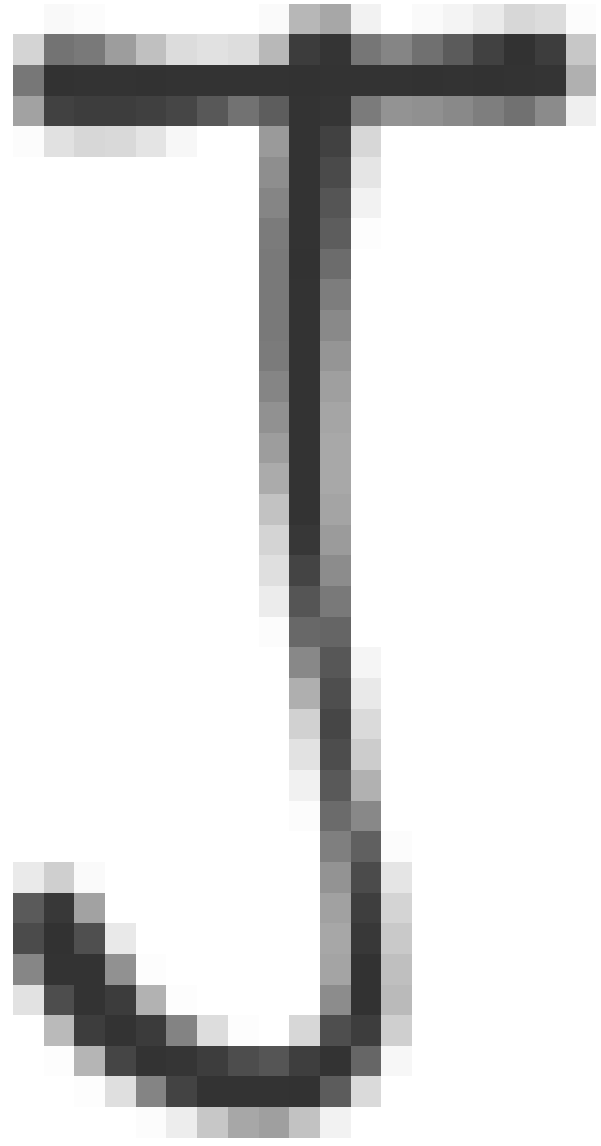


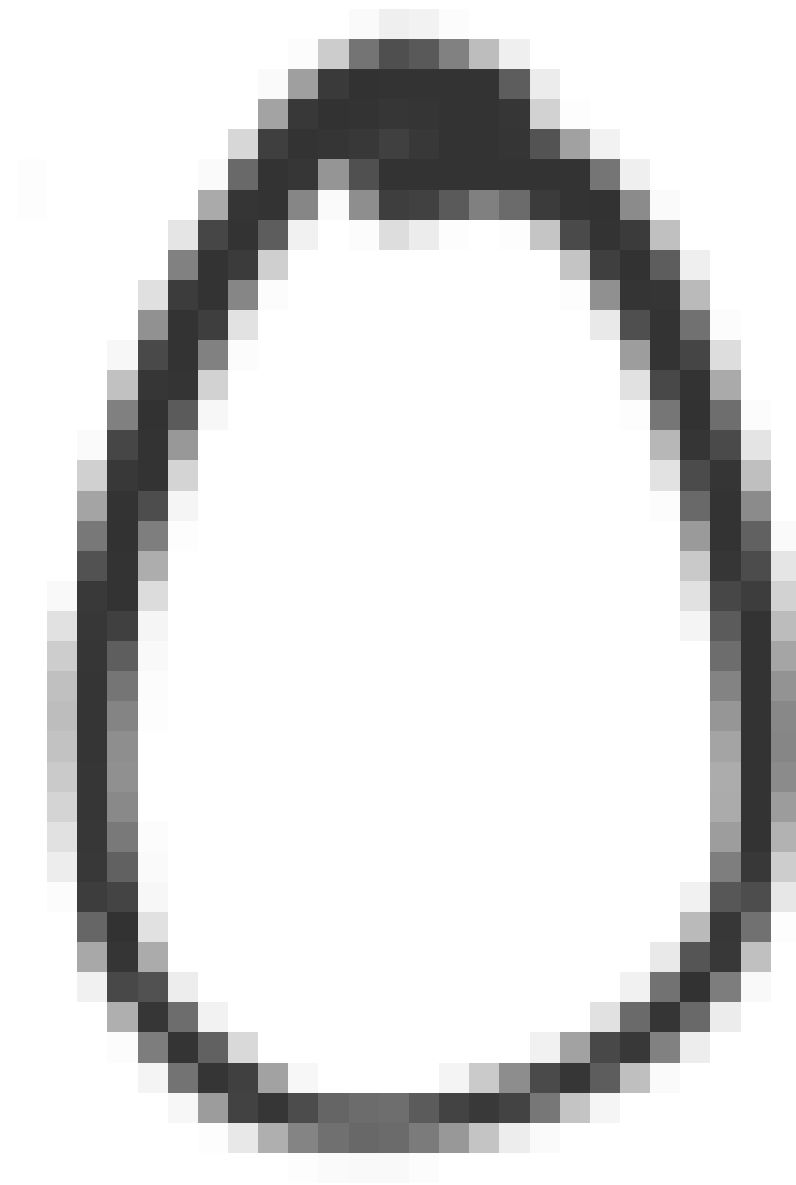


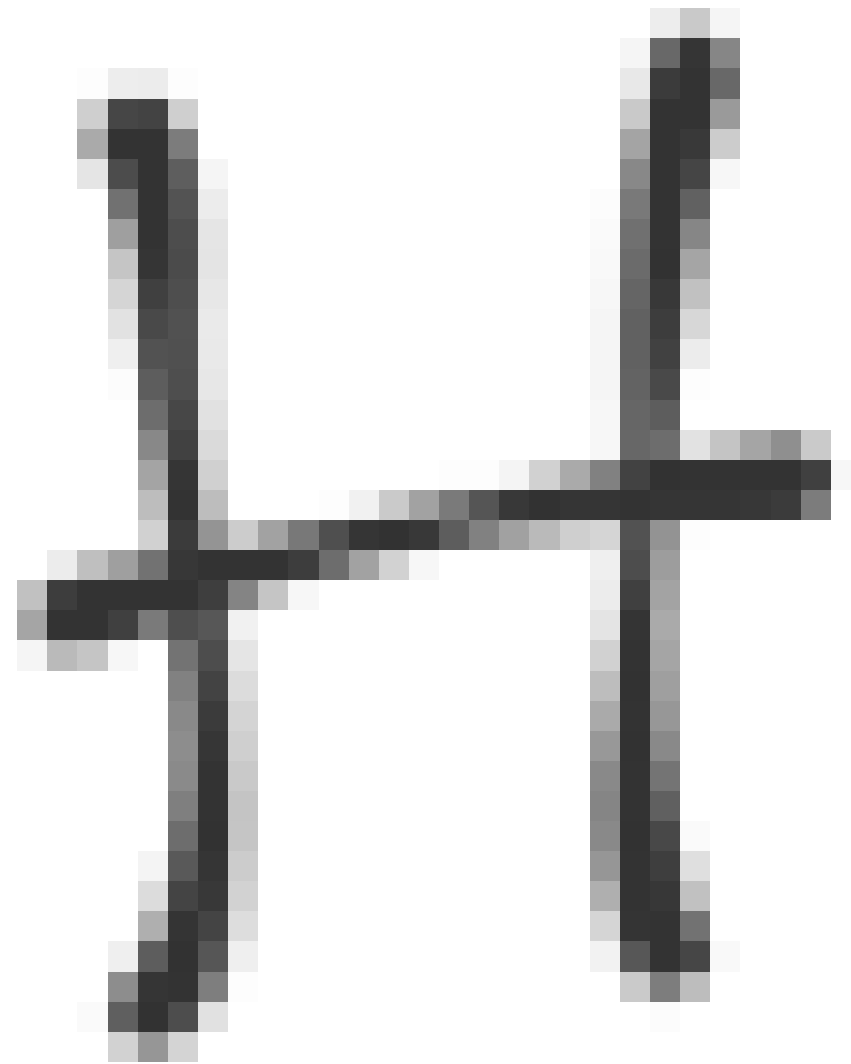




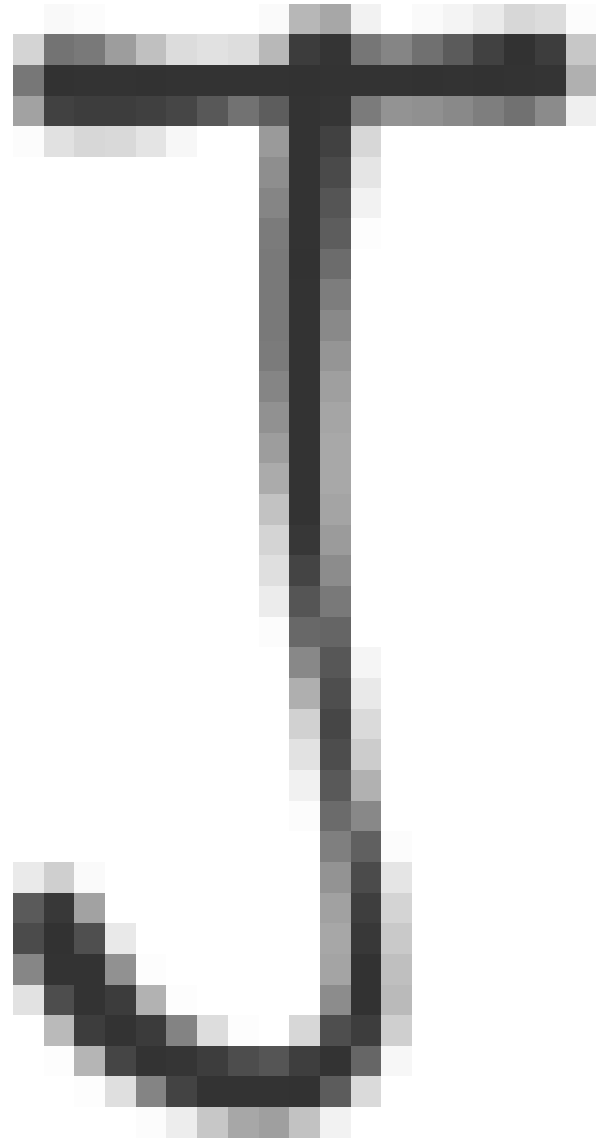
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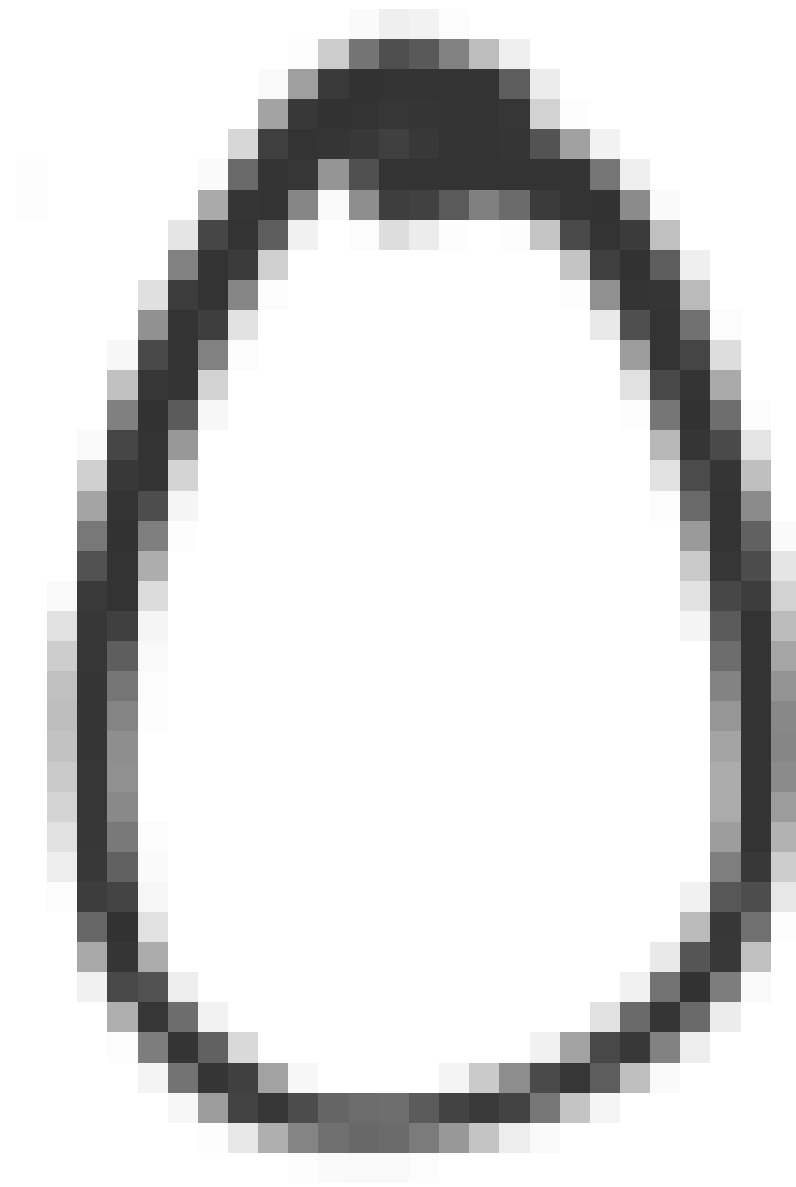


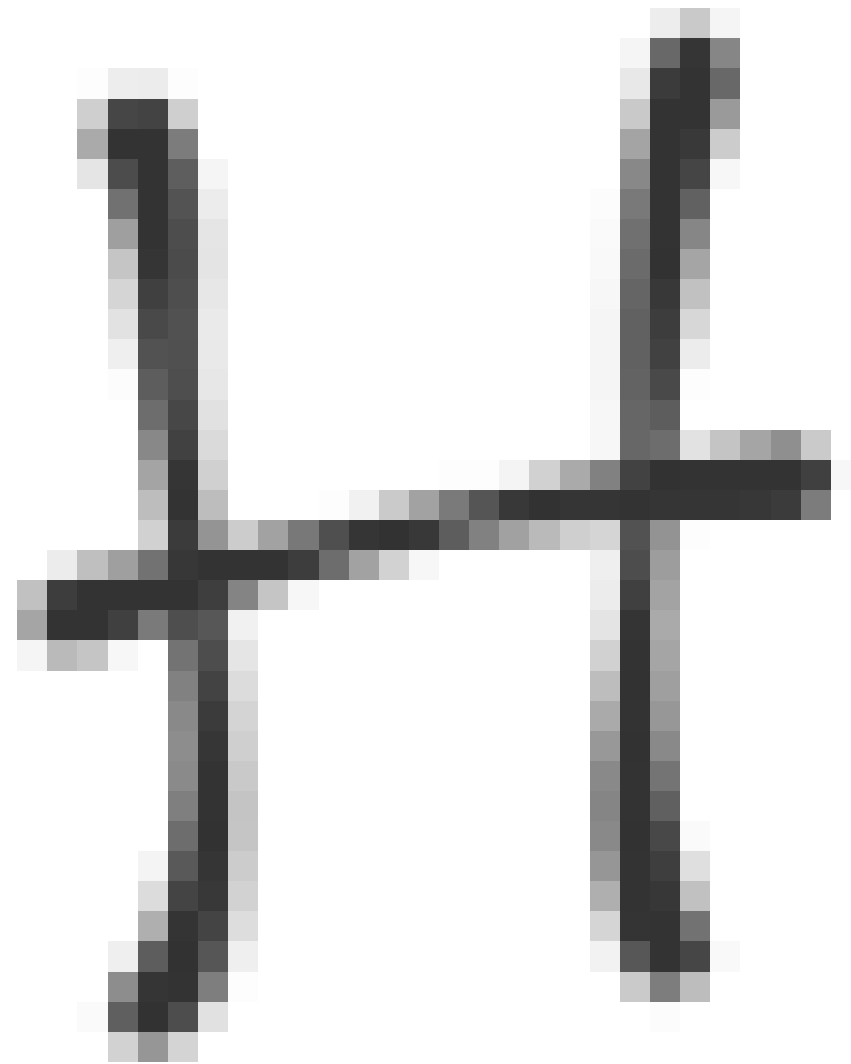




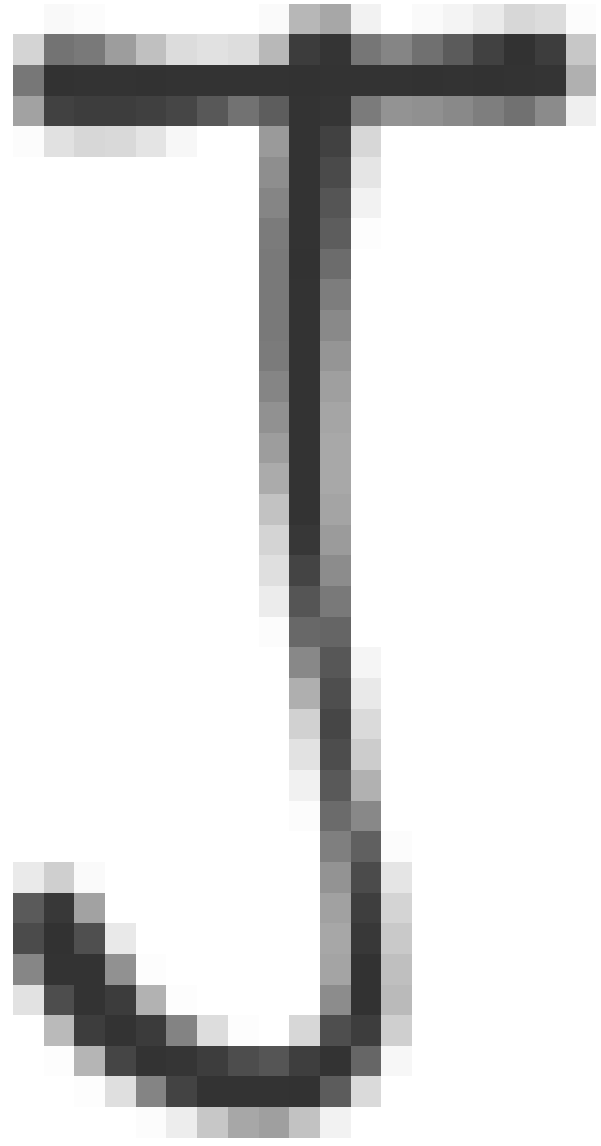
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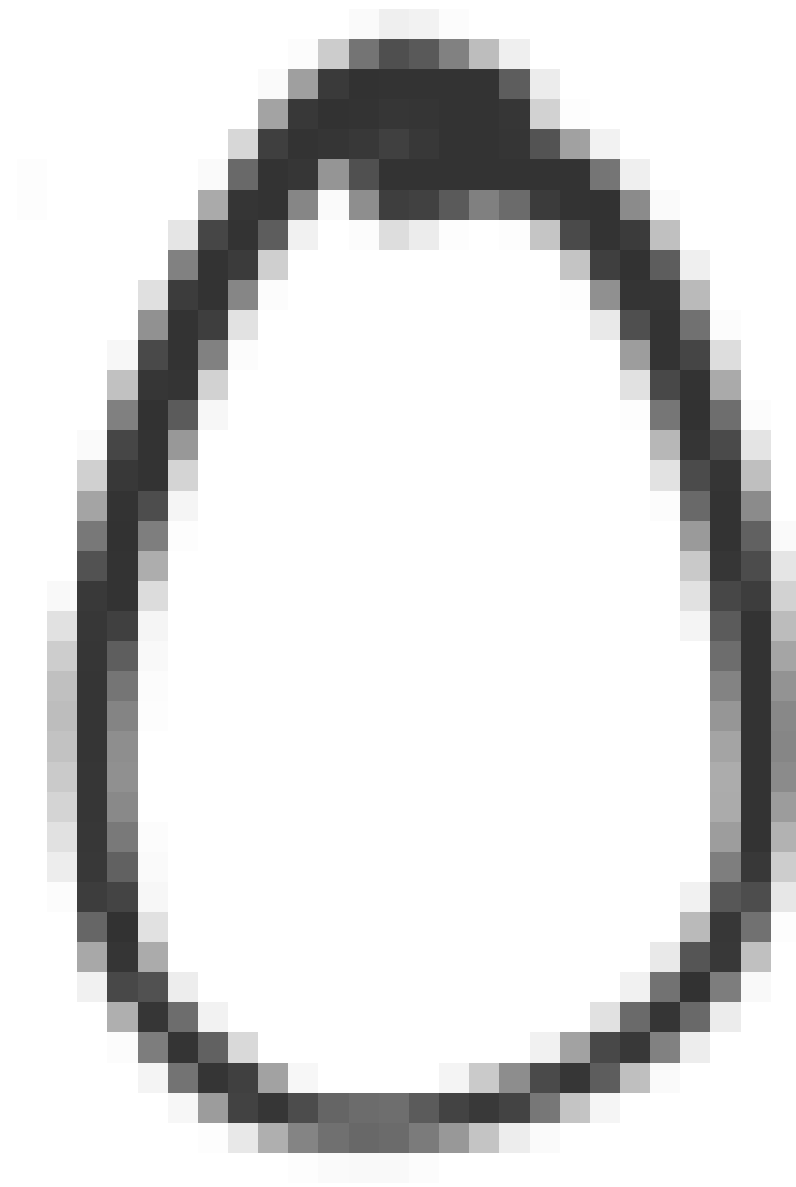


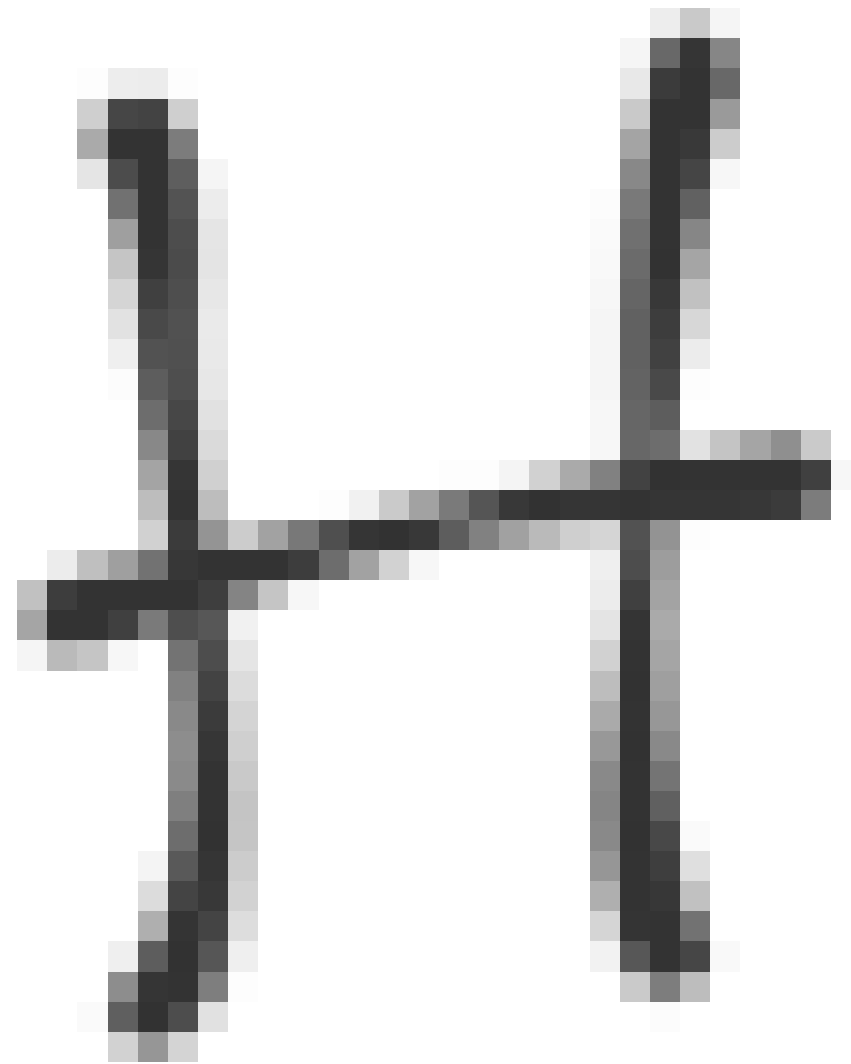




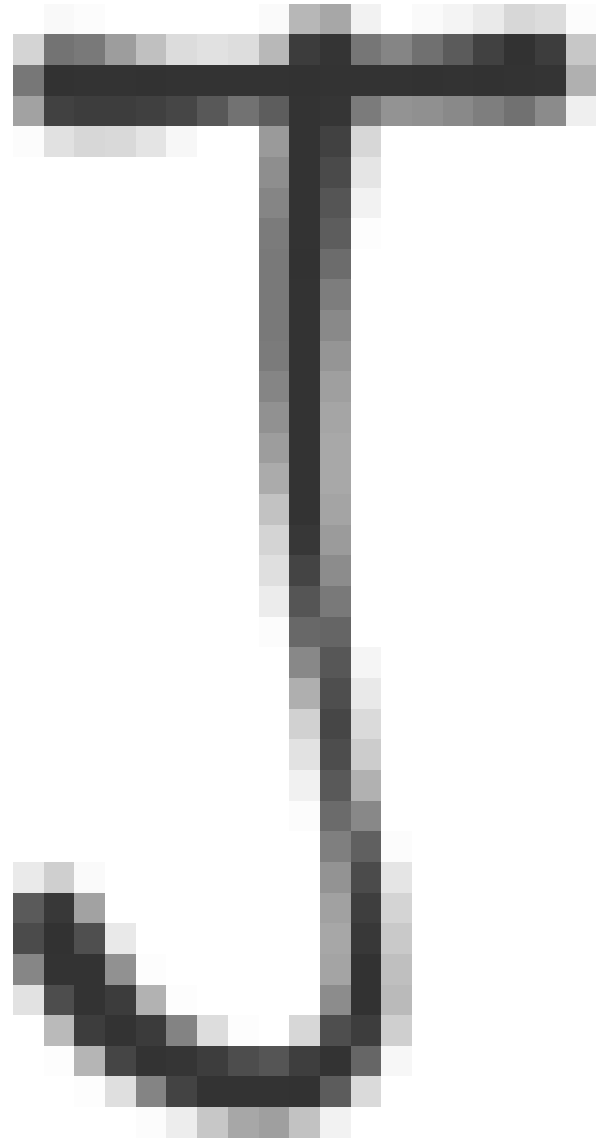
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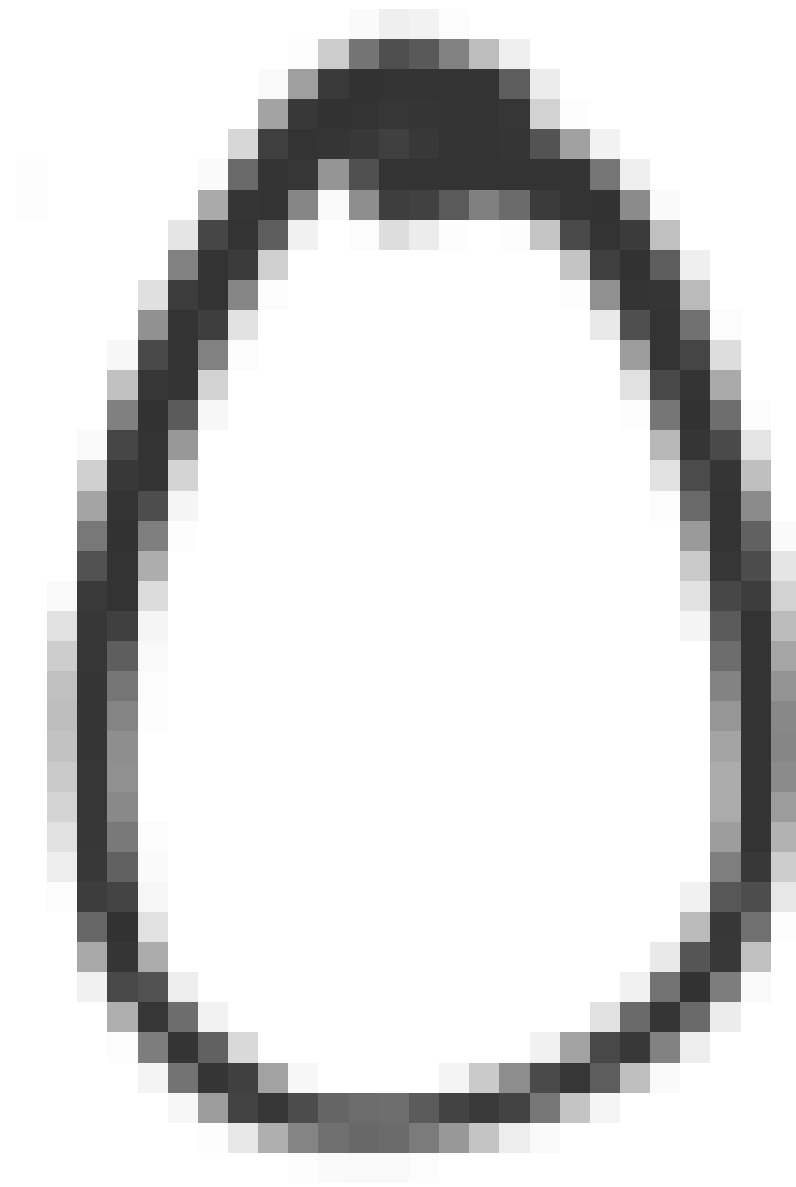


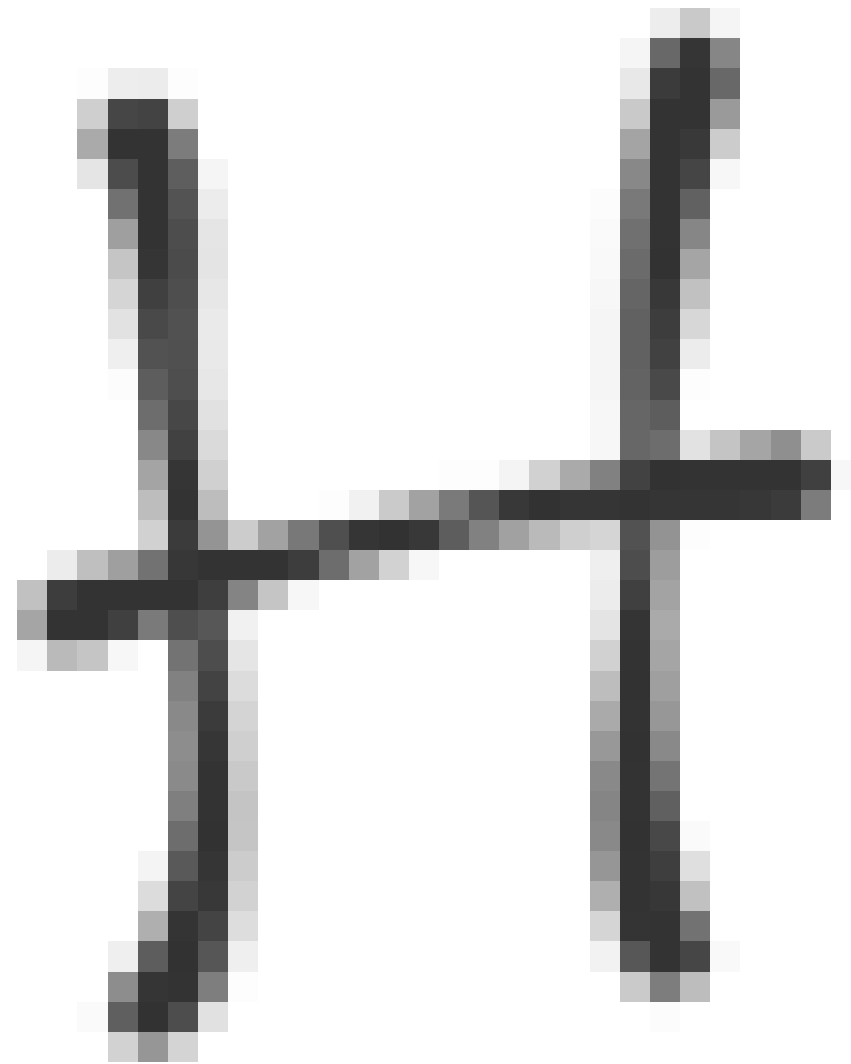




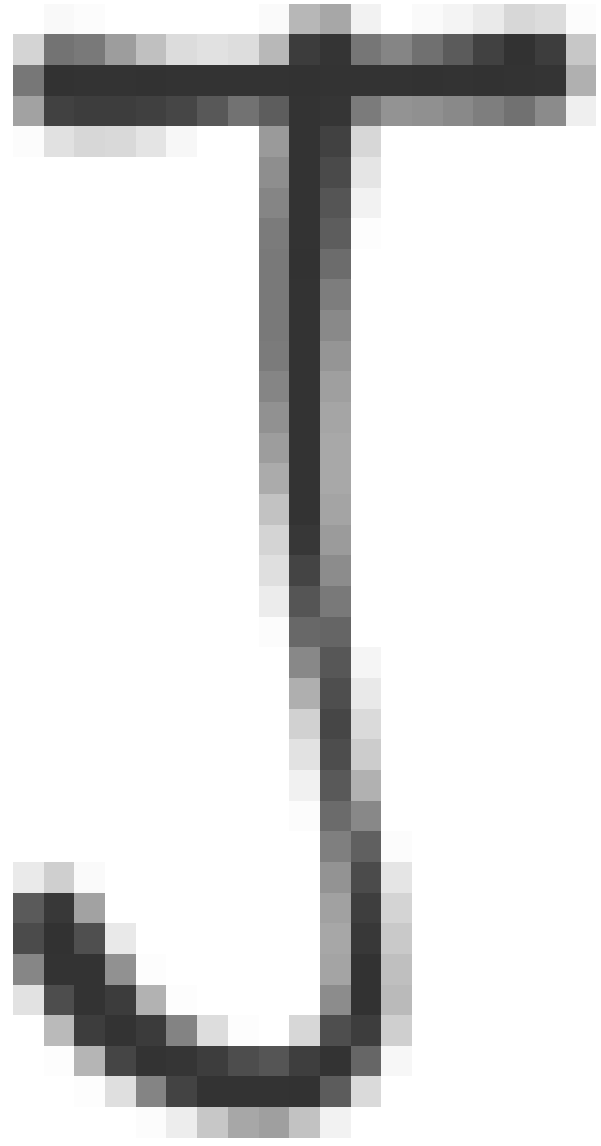
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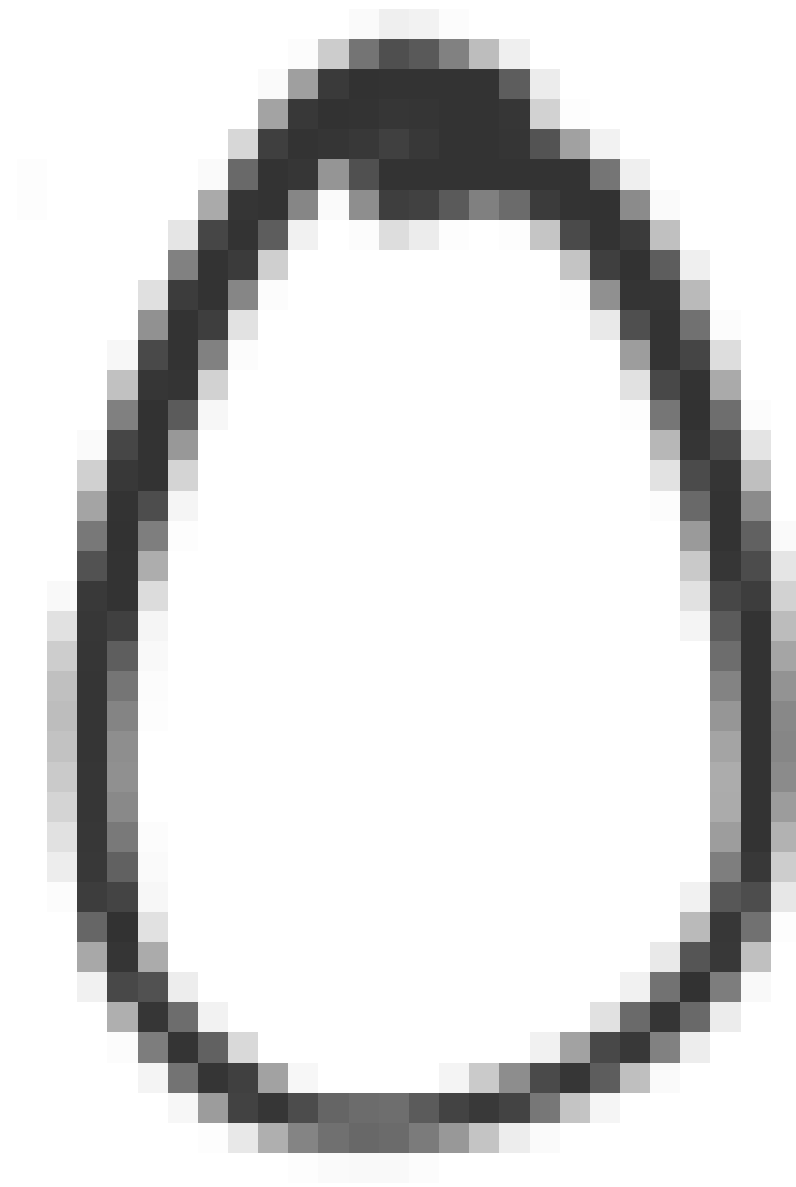


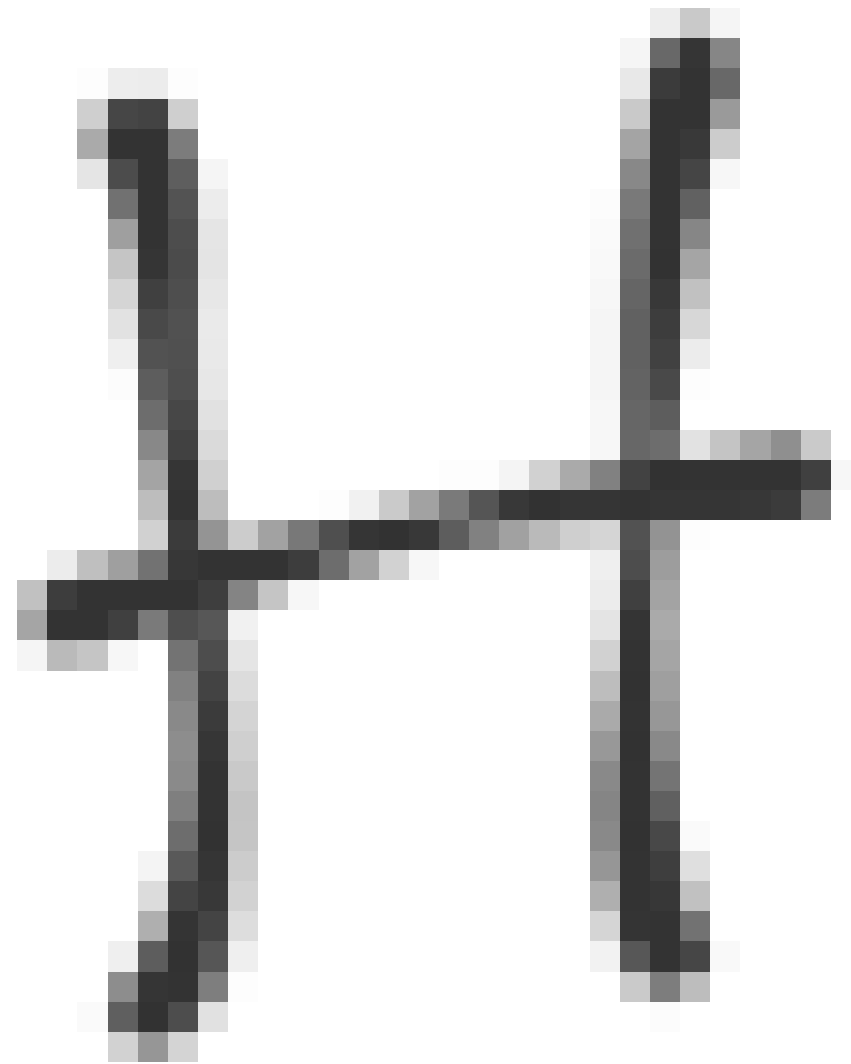




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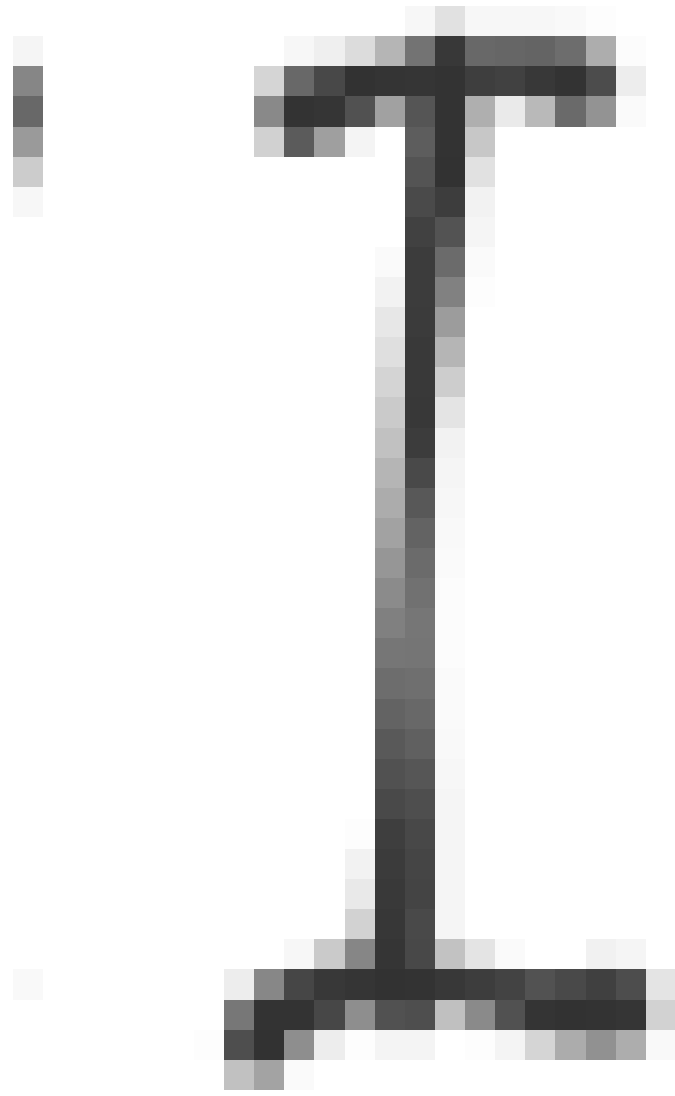


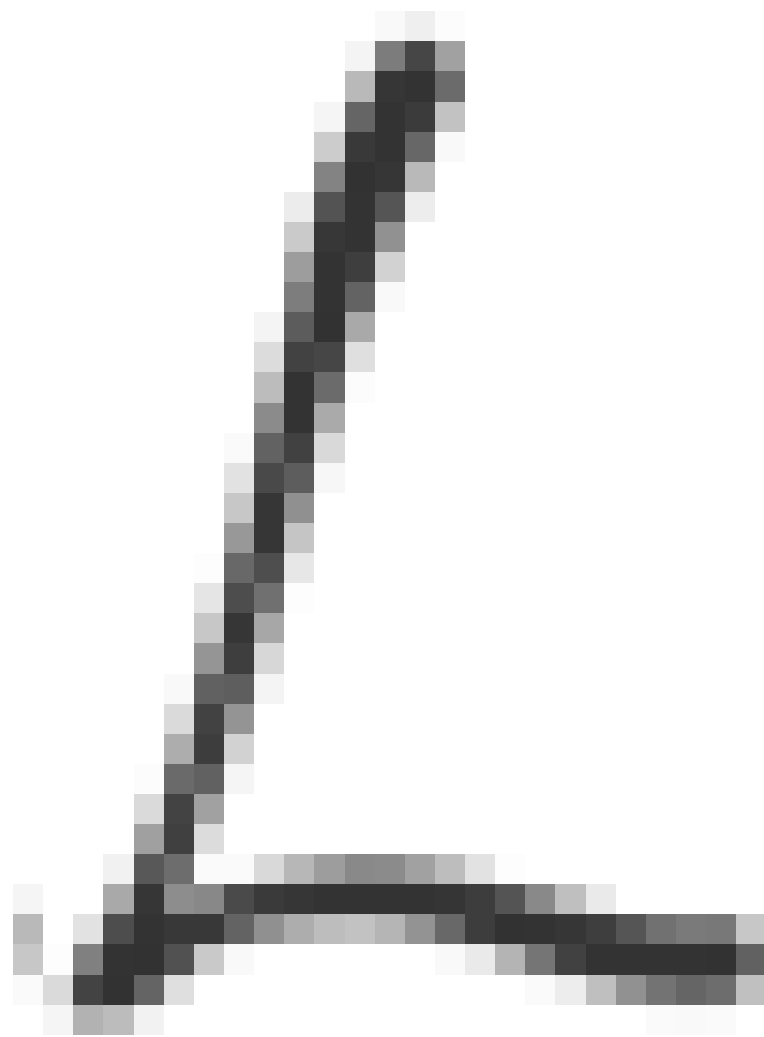


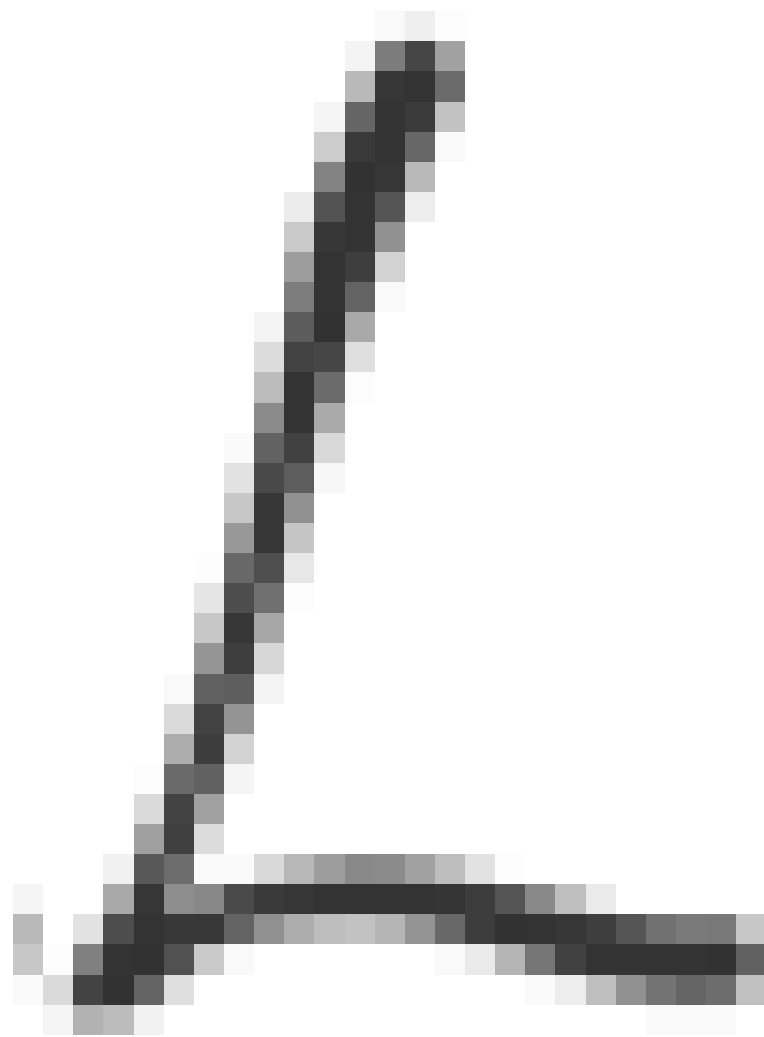


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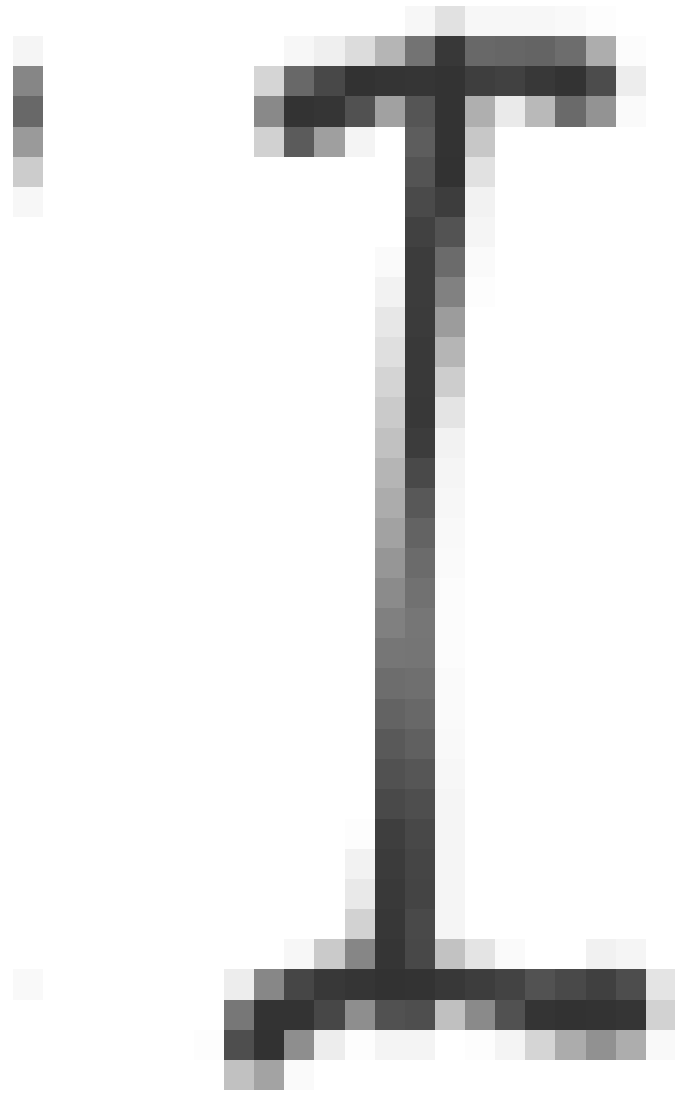


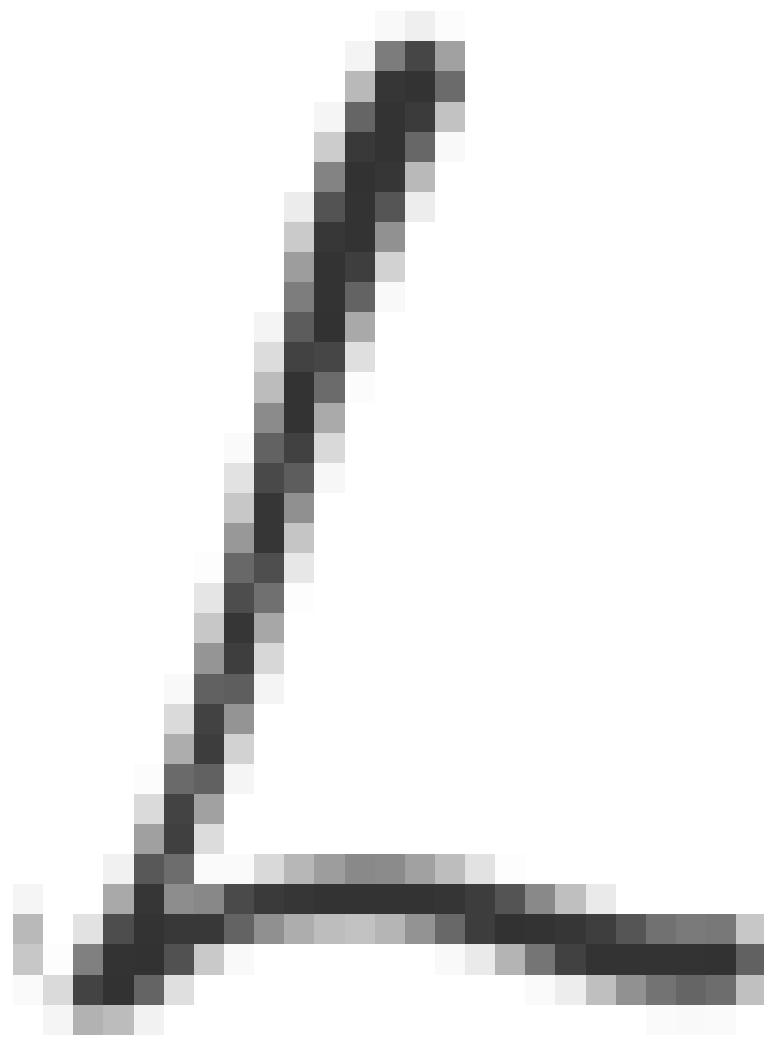


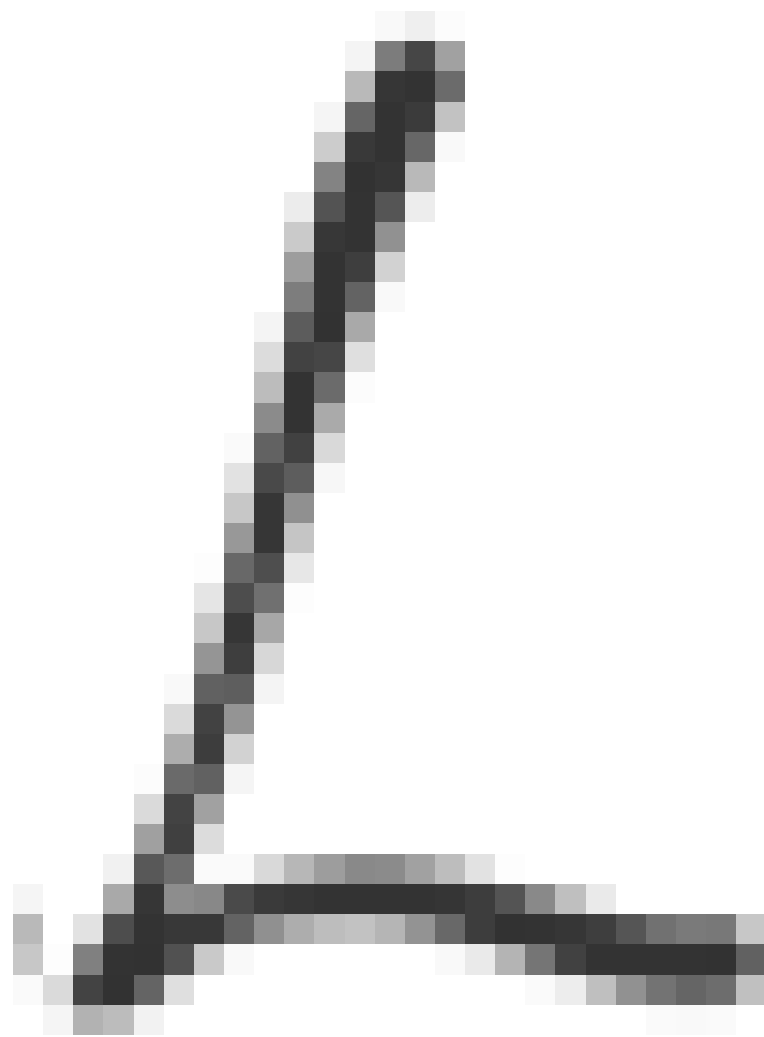




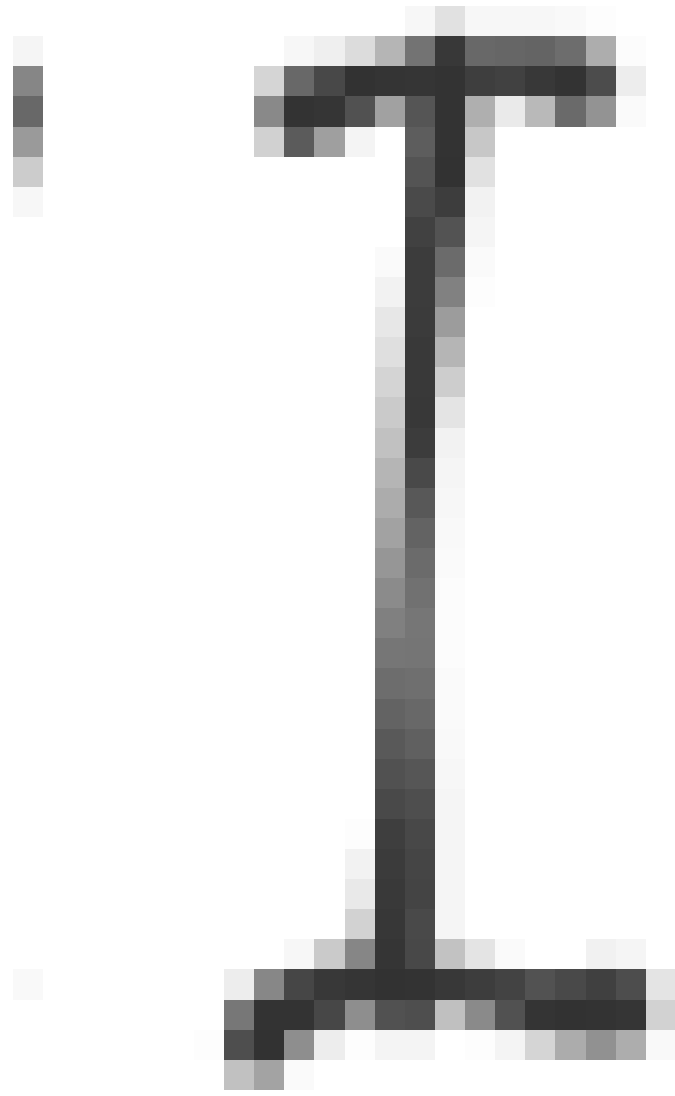


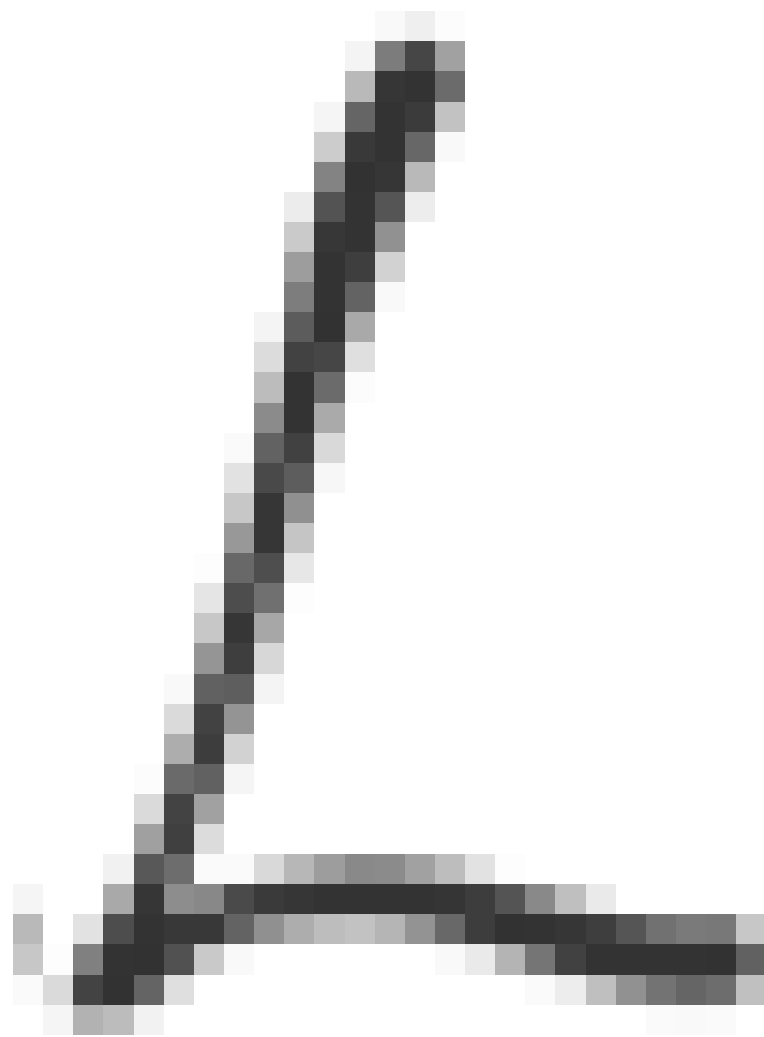


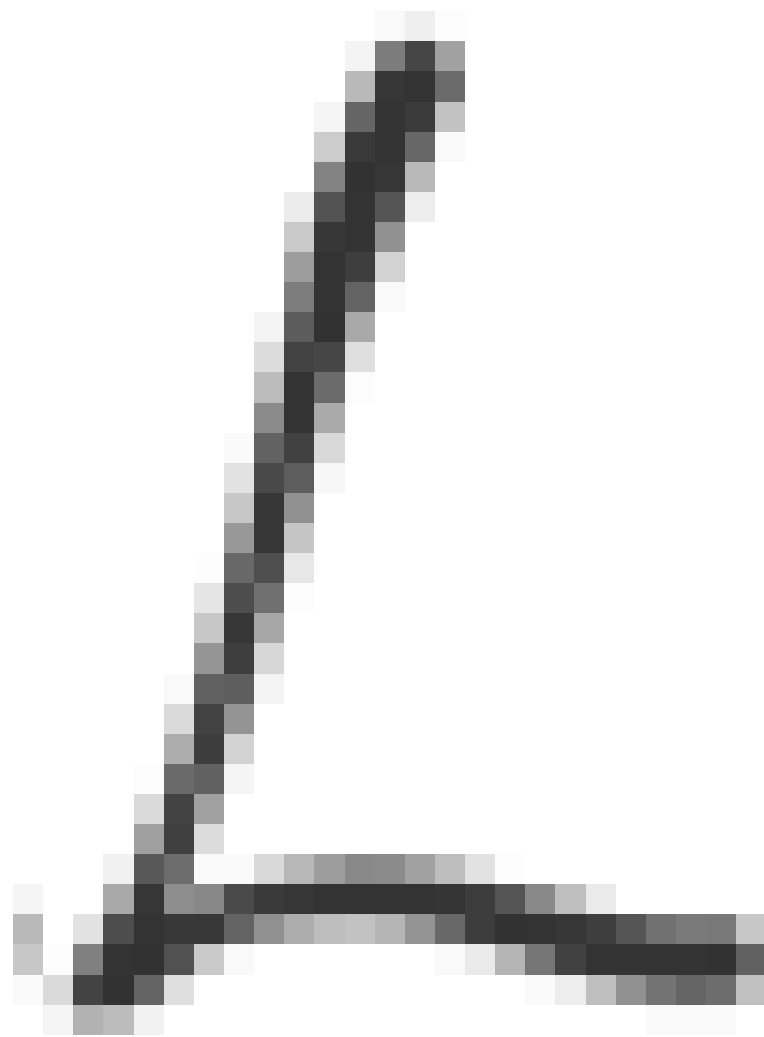




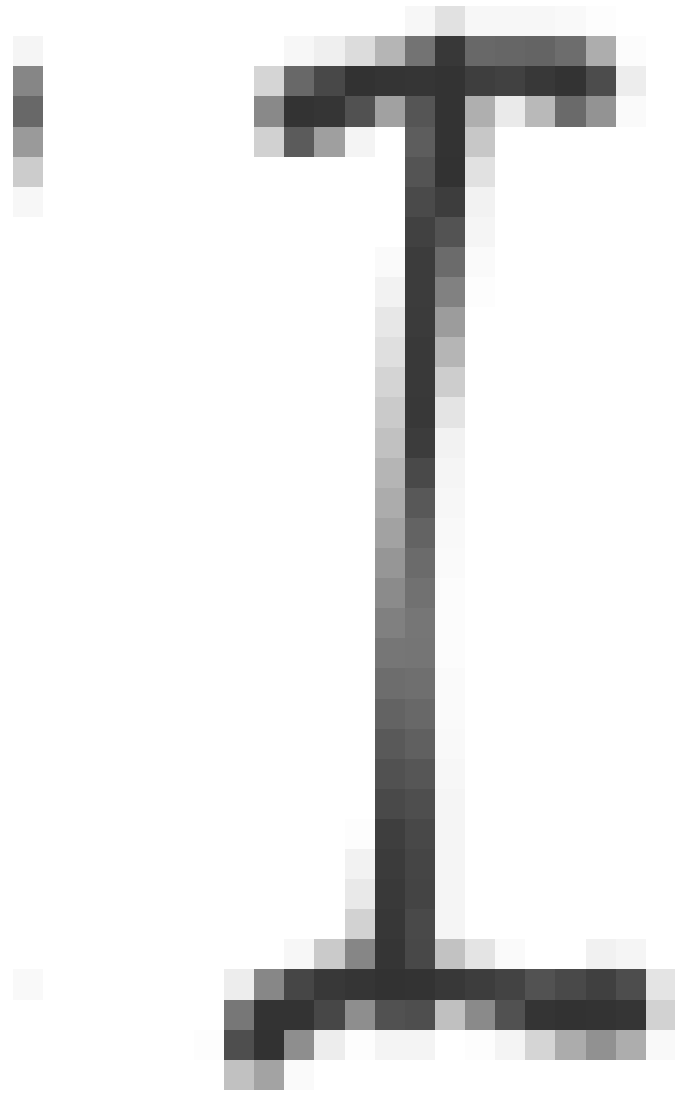


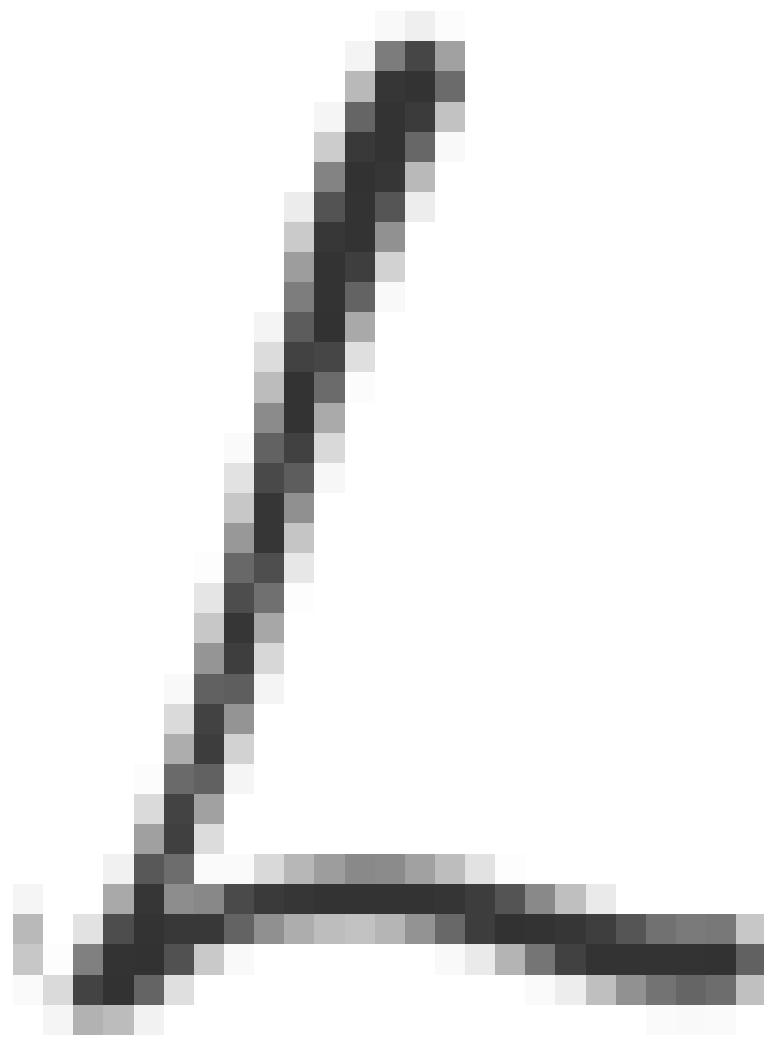


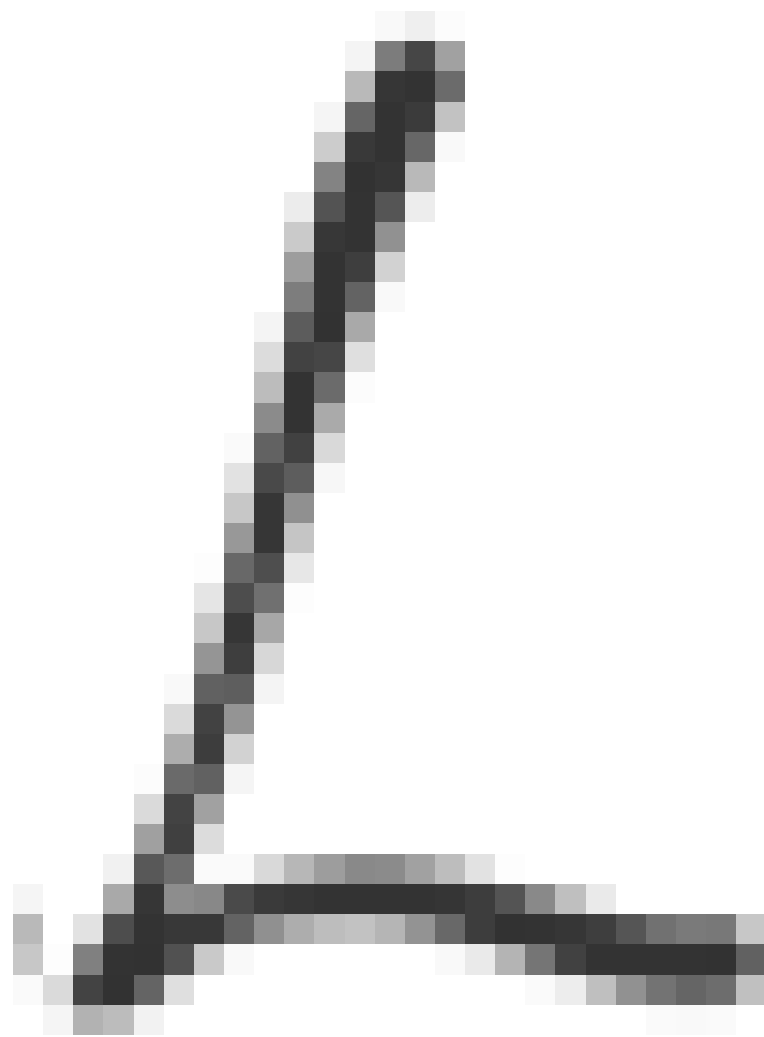




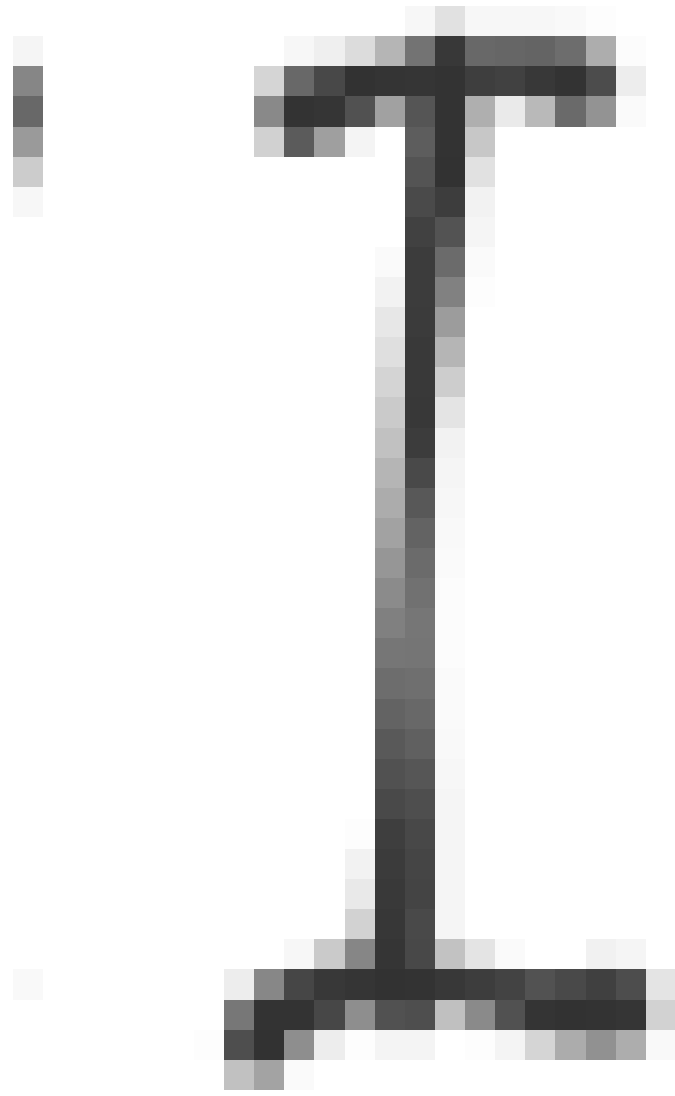


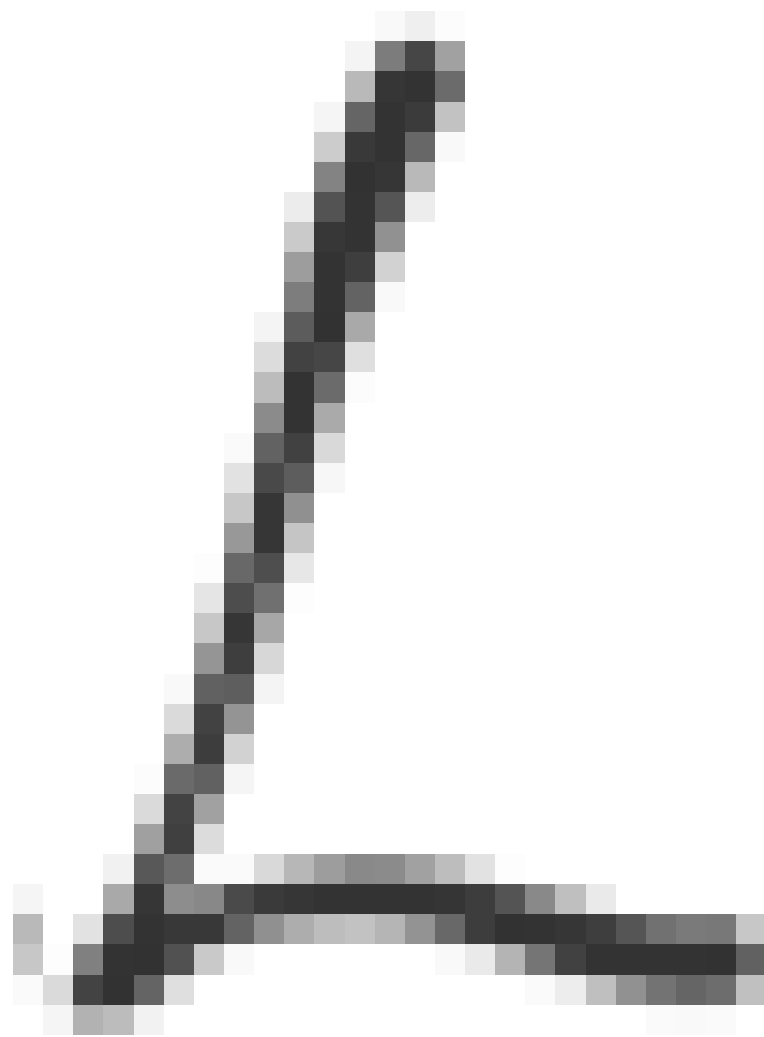


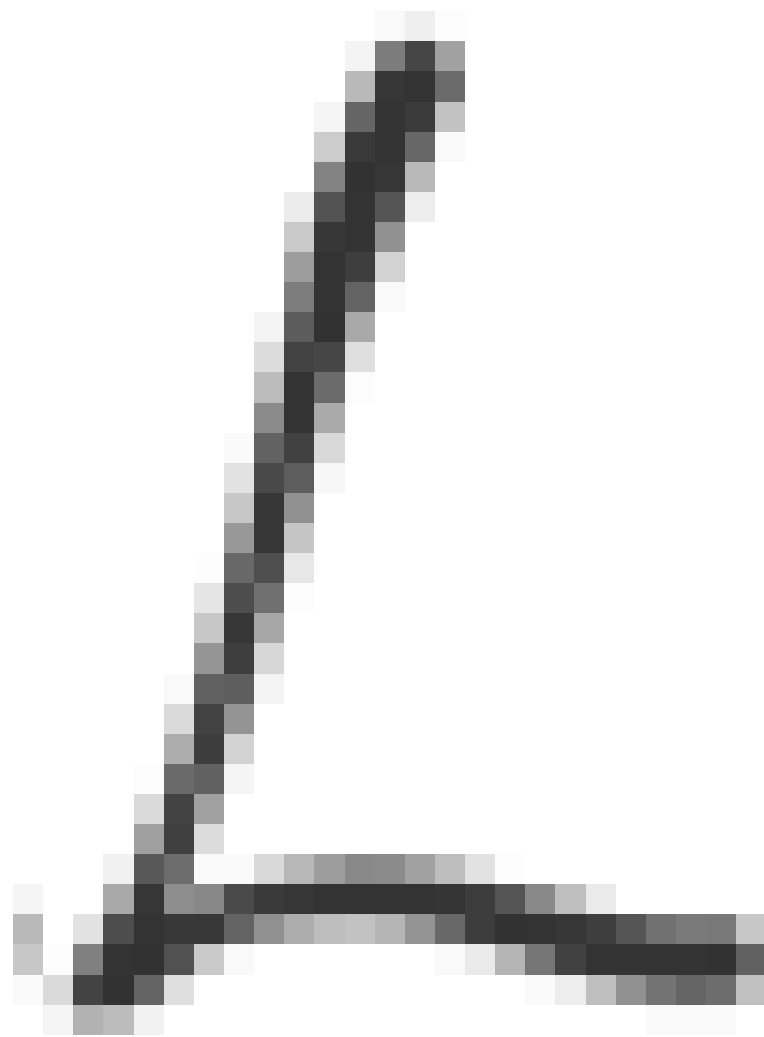


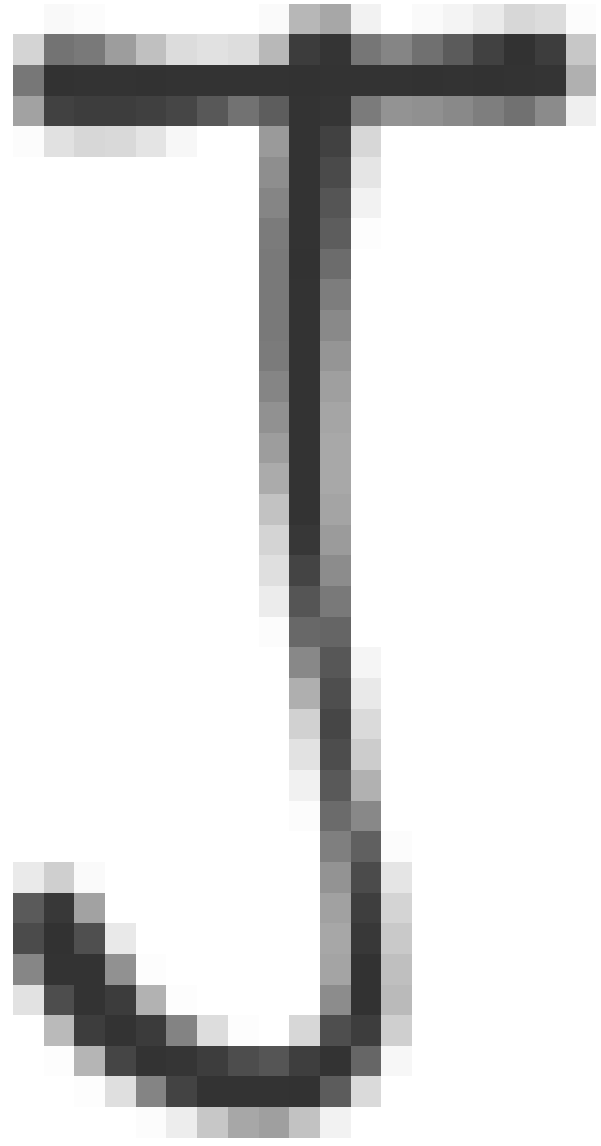


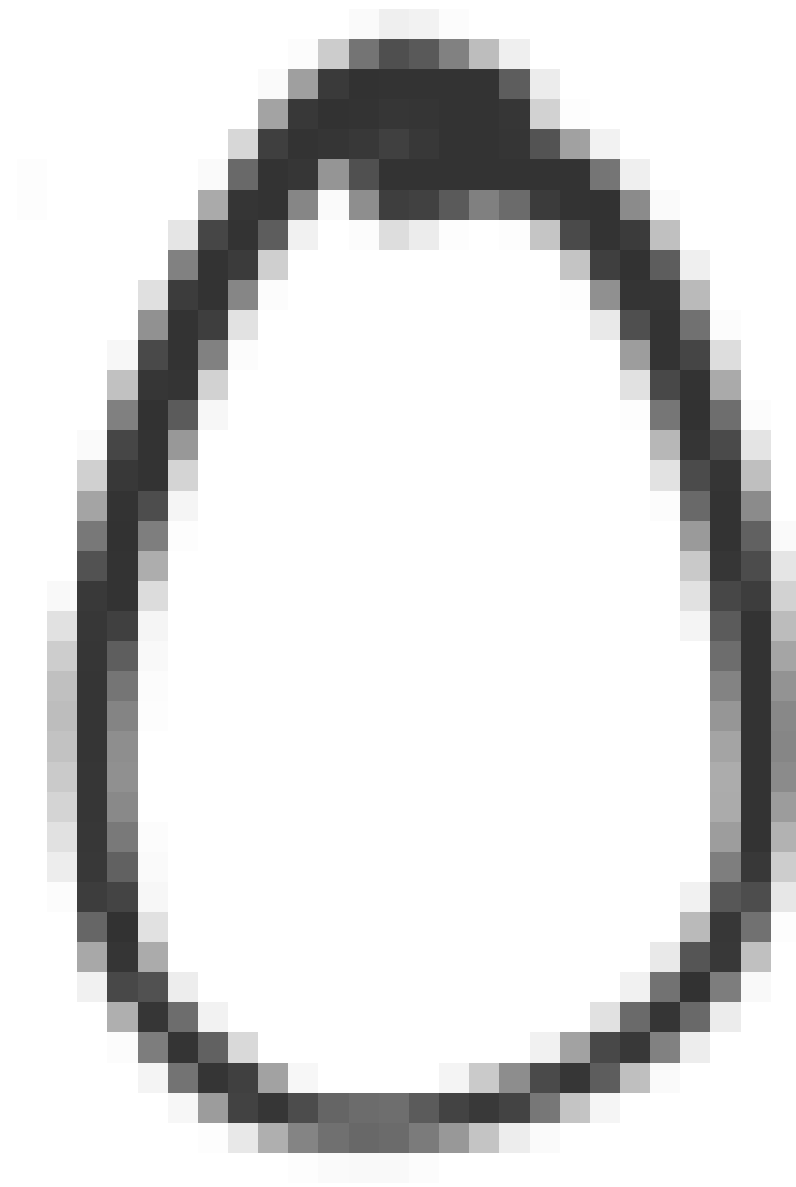


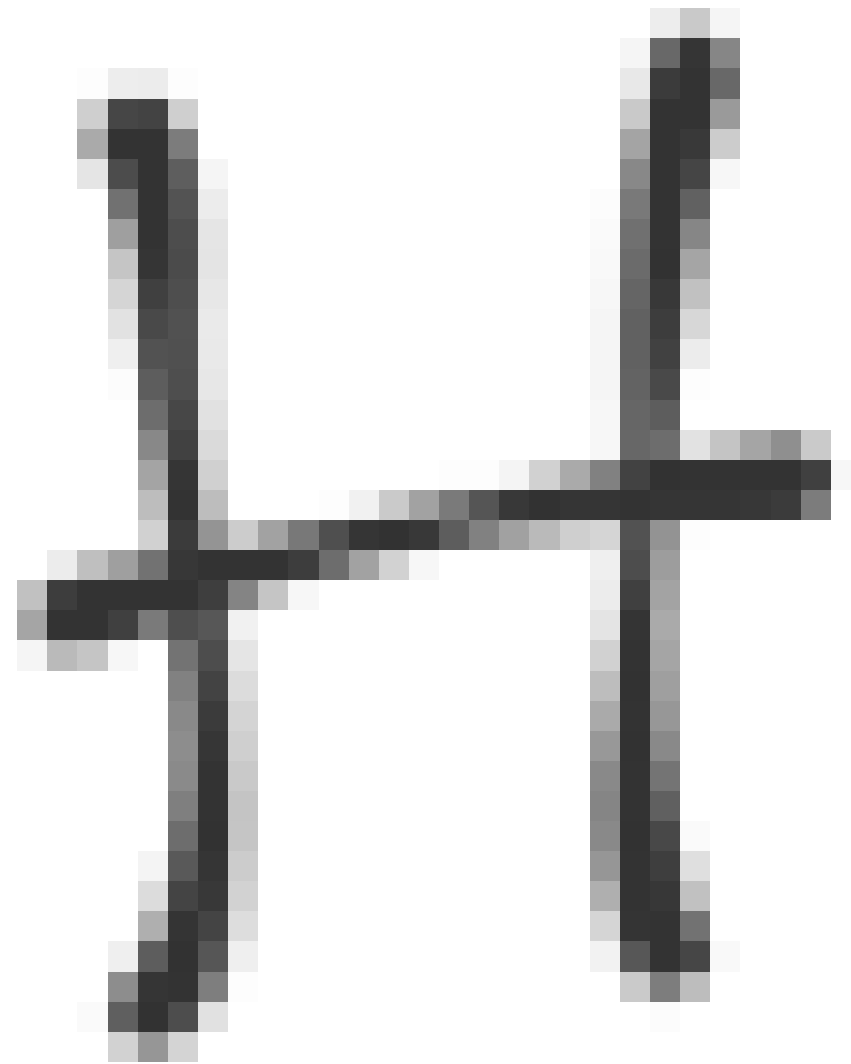




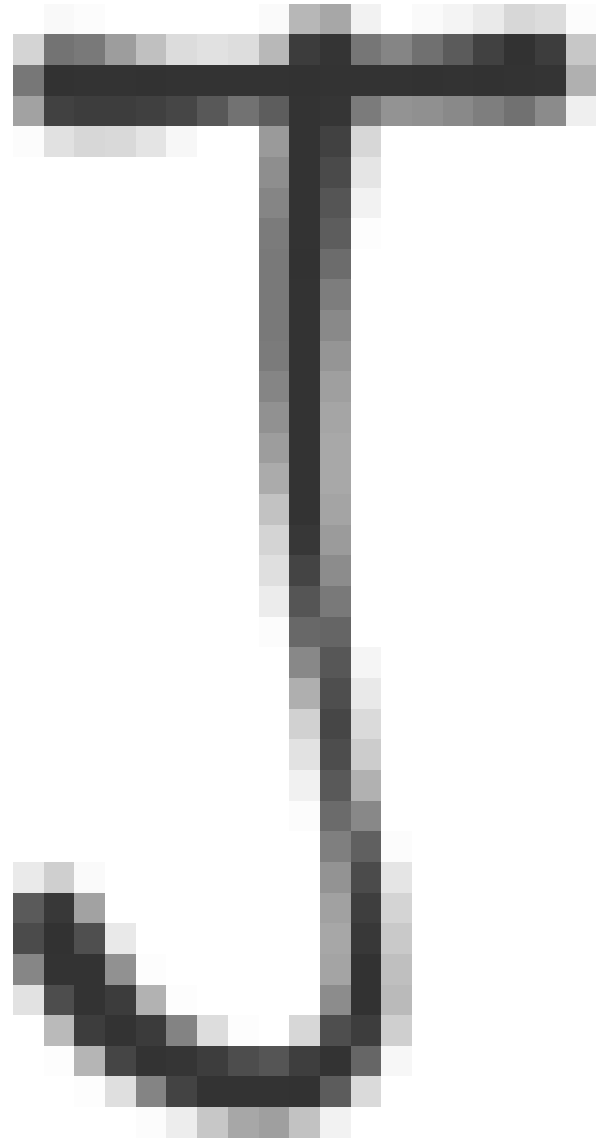


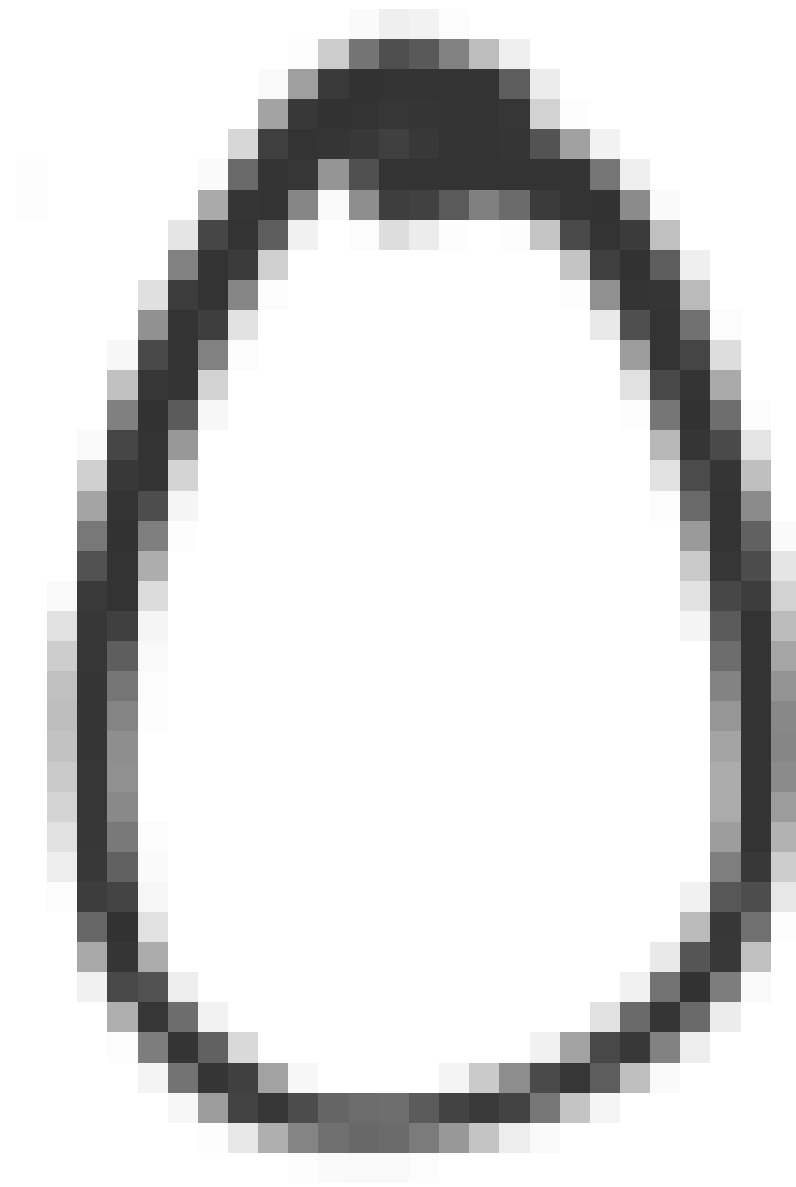


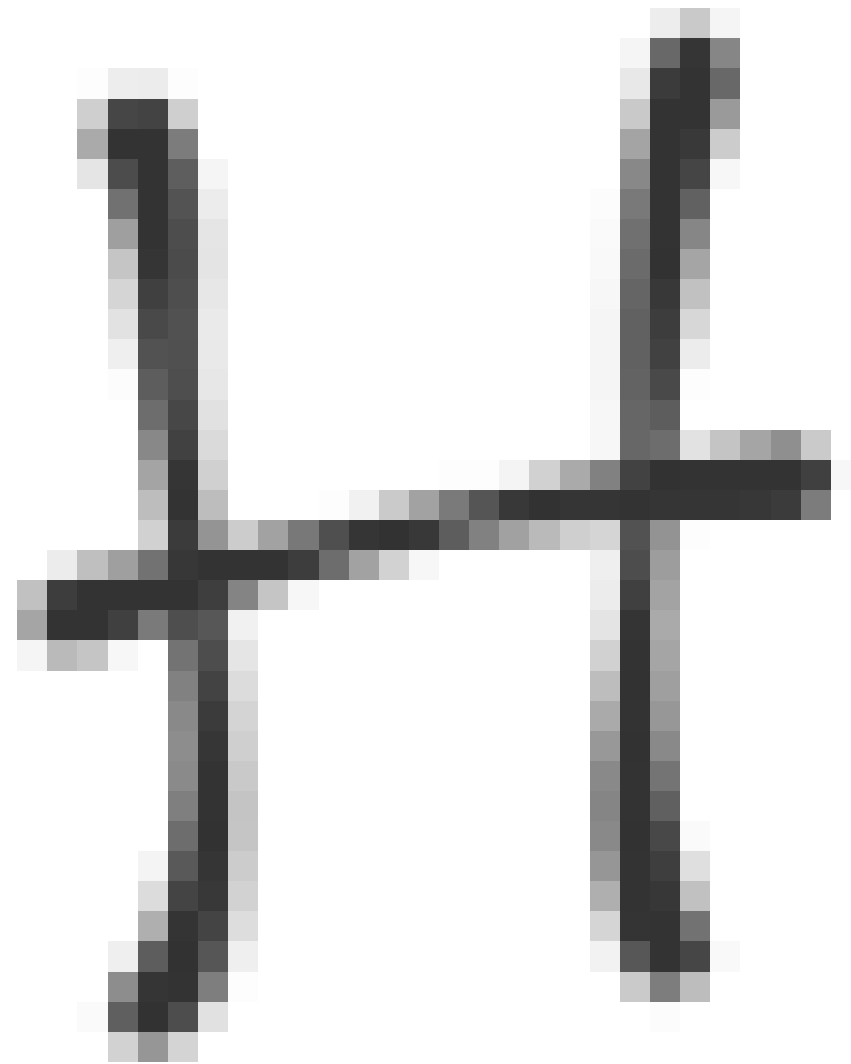




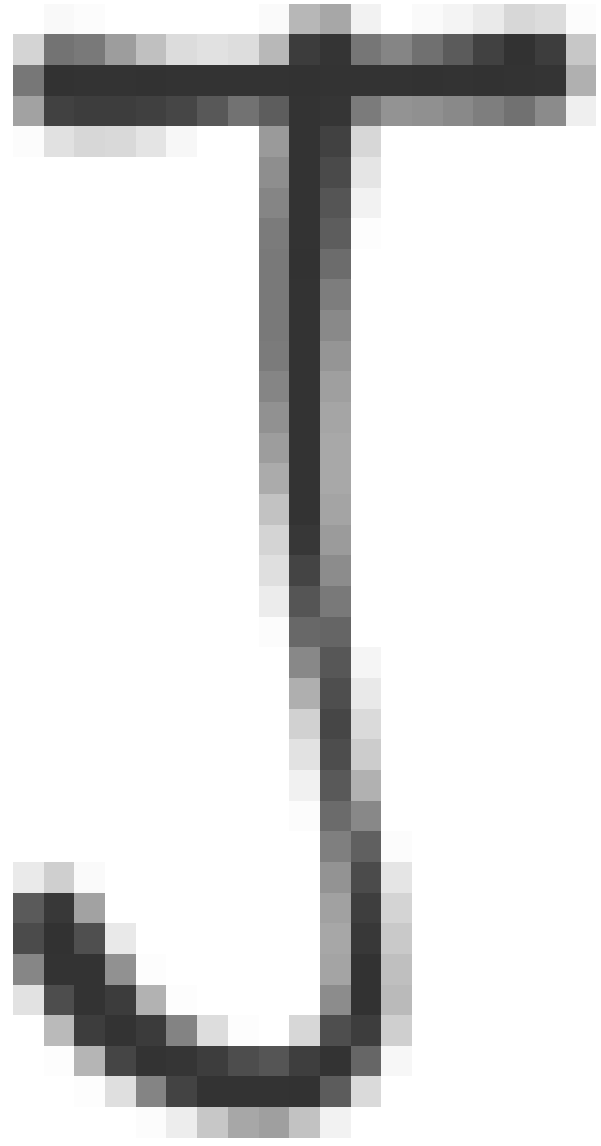
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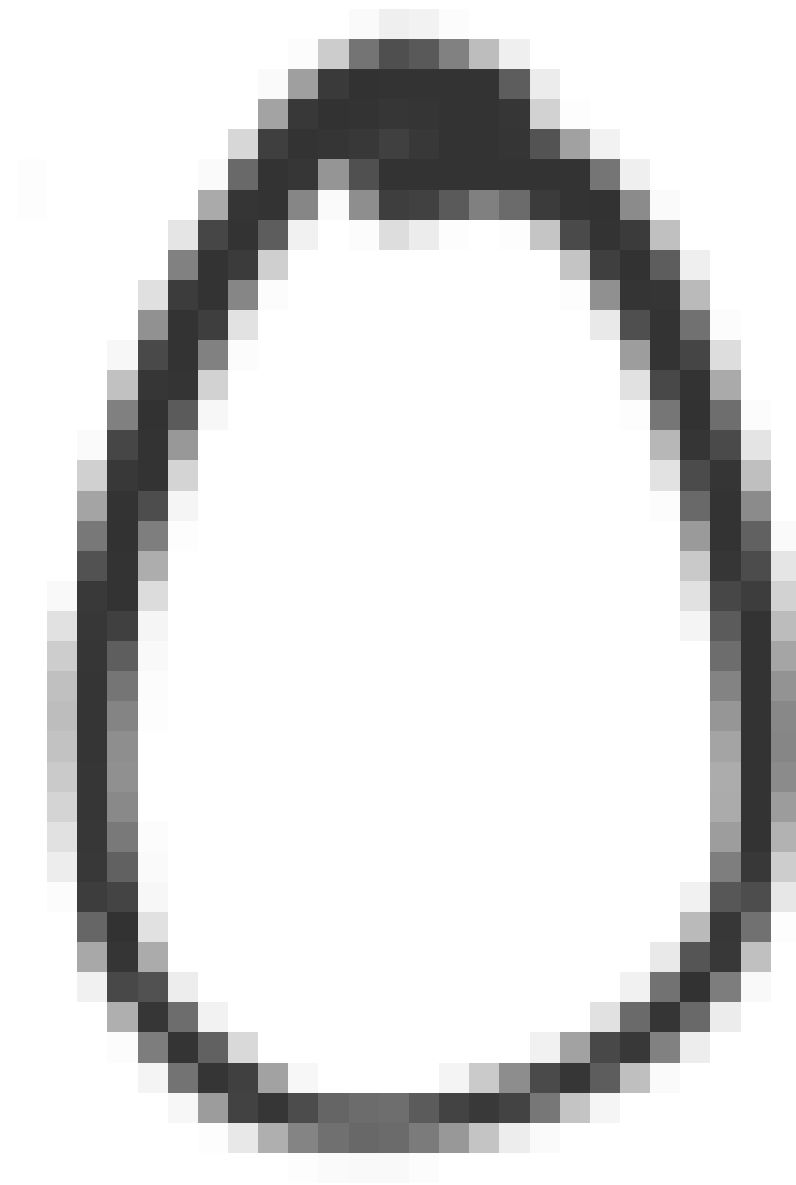


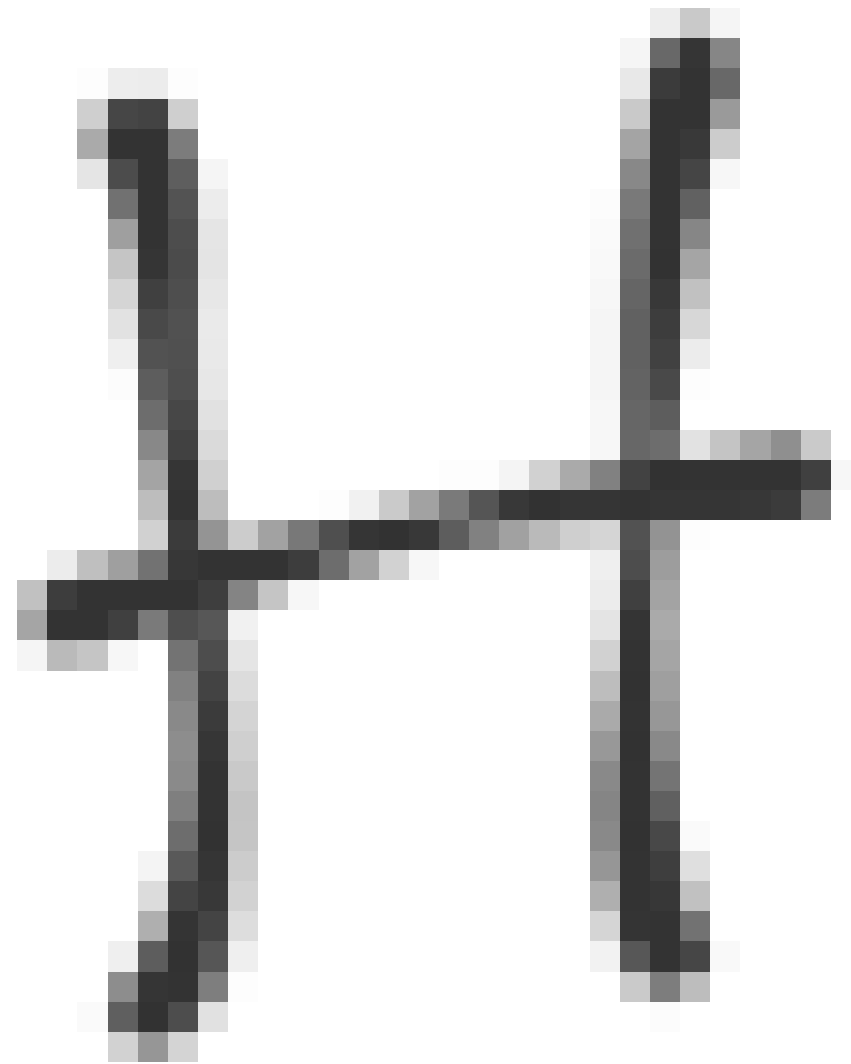




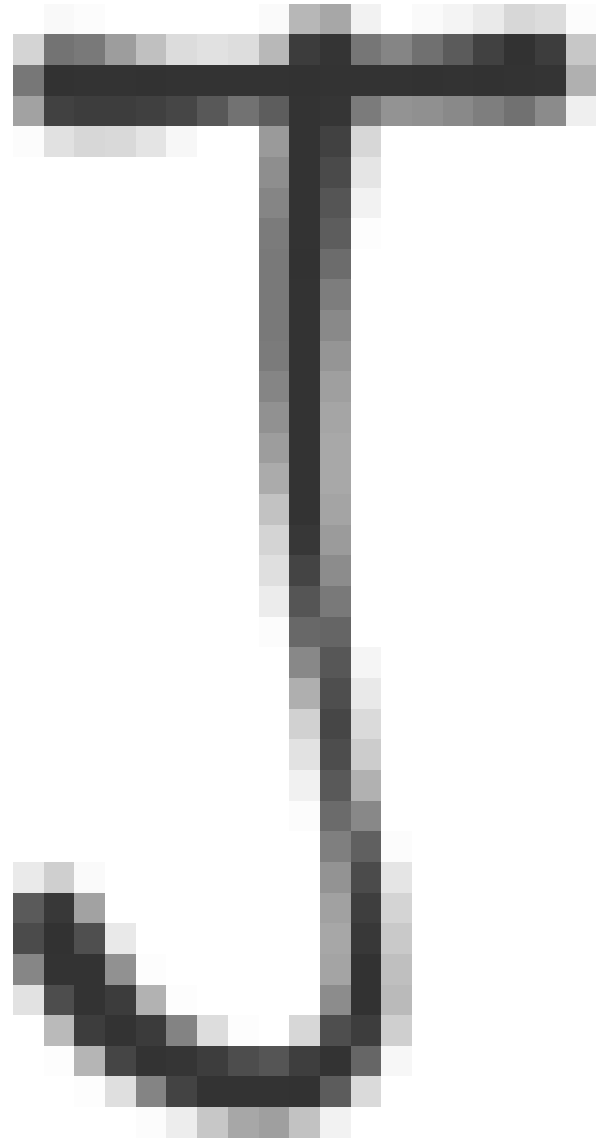
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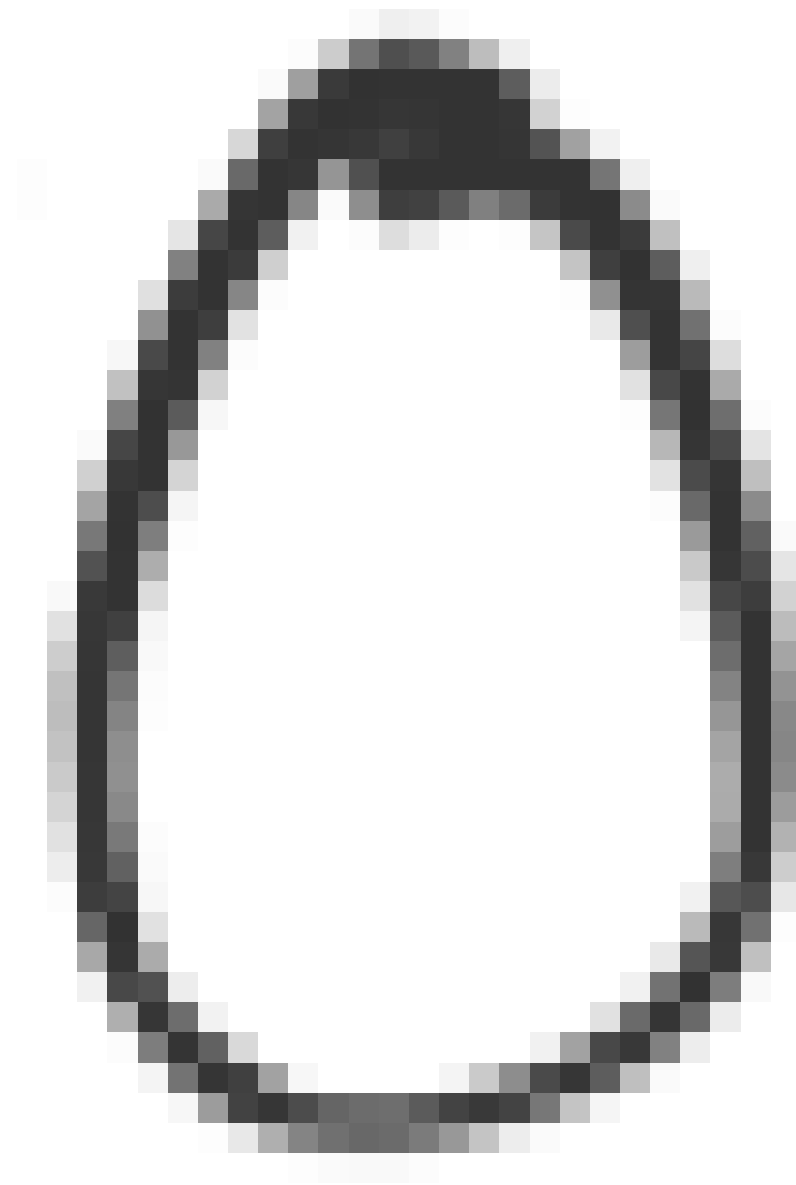


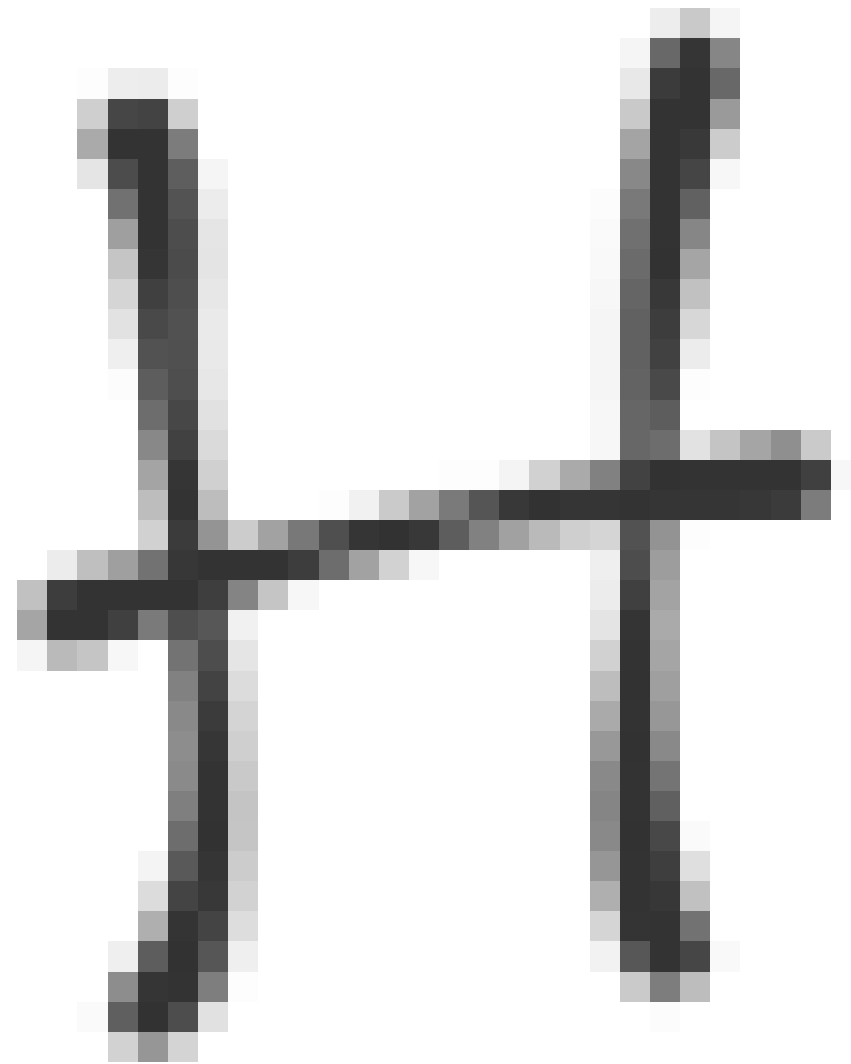




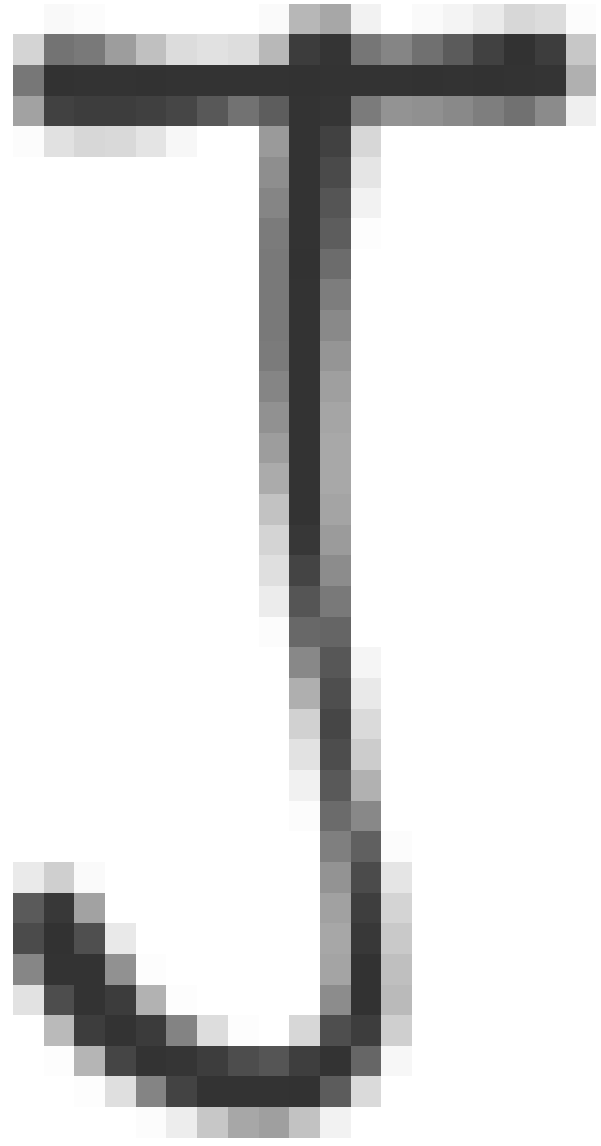
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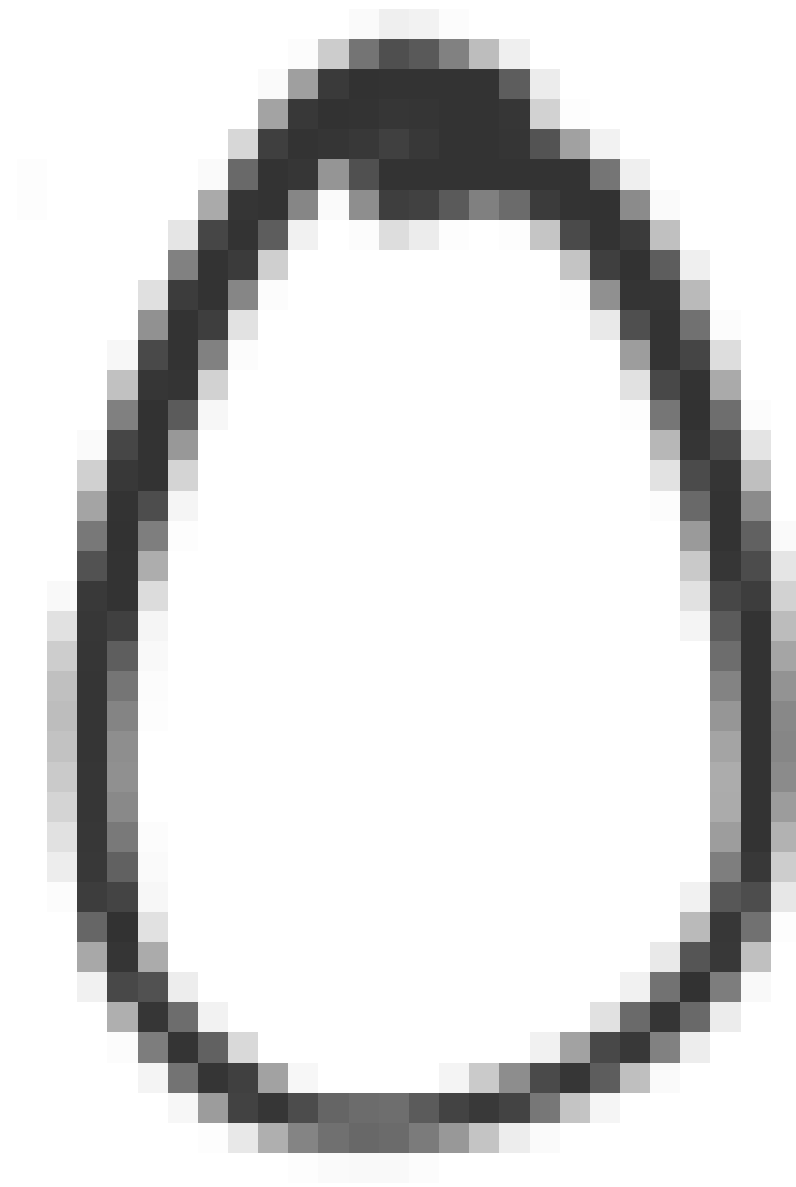


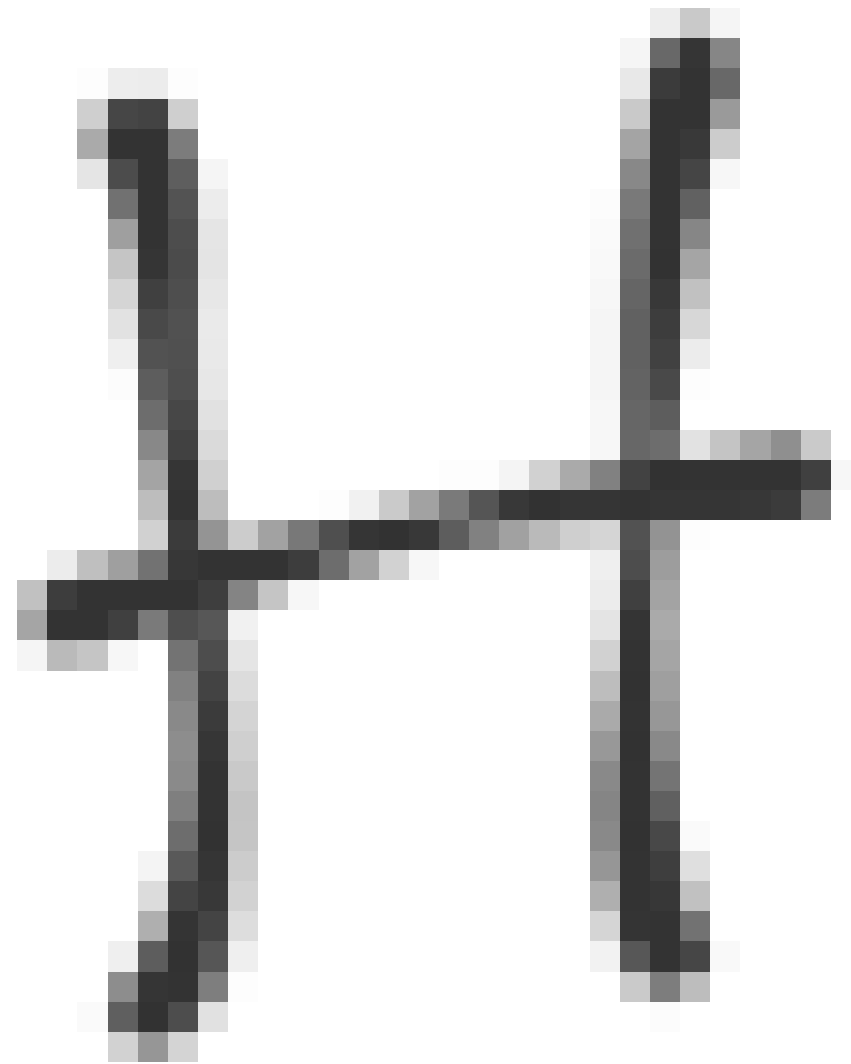




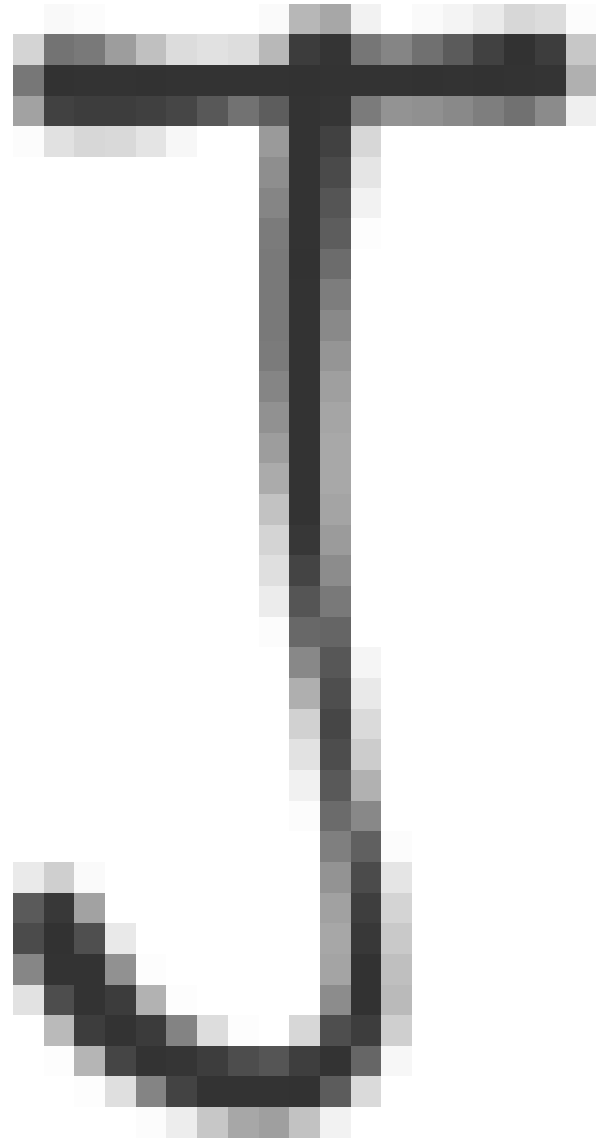
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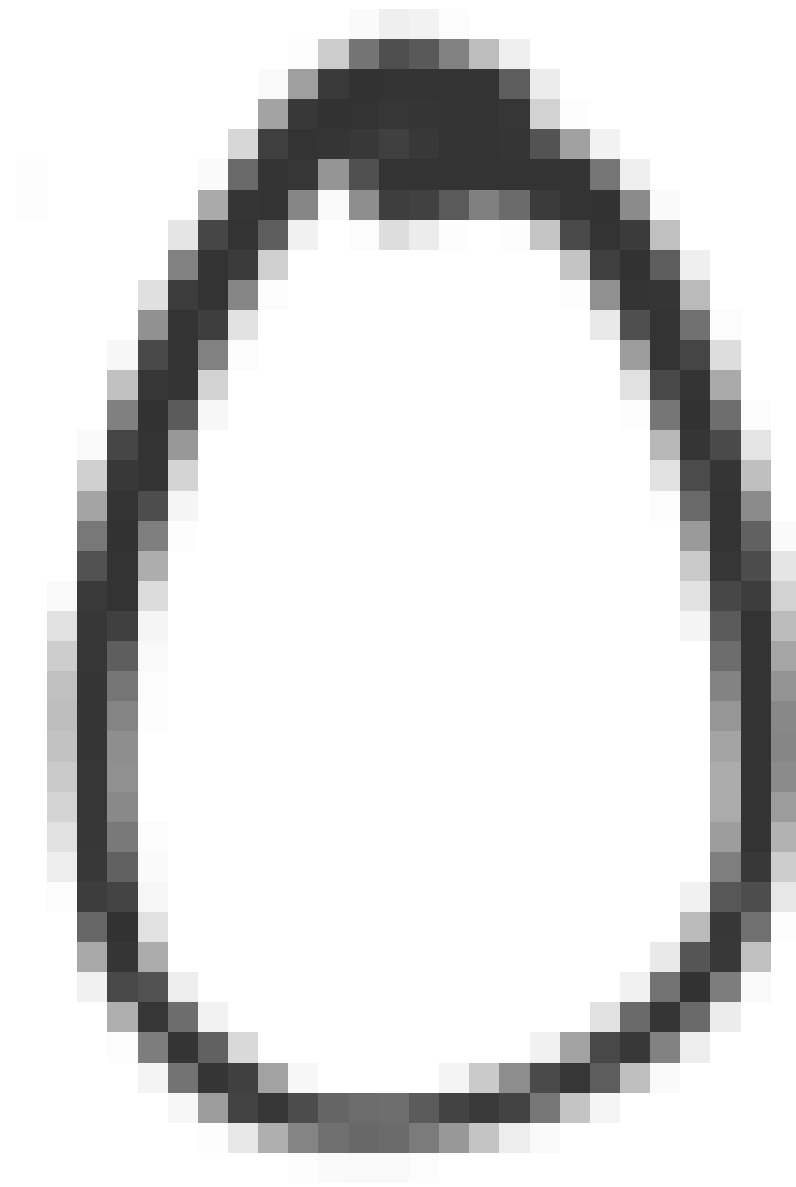


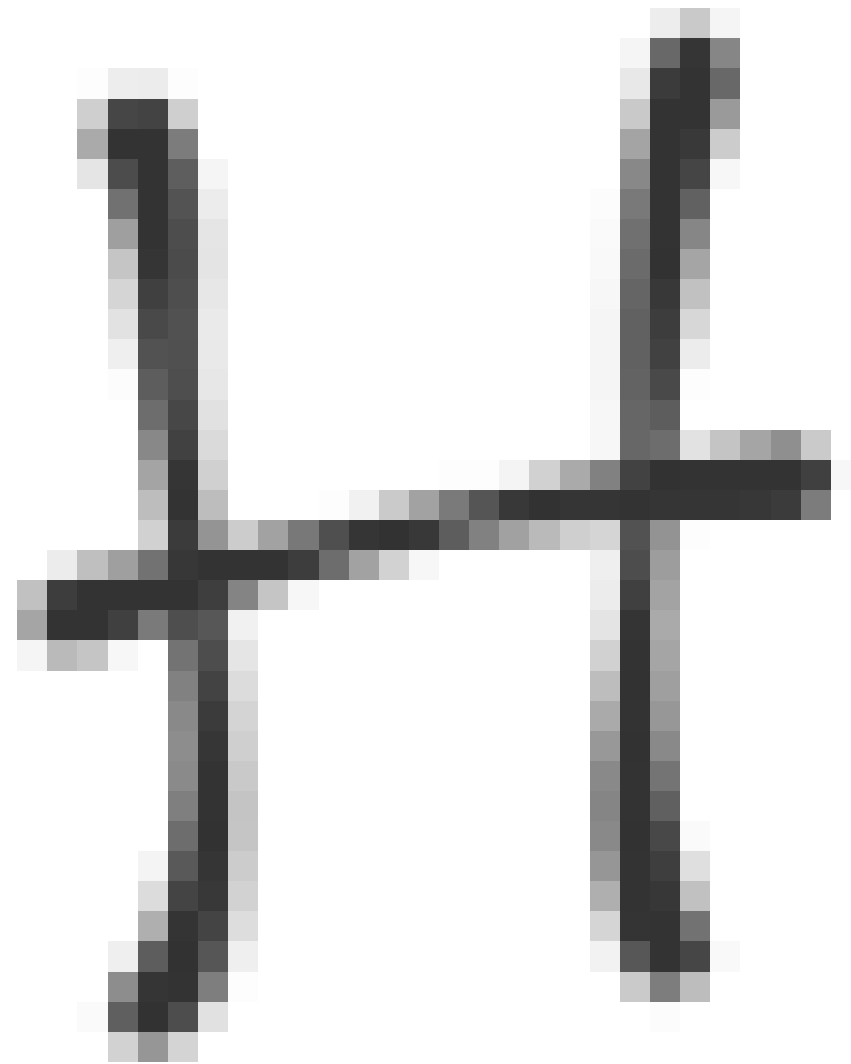




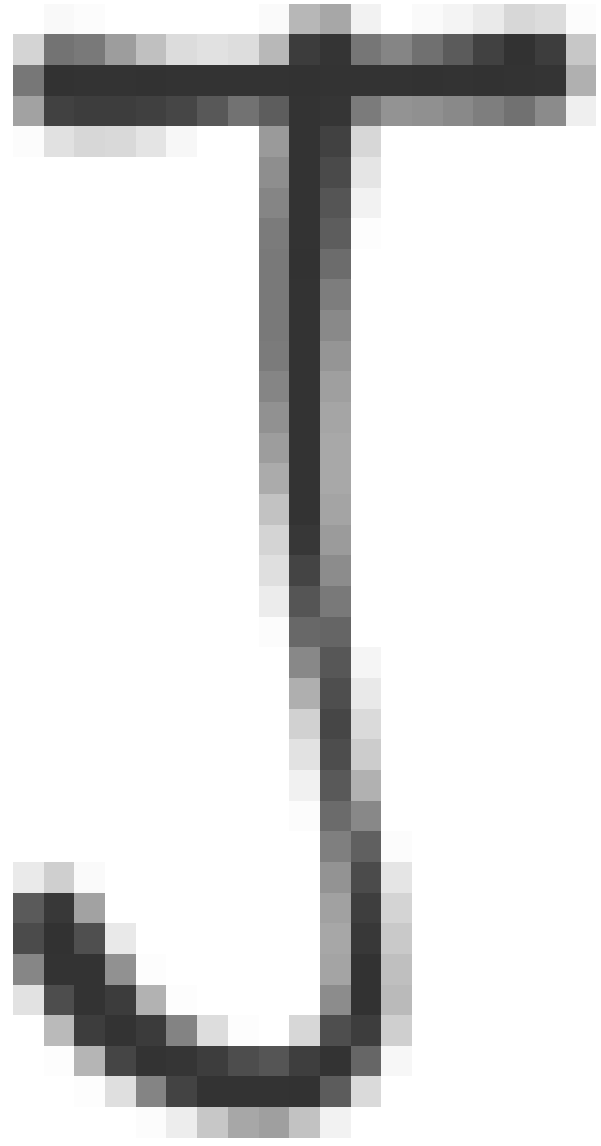
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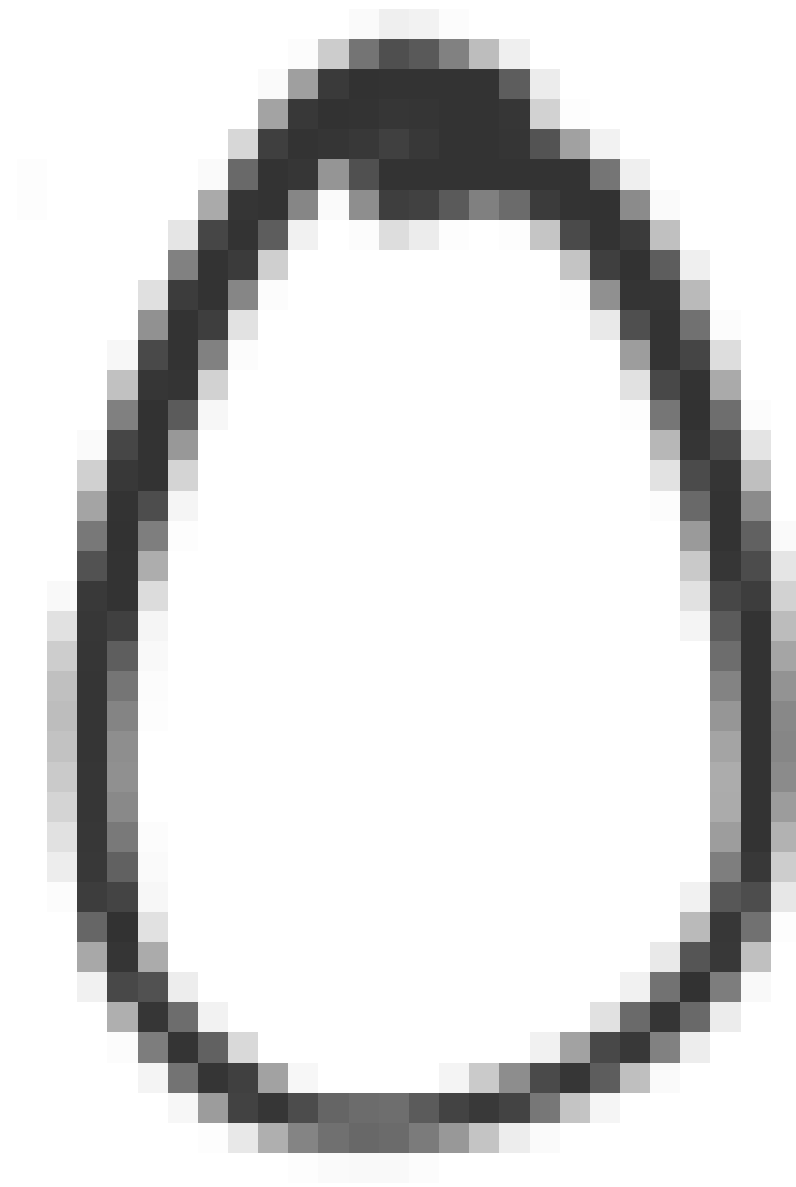


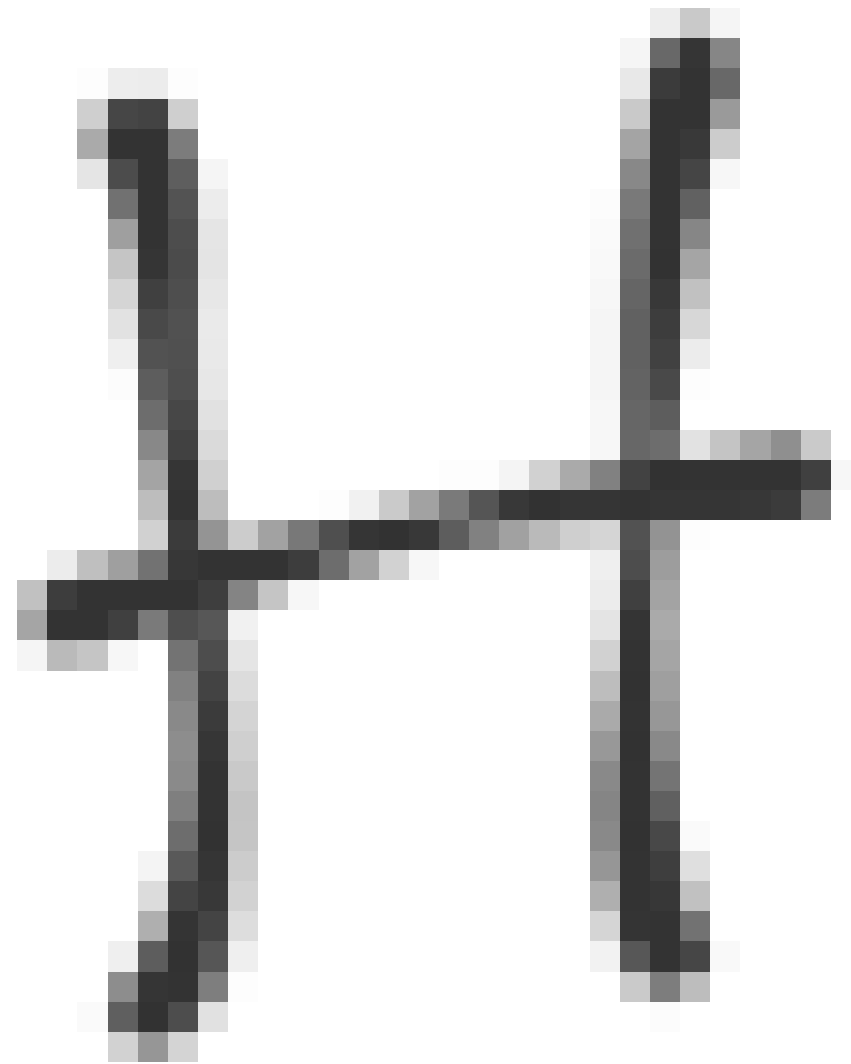




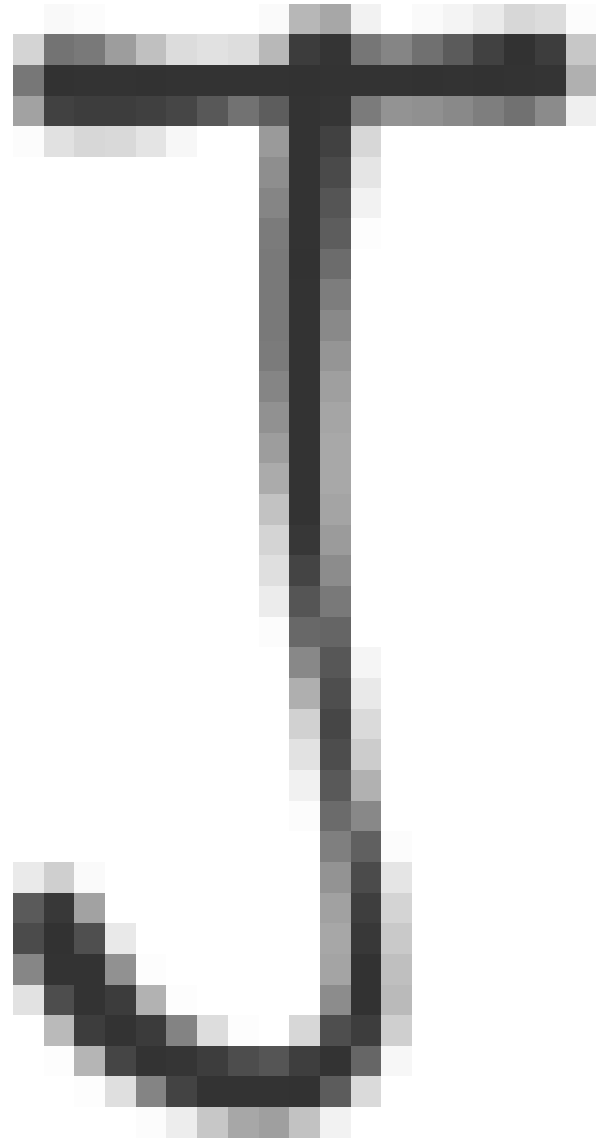
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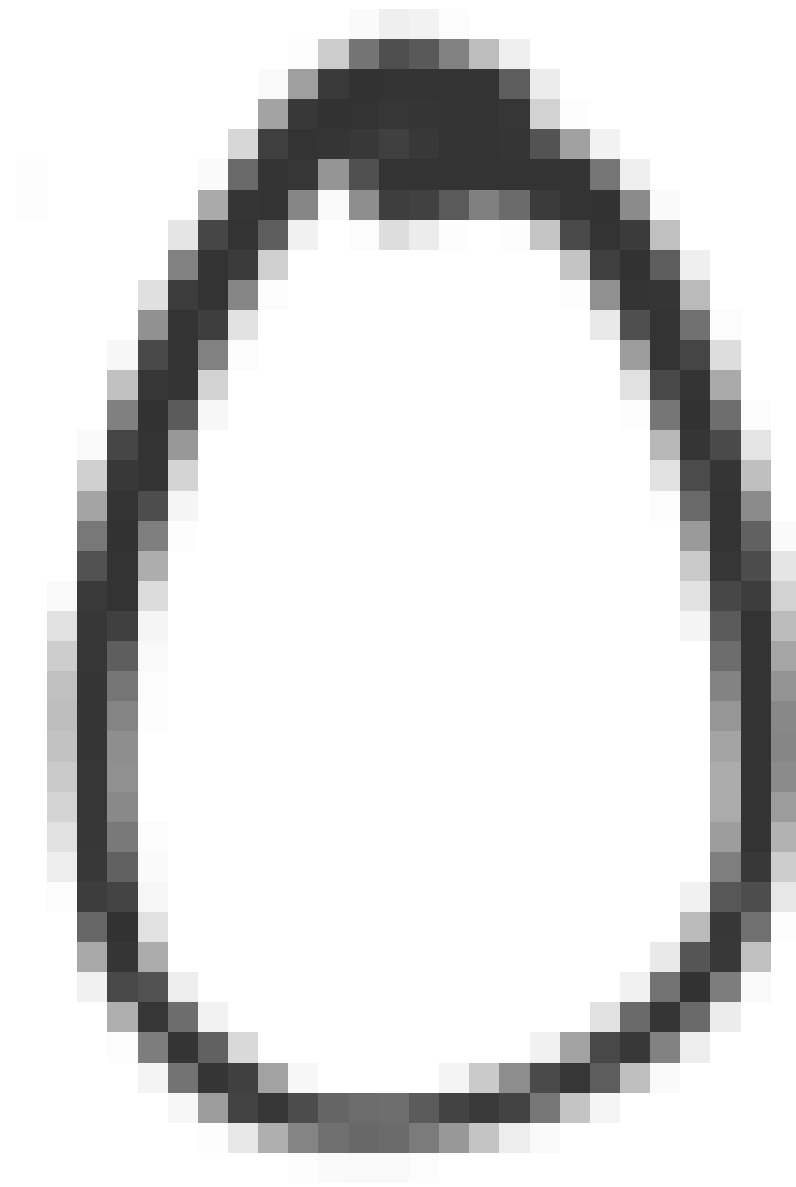


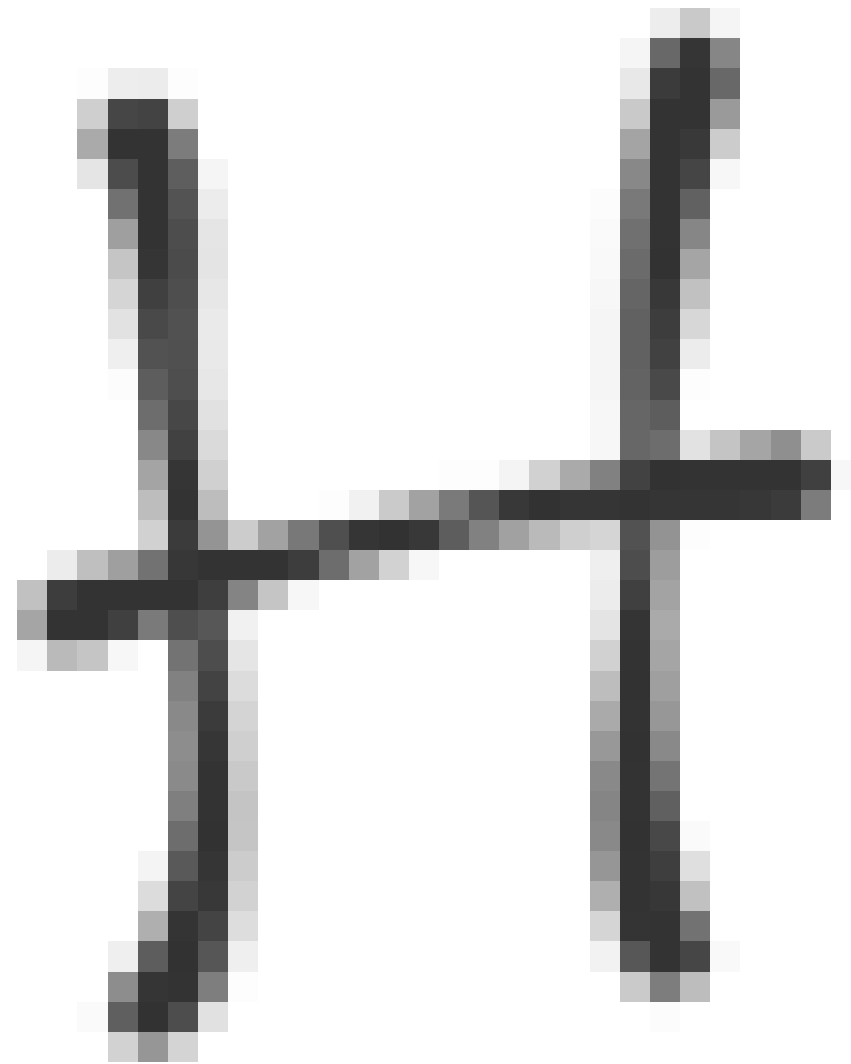




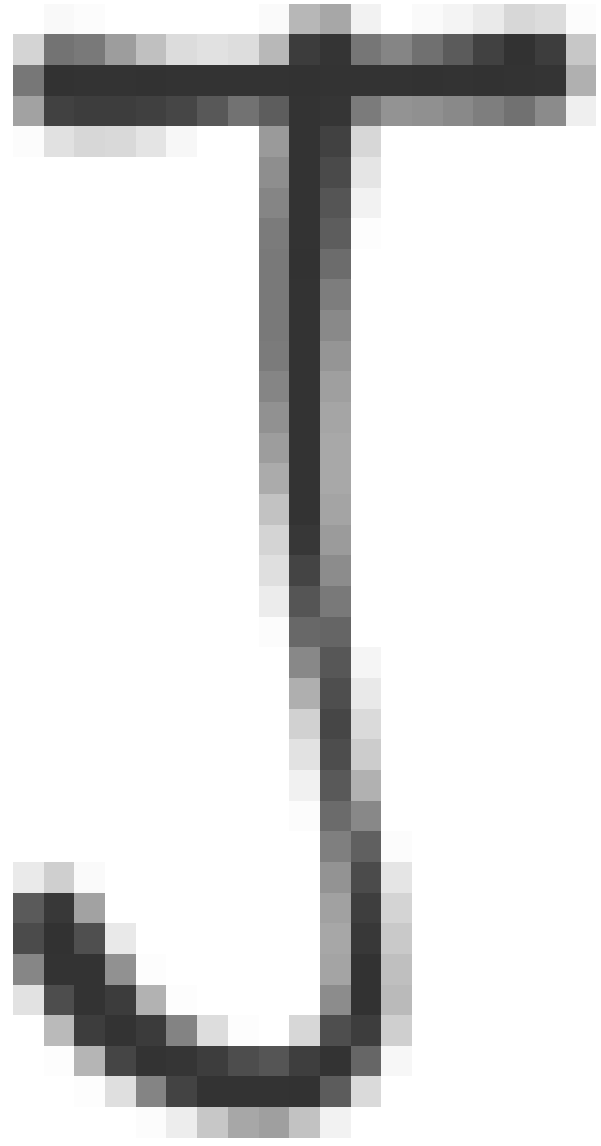
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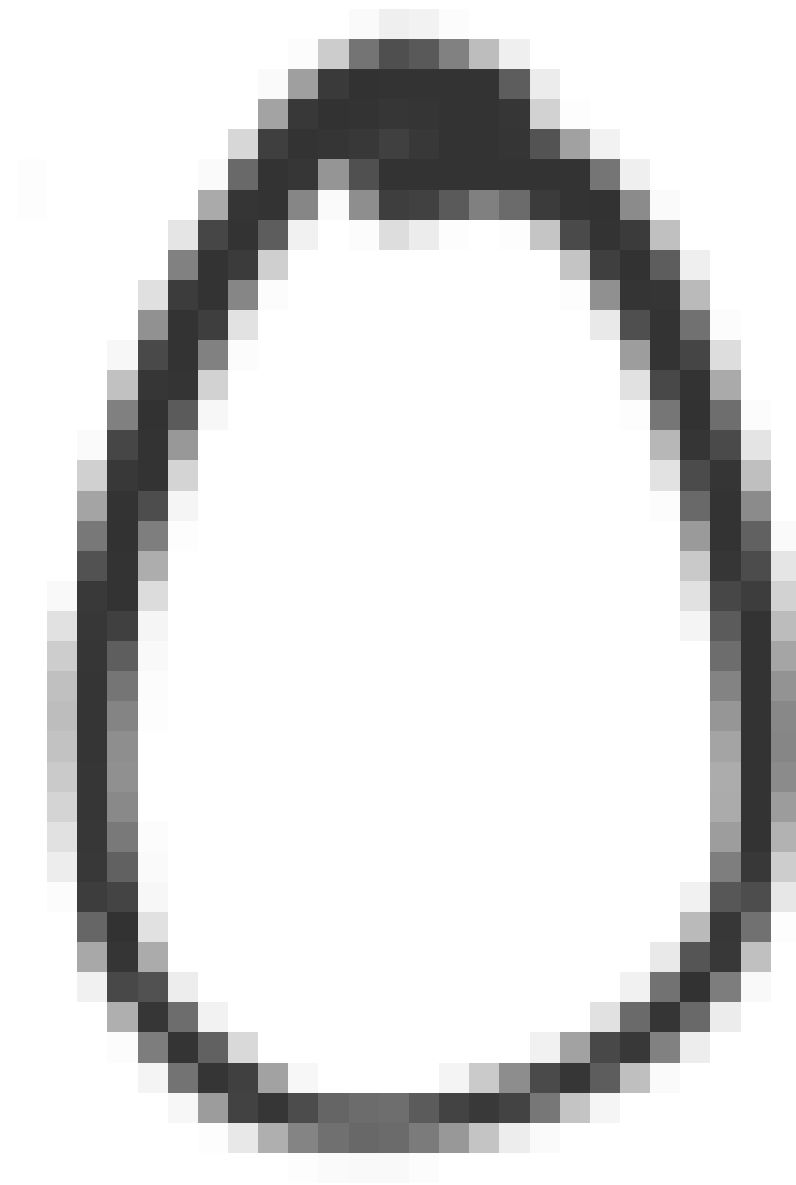


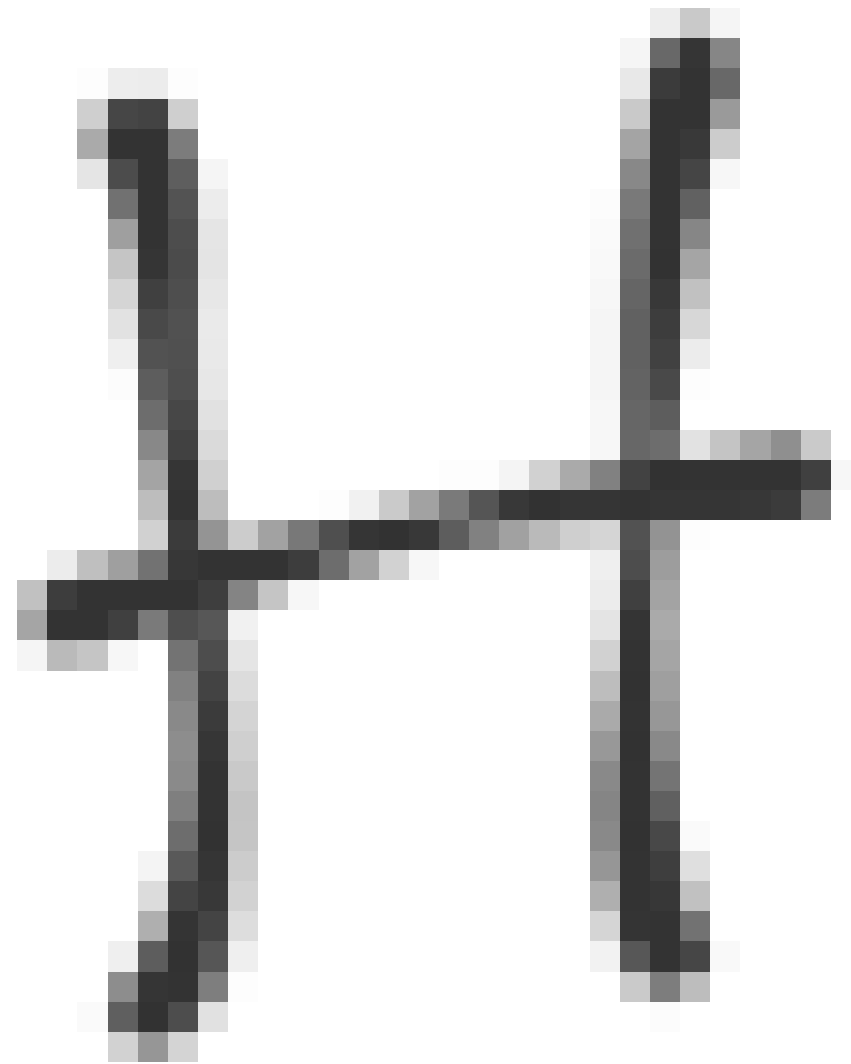




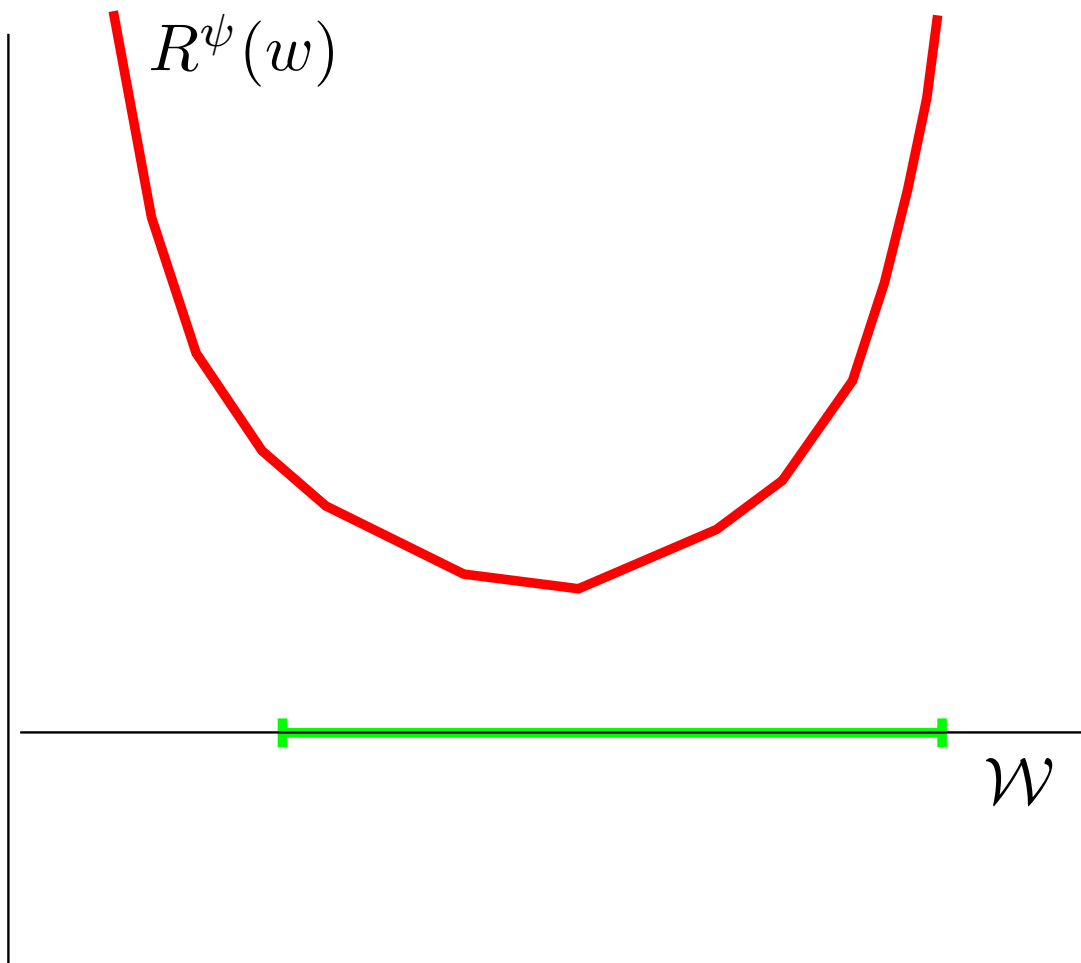
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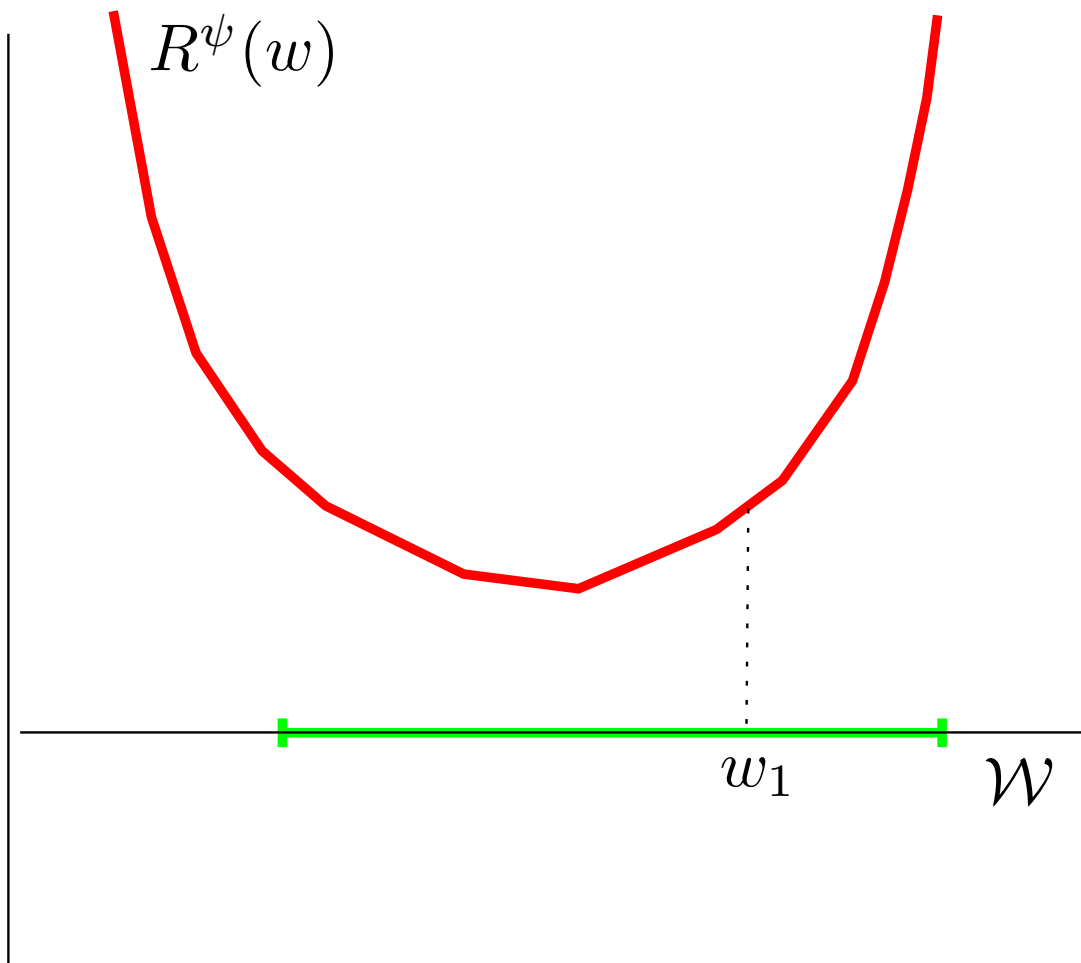


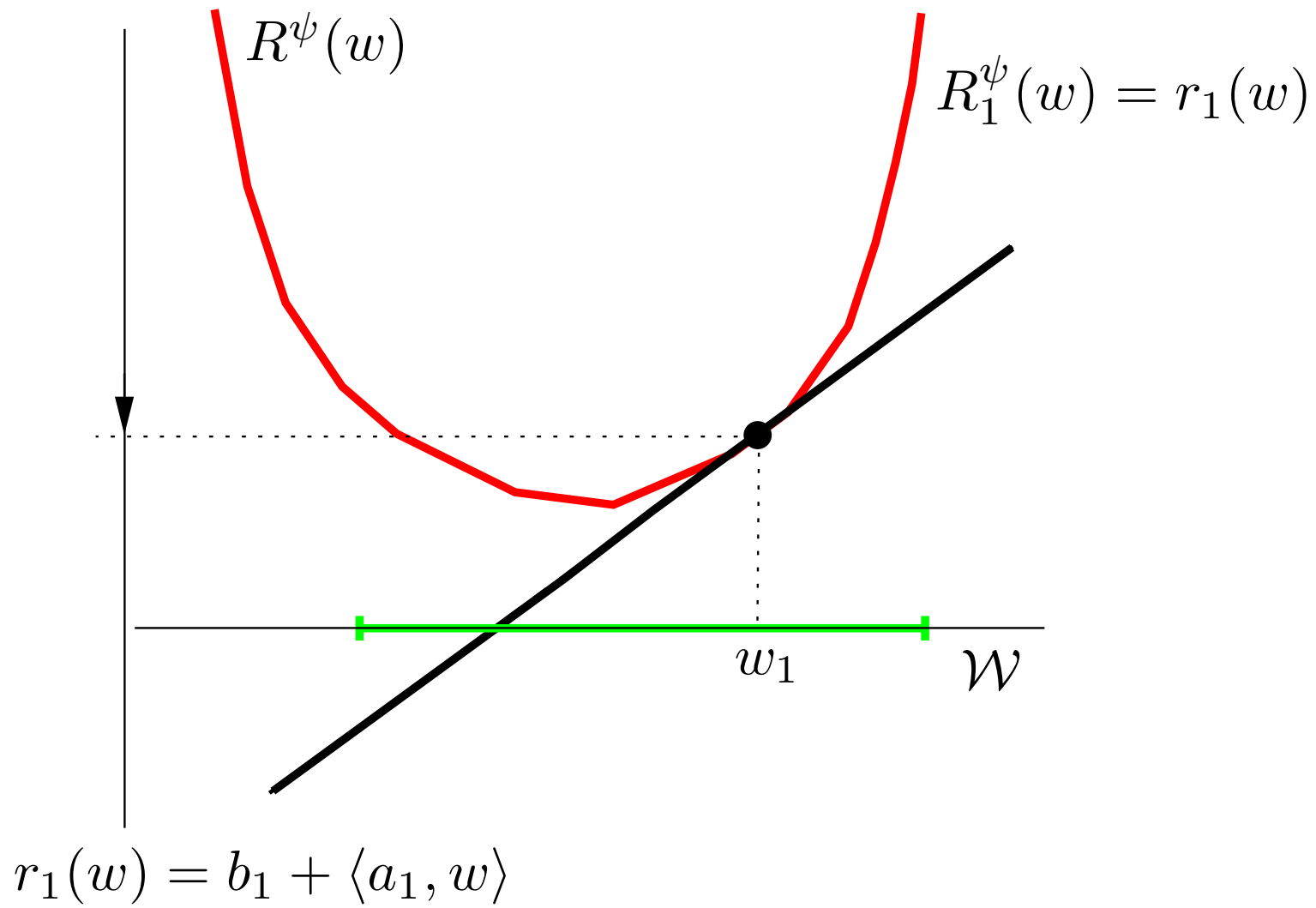


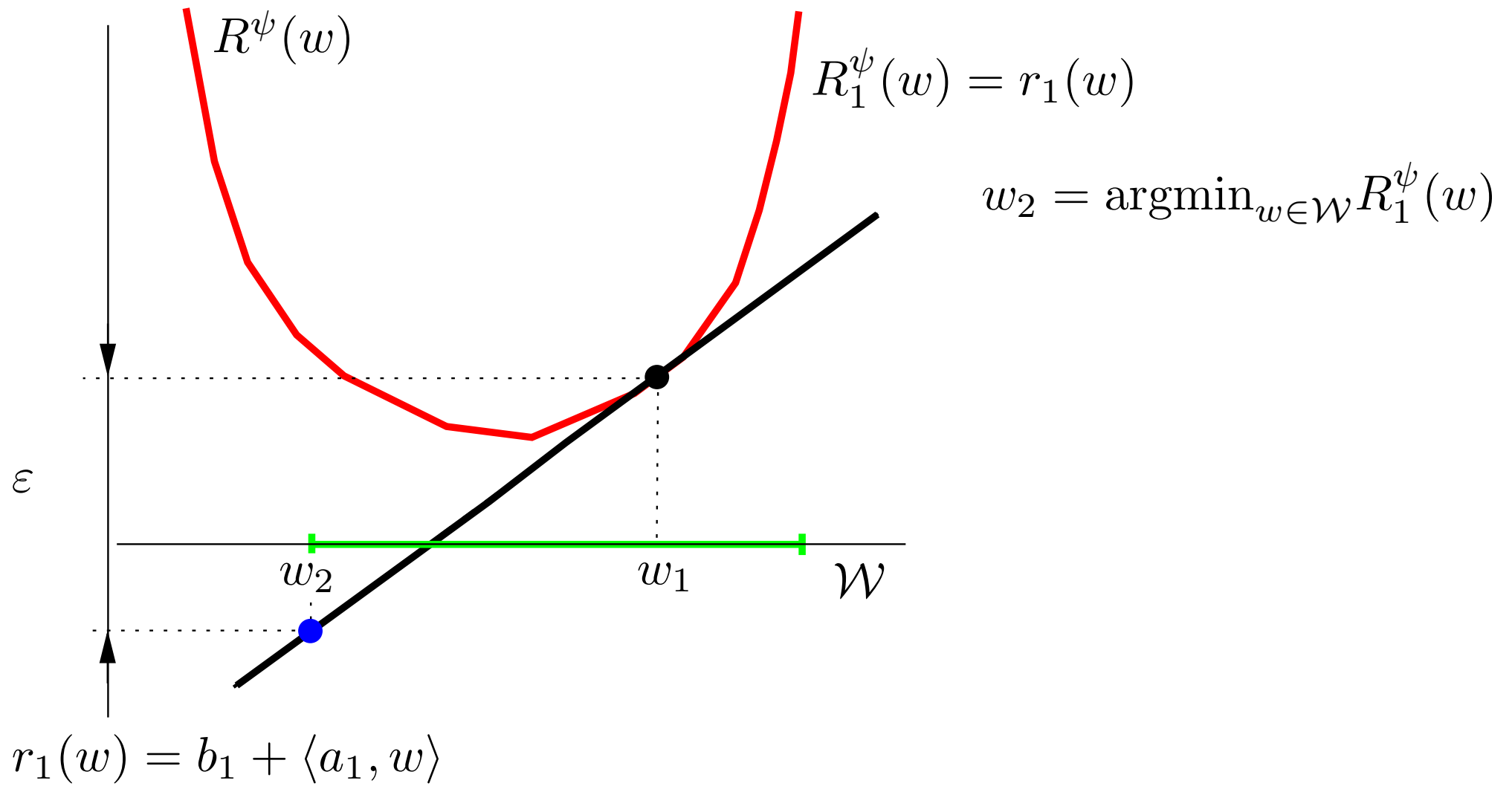


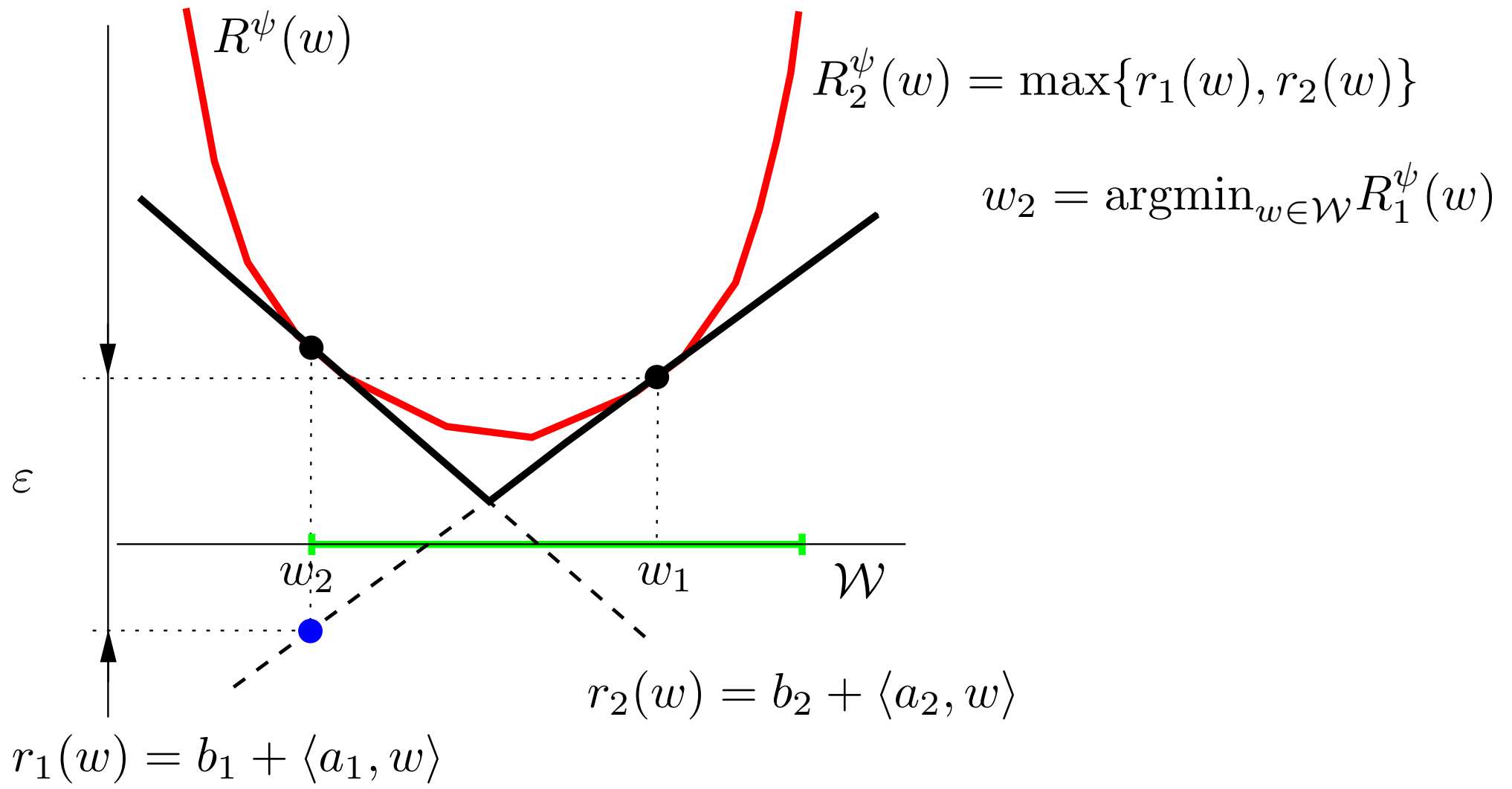
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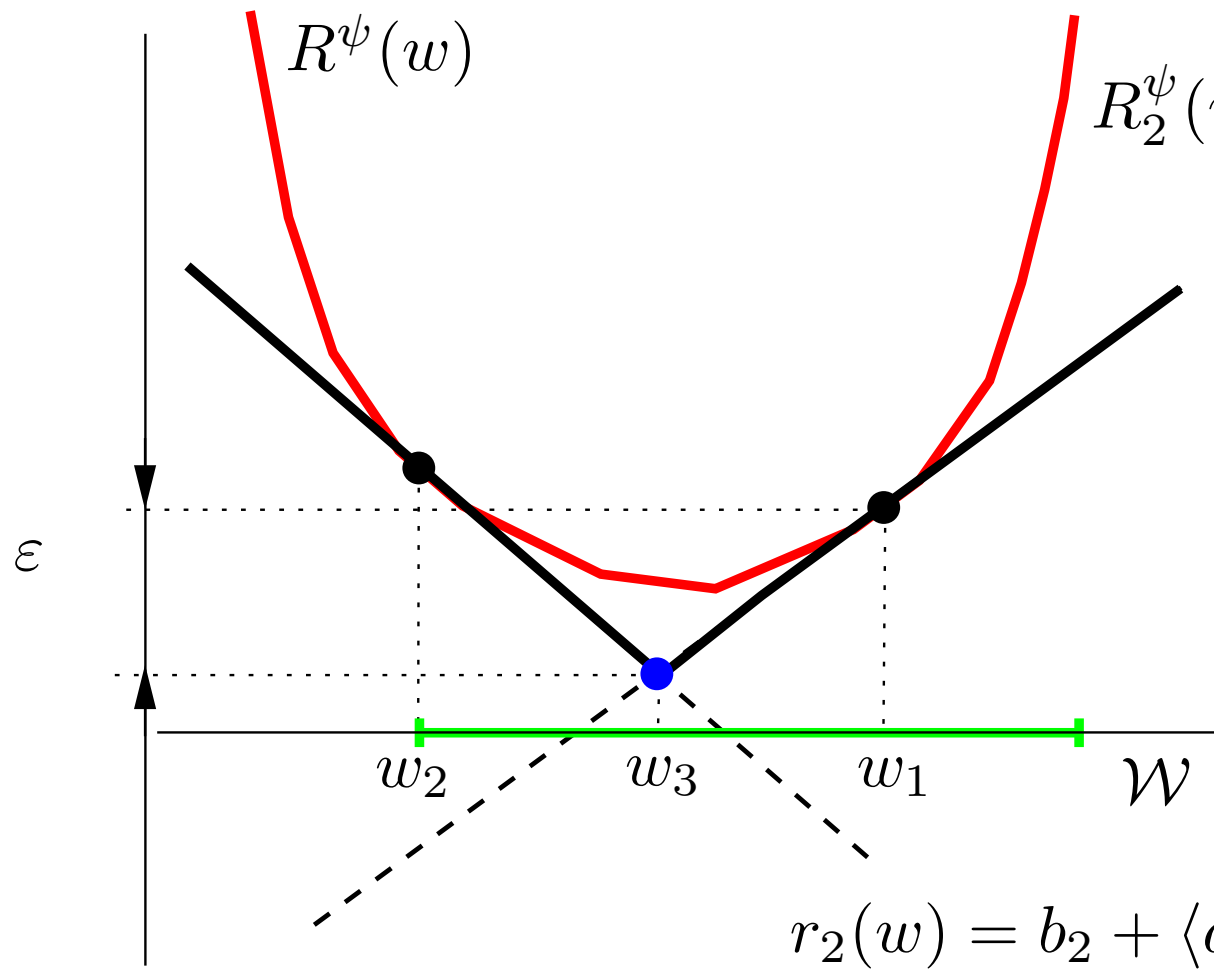












$$R_2^\psi(w) = \max\{r_1(w), r_2(w)\}$$

$$w_2 = \operatorname{argmin}_{w \in \mathcal{W}} R_1^\psi(w)$$

$$w_3 = \operatorname{argmin}_{w \in \mathcal{W}} R_2^\psi(w)$$

$$r_1(w) = b_1 + \langle a_1, w \rangle$$

$$r_2(w) = b_2 + \langle a_2, w \rangle$$

