

CZECH TECHNICAL UNIVERSITY IN PRAGUE

Faculty of Electrical Engineering Department of Cybernetics

Parallel Evolutionary Algorithms. Coevolution.

Petr Pošík



Parallel Evolutionary Algorithms



- Motivation
- Agenda
- Impl. vs model

Global model

Island Model

Other Parallel Models

Summary: PGAs

Coevolution

Problems in coevolution

Summary: Coevolution

Motivation

EAs applied on complex tasks need long run times to solve the problem:

What is usually the most time-consuming task when solving real-world problems?



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- Impl. vs model

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Island Model

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Summary: PGAs

Coevolution

Problems in coevolution

Summary: Coevolution

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 - Fitness evaluation!!!
 - In complex tasks solved by GAs, chromosome is long, often genotype-phenotype mapping must be applied, ...
 - In GP, when evolving classifiers, functions, or programs, the fitness must be assessed by measuring the success when applying the classifier, function, or program on a set of training task instances



- Motivation
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- Impl. vs model

Global model

Island Model

Other Parallel Models

Summary: PGAs

Coevolution

Problems in coevolution

Summary: Coevolution

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- Motivation
- Agenda
- Impl. vs model

Global model

Island Model

Other Parallel Models

Summary: PGAs

Coevolution

Problems in coevolution

Summary: Coevolution

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 \Rightarrow PARALLELIZE!!!



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- Agenda
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Global model

Island Model

Other Parallel Models

Summary: PGAs

Coevolution

Problems in coevolution

Summary: Coevolution

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- ⇒ PARALLELIZE!!!
 - Which of the above can be parallelized easilly???



Agenda

How can we parallelize?

PGA

- Motivation
- Agenda
- Impl. vs model

Global model

Island Model

Other Parallel Models

Summary: PGAs

Coevolution

Problems in coevolution

Summary: Coevolution



Agenda

How can we parallelize?

1. Run several independent GAs in parallel.

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- Motivation
- Agenda
- Impl. vs model

Global model

Island Model

Other Parallel Models

Summary: PGAs

Coevolution

Problems in coevolution

Summary: Coevolution



- Motivation
- Agenda
- Impl. vs model

Global model

Island Model

Other Parallel Models

Summary: PGAs

Coevolution

Problems in coevolution

Summary: Coevolution

Agenda

- 1. Run several independent GAs in parallel.
- 2. Run a single GA, but distribute the time consuming things to parallel machines. (**Master-slave model.**)



- Motivation
- Agenda
- Impl. vs model

Global model

Island Model

Other Parallel Models

Summary: PGAs

Coevolution

Problems in coevolution

Summary: Coevolution

Agenda

- 1. Run several independent GAs in parallel.
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- Motivation
- Agenda
- Impl. vs model

Global model

Island Model

Other Parallel Models

Summary: PGAs

Coevolution

Problems in coevolution

Summary: Coevolution

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- 4. Run a single GA with selection that takes only a few individuals into account. (**Spatially embedded model.**)



- Motivation
- Agenda
- Impl. vs model

Global model

Island Model

Other Parallel Models

Summary: PGAs

Coevolution

Problems in coevolution

Summary: Coevolution

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- 5. Run a hybrid parallel GA. (Hierarchical model.)



- Motivation
- Agenda
- Impl. vs model

Global model

Island Model

Other Parallel Models

Summary: PGAs

Coevolution

Problems in coevolution

Summary: Coevolution

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- 6. Other, less standard possibilities. (**Injection model, heterogenous PGA.**)



- Motivation
- Agenda
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Global model

Island Model

Other Parallel Models

Summary: PGAs

Coevolution

Problems in coevolution

Summary: Coevolution

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But first:

■ The difference between parallel model and parallel implementation.

Parallel Implementation vs. Parallel Model

Sequential implementation:

The algorithm is able to run on a single machine in a single process, often in a single thread only.

Parallel implementation:

■ The algorithm is able to take advantage of multiple CPU cores or multiple machines.

The effect of parallelization:

- Reduction in the solution time by *increasing* computational power.
- The speed-up should be proportional to the number of parallel machines.

Global model:

The population is not divided in any way, the selection operator can consider all individuals.

Parallel model:

■ The population is somehow divided into subpopulations, which limits mainly the selection operator.

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Changes the algorithm behavior substantially.

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Possible combinations:

- Sequential implementation of the global model (usual case, simple GA)
- Parallel implementation of the global model (master-slave, brute-force speed-up)
- Sequential implementation of a parallel model (modified behavior)
- Parallel implementation of a parallel model (modified behavior, brute-force speed-up)



Parallelization of the Global Model



Global model

• Master-slave model

Island Model

Other Parallel Models

Summary: PGAs

Coevolution

Problems in coevolution

Summary: Coevolution

Master-slave model

Master

- runs the evolutionary algorithm, and
- controls the slaves, distributes the work.

Slaves

- take batches of individuals from the master,
- evaluate them, and
- send their fitness back to the master.

Other possibilities:

- Sometimes we can parallelize also initialization, mutation, and (with a bit of care) crossover.
- The hardest parts to parallelize are selection and replacement.
- When does the parallelization actually pay off???



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Island Model

Other Parallel Models

Summary: PGAs

Coevolution

Problems in coevolution

Summary: Coevolution

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Master-slave implementation does not change the behavior of the global model.

■ Hints on implementation (locking, synchronizing) can be found in [Luk09, chap. 5].

[Luk09] Sean Luke. Essentials of Metaheuristics. 2009. available at http://cs.gmu.edu/~sean/book/metaheuristics/.



Island Model



Island Model

Also called *coarse-grained PGA* or *multi-deme GA*:

■ By far the most often used model of PGA.

PGA

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Island Model

- Island Model
- Migration
- Migration (cont.)

Other Parallel Models

Summary: PGAs

Coevolution

Problems in coevolution

Summary: Coevolution



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Coevolution

Problems in coevolution

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Coevolution

Problems in coevolution

Summary: Coevolution

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- Demes evolve independently.



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Problems in coevolution

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Coevolution

Problems in coevolution

Summary: Coevolution

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Summary: PGAs

Coevolution

Problems in coevolution

Summary: Coevolution

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The profit from island model:

- Demes are smaller:
 - converge faster,
 - can converge to different local optima, but
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Other Parallel Models

Summary: PGAs

Coevolution

Problems in coevolution

Summary: Coevolution

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Summary: PGAs

Coevolution

Problems in coevolution

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DEMO: Island model of PGA applied on TSP

http://labe.felk.cvut.cz/~posik/pga

Migration topology: Where should we take the migrants from and where should we put them?

- static: given in advance, does not change during evolution
- dynamic: the sources and targets are chosen right before particular migration event
 - can take the similarity of demes into account when choosing sources and targets

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 - the number of demes used as sources of migrants for another deme in one particular migration event
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 - \blacksquare diversity \rightarrow convergence; population convergence vs. convergence in time

Migration (cont.)

Migration type: Can the migration events occur individually or in batches?

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Which individuals should be selected as emigrants? Which individuals should be replaced by imigrants?

- Best, worst
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- term *epoch* in the context of PGAs describes the part of evolution betweem 2 migration events



Other Parallel Models



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Island Model

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- Spatially Embedded Model
- Model Combinations
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Summary: PGAs

Coevolution

Problems in coevolution

Summary: Coevolution

Spatially Embedded Model

- Population has a structure (1D grid, 2D toroidal grid, 3D cube, etc.)
- Each individual has a position in this structure.



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Island Model

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Problems in coevolution

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Island Model

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Island Model

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- Easy parallelization via multithreading.
- Very efficient model for vector processors, often found on GPUs:
 - many identical operations can be performed in parallel in the same time



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Coevolution

Problems in coevolution

Summary: Coevolution

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Hierarchical model:

- various combinations of the above mentioned models, e.g.
- island model where each deme uses master-slave fitness evaluation,
- island model where each deme uses spatilly embedded model, etc.



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Island Model

Other Parallel Models

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Coevolution

Problems in coevolution

Summary: Coevolution

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 - Different parameter settings
 - Different operators of selection, crossover, mutation and/or replacement
 - Completely different optimization algorithm (local search, differential evolution, ...)



Global model

Island Model

Other Parallel Models

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Coevolution

Problems in coevolution

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 - Can each deme use a different fitness function????



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Coevolution

Problems in coevolution

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Injection Model

Heterogenous island model where

- each deme uses a different fitness function!!!
- Usable when many quality criteria must be assessed; each deme
 - concentrates on one criterion and
 - submits partial solutions to other demes to be reworked using another criterion.
- Each deme preserves solutions of high quality when only its particular criterion is applied.



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Other Parallel Models

Summary: PGAs

- Summary
- Learning outcomes

Coevolution

Problems in coevolution

Summary: Coevolution

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- Parallelization can increase the speed the EA:
 - parallel implementations
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Global model

Island Model

Other Parallel Models

Summary: PGAs

- Summary
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Coevolution

Problems in coevolution

Summary: Coevolution

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- Parallel models change the behavior of the EA:
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Summary: PGAs

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Coevolution

Problems in coevolution

Summary: Coevolution

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 - parallel implementations
 - parallel models
- Parallel models change the behavior of the EA:
 - they can reduce the danger of premature convergence and speed-up the algorithm in the same time.
- There are many possibilities on parallelization:
 - the optimal decision depends on the (parallel) computer architecture and on the task being solved
 - all possibilities introduce their own set of tunable parameters :-(



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Learning outcomes

After this lecture, a student shall be able to

- explain the main motivation for parallelization;
- explain the difference between parallel *implementation* and parallel *model* of EA;
- describe the features of individual combinations of sequential/parallel implementation and global/parallel model;
- know which parts of individual EAs (fitness evaluation, selection, replacement, mutation, crossover, model building, etc.) can be implemented in parallel easily, and explain why;
- explain the principle and features of the master-slave parallelization;
- implement island model and explain its features, describe the characteristics of migration operator (type, topology, degree of connectivity, trigger, selection/replacement strategy, count);
- describe spatially embedded model, heterogeneous model, injection model, and their use cases.



Coevolution



What is "coevolution"?

PGA

Global model

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Other Parallel Models

Summary: PGAs

Coevolution

- What?
- Types
- 1-pop comp.
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Problems in coevolution

Summary: Coevolution



Global model

Island Model

Other Parallel Models

Summary: PGAs

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Coevolution in EAs:

- The fitness of individuals in a population
 - is not given by the characteristics of the individual (only), but
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- It is closer to the biological evolution than ordinary EAs are.



Global model

Island Model

Other Parallel Models

Summary: PGAs

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Coevolution can help in

- dealing with increasing difficulty of the problem,
- providing diversity in the system,
- producing not just high-quality, but also robust solutions,
- solving complex or high-dimensional problems by breaking them into nearly decomposable parts.



Types of coevolution

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Global model

Island Model

Other Parallel Models

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Island Model

Other Parallel Models

Summary: PGAs

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By relation type:

- cooperative (synergic, compositional)
- competitive (antagonistic, test-based)



Global model

Island Model

Other Parallel Models

Summary: PGAs

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By relation type:

- cooperative (synergic, compositional)
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By the entities playing role in the relation:

- 1-population
 - intra-population
 - individuals from the same population cooperate or compete
- N-population
 - inter-population
 - individuals from distinct populations cooperate or compete



1-population competitve coevolution

Example: The goal is to evolve a game playing strategy

successful against diverse opponents!!!

How would you proceed in an ordinary EA?

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Global model

Island Model

Other Parallel Models

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Global model

Island Model

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Global model

Island Model

Other Parallel Models

Summary: PGAs

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Island Model

Other Parallel Models

Summary: PGAs

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Island Model

Other Parallel Models

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Other Parallel Models

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Solution: Intra-population competitive coevolution

- by playing several games against other strategies in the population.
- All individuals of the same type.
- In the beginning, all are probably quite bad, but some of them are a bit better.
- The fitness (the number of games won) may not rise as expected since your opponents improve with you.



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Island Model

Other Parallel Models

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Example: The goal is to evolve a sorting algorithm

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Island Model

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Global model

Island Model

Other Parallel Models

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Solution: Inter-population competitive coevolution

- 2 populations, 2 species:
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Global model

Island Model

Other Parallel Models

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Island Model

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 - test cases (sequences to sort)
- Fitness evaluation:
 - Algorithm: by its ability to sort. How many sequences is it able to sort correctly? How quickly?
 - Test case: by its difficulty for the current sorting algorithms. How many algorithms did not sort it?
- Predator-prey relationship



Global model

Island Model

Other Parallel Models

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N-population cooperative coevolution

Example: The goal is to evolve a team consisting of

- a goalie, back, midfielder, and forward
- so that they form a good team together.

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Island Model

Other Parallel Models

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Island Model

Other Parallel Models

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Island Model

Other Parallel Models

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Island Model

Other Parallel Models

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Cooperation:

- symbiotic relationship
- \blacksquare good performance of the team \Rightarrow high contribution to fitness of all members



1-population cooperative coevolution

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Global model

Island Model

Other Parallel Models

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Global model

Island Model

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Example: Niching methods for

- diversity preservation
- maintaining several stable subpopulations in diverse parts of the search space



Global model

Island Model

Other Parallel Models

Summary: PGAs

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Global model

Island Model

Other Parallel Models

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Principle:

- better individuals similar to others already in population are thrown away in favour of worse, but diverse individuals
- the selection process is affected by the presence of other individual in the neighborhood



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Ideally, external fitness

- should be static, deterministic and absolute
- can easilly be used as internal fitness

External fitness in coevolution:

- impossible (hard) to define
- often, it is relative, but measured with a carefully chosen, large enough set of other individuals (static) sufficiently many times (almost deterministic)

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Internal fitness in coevolution:

- **relative**: affected by other individuals
- dynamic: affected by evolving individuals (needs re-evaluation)
- **stochastic**: usually evaluated against a smaller number of individuals



"Fitness" in sport

Football league:

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- all teams play against all others
- points awarded for win, draw, and loss
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- Is Arnold Palmer better than Tiger Woods?
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The same holds for fitness assessment in coevolution!



Problems with fitness assessment: 1-pop. competitive coevolution

Cycles, etc.

■ What if A beats B, B beats C, but C beats A?

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Global model

Island Model

Other Parallel Models

Summary: PGAs

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- "Fitness" in sport
- 1-pop. comp.
- Predator-prey
- 2-pop. comp.
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- What if A beats B, B beats C, but C beats A?
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Island Model

Other Parallel Models

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Island Model

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- The quality assessment depends on what we really want:
 - A player that beats the most other players?
 - A player that beats the most other "good" players?
 - A player that wins by the most total points on average?
- Often, additional matches are executed.
- But, do you want to spend your fitness budget
 - on evaluating current individuals more precisely, or
 - on searching further?



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- N-pop. coop.

Summary: Coevolution

2 competitive populations (illustration)

Lotka-Volterra model (Predator-prey population dynamics):

$$\frac{dx}{dt} = \alpha x - \beta x y$$

$$\frac{dy}{dt} = -\gamma y + \delta xy$$

where *x* is the number of prey (rabbits) and *y* is the number of predators (wolves).

Assumptions:

- 1. The prey population has always food enough.
- 2. The predators eat only the prey.
- 3. The rate of change of population is proportional to its size.
- 4. The environment is static.



Global model

Island Model

Other Parallel Models

Summary: PGAs

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Meaning:

- The change of the prey population (dx/dt) is composed of
 - increase due to the newly born individuals (proportional to the population size, αx) and
 - decrese caused by the predation (which is proportional to the rate of predator-prey meetings, βxy).
- The change of the predator population (dy/dt) is composed of
 - decrease due to natural death (proportional to the population size, γy) and
 - increase allowed by the food suply (proportional to the rate of predator-prey meetings, δxy).



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Island Model

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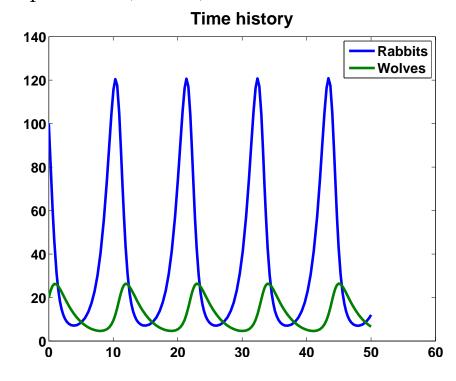
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PGA

Island Model

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- one population learns a trick and forces the second population to learn a new trick to beat the first one...
- one population may evolve faster than the other:



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Island Model

Other Parallel Models

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Island Model

Other Parallel Models

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Other Parallel Models

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Island Model

Other Parallel Models

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- not exactly what was shown by Lotka-Volterra, but similar
- Solution:
 - detect such situation (but how?)
 - delay the evolution of the better population until the worse one catches up

Problems with fitness assessment: N-pop. cooperative coevolution

Hijacking (in team of goalie, back, midfield, and forward):

- a really good forward takes over one population, any team will play well thanks to him
- \blacksquare members of all other populations have almost the same fitness \Rightarrow uniform random selection
- Solution: apply some form of *credit assignment*

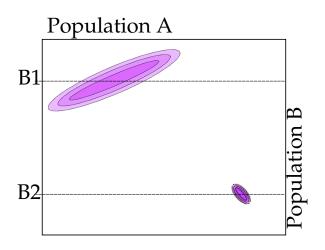
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Relative overgeneralization

- when evaluated by average score, worse (but more robust) individual B1 will have higher score than better (but volatile) B2
- use maximum score (more tests needed)
- but again, the choice depends on what we want a player able to get the highest score, or a player that would form a good team with the most other team members?



Problems with fitness assessment: N-pop. cooperative coevolution

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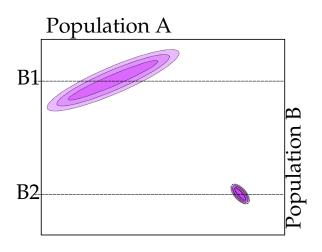
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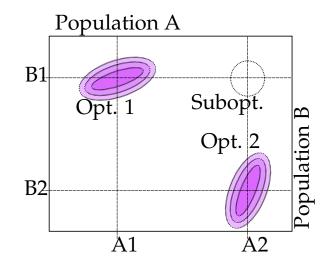
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Miscoordination

- when the team components are not independent
- Pop. A evolved A2 (but not A1), pop. B evolved B1 (but not B2)
- Neither A2 nor B1 survives







Summary: Coevolution



Global model

Island Model

Other Parallel Models

Summary: PGAs

Coevolution

Problems in coevolution

Summary: Coevolution

- Summary
- Learning outcomes

Summary

Coevolution

- can be cooperative or competitive (or both)
- can take place in 1 population or in more populations
- fitness is not fixed during evolution
- introduces new unexpected dynamics to the system (new issues to be solved)



Global model

Island Model

Other Parallel Models

Summary: PGAs

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Summary: Coevolution

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Appropriate when

- no explicit fitness function can be formed
- there are too many fitness cases
- the problem is modularizable (divide and conquer)



Global model

Island Model

Other Parallel Models

Summary: PGAs

Coevolution

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Summary: Coevolution

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Learning outcomes

After this lecture, a student shall be able to

- define "coevolution", explain what makes it different from ordinary evolution in the context of optimization algorithms;
- explain differences between cooperative and competitive coevolution;
- explain differences between *intra* and *inter*-population coevolution;
- define features of fitness measure (static/dynamic, deterministic/stochastic, absolute/relative, internal/external);
- describe the features of an ideal external (and internal) fitness, and describe the features of internal fitness in coevolution;
- exemplify individual types of cooperative/competitive intra-/inter-population coevolution; and
- exemplify various types of issues that can be observed in them (how to order individuals based on inconsistent matches, loss of diversity when one population evolves faster than the other, hijacking, relative overgeneralization, miscoordination).