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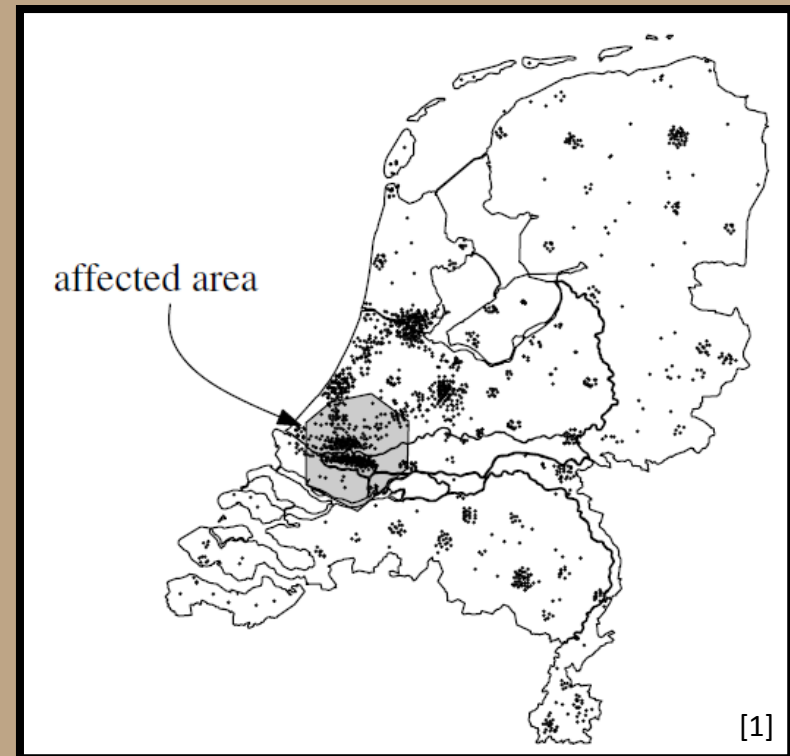
Partition trees

Radek Loucký

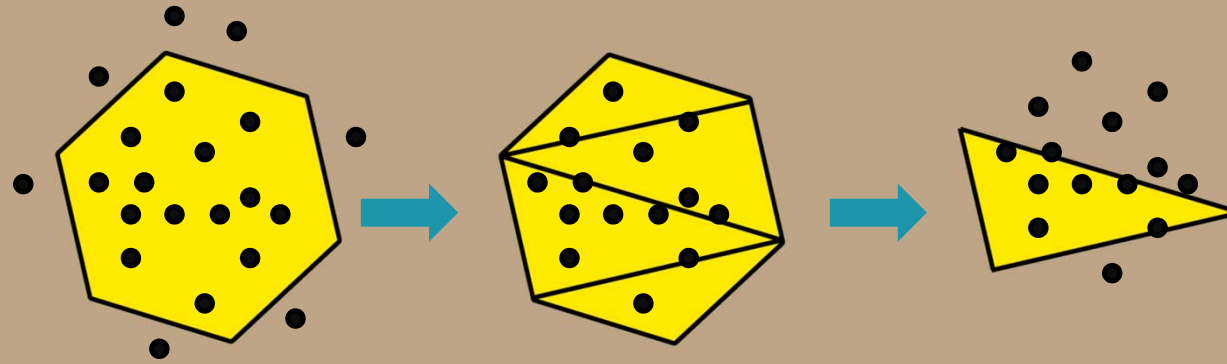
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What is it about?

- set of points in the plane and we want to count the points lying inside a query region
- count number of cities in range



Query region



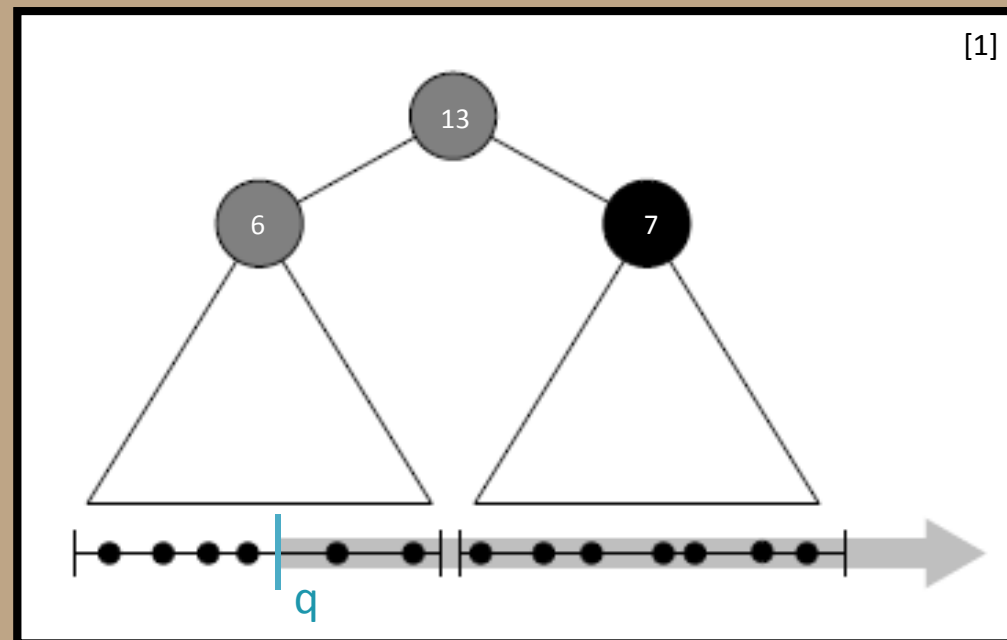
- preprocessing
- query region is a polygon (if no, we can approximate it)
- triangulate region
- query each of the resulting triangles
- return set of points in all triangles

... but first, let's start with something easier

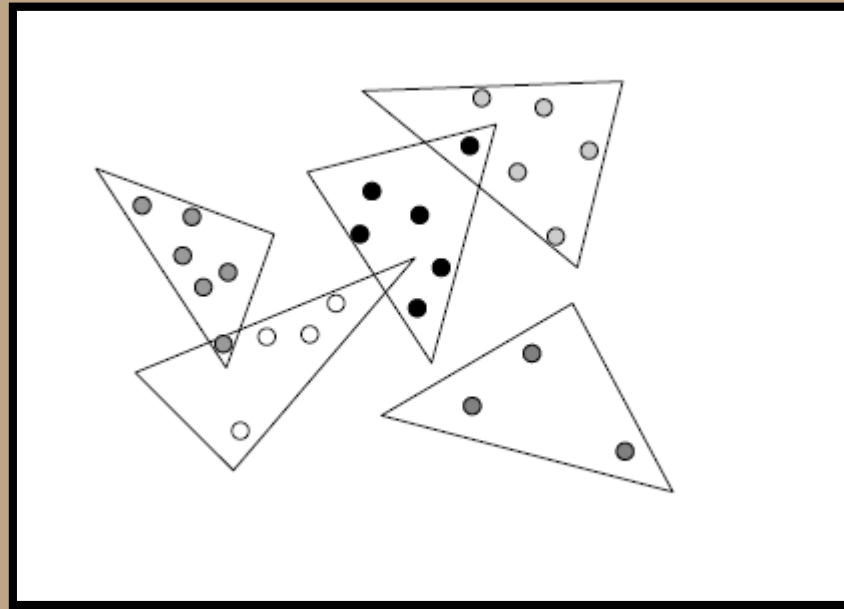
The 1D case

- how does it look like in 1D ?
- binary search tree
- **one region is completely contained in query line, one is disjoint**

On each level is visited only 0 – 1 subtree recursively

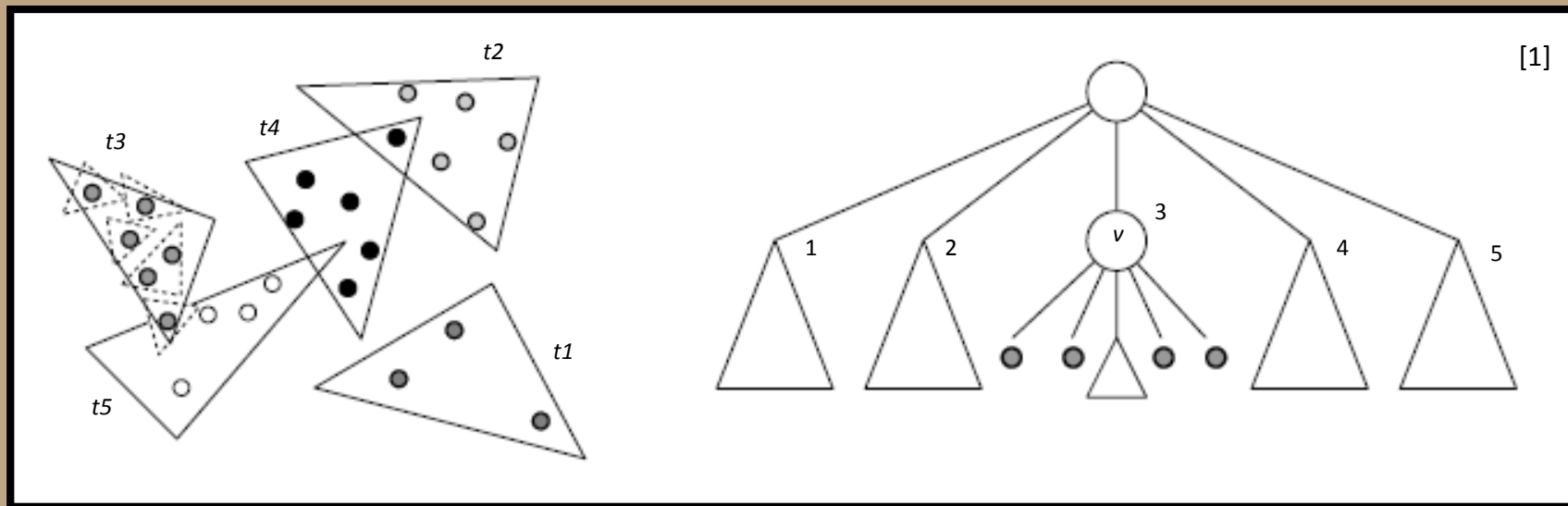


Can we use same approach in 2D?

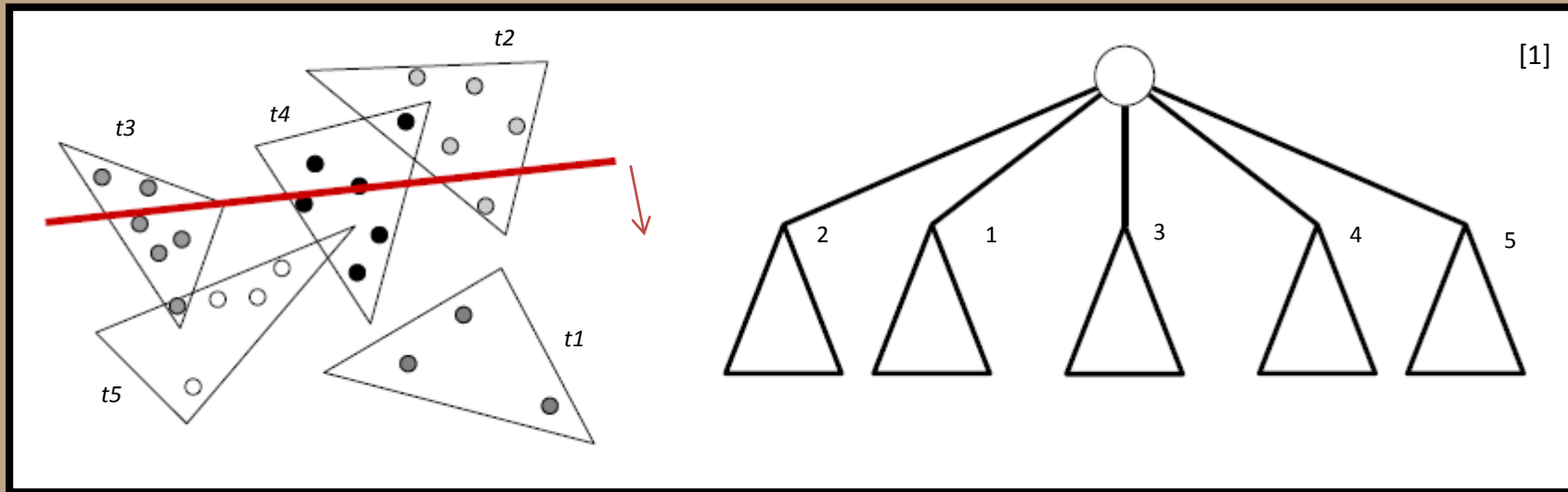


The 2D case – partition tree

- the structure is a tree T of branching degree r
- with each child v we store the triangle $t(v)$
- *crossing number* ... maximum triangles crossed by any line
- *fine partition* ... every group contains $\leq 2n/r$ points
the subsets are fairly equally distributed



2D example

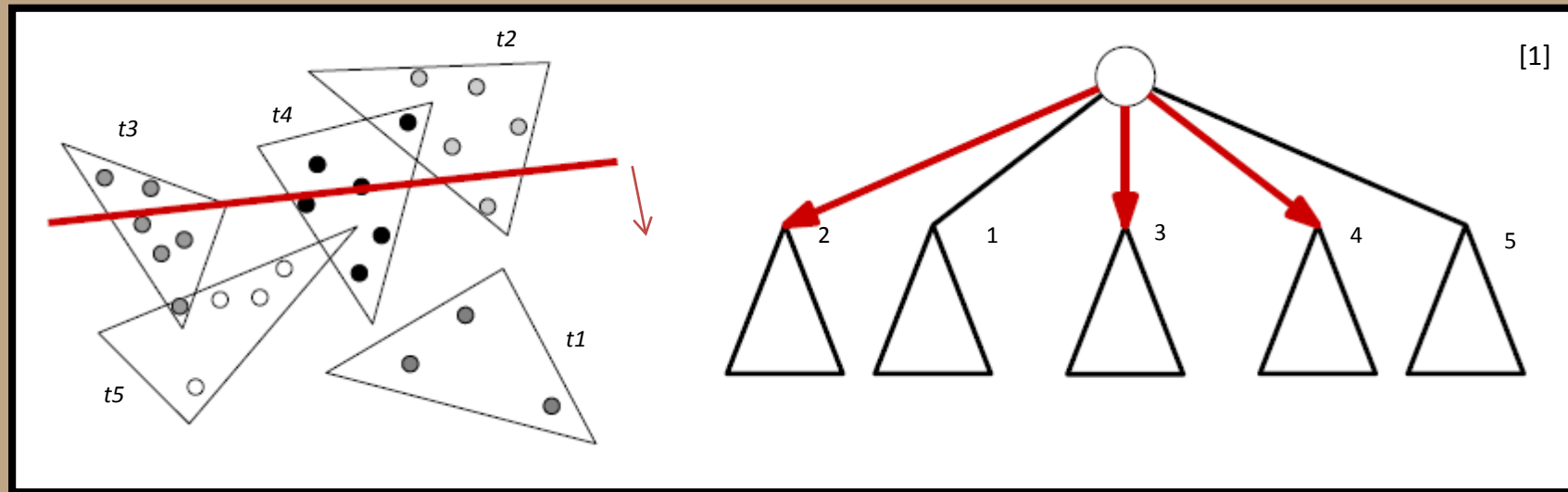


Pseudo-code

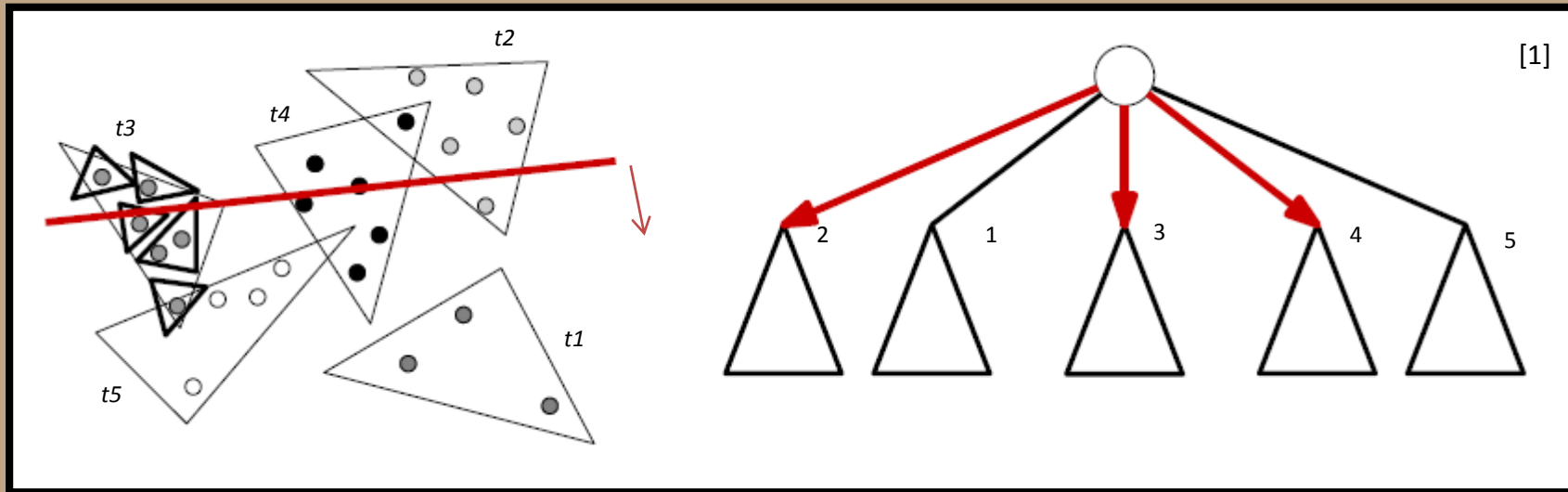
```
SELECTINHALFPLANE(half-plane  $h$ , partition tree  $\mathcal{T}$ )
 $N \leftarrow \emptyset$   { set of selected nodes }
if  $\mathcal{T} = \{\mu\}$  then
  | if point stored at  $\mu$  lies in  $h$  then
  | |  $N \leftarrow \{\mu\}$ 
else
  | for each child  $\nu$  of the root of  $\mathcal{T}$  do
  | | if  $t(\nu) \subset h$  then
  | | |  $N \leftarrow N \cup \{\nu\}$ 
  | | else
  | | | if  $t(\nu) \cap h \neq \emptyset$  then
  | | | |  $N \leftarrow N \cup \text{SELECTINHALFPLANE}(h, \mathcal{T}_\nu)$ 
return  $N$ 
```

[1]

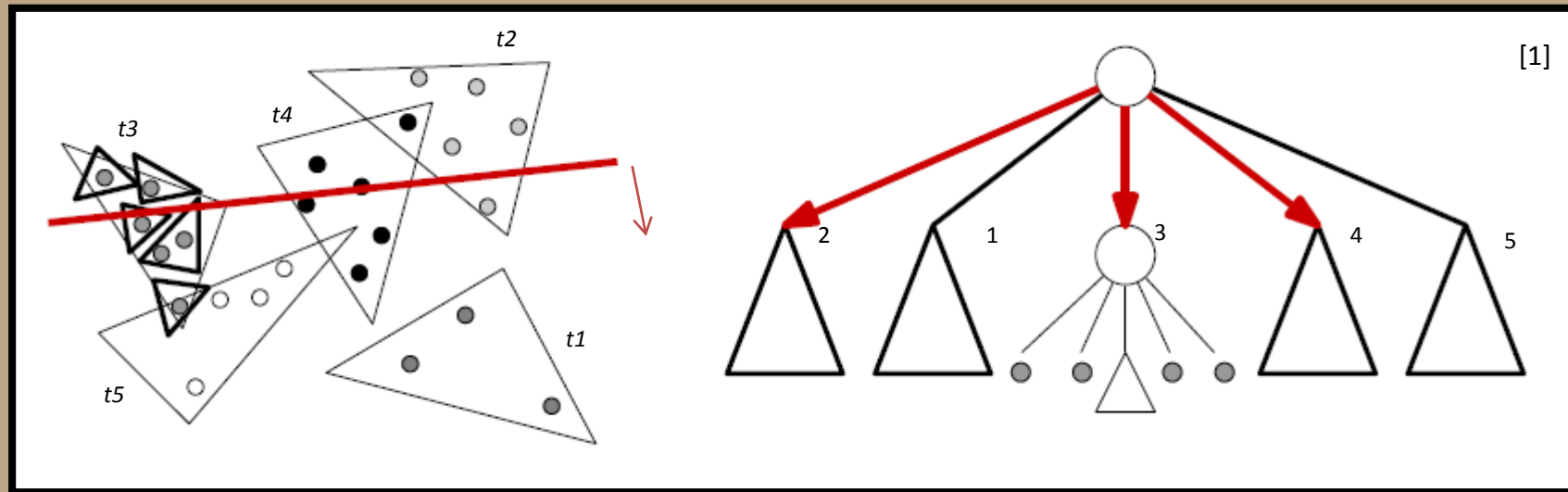
2D example



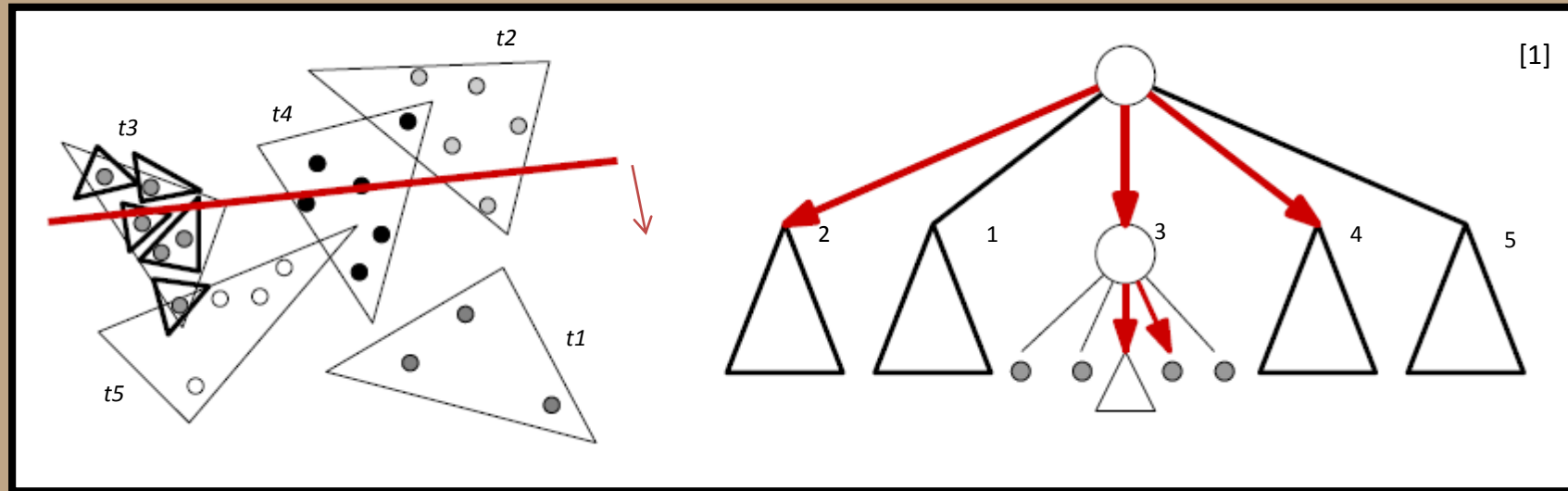
2D example



2D example

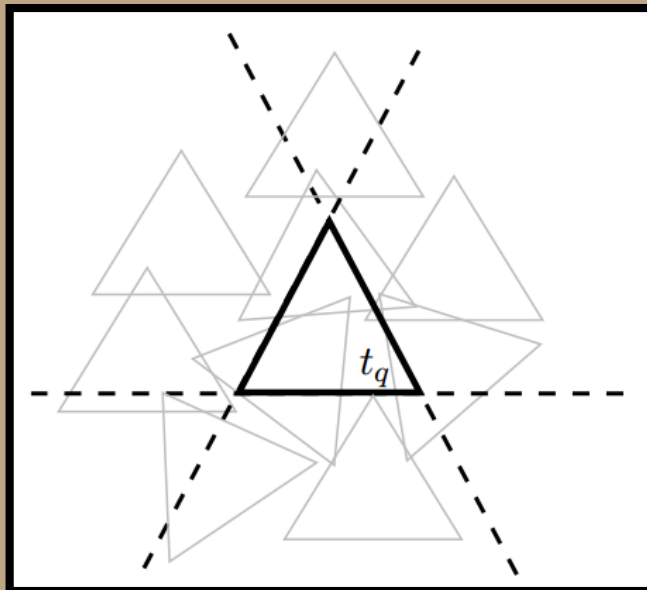


2D example



Which modifications do we need if we want to use triangles instead of half-planes?

None



Tree properties

Theorem:

For any set S of n points in the plane and any parameter r with $1 \leq r \leq n$, ψS of size r and crossing number $O(\sqrt{r})$ exists.

Moreover, for any $\varepsilon > 0$ such ψS can be constructed in time $O(n^{1+\varepsilon})$.

[2]

- *crossing number* ... maximum triangles crossed by any line

Theorem:

Given a set S of n points in the plane, for any $\varepsilon > 0$, a **triangular range-counting query can be answered in $O(n^{1/2+\varepsilon})$ time** using a partition tree.

The tree can be **built in $O(n^{1+\varepsilon})$ time and uses $O(n)$ space.**

[2]

References

[1] M. de Berg, O. Cheong, M. van Kreveld, M. Overmars
Computational geometry, Algorithm and applications

[2] J. Matoušek, Efficient partition trees, Discrete & Computational Geometry

[3] Dr. André Schulz, Advanced Data Structures lecture
<http://courses.csail.mit.edu/6.851/spring10/scribe/lec06.pdf>



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