Machine Learning and Data Analysis
Infinite Hypothesis Spaces

Filip Železný

Czech Technical University in Prague
Faculty of Electrical Engineering
Department of Cybernetics
Intelligent Data Analysis lab
http://ida.felk.cvut.cz

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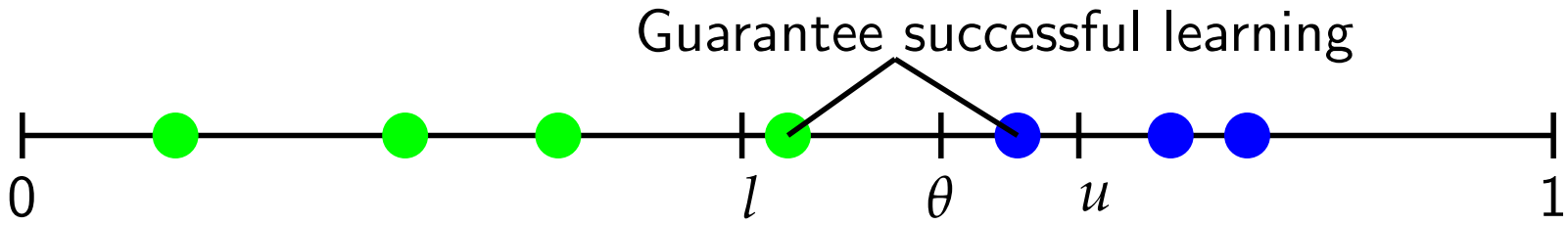
PAC Learning Summary

Concept class (efficiently) PAC learnable by a hypothesis class if

- a *consistent* hypothesis can be (efficiently) produced for each sample
- size of hypothesis space at most exponential

Two weeks ago we proved PAC-learnability of threshold hypotheses on $[0;1]$



Here PAC-learnability does not follow from the above principle since there are ∞ threshold hypotheses. Can we extend the above principle to cover infinite hypothesis classes?

An Intuitive Approach

Assume θ has finite precision, say 64 bits. In a digital machine, this is the case anyway.

For threshold hypotheses on $[0,1]$:

$$\ln|\mathcal{F}| = \ln|2^{64}| = 64\ln 2$$

For threshold hypotheses

$$f(x) = 1 \text{ iff } \theta_1 x^{(1)} + \theta_2 x^{(2)} > 0$$

on $[0,1]^2$:

$$\ln|\mathcal{F}| = \ln|2^{2\cdot 64}| = 128\ln 2$$

Generally for hypothesis classes with n parameters

$$\ln|\mathcal{F}| = \ln|2^{64n}| = 64n\ln 2 = \mathcal{O}(n)$$

An Intuitive Approach (cont'd)

$\ln |\mathcal{F}|$ linear in number of hypothesis-class parameters and precision of real-number representation

Approach seems viable, allows PAC-learning

Problem:

$$\begin{array}{lll} \mathcal{F}_1: & f(x) = 1 \text{ iff } \theta_1 x^{(1)} + \theta_2 x^{(2)} > 0 & \text{2 parameters} \\ \mathcal{F}_2: & f(x) = 1 \text{ iff } |\theta_1 - \theta_2| x^{(1)} + |\theta_3 - \theta_4| x^{(2)} > 0 & \text{4 parameters} \end{array}$$

Different number of parameters but $\mathcal{F}_1 = \mathcal{F}_2$!

Instead of the number of parameters and precision, we will build a different characterization of infinite hypothesis classes.

$\Pi_{\mathcal{F}}$ function

A finite sample from P_X will be called an *x-sample*.

- $x_1, x_2, \ldots$ instead of $(x_1, y_1), (x_2, y_2), \ldots$

Remind the set-notation we earlier introduced for hypotheses:

- $x \in f$ means the same as $f(x) = 1$

$\Pi_{\mathcal{F}}$ function

For any X and $\mathcal{F}$ and a finite x-sample S define

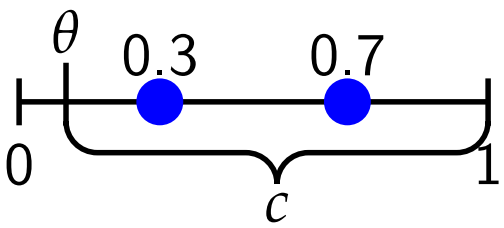
$$\Pi_{\mathcal{F}}(S) = \{f \cap S \mid f \in \mathcal{F}\}$$

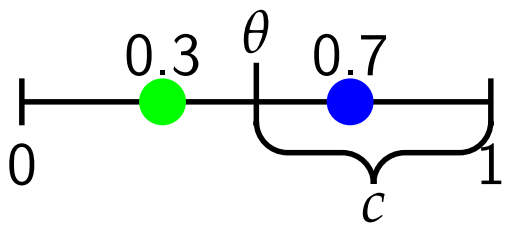
We call $f \cap S$ a *labelling* on S. $\Pi_{\mathcal{F}}(S)$ gives all labellings of S possible with hypotheses from $\mathcal{F}$

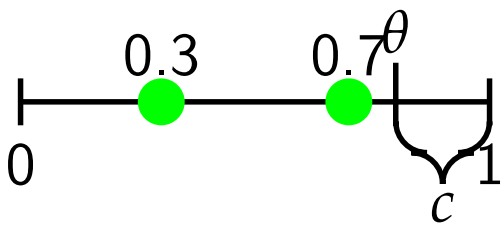
$\Pi_{\mathcal{F}}$ function: Example

Let $\mathcal{F}$ be threshold hypotheses on $[0,1]$ and $S = \{0.3, 0.7\}$

$$\Pi_{\mathcal{F}}(S) = \{\{0.3, 0.7\}, \{0.7\}, \{\}\}$$

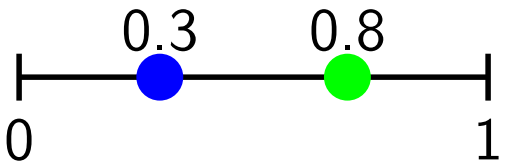






but

$$\{0.3\} \notin \Pi_{\mathcal{F}}(S)$$



Shattering

Shattering

If $|\Pi_{\mathcal{F}}(S)| = 2^{|S|}$ then S is *shattered* by $\mathcal{F}$.

S is shattered by $\mathcal{F}$ if for *any* subset $S' \subseteq S$ there is a hypothesis $f \in \mathcal{F}$ such that $f \cap S = S'$.

Example: let $\mathcal{F}$ be threshold hypotheses on $[0, 1]$

- $\{0.3\}$ and $\{0.7\}$ are shattered by $\mathcal{F}$
- $\{0.3, 0.7\}$ is not shattered by $\mathcal{F}$

VC Dimension

VC Dimension

The *Vapnik-Chervonenkis* dimension of $\mathcal{F}$, denoted $\mathcal{V}(\mathcal{F})$, is the largest d such that some x-sample of cardinality d is shattered by $\mathcal{F}$. If no such d exists, then $\mathcal{V}(\mathcal{F}) = \infty$.

Example: let $\mathcal{F}$ be threshold hypotheses on $[0, 1]$

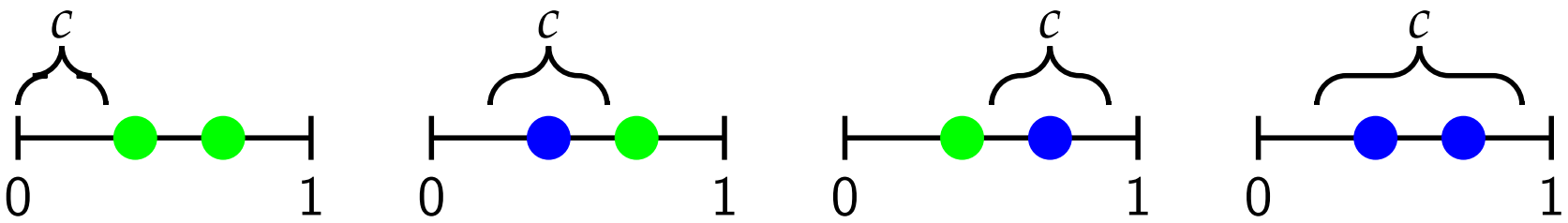
- $\{0.3\}$ is shattered by $\mathcal{F}$
- No x-sample S of cardinality 2 is shattered by $\mathcal{F}$ because $\{\min S\} \subseteq S$, but $S \cap f = \{\min S\}$ for no $f \in \mathcal{F}$.
- Since no x-sample of cardinality 2 is shattered, no x-sample of cardinality > 2 is shattered
- Therefore $\mathcal{V}(\mathcal{F}) = 1$.

VC Dimension: Examples

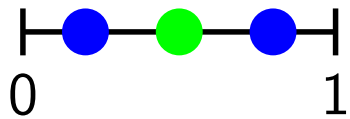
Let $\mathcal{F}$ be intervals $[a,b]$, $0 < a,b < 1$

- $\{0.3, 0.7\}$ is shattered by $\mathcal{F}$
- No x-sample of cardinality 3 or higher is shattered by $\mathcal{F}$ because $\{\min S, \max S\} \subseteq S$ but $S \cap f = \{\min S, \max S\}$ for no $f \in \mathcal{F}$.
- Therefore $\mathcal{V}(\mathcal{F}) = 2$.

Two points shattered



No three points can be shattered, the middle one can never be left out



VC Dimension: Examples

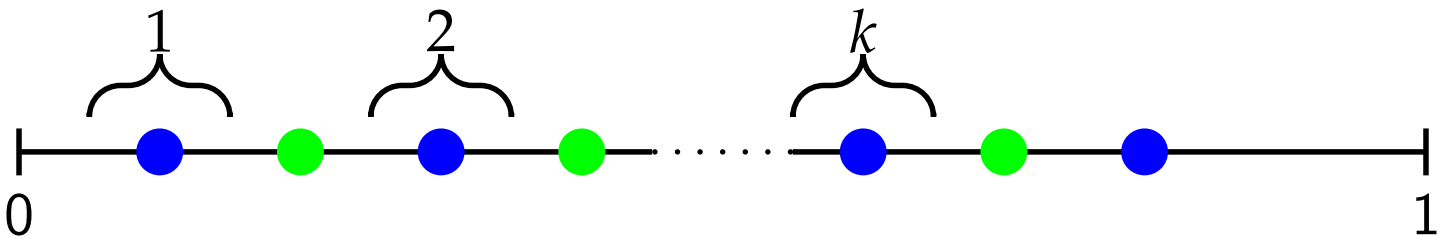
Let $\mathcal{F}$ be unions of k disjoint intervals $[a, b]$

- An x-sample of $2k$ elements shattered by $\mathcal{F}$
- No x-sample of cardinality $2k+1$ or higher is shattered by $\mathcal{F}$. Let $S = \{x_1, x_2, \ldots, x_{2k+1}\}$ such that $x_i < x_j$ for $i < j$. Then for

$$S' = \{x_1, x_3, \ldots x_{2k+1}\}$$

  $S' \subseteq S$ but $S' = S \cap c$ for no $f \in \mathcal{F}$.
- Therefore $\mathcal{V}(\mathcal{F}) = 2k$.

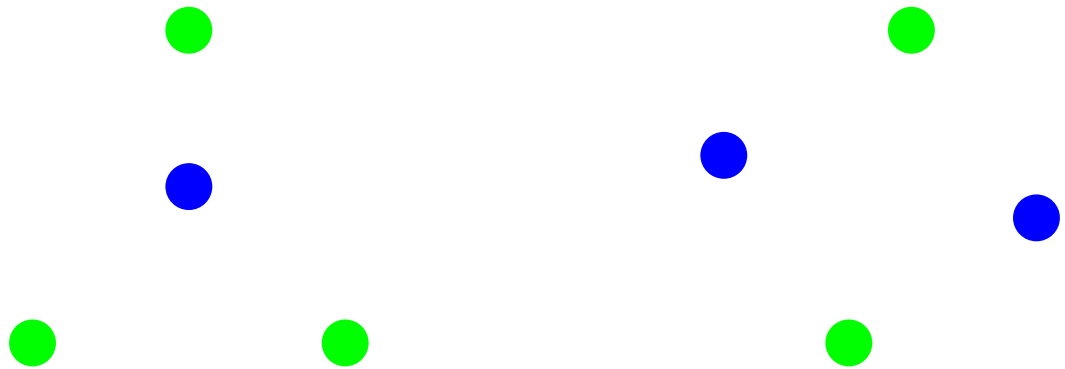
No $2k+1$ points can be shattered



VC Dimension: Examples

Let $\mathcal{F}$ be half-planes in R^2

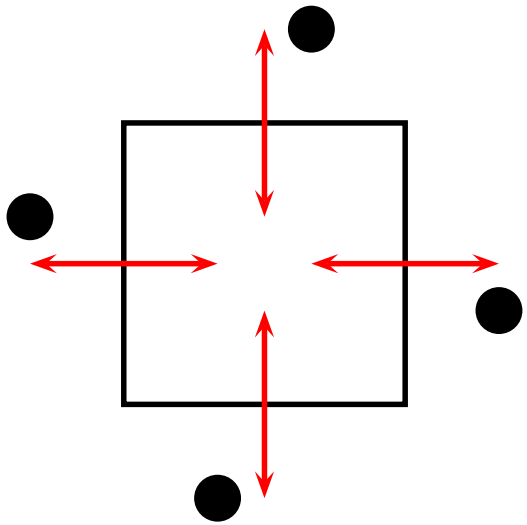
- Some 3 points can be shattered (obvious)
- No 4 points can be shattered. Clear if three of them in line. If not, then two cases possible, and impossible labelling exists in each:



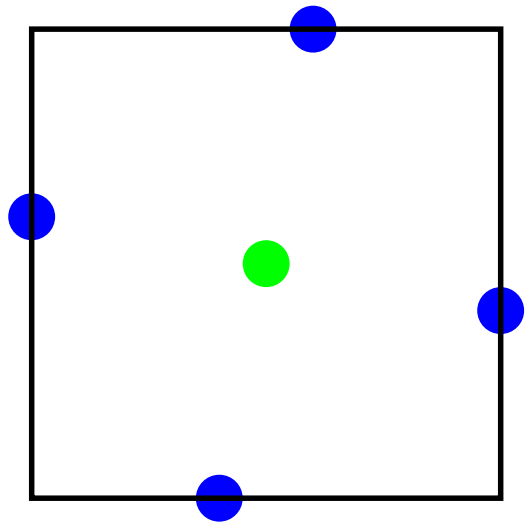
- $\mathcal{V}(\mathcal{F}) = 3$
- similarly shown: $\mathcal{V}(\text{circles in } R^2) = 3$
- Generally, $\mathcal{V}(\text{half-planes in } R^n) = n + 1$

VC Dimension: Examples

Let $\mathcal{F}$ be rectangles in R^2



Some four points can be shattered



Five can never be shattered

- $\mathcal{V}(\mathcal{F}) = 4$
- More generally, $\mathcal{V}(\text{convex tetragons}) = 9$
- More generally, $\mathcal{V}(\text{convex } d\text{-gons}) = 2d + 1$

PAC Learning with Infinite $\mathcal{F}$: Result

PAC Learning with Infinite $\mathcal{F}$

Let $\mathcal{F}$ be a hypothesis class with a finite $\mathcal{V}(\mathcal{F})$ and $\mathcal{C}$ be concept class, both on X. Let $c \in \mathcal{C}$ be a concept. A hypothesis f consistent with a sample $\{(x_1, c(x_1)), \ldots, (x_m, c(x_m))\}$ will have $e(f) \leq \epsilon$ with probability at least $1 - \delta$ if

$$m \geq \max\left(\frac{8}{\epsilon}\log_2\frac{2}{\delta}\,,\ \frac{8\mathcal{V}(\mathcal{F})}{\epsilon}\log_2\frac{13}{\epsilon}\right)$$

Therefore any $\mathcal{C}$ is (efficiently) PAC-learnable by $\mathcal{F}$ if there is an (efficient) learner producing a consistent $f \in \mathcal{F}$ for any sample, and $\mathcal{V}(\mathcal{F})$ is polynomial (in the size of examples n).

As we have seen, $\mathcal{V}(\mathcal{F})$ is usually linear in the number of hypothesis class parameters, which corresponds to n.

$\mathcal{V}(\mathcal{F})$: Remarks

- The result can be rewritten into a simpler form

$$m \geq c_0 \left(\frac{\mathcal{V}(\mathcal{F})}{\epsilon} \log_2 \frac{1}{\epsilon} + \frac{1}{\epsilon} \log_2 \frac{1}{\delta} \right)$$

  where c_0 is a constant.
- The result holds also for finite $\mathcal{F}$. For some $\mathcal{F}$, it may even provide better bounds than those we derived specially for finite $\mathcal{F}$.
- Finite $\mathcal{V}(\mathcal{F})$ is also a necessary condition for PAC-learning. It can be proved that at least

$$\frac{\mathcal{V}(\mathcal{F}) - 1}{64\epsilon}$$

  examples are needed to PAC-learn a concept class with $\mathcal{F}$ if $\delta \leq 1/15$.

Error Bounds for Infinite $\mathcal{F}$

$\mathcal{V}(\mathcal{F})$ also enables to derive error bounds for inconsistent hypotheses.
$\mathcal{V}(\mathcal{F})$ is 'analogical' to $\ln|\mathcal{F}|$ for finite hypothesis classes.

With probability at least $1-\delta$, for a training set S:

$$|e(f) - e(S,f)| \leq \mathcal{O}\left(\sqrt{\frac{\mathcal{V}(\mathcal{F})}{m}\log_2\frac{m}{\mathcal{V}(\mathcal{F})} + \frac{1}{m}\log_2\frac{1}{\delta}}\right)$$

and if f minimizes training error $e(f,S)$ then with probability at least $1-\delta$:

$$e(f) \leq e(f^*) + \mathcal{O}\left(\sqrt{\frac{\mathcal{V}(\mathcal{F})}{m}\log_2\frac{m}{\mathcal{V}(\mathcal{F})} + \frac{1}{m}\log_2\frac{1}{\delta}}\right)$$

where f^* minimizes classification error $e(f)$.

Bias-Variance Trade-off Revisited

Remind: in the finite $\mathcal{F}$ case, by extending $\mathcal{F}$

$$e(f) \leq \underbrace{\left(\min_{f \in \mathcal{F}} e(f)\right)}_{\text{'bias': may decrease}} + \underbrace{2\sqrt{\frac{1}{2m} \ln \frac{2|\mathcal{F}|}{\delta}}}_{\text{'variance': will increase}}$$

This holds analogically for infinite $\mathcal{F}$

$$e(f) \leq \underbrace{\left(\min_{f \in \mathcal{F}} e(f)\right)}_{\text{'bias': may decrease}} + \underbrace{\mathcal{O}\left(\sqrt{\frac{\mathcal{V}(\mathcal{F})}{m} \log_2 \frac{m}{\mathcal{V}(\mathcal{F})} + \frac{1}{m} \log_2 \frac{1}{\delta}}\right)}_{\text{'variance': will increase}}$$

Bias-Variance Trade-off Revisited (cont'd)

Resulting behavior (we have seen this before)