Relaxations

PAH (Planning and Games) Michal Štolba

michal.stolba@agents.fel.cvut.cz

Relaxations

- General approach to computing heuristic estimates
- Relax some constraints
 - I.e. Ignore delete effects
- Compute or estimate cost/length of (optimal) relaxed plan

- Heuristic *h* dominates *h* when
 - 1. $h \le h'$ for all states
 - 2. $h \ge h'$ for all states
 - 3. h = h' for all states

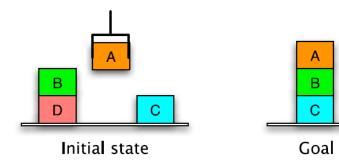
Answer:

2. $h \ge h$ for all states

- What is the most commonly used relaxation of a STRIPS action $a = \langle pre(a), add(a), del(a) \rangle$?:
 - 1. $a^+=<\emptyset,add(a),del(a)>$
 - 2. $a^+=<pre(a), \emptyset, del(a)>$
 - 3. $a^+=<pre(a),add(a), \emptyset >$

Answer:

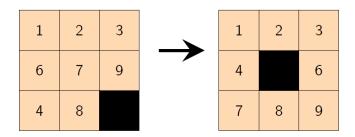
3. $a^+ = \langle pre(a), add(a), \emptyset \rangle$



- Relaxed plan for:
 - 1. put-A-on-B, pickup-B, put-B-on-C, put-A-on-B
 - 2. put-A-on-C, pickup-B, put-B-on-C, put-A-on-B
 - 3. pickup-B, put-B-on-C, put-A-on-B

Answer:

1. put-A-on-B, pickup-B, put-B-on-C, put-A-on-B



- Optimal relaxed plan for:
 - 1. 9d, 7l, 7d, 4u, 6r, 6r
 - 2. 9d, 7r, 6r, 6r, 4u, 7l, 7l, 7d
 - 3. 9d, 8r, 7d, 6r, 6r, 4u, 7l

Answer:

3. 9d, 8r, 7d, 6r, 6r, 4u, 7l

- What is not true:
 - 1. Relaxations of plans are relaxed plans.
 - 2. Relaxations are no harder to solve than the original task.
 - 3. Optimal relaxed plans may be longer than optimal plans for original tasks.

Answer:

3. Optimal relaxed plans may be longer than optimal plans for original tasks.

What heuristic is defined by

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 cost(p) = min(cost(a_1),...,cost(a_n))
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$$cost(a) = max(cost(p_1),...,cost(p_n))$$
:

- 1. h_{max}
- $2. \quad h_{add}$
- h_{STRIPS}

Answer:

1. h_{max}

- For hadd is not true.
 - 1. Assumes independence of facts.
 - 2. All facts are assumed to be achieved by the cheapest action.
 - 3. Is admissible.

Answer:

3. Is not admissible.

- Which heuristic is typically the most informative?:
 - 1. h_{max}
 - 2. h_{add}
 - h_{STRIPS}

Answer:

1. h_{add}

- Which heuristic is admissible?:
 - 1. h_{max}
 - 2. h_{add}
 - h_{STRIPS}

Answer:

1. h_{max}