A Shallow Introduction into the Deep Machine Learning

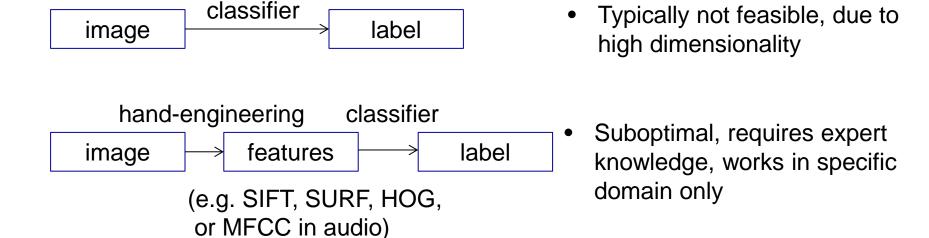


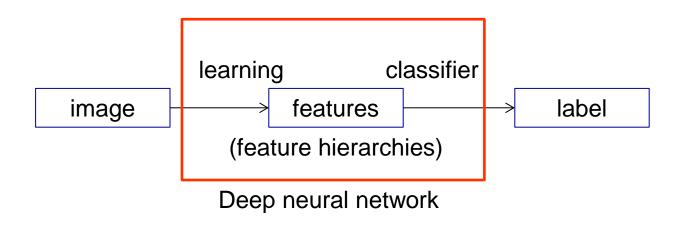
Jan Čech

What is the "Deep Learning"?



- Deep learning
 - = both the classifiers and the features are learned automatically





Deep learning successes



- successes
- Deep learning methods have been extremely successful recently
 - Consistently beating state-of-the-art results in many fields, winning many challenges by a significant margin

Computer vision:

- Hand writing recognition, Action/activity recognition, Face recognition
- Large-scale image category recognition (ILSVRC' 2012 challenge)

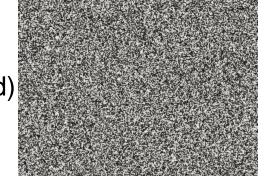
INRIA/Xerox 33%,
Uni Amsterdam 30%,
Uni Oxford 27%,
Uni Tokyo 26%,
Uni Toronto 16% (deep neural network) [Krizhevsky-NIPS-2012]

Automatic speech recognition:

- TIMIT Phoneme recognition, speaker recognition Natural Language Processing, Text Analysis:
- IBM Watson, Google translate



- Natural image statistics
 - Luckily, there is a redundancy in natural images
 - Pixel intensities are not i.i.d. (but highly correlated)
- Sparse coding [Olshausen-1996, Ng-NIPS-2006]



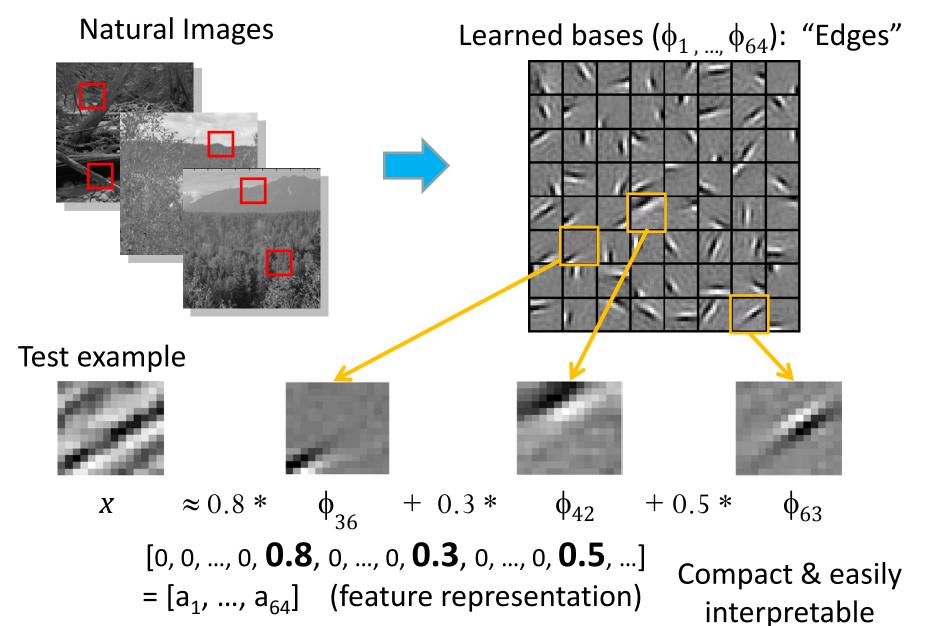
Input images:
$$x^{(1)}, x^{(2)}, \dots, x^{(m)}; (x^{(i)} \in \mathbb{R}^{n \times n})$$

Learn dictionary of basis functions $\phi_1, \phi_2, \ldots, \phi_k$; $(\phi_j \in R^{n \times n})$ that

 $x pprox \sum_{j=1}^{\kappa} a_j \phi_j$; s.t. a_j are mostly zero, "sparse"

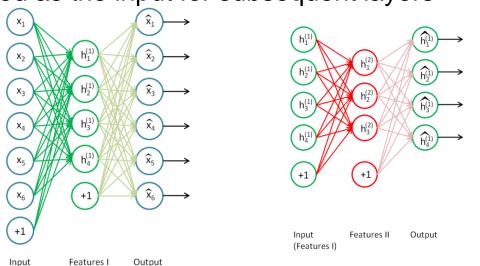
$$\min_{a,\phi} \sum_{i=1}^{m} \left(\left\| x^{(i)} - \sum_{j=1}^{k} a_j^{(i)} \phi_j \right\|^2 + \lambda \sum_{j=1}^{k} |a_j^{(i)}| \right)$$



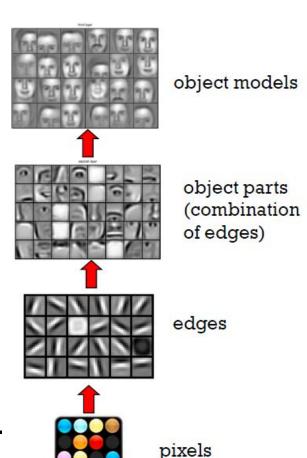


Unsupervised Learning Hierarchies of features

- Many approaches to unsupervised learning of feature hierarchies
 - Sparse Auto-encoders [Bengio-2007]
 - Restricted Boltzmann Machines [Hinton-2006]
- These model can be stacked: lower hidden layer is used as the input for subsequent layers



- The hidden layers are trained to capture higherorder data correlations.
- Learning the hierarchies and classification can be implemented by a (Deep) Neural Network



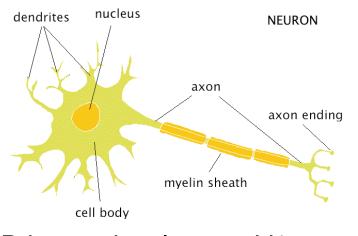
[Lee-ICML-2009]



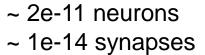
Resemblance to sensory processing in the brain

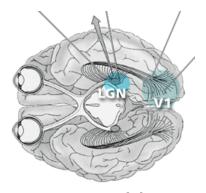


Needless to say that the brain is a neural network









- Primary visual cortex V1
 - Neurophysiological evidences that primary visual cells are sensitive to the orientation and frequency (Gabor filter like impulse responses)
 - [Hubel-Wiesel-1959] (Nobel Price winners)
 - Experiments on cats with electrodes in the brain





- A single learning algorithm hypothesis ?
 - "Rewiring" the brain experiment [Sharma-Nature-2000]
 - Connecting optical nerve into A1 cortex (a subject was able to solve visual tasks by using the processing in A1)

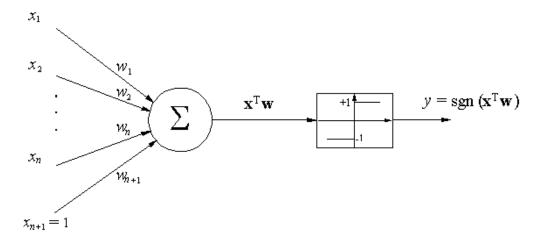
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(Artificial) Neural Networks

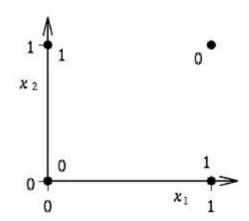




- Neural networks are here for more than 50 years
 - Rosenblatt-1956 (perceptron)

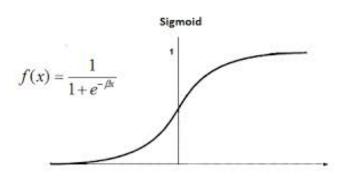


Minsky-1969 (xor issue, => skepticism)



Rumelhart and McClelland – 1986:

- Multi-layer perceptron,
- Back-propagation (supervised training)
 - Differentiable activation function
 - Stochastic gradient descent



Empirical risk

$$Q(w) = \sum_{i=1}^{n} Q_i(w),$$

Update weights:

$$w := w - \alpha \nabla Q_i(w).$$

Back-propagate error signal to get derivatives for learning

Compare outputs with correct answer to get error signal

outputs

hidden layers

What happens if a network is deep? (it has many layers)

What was wrong with back propagation?

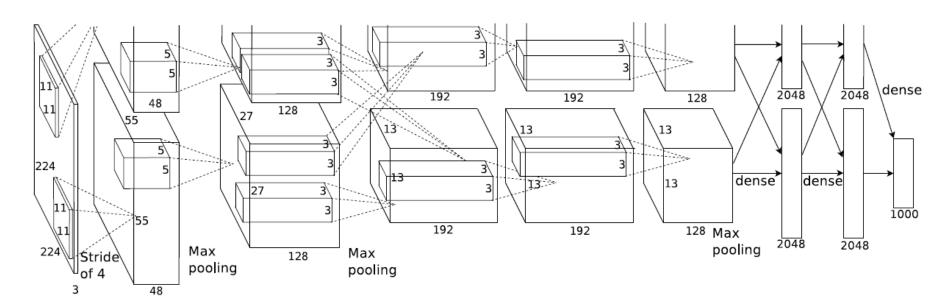


- Local optimization only (needs a good initialization, or re-initialization)
- Prone to over-fitting
 - too many parameters to estimate
 - too few labeled examples
- Computationally intensive
- => Skepticism: A deep network often performed worse than a shallow one
- However nowadays:
 - Weights can be initialized better (Use of unlabeled data, Restricted Boltzmann Machines)
 - Large collections of labeled data available
 - ImageNet (14M images, 21k classes, hand-labeled)
 - Reducing the number of parameters by weight sharing
 - Convolutional layers [LeCun-1989]
 - Fast enough computers (parallel hardware, GPU)
- => Optimism: It works!

Deep convolutional neural networks



- An example for Large Scale Classification Problem:
 - Krizhevsky, Sutskever, Hinton: ImageNet classification with deep convolutional neural networks. NIPS, 2012.
 - Recognizes 1000 categories from ImageNet
 - Outperforms state-of-the-art by significant margin (ILSVRC 2012)



- 5 convolutional layers, 3 fully connected layers
- 60M parameters, trained on 1.2M images (~1000 examples for each category)

Deep convolutional neural networks



- Additional tricks: "Devil is in the details"
 - Rectified linear units instead of standard sigmoid
 - => Mitigate vanishing gradient problem $f(x) = \max(0, x)$
 - Convolutional layers followed by max-pooling
 - Local maxima selection in overlapping windows (subsampling)
 - => dimensionality reduction, shift insensitivity
 - Dropout
 - Averaging results of many independent models (similar idea as in Random forests)
 - 50% of hidden units are randomly omitted during the training, but weights are shared in testing time
 - => Probably very significant to reduce overfitting
 - Data augmentation
 - Images are artificially shifted and mirrored (10 times more images)
 - => transformation invariance, reduce overfitting

Novel tricks





- Network initialization
 - Mishkin, Matas. All you need is a good init. ICLR 2016
 - Weights initialization: zero mean, unit variance, orthogonality
- Batch normalization
 - Iosse, Szegedy. Batch Normalization: Accelerating Deep Network
 Training by Reducing Internal Covariate Shift. NIPS 2015

Zero mean and unit variance weights are "supported" during training

to avoid vanishing gradient

- ⇒ Small sensitivity to learning rate setting (can be higher, faster training
 - 10 times fewer epochs needed)
- ⇒ Regularizer (dropout can be excluded/smaller) (better optimum found)

```
Input: Values of x over a mini-batch: \mathcal{B} = \{x_{1...m}\};

Parameters to be learned: \gamma, \beta

Output: \{y_i = \mathrm{BN}_{\gamma,\beta}(x_i)\}

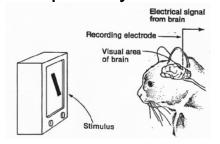
\mu_{\mathcal{B}} \leftarrow \frac{1}{m} \sum_{i=1}^m x_i \qquad \text{// mini-batch mean}
\sigma_{\mathcal{B}}^2 \leftarrow \frac{1}{m} \sum_{i=1}^m (x_i - \mu_{\mathcal{B}})^2 \qquad \text{// mini-batch variance}
\widehat{x}_i \leftarrow \frac{x_i - \mu_{\mathcal{B}}}{\sqrt{\sigma_{\mathcal{B}}^2 + \epsilon}} \qquad \text{// normalize}
y_i \leftarrow \gamma \widehat{x}_i + \beta \equiv \mathrm{BN}_{\gamma,\beta}(x_i) \qquad \text{// scale and shift}
```

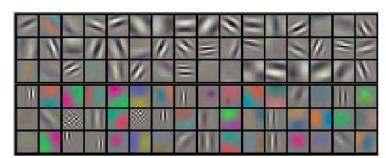
Algorithm 1: Batch Normalizing Transform, applied to activation x over a mini-batch.

Deep convolutional neural networks



- No unsupervised pre-initialization!
 - The training is supervised by standard back-propagation
 - enough labeled data: 1.2M labeled training images for 1k categories
 - Learned filters in the first layer
 - Resemble cells in primary visual cortex



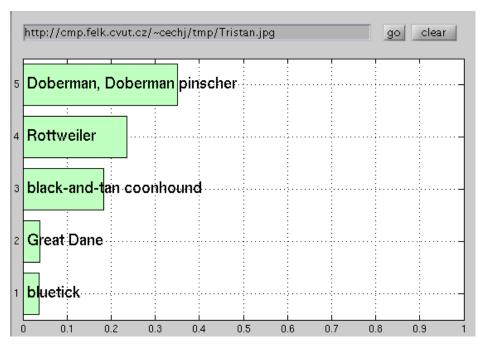


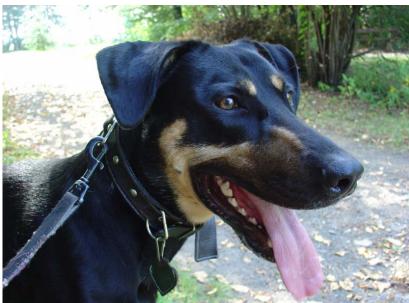
- Training time:
 - 5 days on NVIDIA GTX 580, 3GB memory (Krizhevsky, today faster)
 - 90 cycles through the training set
- Test time (forward step) on GPU
 - Implementation by Yangqing Jia, http://caffe.berkeleyvision.org/
 - 5 ms/image in a batch mode
 - (my experience: 100 ms/image in Matlab, including image decompression and normalization)

Preliminary experiments 1: Category recognition



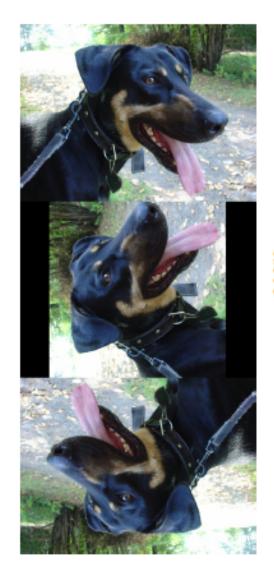
- Implementation by Yangqing Jia, http://caffe.berkeleyvision.org/
 - network pre-trained for 1000 categories provided
- Which categories are pre-trained?
 - 1000 "most popular" (probably mostly populated)
 - Typically very fine categories (dog breeds, plants, vehicles...)
 - Category "person" (or derived) is missing
 - Recognition subjectively surprisingly good...

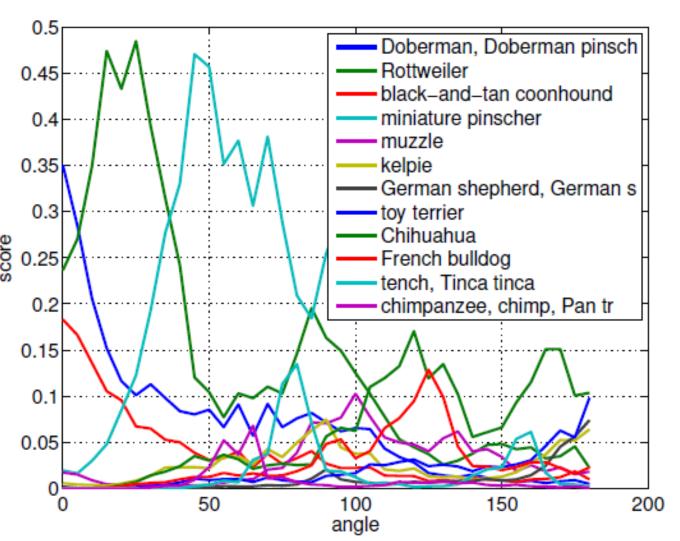




Sensitivity to image rotation





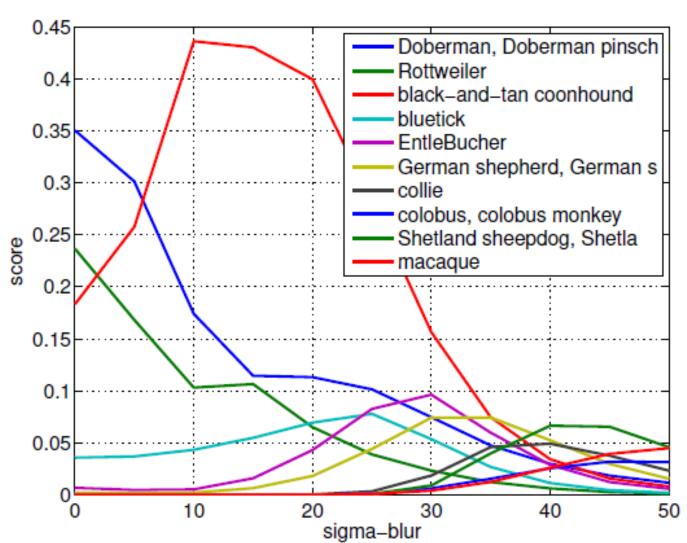


Sensitivity to image blur





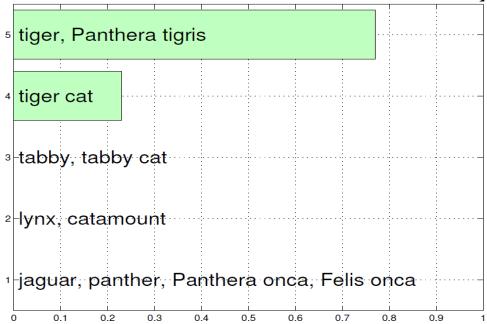




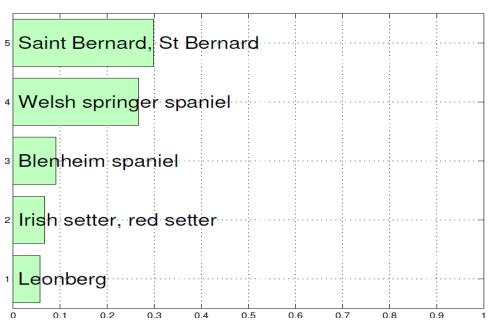
It is not a texture only...





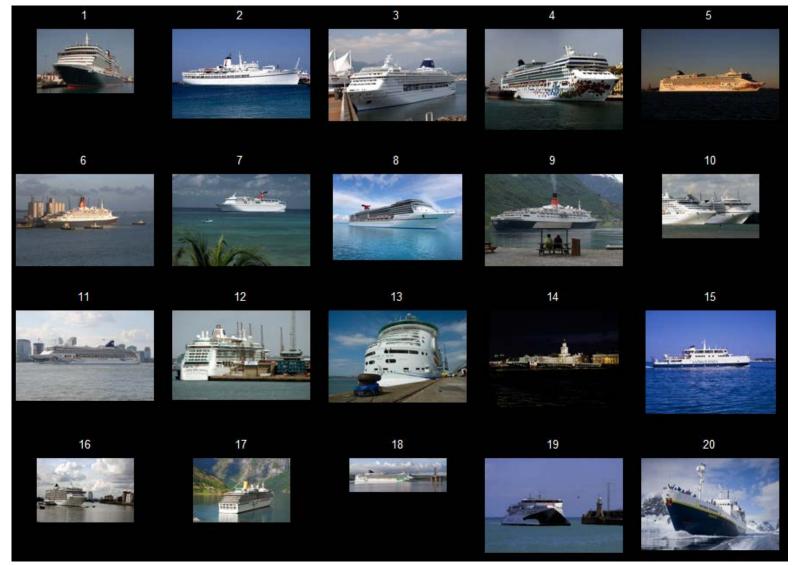






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- Preliminary experiments 2: Category retrieval
- 50k randomly selected images from Profimedia dataset
- Category: Ocean liner



Preliminary experiments 2: Category retrieval





Category: Restaurant (results out of 50k-random-Profiset)



Preliminary experiments 2: Category retrieval

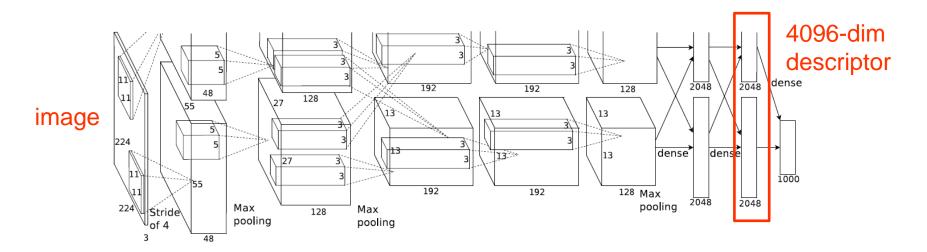


Category: stethoscope (results out of 50k-random-Profiset)





- Indications in the literature that the last hidden layer carry semantics
 - Last hidden layer (4096-dim vector), final layer category responses (1000-dim vector)
 - New (unseen) categories can be learned by training (a linear) classifier on top of the last hidden layer
 - Oquab, Bottou, Laptev, Sivic, CVPR, 2014
 - Girshick, Dphanue, Darell, Malik, CVPR, 2014
 - Responses of the last hidden layer can be used as a compact global image descriptor
 - Semantically similar images should have small Euclidean distance







- Qualitative comparison: (20 most similar images to a query image)
 - 1. MUFIN annotation (web demo), http://mufin.fi.muni.cz/annotation/, [Zezula et al., Similarity Search: The Metric Space Approach.2005.]
 - Nearest neighbour search in 20M images of Profimedia
 - Standard global image statistics (e.g. color histograms, gradient histograms, etc.)
 - Caffe NN (last hidden layer response + Euclidean distance),
 - Nearest neighbour search in 50k images of Profimedia









































MUFIN results







MUFIN results



Caffe NN results









MUFIN results







































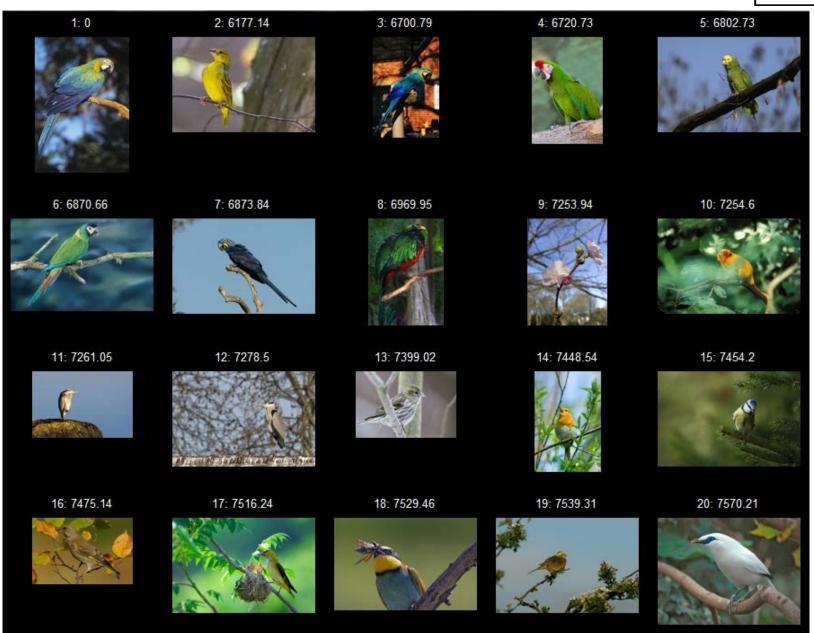


m p

Caffe NN results







MUFIN results







































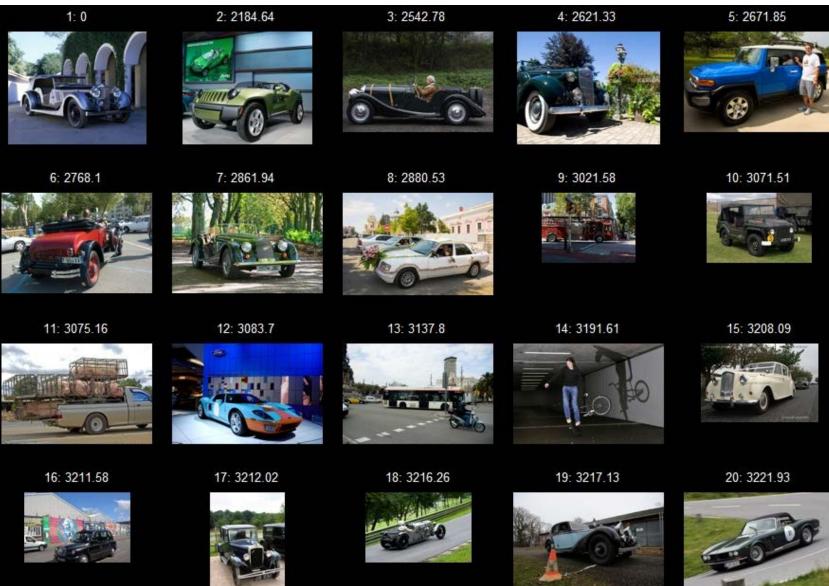


Caffe NN results











MUFIN results









































m p









MUFIN results





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Bo de l'Aigle Maison de la









6: 3477.87

Forêt de Miers











11: 3749.72



12: 3774.72



FLAT SOLD

13: 3786.68







15: 3826.56

16: 3845.7



ROMANIN H Château Romanin

17: 3849.7



19: 3952.4



20: 3979.94



MUFIN results

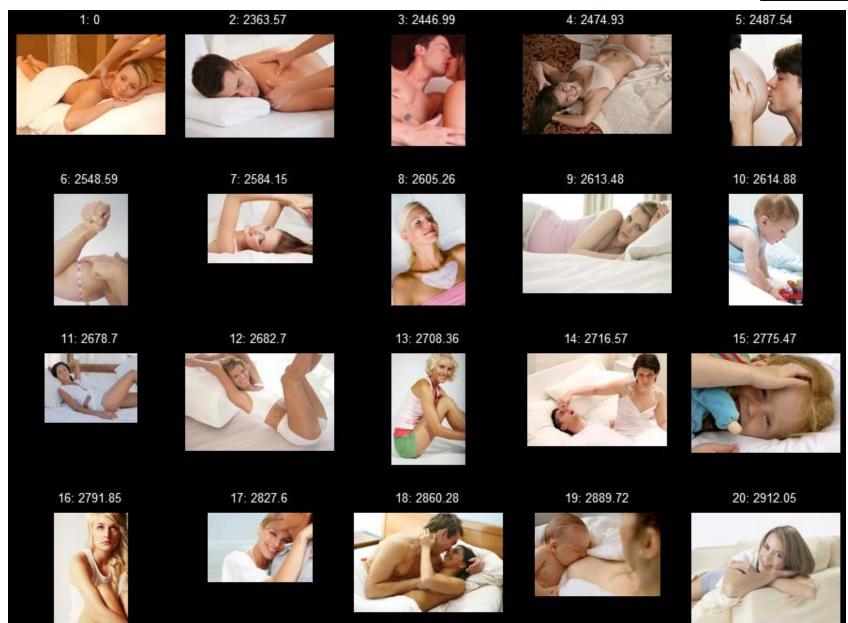


m p

Caffe NN results







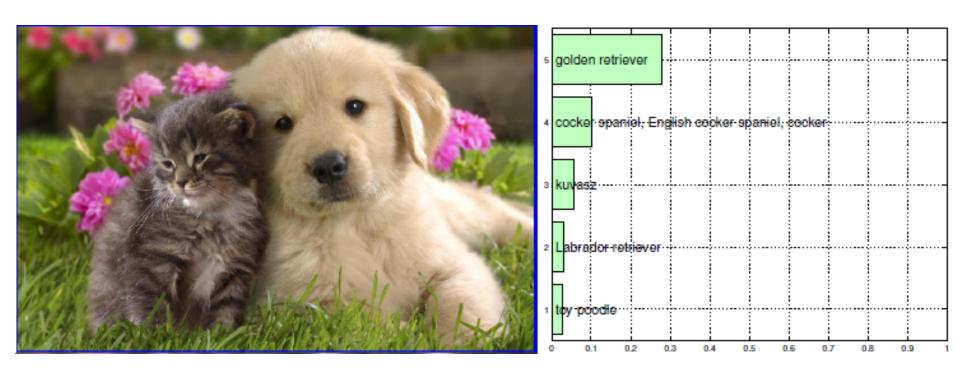
MUFIN results



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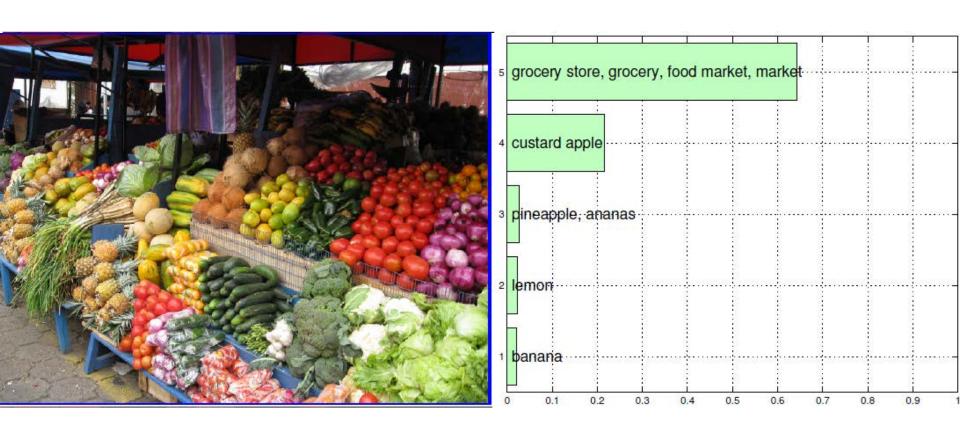




Multiple object classes



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Object detection: Deep Nets and Sliding Windows

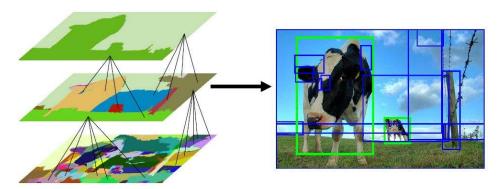




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- An image of a scene contains multiple objects
- Exhaustive sliding window detector is prohibitively slow
- => Category independent region proposals:
 - Objectness [Alexe-TPAMI-2012]
 - Selective search [Uijlings-IJCV-2013]

More recent approches, see next lecture



Edgeboxes [Zitnick-ECCV-2014]



Face interpretation tasks

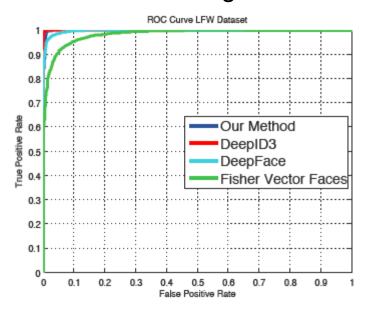


- Face recognition, face verification
 - Architecture similar to AlexNet very deep CNN (softmax at the last) layer)

[Taigman-ECVV-2014] DeepFace: Closing the Gap to Human-Level Performance in Face Verification (authors from Facebook)

[Parkhi-BMVC-2015] Deep Face recognition (authors from Oxford Uni)

- 2.6M images of 2.6k celebrities, trained net available



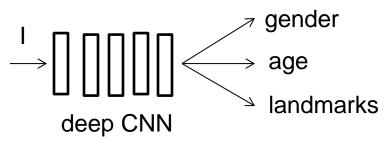
No.	Method	# Training Images	# Networks	Accuracy
1	Fisher Vector Faces	-	-	93.10
2	DeepFace (Facebook)	4 M	3	97.35
3	DeepFace Fusion (Facebook)	500 M	5	98.37
4	DeepID-2,3	Full	200	99.47
5	FaceNet (Google)	200 M	1	98.87
6	FaceNet+ Alignment (Google)	200 M	1	99.63
7	(VGG Face)	2.6 M	1	98.78

Face represented by penultimate layer response, similarity serach, large scale indexing

Face interpretation tasks



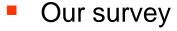
- Facial landmarks, Age / Gender estimation
 - Multitask network
 - Shared representation
 - Combination of both classification and regression problems





Age estimation – How good the network is?





~20 human subjects, ~100 images of 2 datasets

MORPH dataset

True: 22, MAE: 18.8



True: 36, MAE: 17.8



True: 33, MAE: 16.3



True: 22, MAE: 16.1



True: 25, MAE: 16.0



IMDB dataset

True: 25, MAE: 0.5



True: 66, MAE: 1.0



True: 29, MAE: 1.0



True: 19, MAE: 1.0



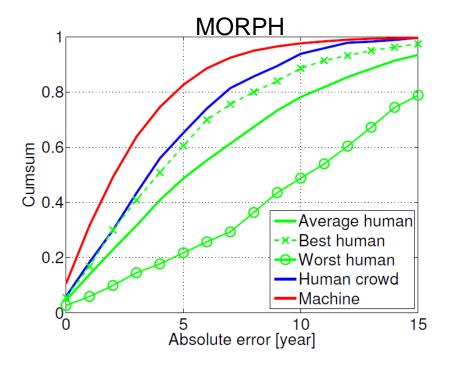
True: 43, MAE: 1.0



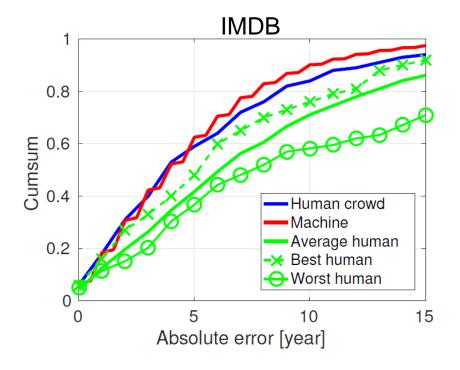
Age estimation – How good the network is?



Better than average human...



	MAŁ	CS5	MaxAL
Average human :	6.8	48.6	24.1
Human crowd :	4.7	65.1	19.0
Machine :	3.2	82.6	26.0



		MAŁ	CS5	Maxae
Average human	:	8.2	41.7	31.5
Human crowd	:	5.7	59.0	21.0
Machine	:	5.1	62.5	42.7

- [Franc-Cech-BwildW-2017]
- Network runs real-time on CPU

General recipe to use deep neural networks



- Recipe to use deep neural network to "solve any problem" (by G. Hinton)
 - Have a deep net
 - If you do not have enough labeled data, pre-train it by unlabeled data;
 otherwise do not bother with pre-initialization
 - Use rectified linear units instead of standard neurons (sigmoid)
 - Use dropout to regularize it (you can have many more parameters than training data)
 - If there is a spatial structure in your data, use convolutional layers
 - − Have fun... ☺
- Novel:
 - Use Batch Normalization [Ioffe-Szegedy-NIPS-2015]
- Experience:
 - Data matters (the more data the better), data augmentation helps
 - Network architecture (if deep enough) is surprisingly not critical

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Conclusions

- It efficiently learns the abstract representation (shared among classes)
 - The network miraculously captures semantics...
- Low computational demands for running, Training needs GPU
- Many "deep" toolboxes: Caffe (Berkeley), MatconvNet (Oxford), TensorFlow (Google), Theano (Montreal), Torch, ...
- NNs are (again) in the "Golden Age" (or witnessing a bubble), as many practical problems seem solvable in near future
- Explosion of interest of DNN in literature, graduates get incredible offers, start-ups appear all the time

Do we understand enough what is going on? http://www.youtube.com/watch?v=LVLoc6FrLi0



