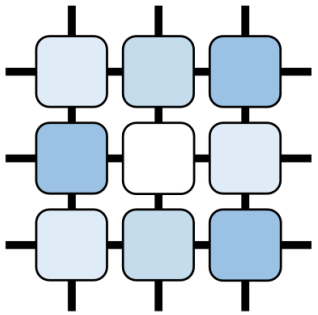


Constraint Satisfaction Problems/Programming

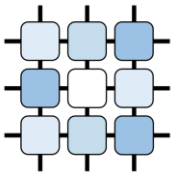
A4B33ZUI, LS 2016

Branislav Bošanský, Ondřej Vaněk, Štěpán Kopřiva

{name.surname}@agents.fel.cvut.cz

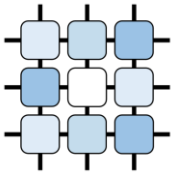
Artificial Intelligence Center, Czech Technical University

State space search → CSP



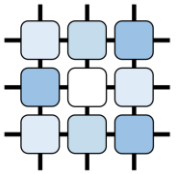
- until now – no assumptions on the states
- CSP:
  - state → array of variables
  - context → domains for variables, set of constraints among the variables
  - goal → all variables have an assigned value, no constraint is violated
- alternative goals
  - optimization variant

Advantages/Disadvantages



- general enough to model many problems
- more efficient algorithms that exploit the structure
  - we can do better than DFS/BFS
  - advanced search techniques can be possibly reused in non-CSP problems
  - generic purpose CSP solvers
- not all problems can be modeled as CSP
- some formulations can be inefficient

Example



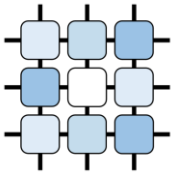
- sudoku

- scheduling requests to hotel rooms
  - list of requests (# of people, from, to)
  - set of rooms (# of beds)
- scheme of the algorithm?
  - states / actions / search algorithm?

Example

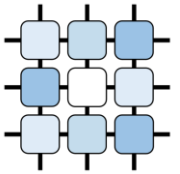
```
function BACKTRACKING-SEARCH(csp) returns solution/failure
    return RECURSIVE-BACKTRACKING({ }, csp)

function RECURSIVE-BACKTRACKING(assignment, csp) returns soln/failure
    if assignment is complete then return assignment
    var ← SELECT-UNASSIGNED-VARIABLE(VARIABLES[csp], assignment, csp)
    for each value in ORDER-DOMAIN-VALUES(var, assignment, csp) do
        if value is consistent with assignment given CONSTRAINTS[csp] then
            add {var = value} to assignment
            result ← RECURSIVE-BACKTRACKING(assignment, csp)
            if result ≠ failure then return result
            remove {var = value} from assignment
    return failure
```

Backjumping



Conflict-driven backjumping

Constraints Graph



Dynamic backjumping

Uzly obarvit barvami 1,2,3, poradi A, B, C, D, E