

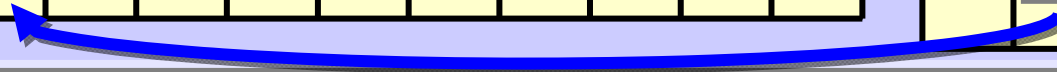
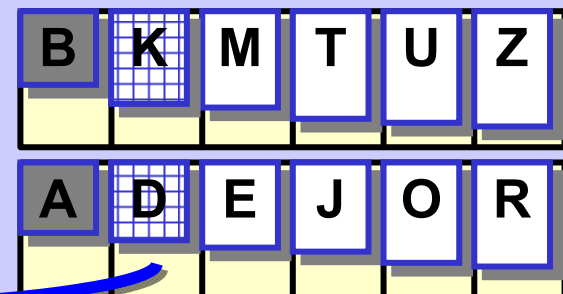
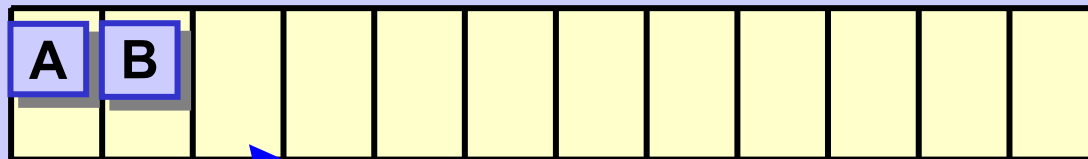
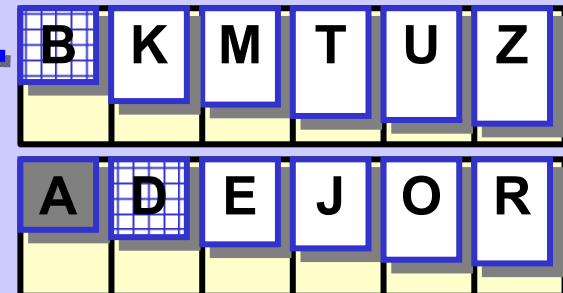
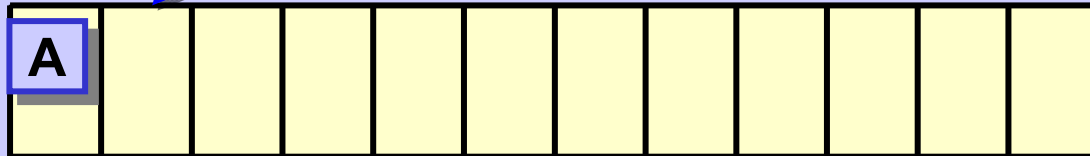
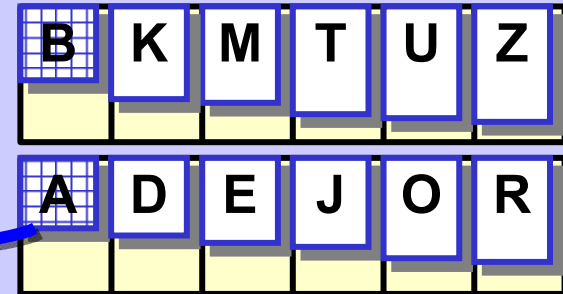
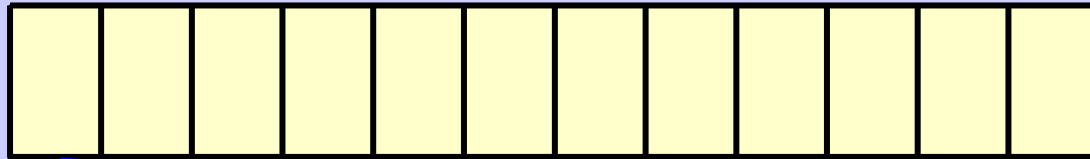
ALG 07

Merge sort (řazení sléváním)

Heap Sort (řazení haldou)

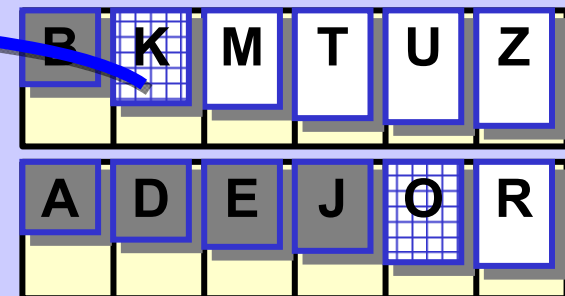
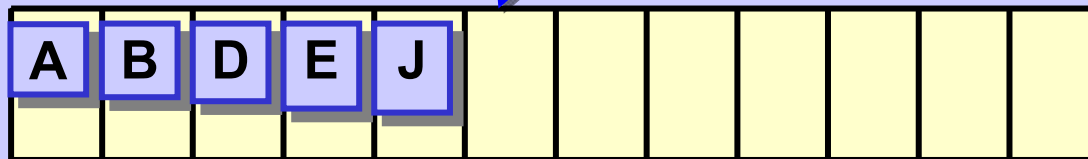
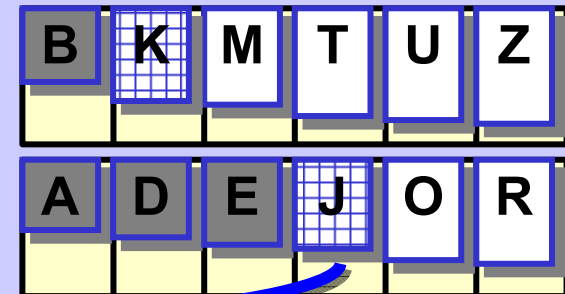
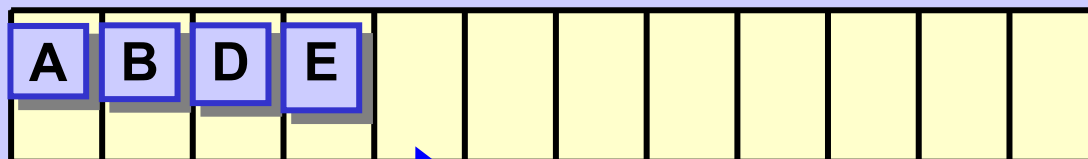
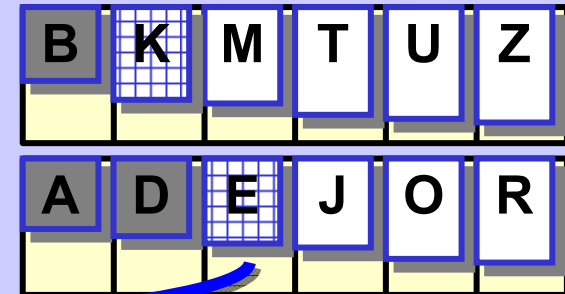
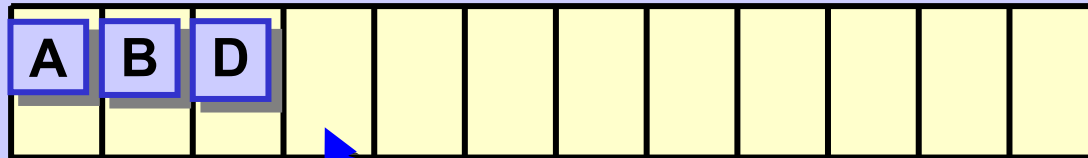
Merge sort

Sluč (slij?) dvě seřazená pole

Porovnávání prvky 

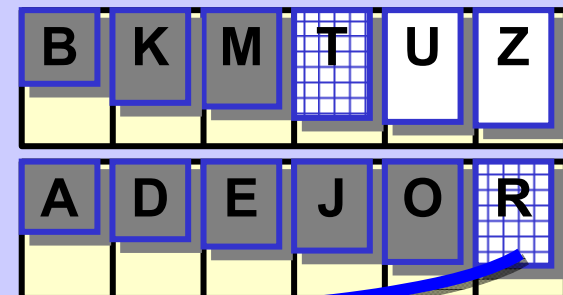
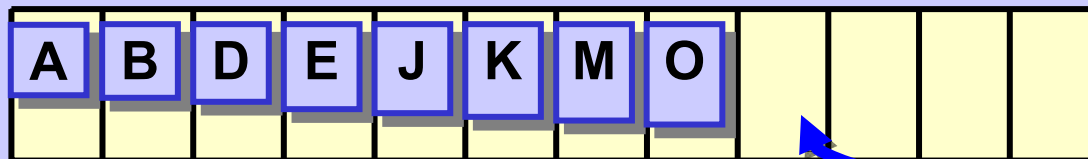
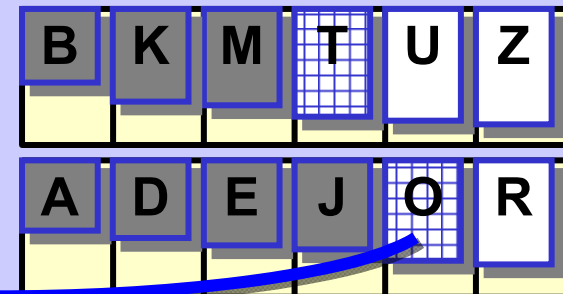
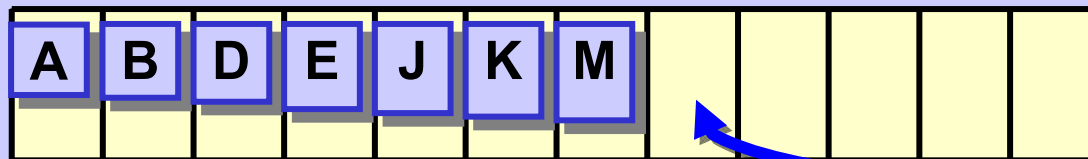
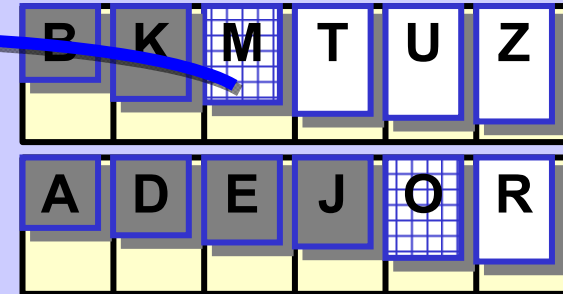
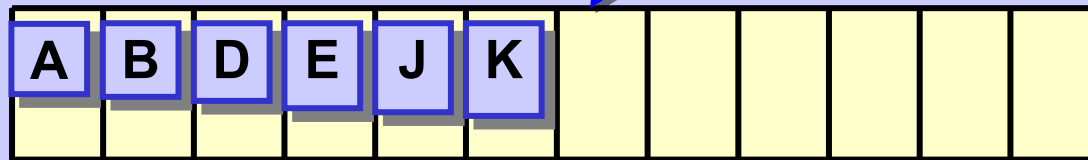
Merge sort

Sluč dvě seřazená pole - pokr.



Merge sort

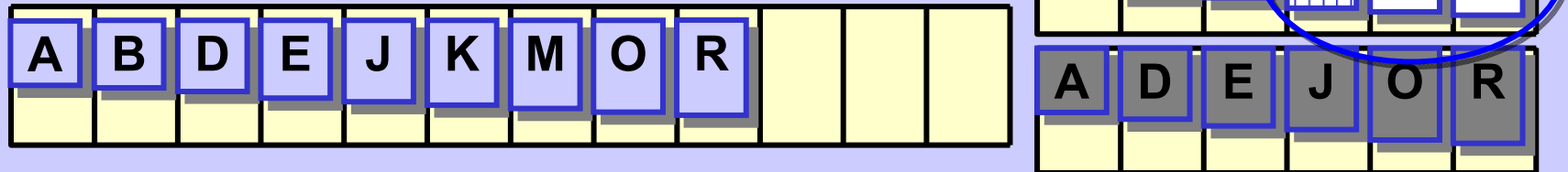
Sluč dvě seřazená pole - pokr.



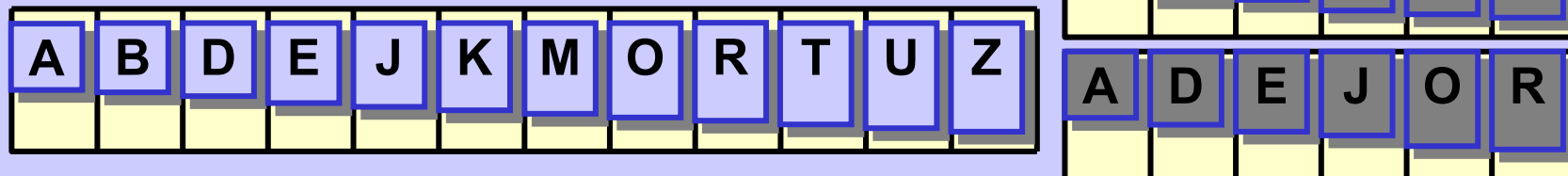
Merge sort

Sluč dvě seřazená pole - pokr.

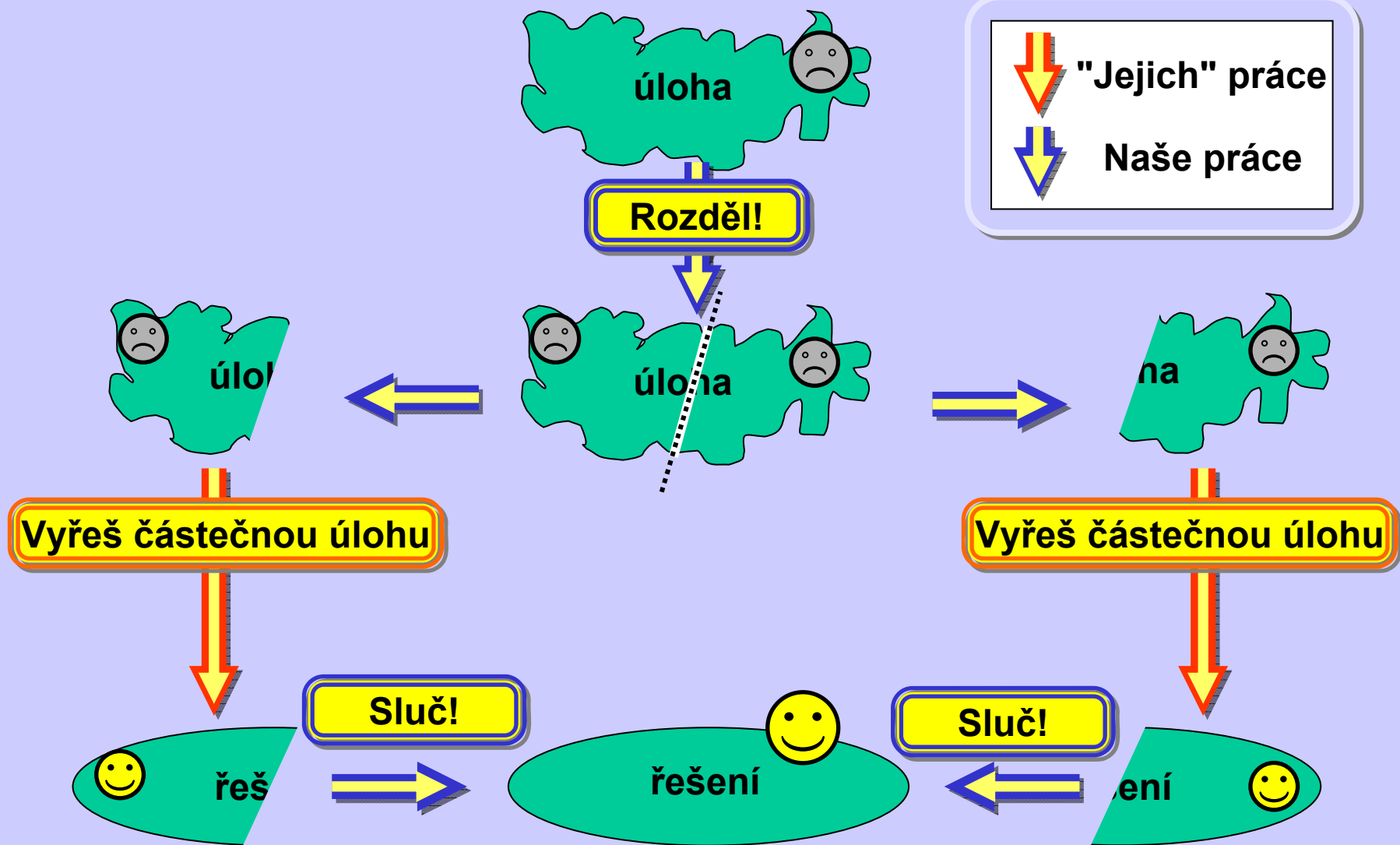
Kopíruj zbytek



Seřazeno



Rozděl a panuj! Divide and conquer! Divide et impera!



Merge sort

Neseřazeno

K Z U B M T E A J R D O

Rozdě!

K Z U B M T

E A J R D O

Zpracuj
odděleně

seřad'!

seřad'!

B K M T U Z

A D E J O R

Panuj!

Sluč!

Seřazeno

A B D E J K M O R T U Z

Merge sort

Neseřazeno

Rozdě!

Rozdě!

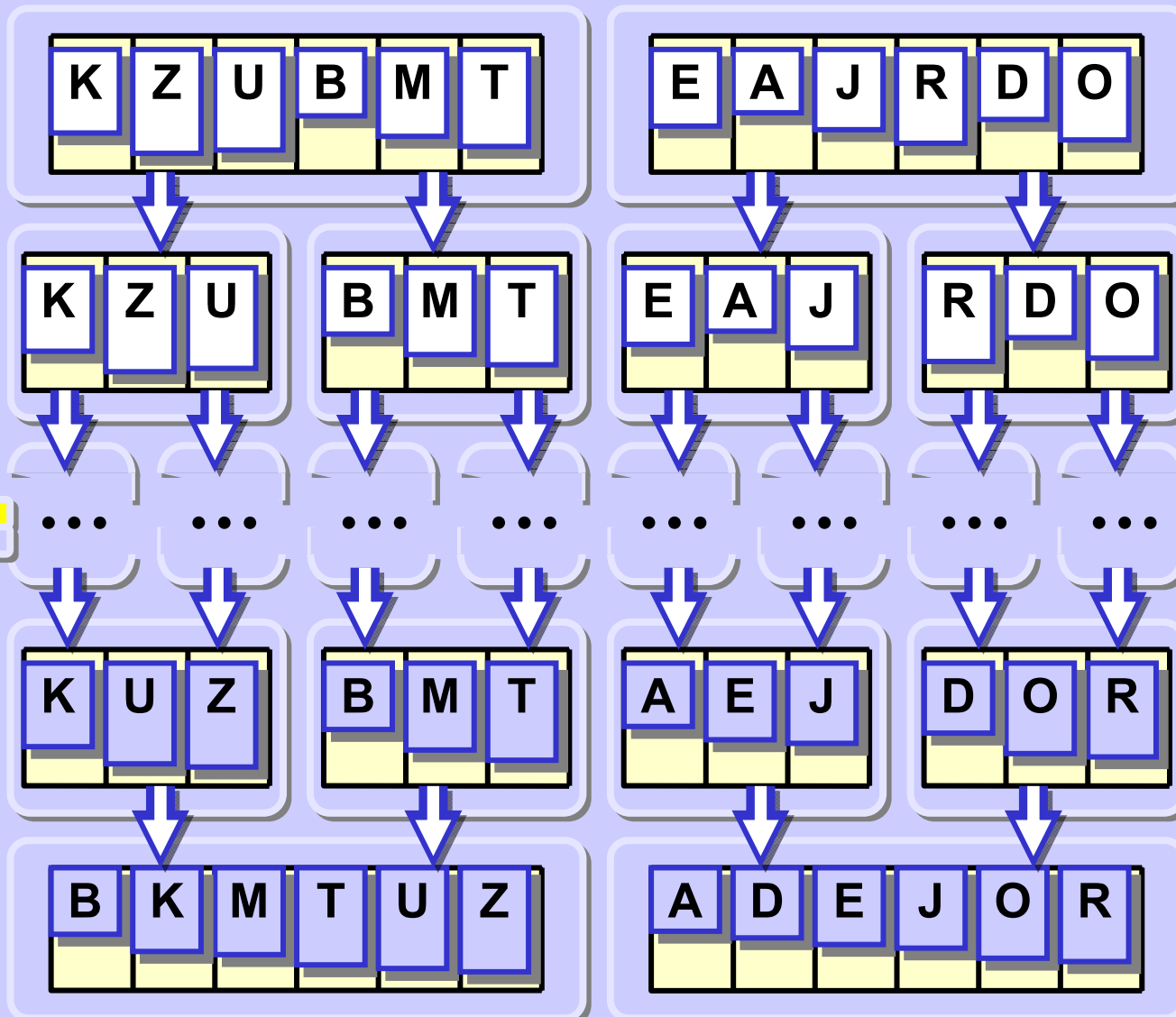
Rozdě!

Sluč!

Sluč!

Sluč!

Seřazeno



Merge sort

```
void mergeSort (int a[], int aux[],  
                int low, int high) {  
    int half = (low+high)/2;  
    int i;  
    if (low >= high) return;           // too small!  
                                        // sort  
    mergeSort(a, aux, low, half);      // left half  
    mergeSort(a, aux, half+1, high);  // right half  
    merge(a, aux, low, high);         // merge halves  
  
                                        // put result back to a  
    for (i = low; i <= high; i++) a[i] = aux[i];  
  
    // optimization idea:  
    /* swapArray(a, aux) */ // better to swap  
                            // references to a & aux!  
}
```

Merge sort

```
void merge(int in[], int out[], int low, int high) {
    int half = (low+high)/2;
    int i1 = low;
    int i2 = half+1;
    int j = low;

                                // compare and merge
    while ((i1 <= half) && (i2 <= high)) {
        if (in[i1] <= in[i2]) { out[j] = in[i1]; i1++; }
        else { out[j] = in[i2]; i2++; }
        j++;
    }

                                // copy the rest
    while (i1 <= half) { out[j] = in[i1]; i1++; j++; }
    while (i2 <= high) { out[j] = in[i2]; i2++; j++; }
}
```

Merge sort

Asymptotická sožitost

Rozdě! $\log_2(n)$ krát \Rightarrow

\Rightarrow Sluč! $\log_2(n)$ krát

Rozdě! $\Theta(1)$ operací

Sluč! $\Theta(n)$ operací

Celkem $\Theta(n) \cdot \Theta(\log_2(n)) = \Theta(n \cdot \log_2(n))$ operací

Asymptotická složitost Merge sortu je $\Theta(n \cdot \log_2(n))$

Merge sort

Stabilita

Rozděl! Nepohybuje prvky

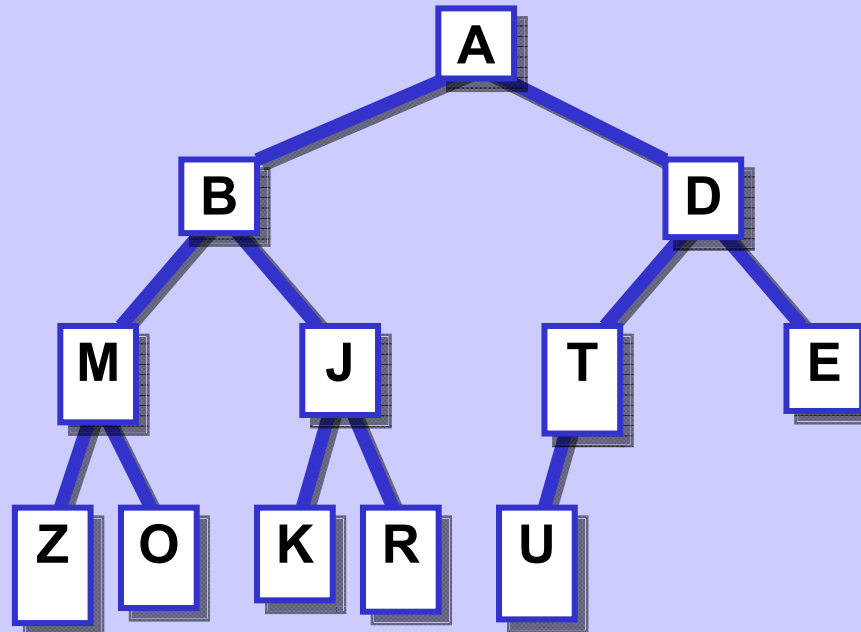
Sluč! “ if (in[i1] <= in[i2]) { out[j] = in[i1]; ...”

**Zařad' nejprve levý prvek,
když slučuješ stejné hodnoty**

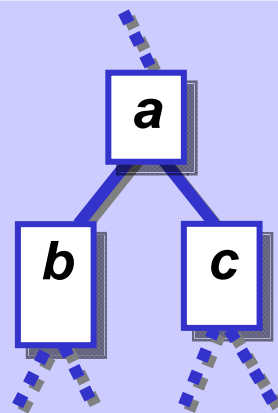
MergeSort je stabilní

Heap sort

Halda



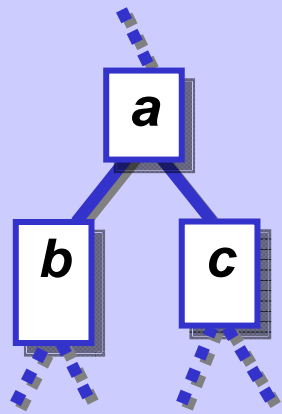
Pravidlo
haldy



$$a \leq b \ \&\& \ a \leq c$$

Heap sort

Terminologie



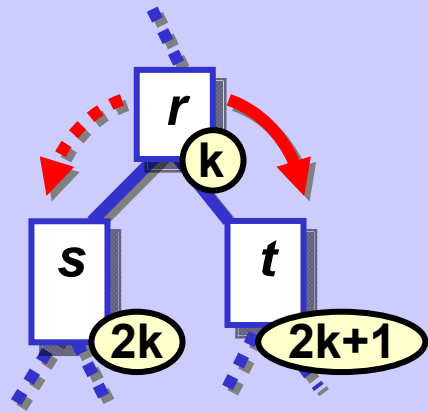
a predecessor, parent of **b** **c**
 předchůdce, rodič

b, **c** successor, child of **a**
 následník, potomek

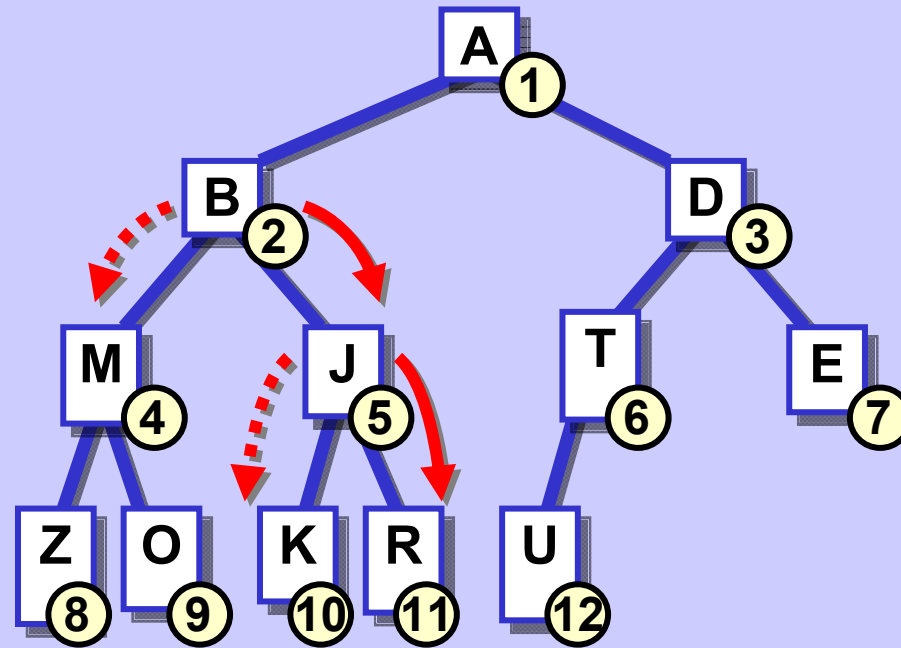
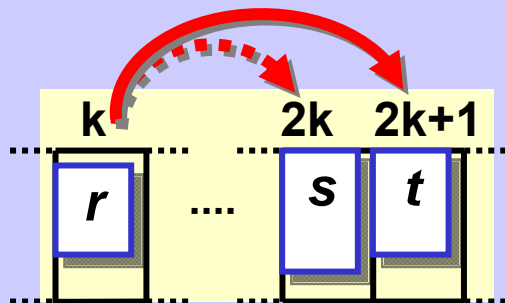


Heap sort

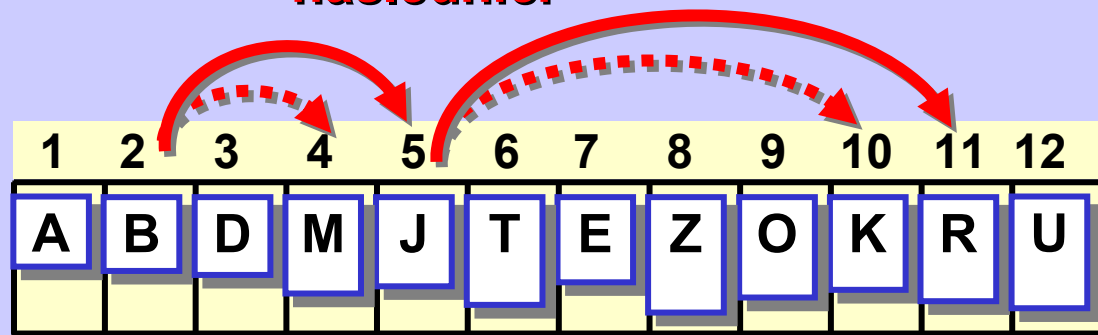
Halda uložená v poli



následníci



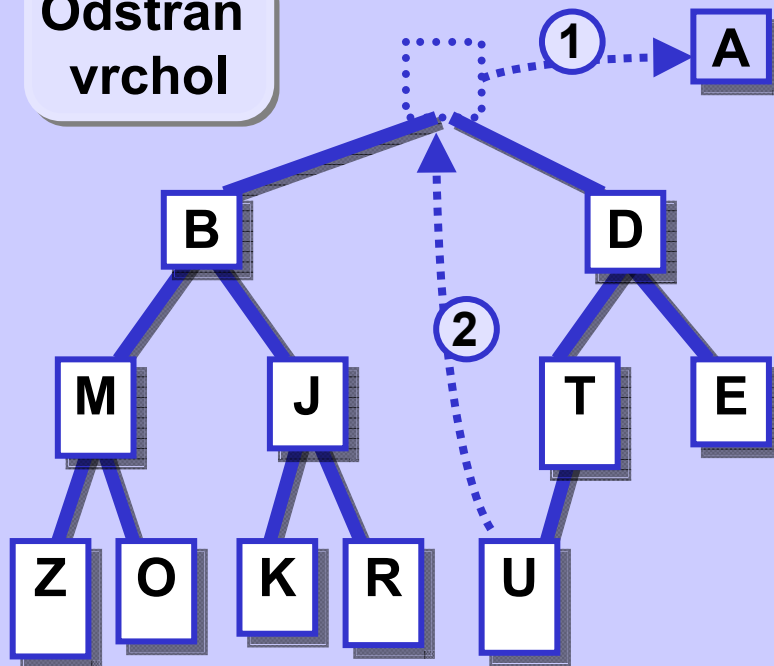
následníci



Oprava haldy

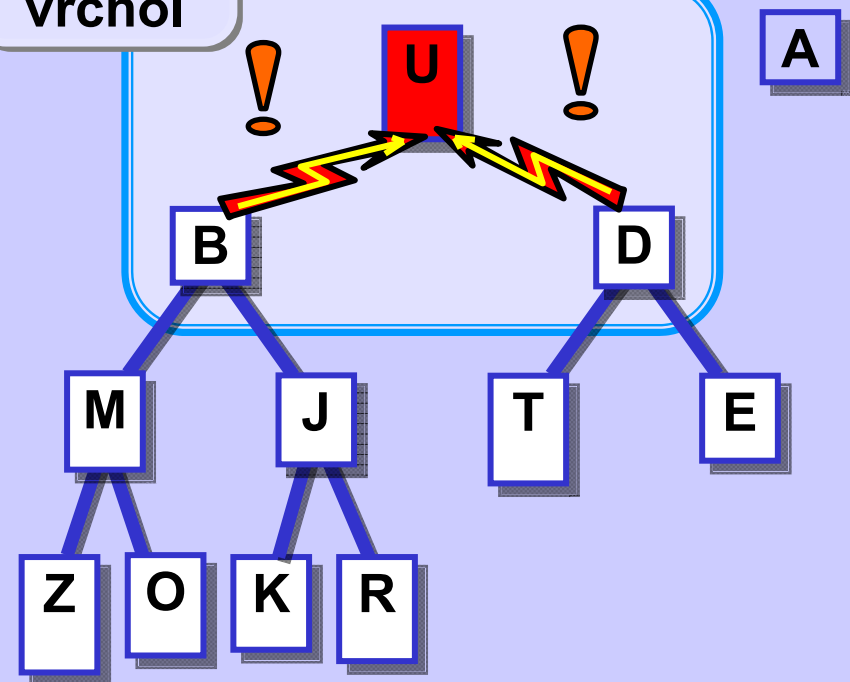
Vrchol odstraněn (1)

①
Odstraň
vrchol



②
poslední \longrightarrow první

③
Vlož na
vrchol

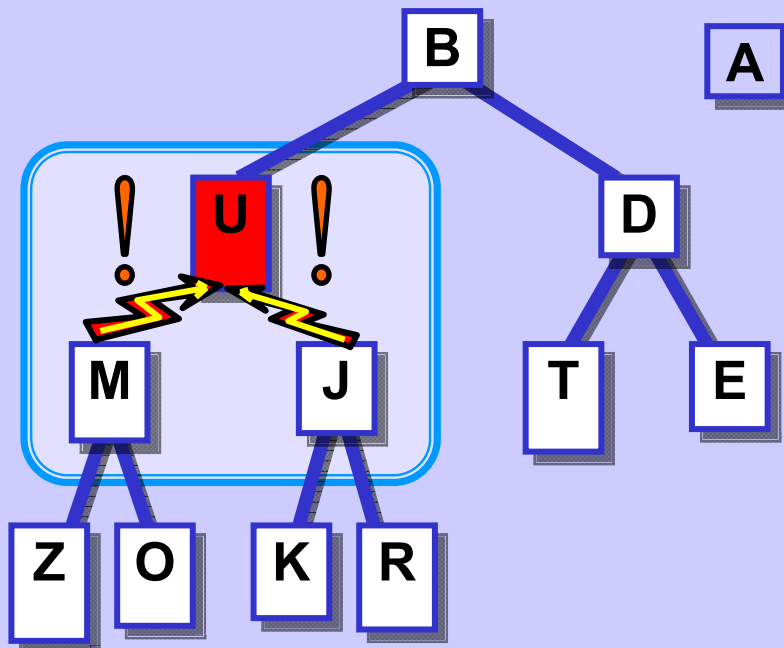


$U > B, U > D, \underline{B < D}$
 \Rightarrow prohod' $B \leftrightarrow U$

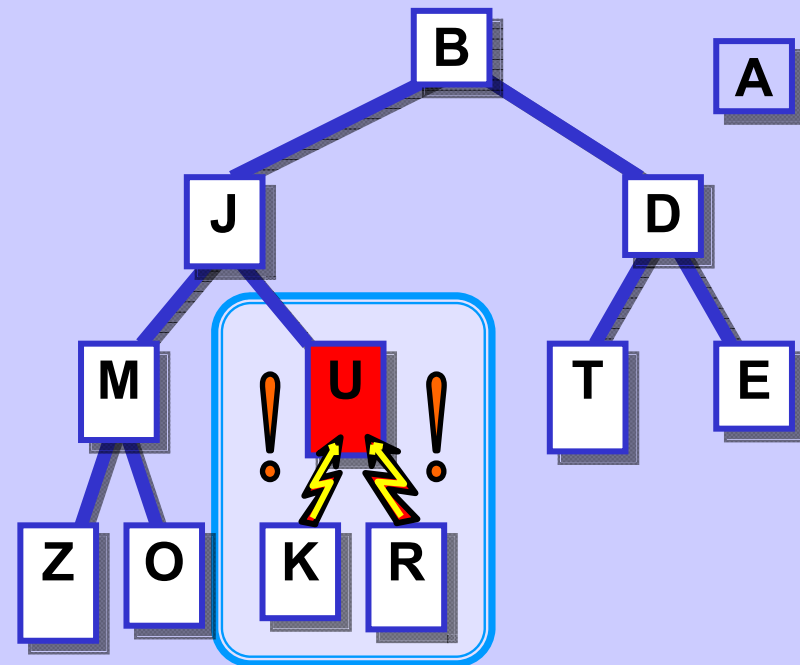
Oprava haldy

Vrchol odstraněn (2)

③ Vlož na vrchol - pokračování



$U > M, U > J, \underline{J < M}$
 \Rightarrow prohod' $J \leftrightarrow U$

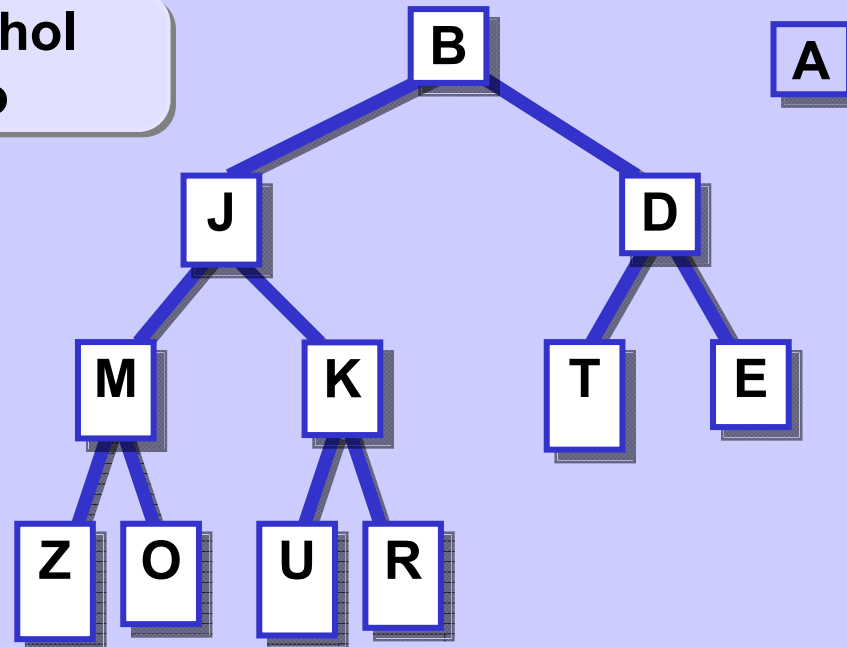


$U > K, U > R, \underline{K < R}$
 \Rightarrow prohod' $K \leftrightarrow U$

Oprava haldy

Vrchol odstraněn (3)

③ Vlož na vrchol
- hotovo

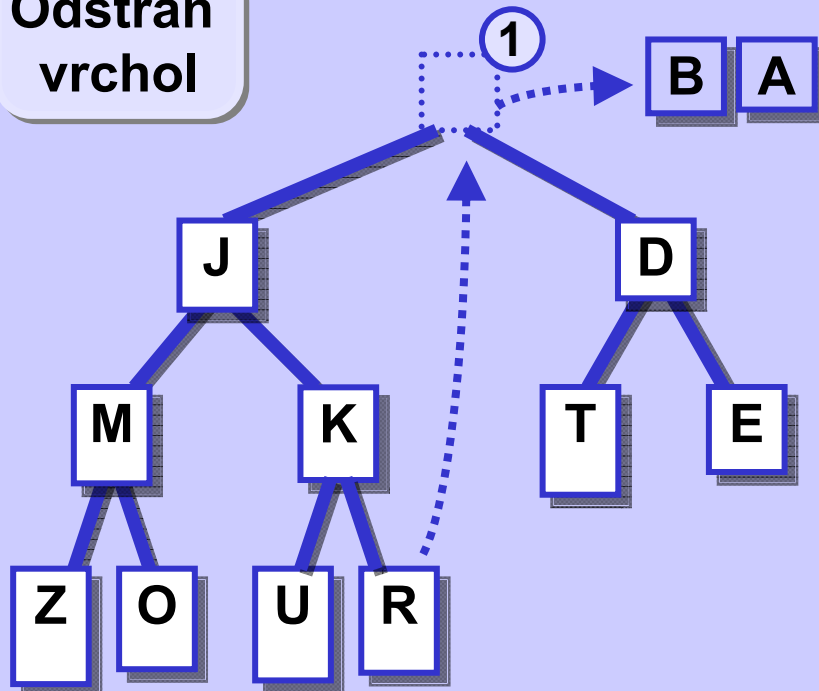


Nová halda

Oprava haldy

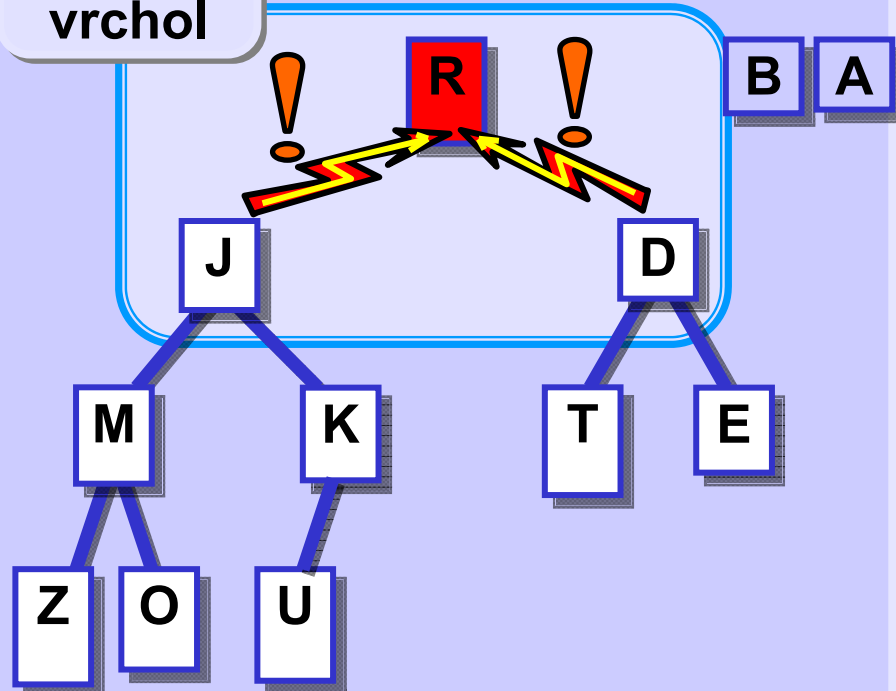
Vrchol odstraněn II (1)

①
Odstraň
vrchol



②
poslední → první

③
Vlož na
vrchol

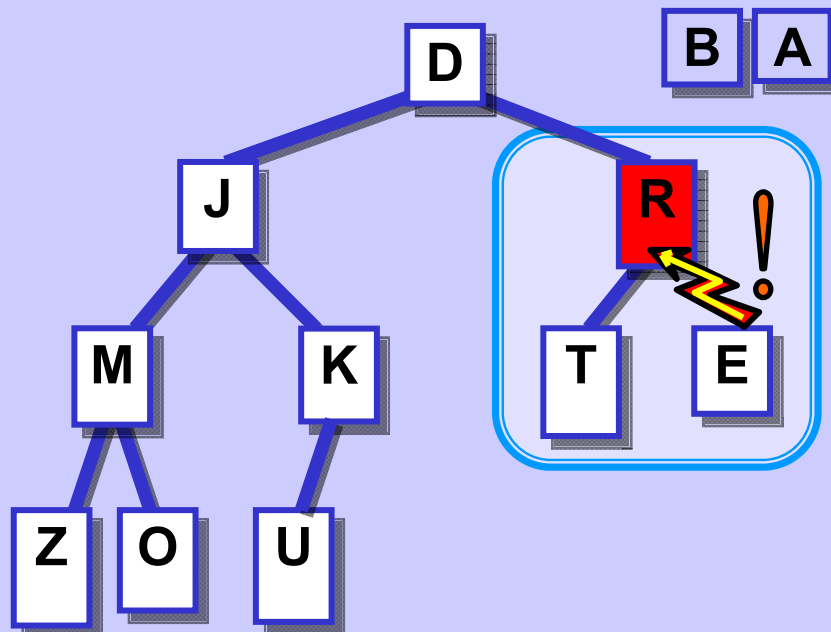


$R > J, R > D, \underline{D} < \underline{J}$
 \Rightarrow prohod' $D \leftrightarrow R$

Oprava haldy

Vrchol odstraněn II (2)

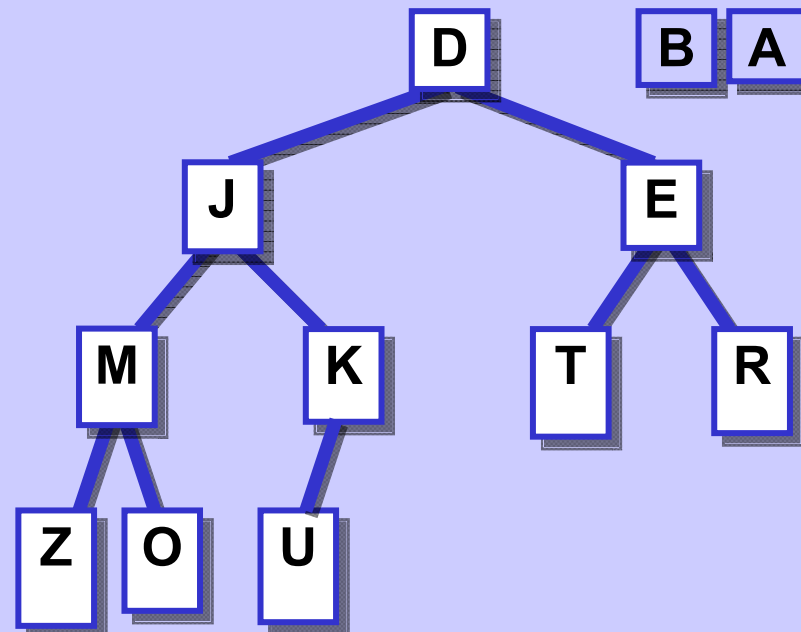
③ Vlož na vrchol - pokračování



$R < T, R > E$
 \Rightarrow prohod' $E \leftrightarrow R$

Vrchol odstraněn II (3)

③ Vlož na vrchol - hotovo

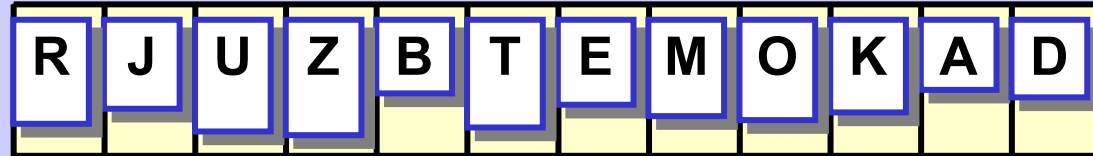


Nová halda

Heap sort

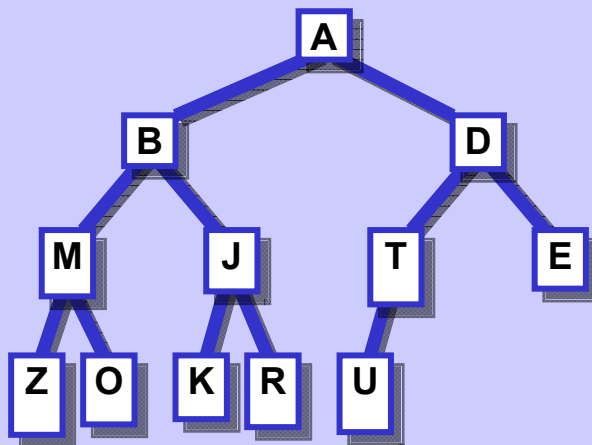
I

Neseřazeno



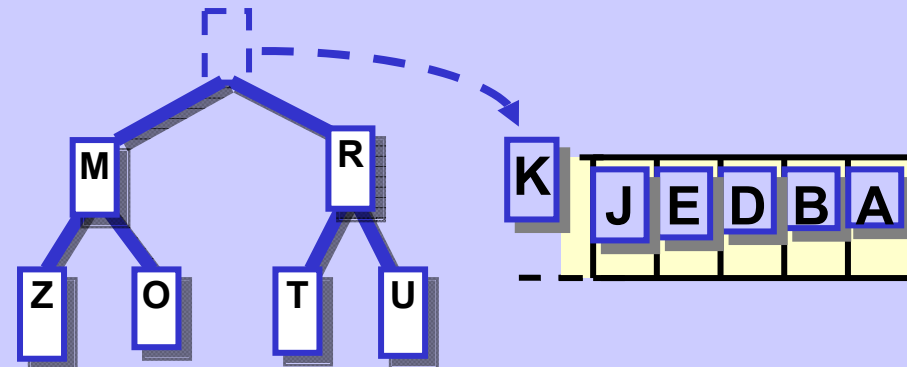
II

Vytvoř haldu



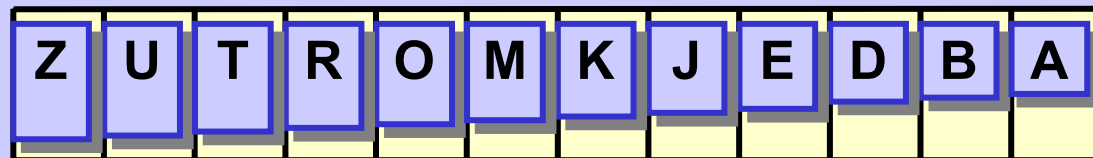
III

```
for (i = 0; i < n; i++)
  a[i] = "odstraň vrchol";
```

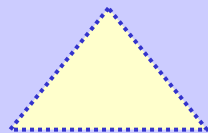
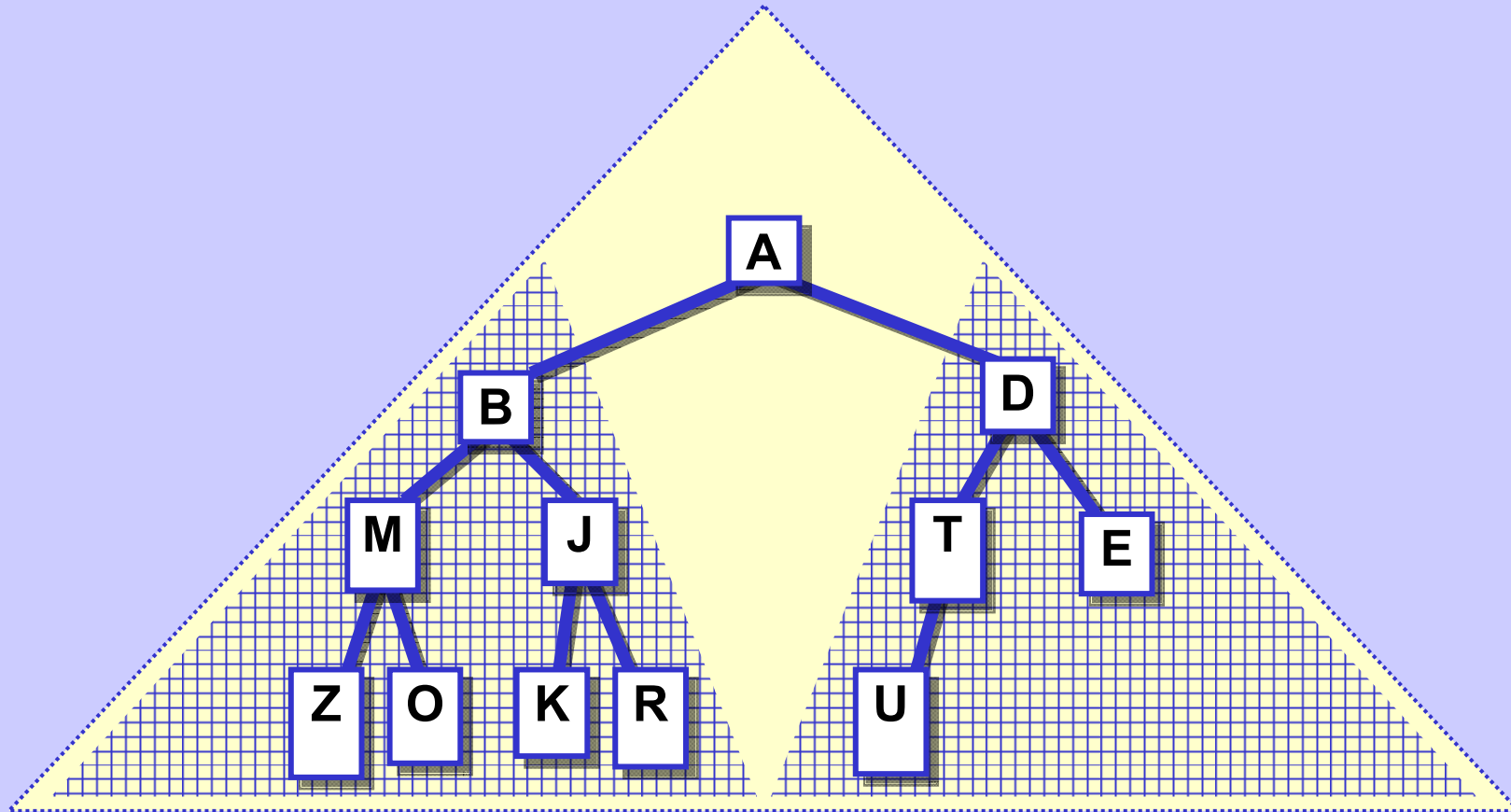


IV

Seřazeno



Rekurzivní vlastnost "býti haldou"



je halda



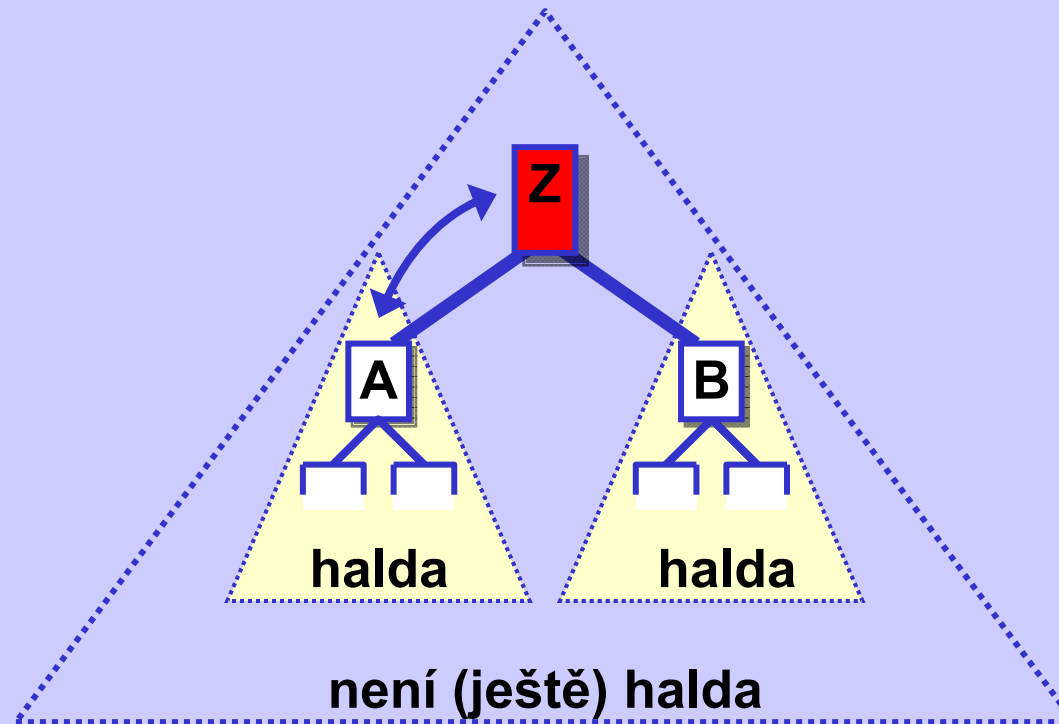
je halda

a



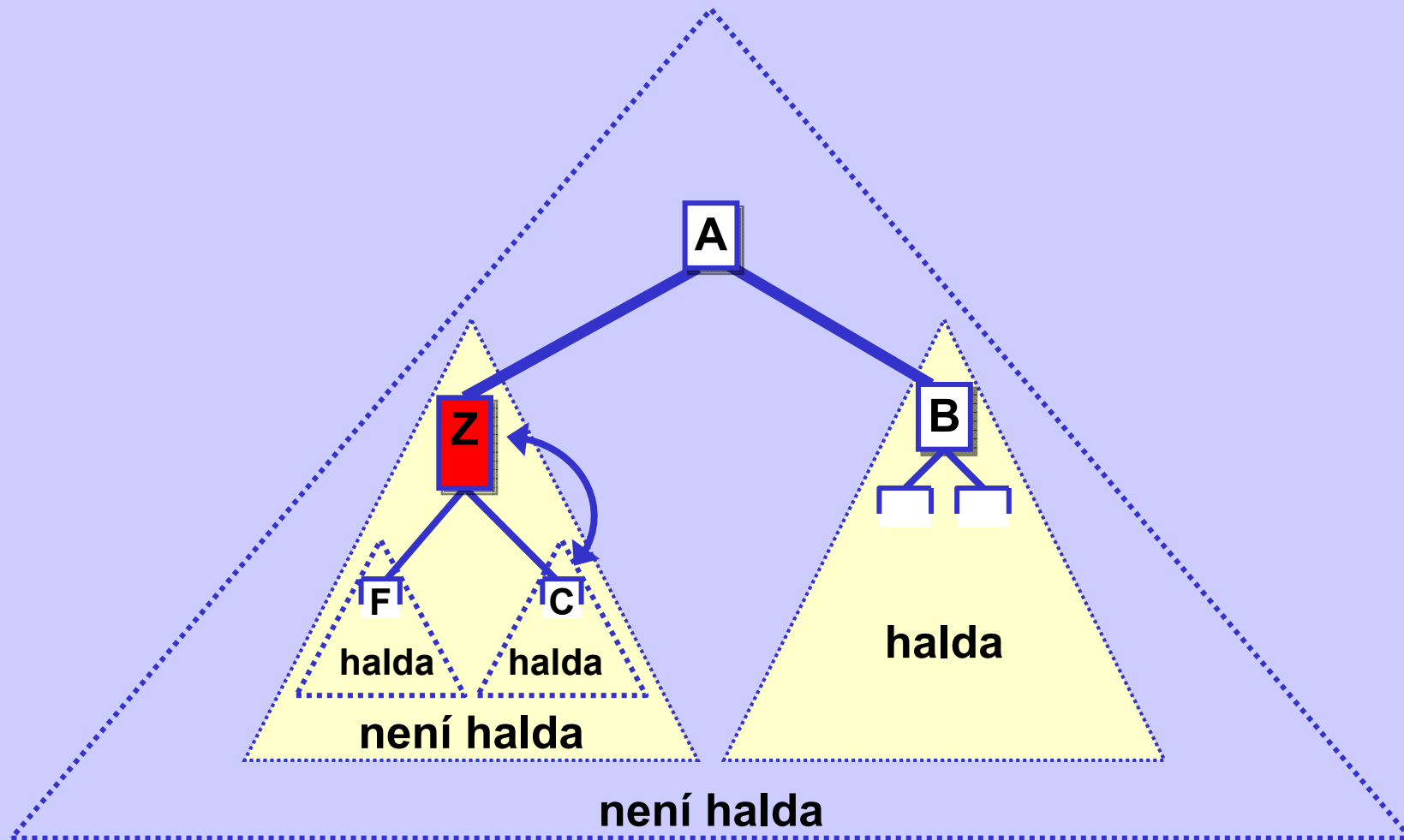
je halda

Vytvoř jednu haldu ze dvou menších

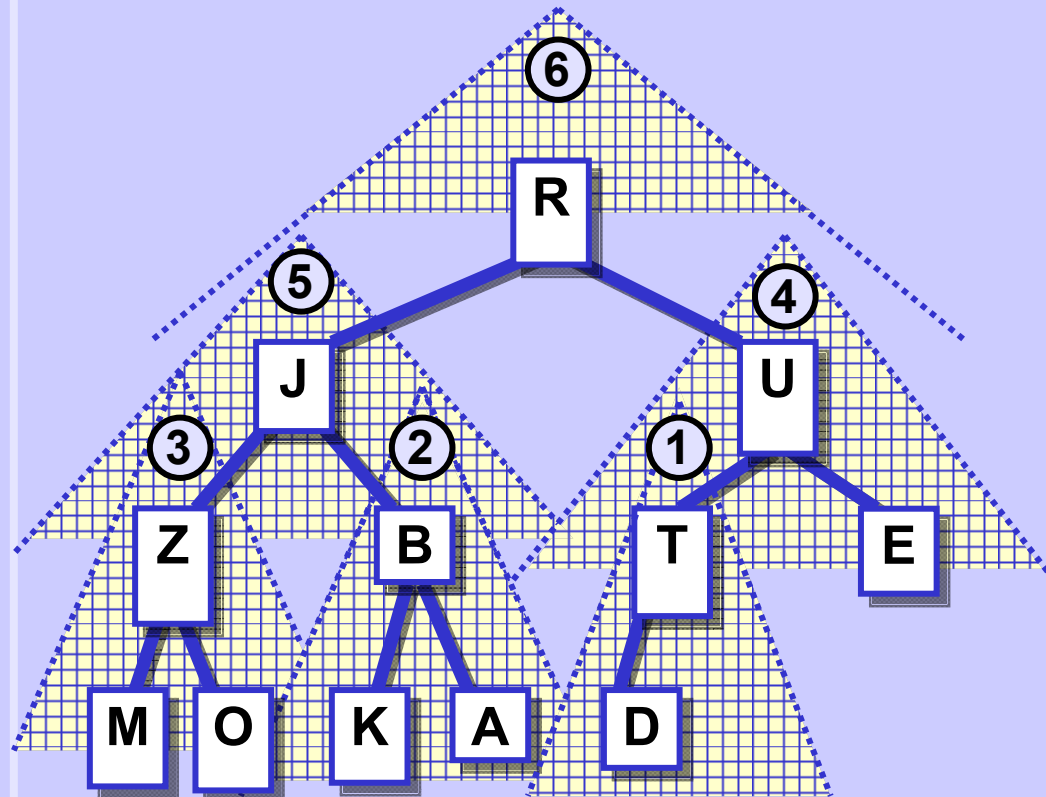


$Z > A$ nebo $Z > B$
 \Rightarrow prohod': $Z \leftrightarrow \min(A, B)$

Vytvoř jednu haldu ze dvou menších



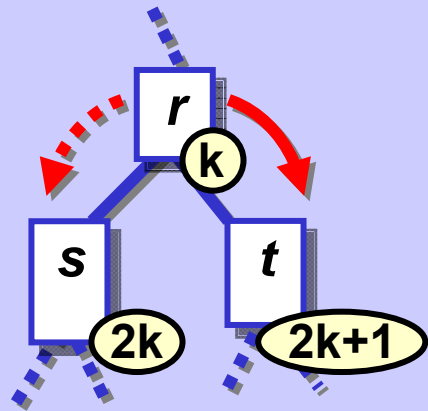
Vytvoř haldu



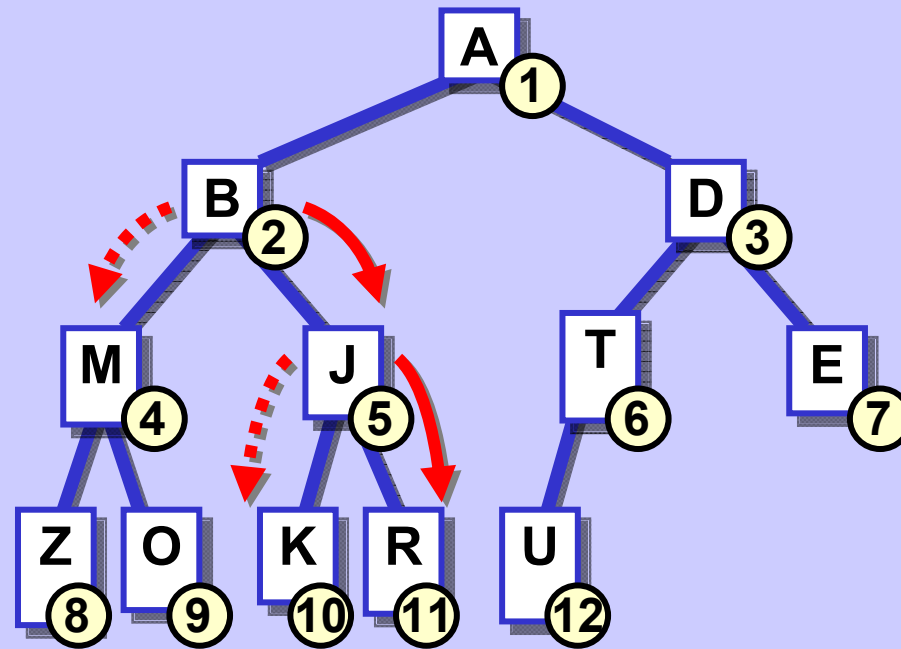
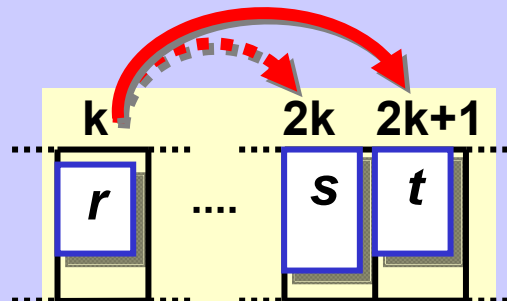
Vytvoř haldu v ① ...
 ... a vytvoř haldu v ② ...
 ... a vytvoř haldu v ③ ...
 ... a vytvoř haldu v ④ ...
 ... a vytvoř haldu v ⑤ ...
 ... a vytvoř haldu v ⑥ ...
 ... a celá halda je hotova.

Halda v poli

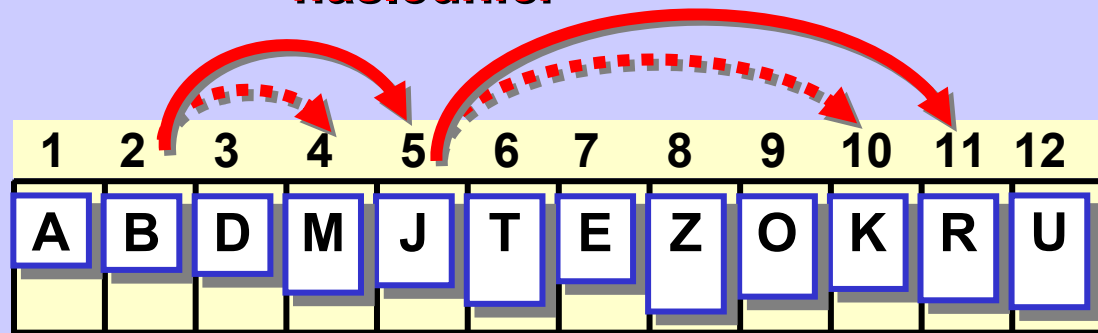
Halda uložená v poli



následníci



následníci

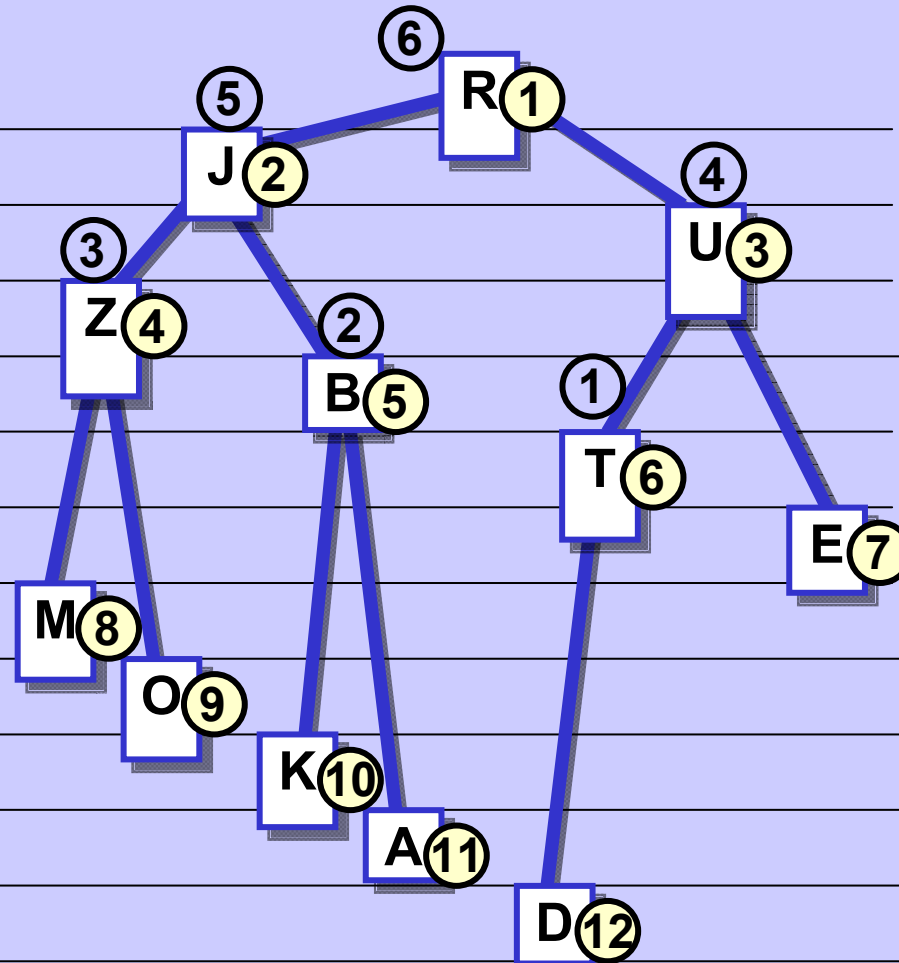


Tvorba haldy v poli

Neseřazeno

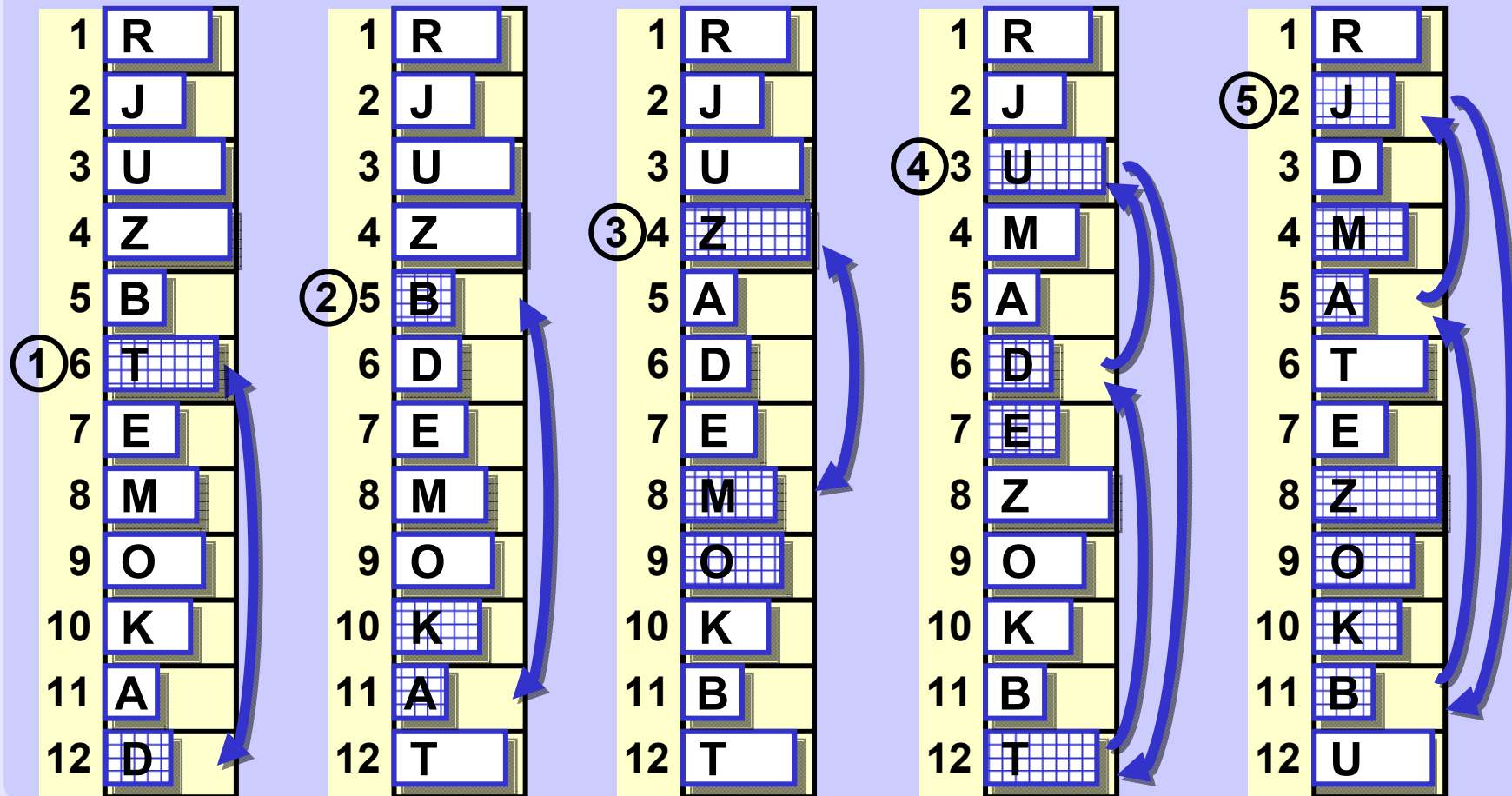
⑥	1	R
⑤	2	J
④	3	U
③	4	Z
②	5	B
①	6	T
	7	E
	8	M
	9	O
	10	K
	11	A
	12	D

Není halda



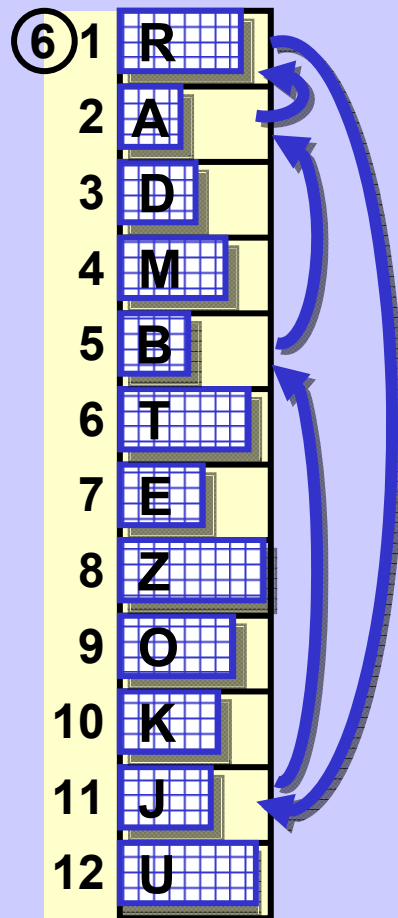
Tvorba haldy v poli

Tvorba haldy:

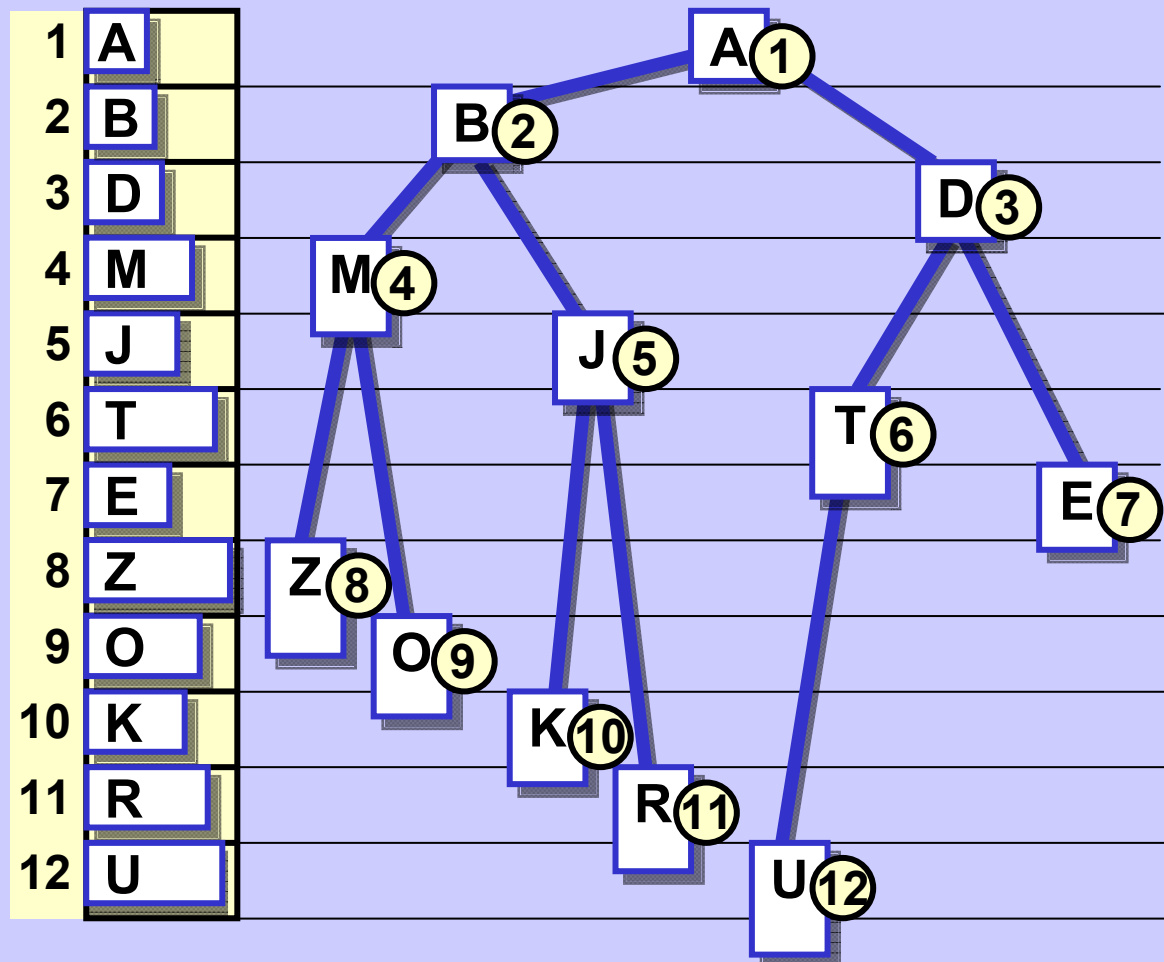


Tvorba haldy v poli

Tvorba haldy

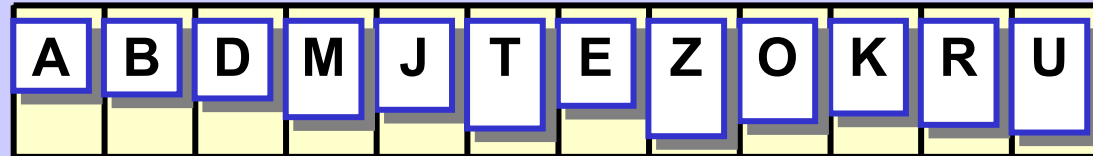


Halda

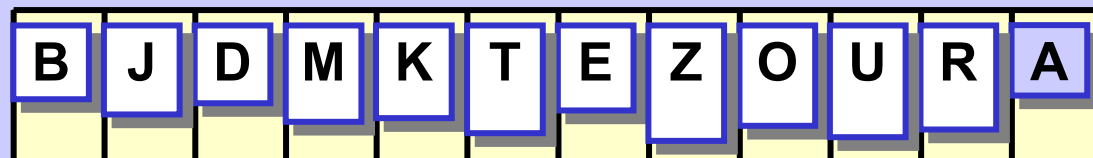
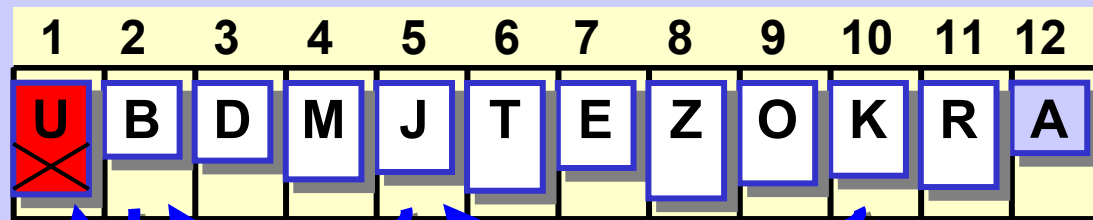
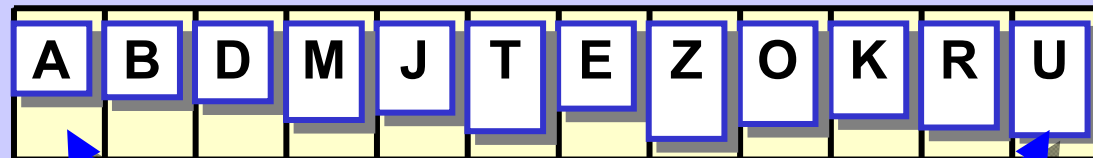


Heap sort

Halda

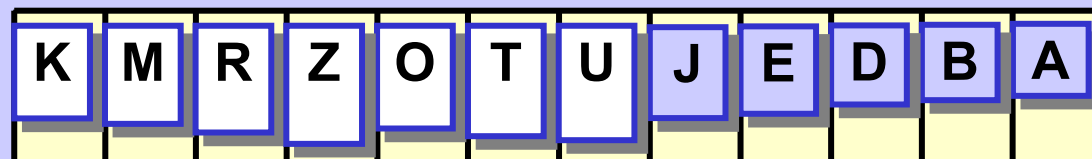
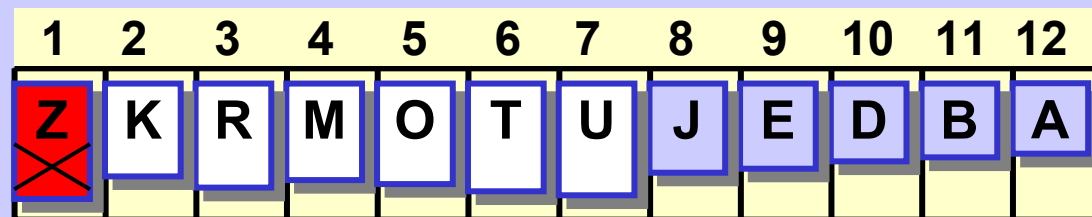
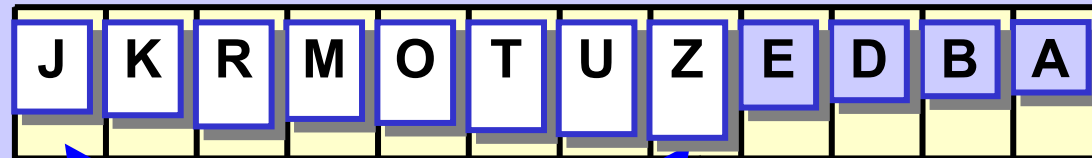


Krok 1



Heap sort

Krok k



Halda

k

Heap sort

```
                                // array: a[1]...a[n] !!!!  
  
void heapSort(Item a[], int n) {  
    int i, j;  
                                // create a heap  
    for (i = n/2; i > 0; i--)  
        repairTop(a, i, n);  
  
                                // sort  
    for (i = n; i > 1; i--) {  
        swap(a, 1, i);  
        repairTop(a, 1, i-1);  
    }  
}
```


Heap sort

```

// array: a[1]...a[n] !!!!!
void repairTop(Item a[], int top, int bott) {
    int i = top;           // a[2*i] and a[2*i+1]
    int j = i*2;          // are successors of a[i]

    Item topVal = a[top];

    // try to find a successor < topVal
    if ((j < bott) && (a[j] > a[j+1])) j++;

    // while (successors < topVal)
    //     move successors up
    while ((j <= bott) && (topVal > a[j])) {
        a[i] = a[j];
        i = j;  j = j*2; // skip to next successor
        if ((j < bott) && (a[j] > a[j+1])) j++;
    }
    a[i] = topVal;      // put the topVal
}

```

Heap sort

repairTop operace nejhorší případ ... $\log_2(n)$ (n =velikost haldy)

vytvoř haldu ... $n/2$ repairTop operací

$$\log_2(n/2) + \log_2(n/2+1) + \dots + \log_2(n) \leq (n/2)(\log_2(n)) = \underline{\underline{O(n \cdot \log_2(n))}}$$

seřad' haldy ... $n-1$ repairTop operací, nejhorší případ:

$$\log_2(n) + \log_2(n-1) + \dots + 1 \leq n \cdot \log_2(n) = O(n \cdot \log_2(n))$$

$$\text{ale i nejlepší případ} = \underline{\underline{\Theta(n \cdot \log_2(n))}}$$

$$\text{celkem ... vytvoř haldu + seřad' haldy} = \underline{\underline{\Theta(n \cdot \log_2(n))}}$$

Asymptotická složitost Heap sortu je $\Theta(n \cdot \log_2(n))$

Heap sort není stabilní