

# Particle Swarm Optimization

- Inspired by biological and sociological motivations
  - Bird flocks
  - Fish schools
  - Swarms of insects



# PSO: Characteristics

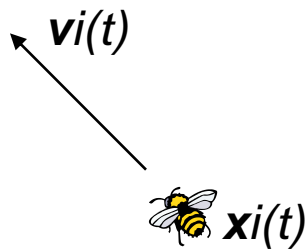
- Population-based optimization technique – originally designed for solving real-valued function optimizations
- Applicable for optimizations in rough, discontinuous and multimodal surfaces
- Does not require any gradient information of the function to be optimized
- Conceptually very simple

# PSO: Characteristics

- Each **candidate solution** of continuous optimization problem is described (encoded) by a real vector N-dimensional search space:  $\mathbf{x} = x_1, \dots, x_n$
- Each candidate solution is called **PARTICLE** and represents one individual of a population called **SWARM**.
- The **particles** change their components and **FLY** through the multi-dimensional search space.
- Particles calculate their **FITNESS** function as the quality of their actual position in the search space using w.r.t. the function to be optimized.
- Particles also compare themselves to their neighbors and imitate the best of that neighbors.

# PSO: Fundamentals

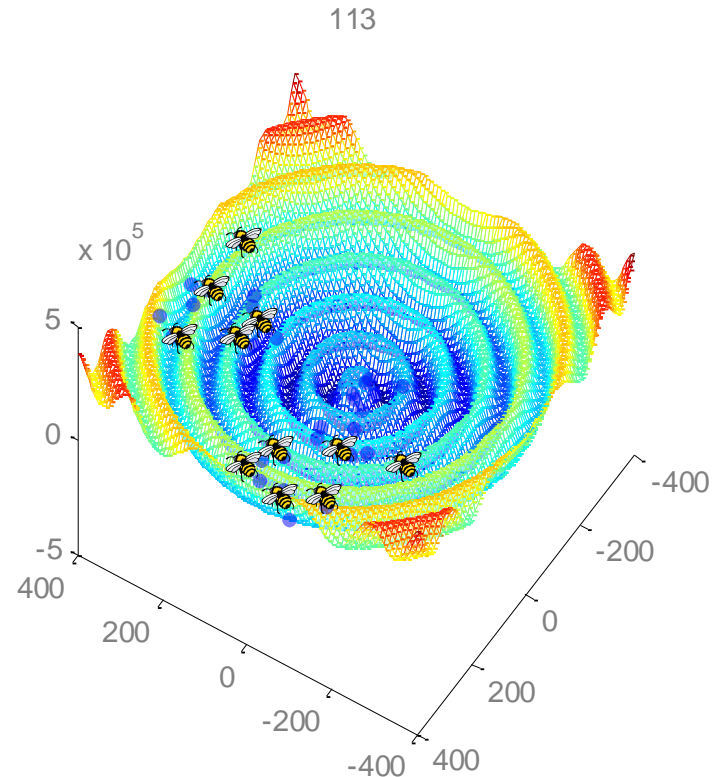
- Swarm of particles is flying through the parameter space and searching for the optimum
- Each particle is characterized by
  - Position vector...  $x_i(t)$
  - Velocity vector...  $v_i(t)$



Particle  $i$



swarm



# PSO: Velocity Update

- Velocity update ( $i^{\text{th}}$  particle):

$$v_i(t+1) = \omega v_i(t) + C_1 \varphi_1 (pbest_i(t) - x_i(t)) + C_2 \varphi_2 (gbest(t) - x_i(t))$$

$pbest_i(t)$  ... personal best experience; the best value of the fitness function found by the  $i$ -th particle up to time  $t$ .

$gbest(t)$  ... global best experience; the best value out of  $pbest_i(t)$  values of all particles in the swarm found up to time  $t$ .

$\omega$  ... inertial factor

$\varphi_1$  and  $\varphi_2$  ... uniformly distributed random numbers that determine the influence of  $pbest_i(t)$  and  $gbest(t)$ .

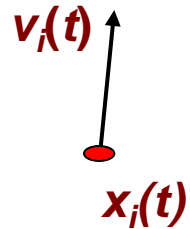
$C_1$  ... particle's self-confidence; controls the contribution towards the self-exploration.

$C_2$  ... swarm confidence; controls the contribution towards the global direction.

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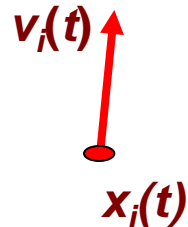
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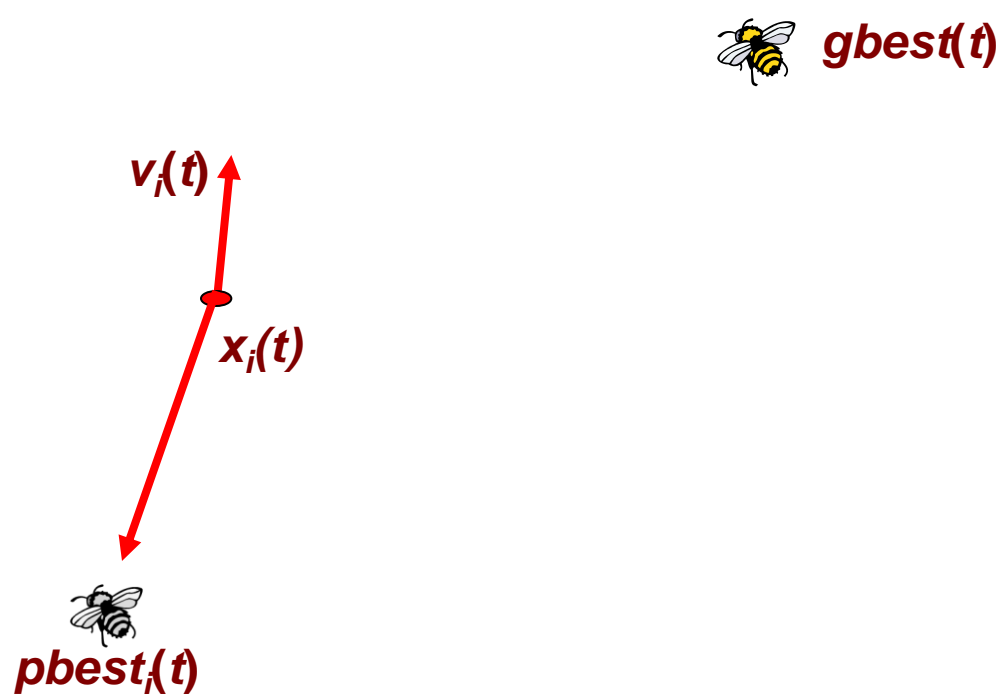
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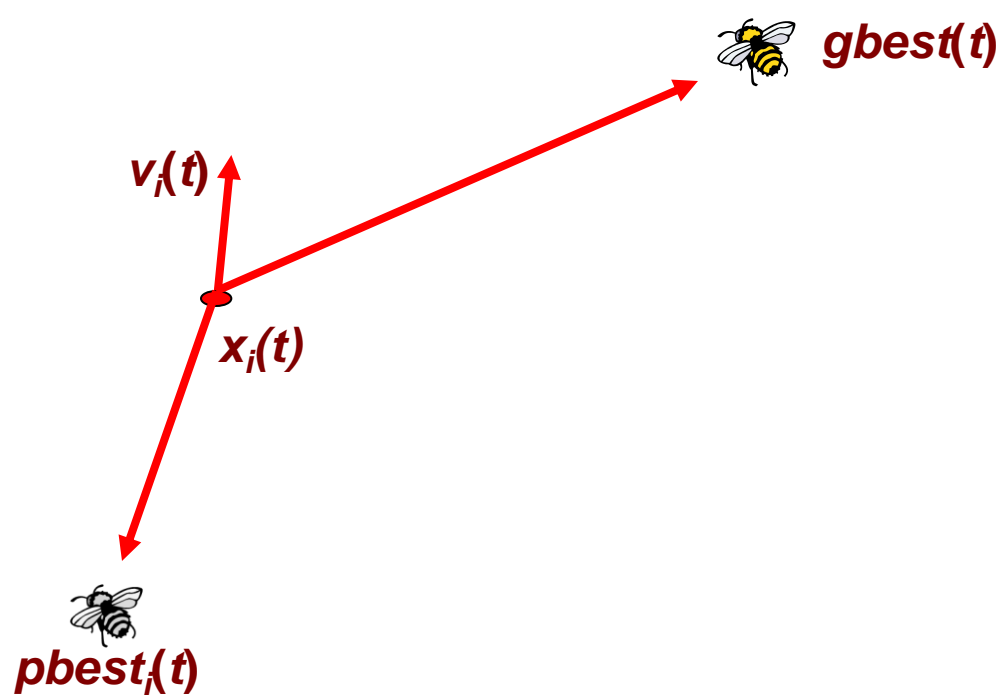




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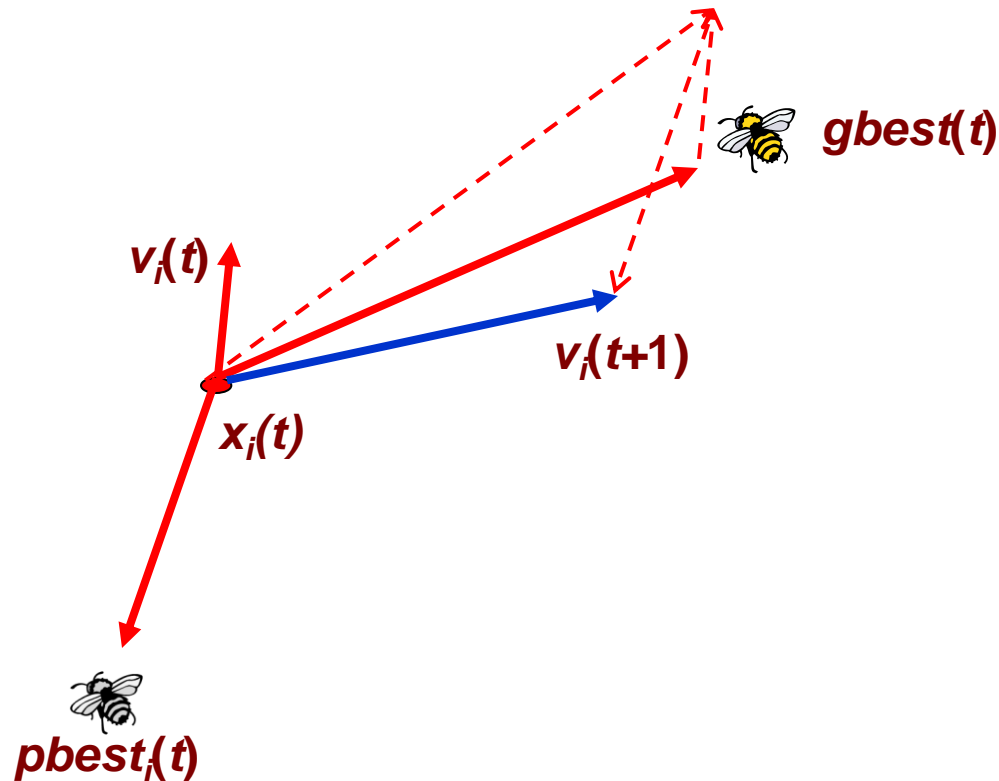
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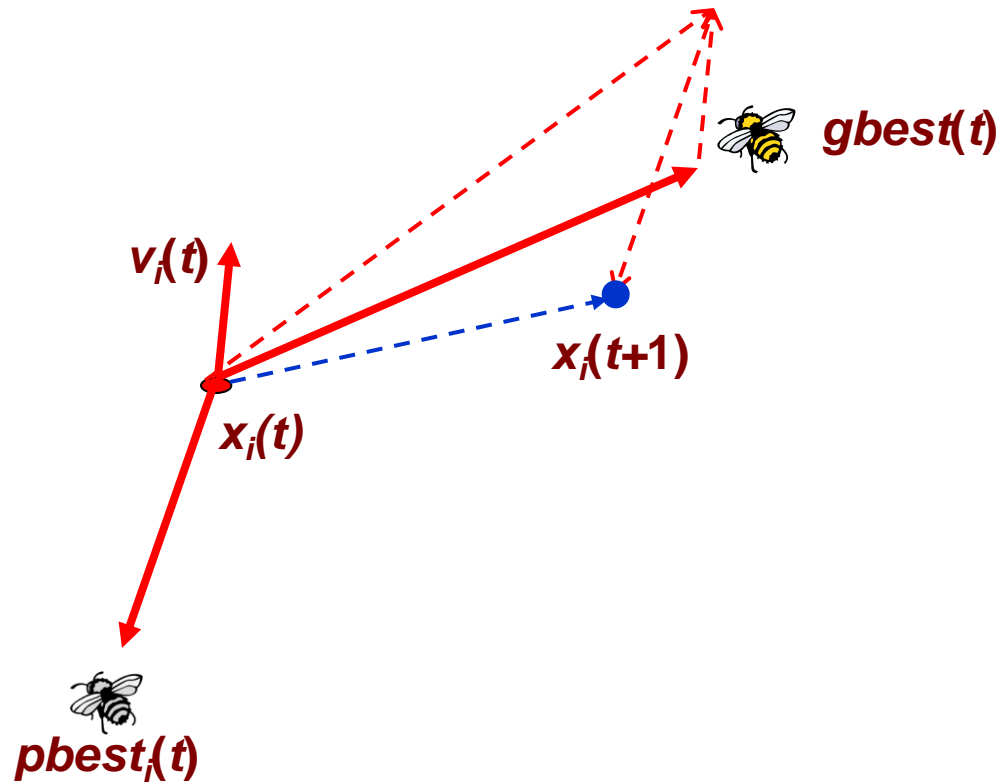
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# PSO: Position Update

- Position update ( $i^{\text{th}}$  particle):

$$x_i(t+1) = x_i(t) + v_i(t+1)$$



# PSO: Algorithm

Input: Randomly initialized position and velocity of the particles:  $\mathbf{X}_i(0)$  and  $\mathbf{V}_i(0)$

Output: Position of the approximate global optima  $\mathbf{X}^*$

```
begin
  while terminating condition is not reached do
    begin
      for i=1 to number_of_particles
        calculate fitness  $f(\mathbf{X}_i)$ 
        update  $\mathbf{p}_i$  and  $\mathbf{g}_i$ 
        adapt velocity of the particle
        update position of the particle
      increase i
    end
  end
end
```

# PSO: Setting the Inertia Factor $\omega$

- Static parameter setting
  - $\omega \ll 1$  ... only little momentum is preserved from the previous time-step.  
 $\omega = 0$  ... the particle moves in each step totally ignoring information about the past velocity.
  - $\omega > 1$  ... particles can hardly change their direction which implies a reluctance against convergence towards optimum.  
 $\omega > 1$  is always used with  $V_{max}$  to avoid *swarm explosion*.
- Dynamic parameter setting – annealing scheme;  $\omega$  decreases linearly with time from  $\omega = 0.9$  to  $\omega = 0.4$ .

Globally explores the search space in the beginning of the run.

Performs local search in the end.
- $V_{max}$  can be set to the full search range of the particle's position in order to allow global search.

# PSO: Swarm Size

- Swarm size has no significant effect on the performance of the PSO.  
Typical values are 20-60.

# PSO: Acceleration Coefficients $C_1$ and $C_2$

- Static setting

Usually  $C_1=C_2$  and range from  $[0, 4]$ , for example  $C_1=C_2=1.494$ .

- Dynamic setting - coefficients vary with time according to

$$C_1 = (C_{1f} - C_{1i}) \frac{i}{MAXITER} + C_{1i}$$

$$C_2 = (C_{2f} - C_{2i}) \frac{i}{MAXITER} + C_{2i}$$

where  $C_{1f}$  and  $C_{2f}$  are final values for  $C_1$  and  $C_2$ ,  $C_{1i}$  and  $C_{2i}$  are current values at iteration  $i$ , and  $MAXITER$  is the maximum number of iterations.

Particular scheme:  $C_1$  decreases from 2.5 to 0.5;  $C_2$  increases from 0.5 to 2.5.

Effect: Global search during the early phase of the optimization process; convergence to global optimum at the final stage of the optimization process.

# References

Das S. et al.: Particle Swarm Optimization and Differential Evolution Algorithms: Technical Analysis, Applications and Hybridization Perspectives, 2008  
<http://www.softcomputing.net/aciis.pdf>