

Planning Problem Representation

PDDL + Assignment #1-1

Michaela Urbanovská

PUI Tutorial
Week 2

- Any questions regarding the lecture or organization?

when your lecturer asks if you have any questions



Organization Recap

- One assignment for every part of the class
- Assignment #1 has 3 parts
- We collect feedback every week to improve the course as we go
- The assignment for classical planning is new → feedback is appreciated

Planning Motivation

- **General problem solving**
- Basically can solve all your problems

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- Problem

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- Problem + representation

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Planning Motivation

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- Basically can solve all your problems
- Problem + representation + solver = **solution**

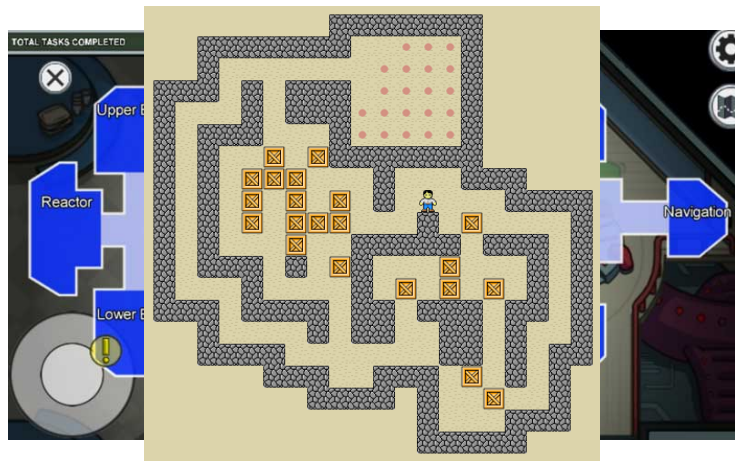
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The image shows a screenshot of a course website with a central list of assignments and tests. The background features a 3D architectural rendering of a building with various rooms and corridors, overlaid with a semi-transparent white box containing the course content.

SMU - Symbolic Machine Learning (B4M46SMU + BE4M46SMU)

- ILP - LGG agent
- PR1 - Project 1
- PR2 - Project 2
- PR4 - Project 4 - reinforcement learning

PUI - Planning for Artificial Intelligence

- cp - Classical Planning Assignment
- inclass - Inclass programming exercise
- wumpus1 - Wumpus World - Task 1
- wumpus2 - Wumpus World - Task 2
- wumpus3 - Wumpus World - Task 3

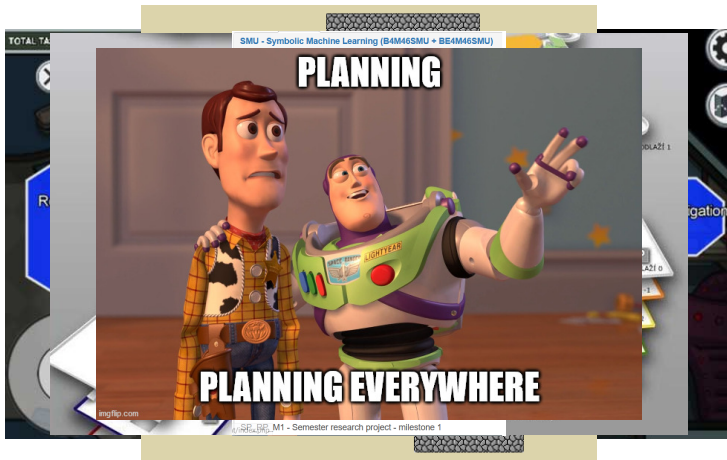
KO - Combinatorial Optimization / Kombinatorická optimalizace

Assignments Tests

- HW1 - Homework 1 - calicenter scheduling
- HW2 - Homework 2 - survey design
- HW3 - Homework 3 - object tracking
- HW4 - Homework 4 - Bratley algorithm
- HW5 - Homework 5 - Image unshredding
- PT_101_102 - Practical test - labs 101+102
- SP_CC_O - Cocontest - Optimal
- SP_CC_R - Cocontest - Ranking
- SP_CC_T - Cocontest - Threshold
- SP_CHOICE - Semester project - choice
- SP_RE_M1 - Semester research project - milestone 1

Planning Motivation

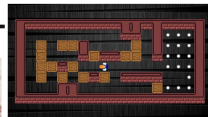
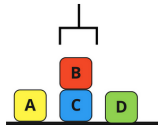
- **General problem solving**
- Basically can solve all your problems
- Problem + representation + solver = **solution**



Planning Benchmarks

For example...

- Airport
- Depot
- Sokoban
- Blocksworld
- Elevators
- Floortile
- Parking
- Pipesworld
- Tetris
- Tidybot
- Woodworking



- Often inspired by real-world problems
- Sometimes even modeled real-world problems
- Problems with interesting properties to test performance of algorithms / heuristics
- Doesn't have to correlate with real-world performance

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- Problems with interesting properties to test performance of algorithms / heuristics
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...this is not the class with robots.

There are many different types of planning...

In this part of the course → **classical planning**

- Fully defined environment
- Deterministic actions
- Domain-independent approaches

- **P**lanning **D**omain **D**efinition **L**anguage
- General language to describe planning problems
- Based on first-order logic
- Syntax similar to LISP
- **Domain definition**
 - defines the world / environment
- **Problem definition**
 - defines problem instance in the modeled world
- Online editor: *<http://editor.planning.domains>*

Domain definition

- Defines the environment / world
 - Hierarchy of types
 - Predicates (properties, relations)
 - Action schemas

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Domain file structure

```
(define (domain name)  
  PDDL definition of types  
  PDDL definition of predicates  
  PDDL definition of actions  
)
```

Problem definition

- Defines the problem instance we want to solve
 - Objects and their types
 - Initial state of the world
 - Goal condition

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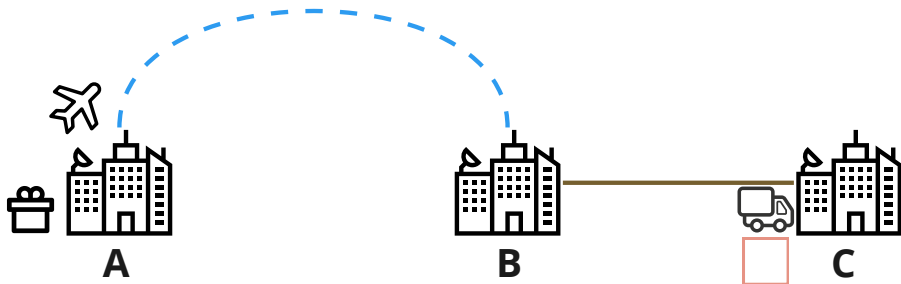
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Problem file structure

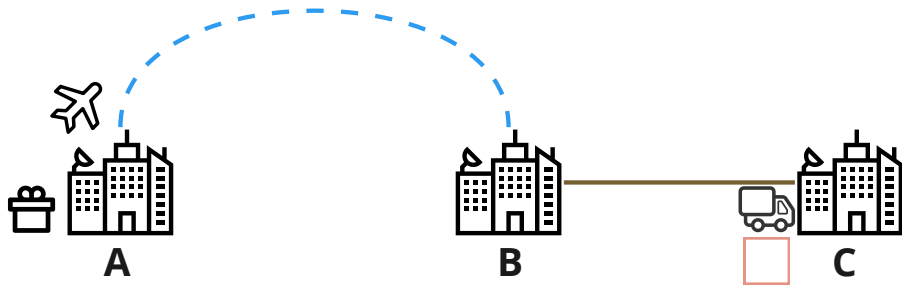
```
(define (problem name) (:domain name)  
  PDDL definition of objects  
  PDDL definition of initial state  
  PDDL definition of goal  
)
```

...now what?

Logistics example

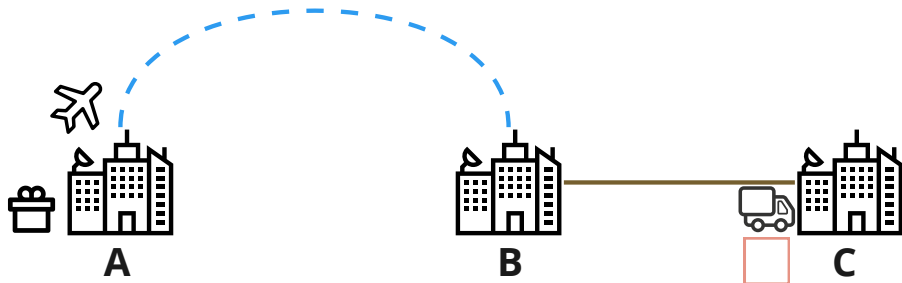


Let's try it out (<http://editor.planning.domains>)



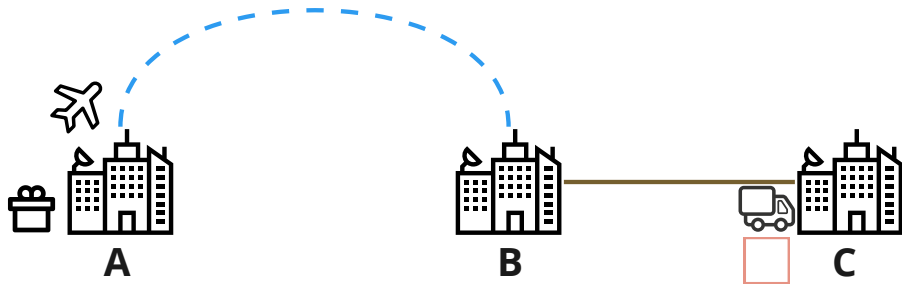
Domain definition

- *types:*
- *predicates:*
- *actions:*



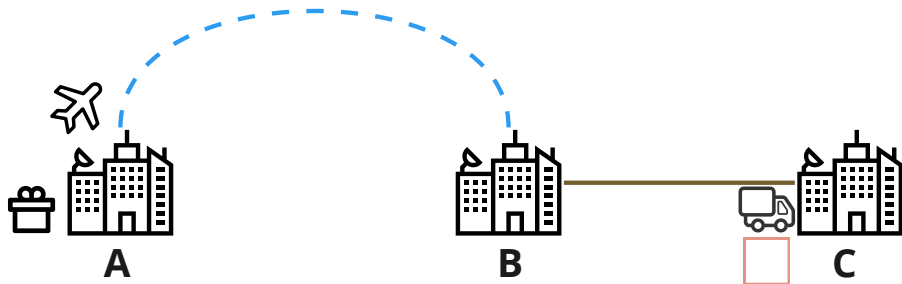
Domain definition

- *types*: location, vehicle, package, ...
- *predicates*:
- *actions*:



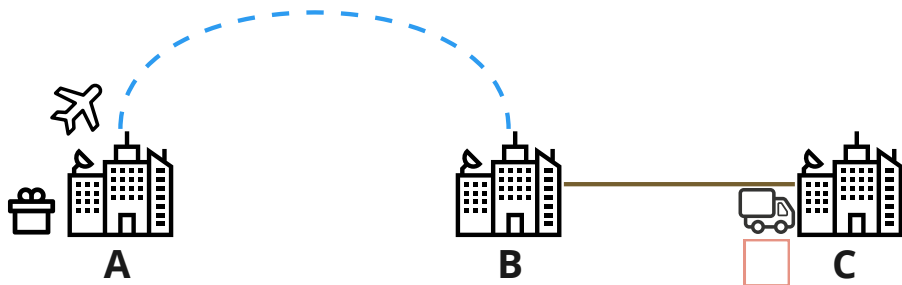
Domain definition

- *types*: location, vehicle, package, ...
- *predicates*: where is truck, where is package, is there a route between locations, ...
- *actions*:



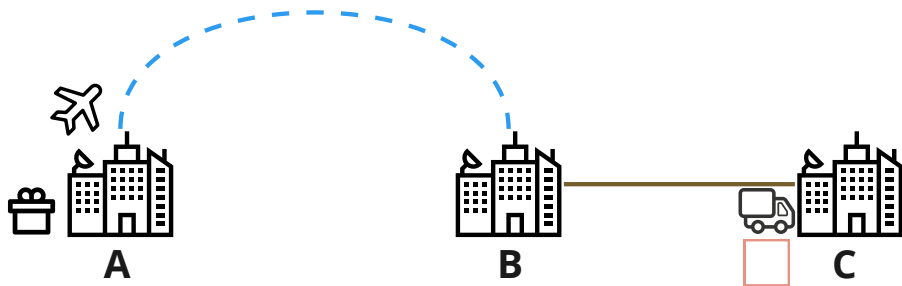
Domain definition

- *types*: location, vehicle, package, ...
- *predicates*: where is truck, where is package, is there a route between location, ...
- *actions*: load package, drive truck, ...



Action schema

- *parameters*: objects and their types
- *preconditions*: what has to hold so that action can be applied
- *effects*: what happens after we apply the action

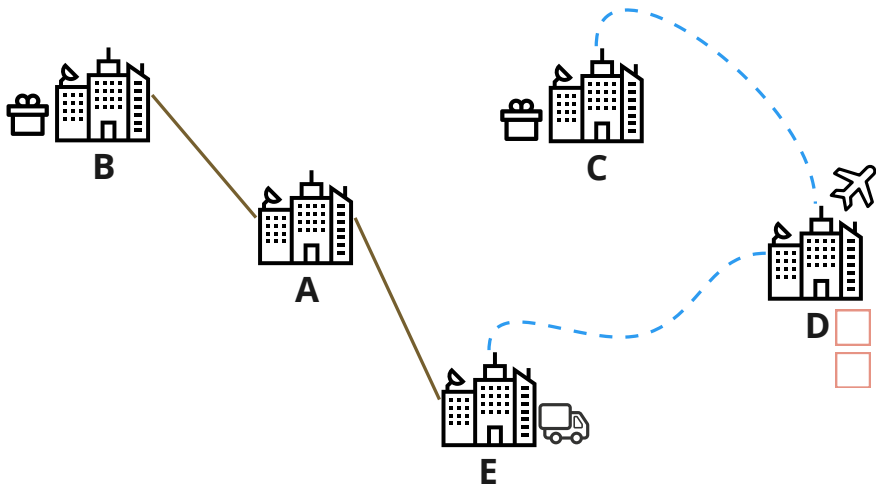


Problem definition

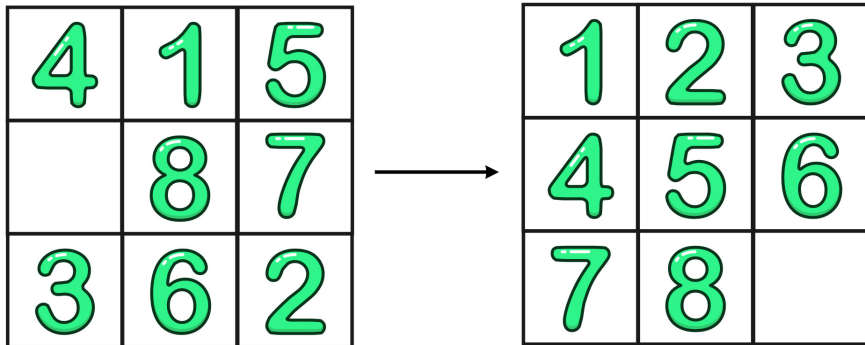
- *objects*: airplane, package, location A, ...
- *initial state*: package is at A, truck is at C, B is connected to C, ...
- *goal condition*: package is at C

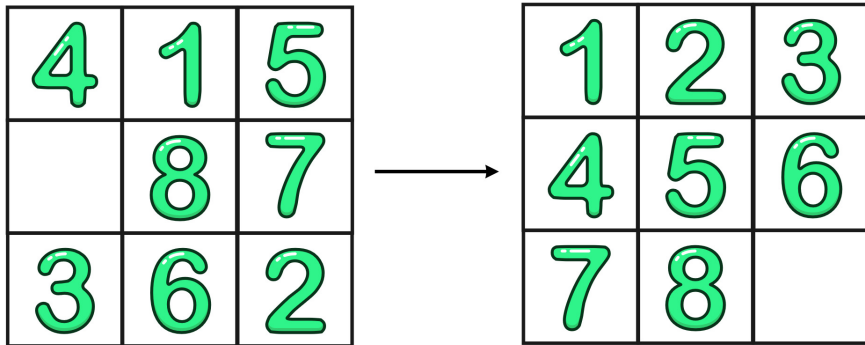
PDDL Example

Let's reuse the domain definition and solve another logistics problem.



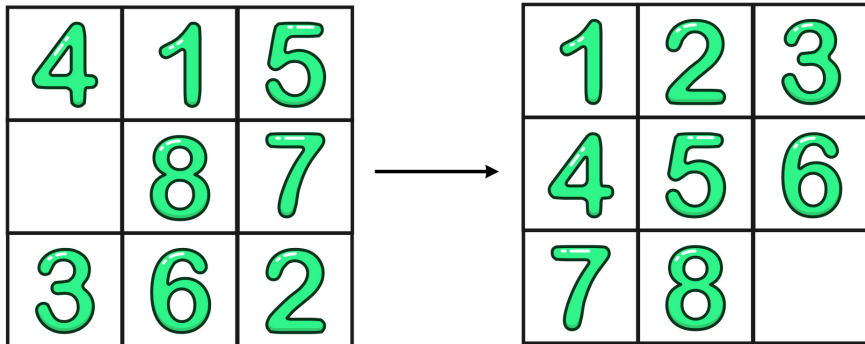
Sliding puzzle example





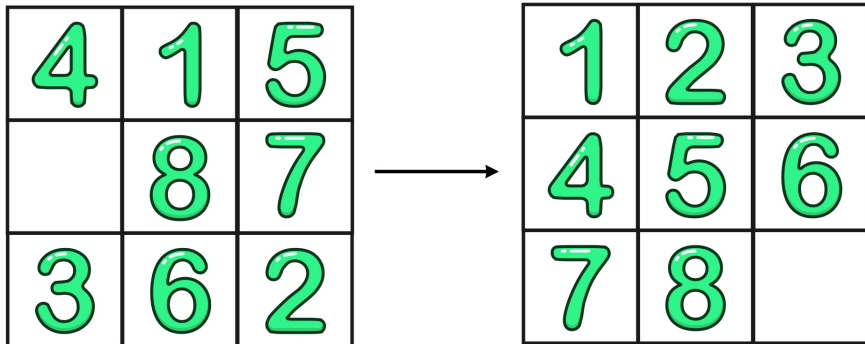
Domain definition

- *types:*
- *predicates:*
- *actions:*



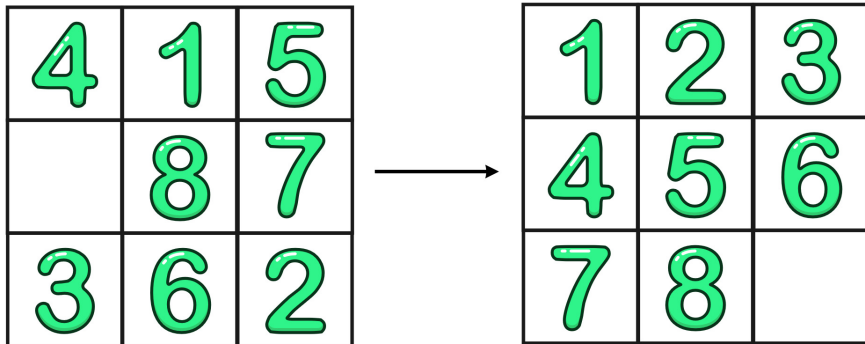
Domain definition

- *types*: tiles and numbers
- *predicates*:
- *actions*:



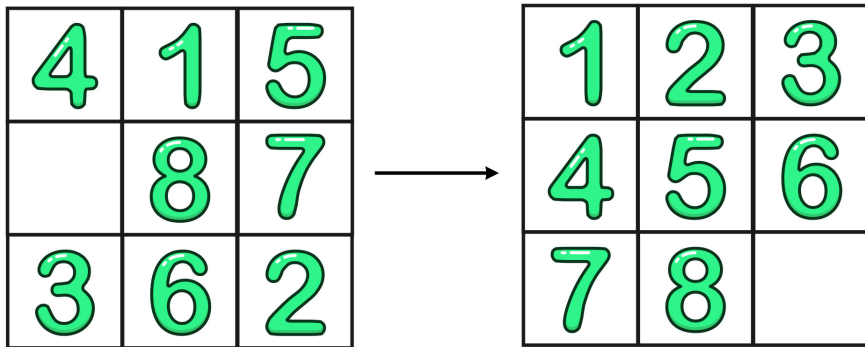
Domain definition

- *types*: tiles and numbers
- *predicates*: connection between tiles, location of numbers, ...
- *actions*:



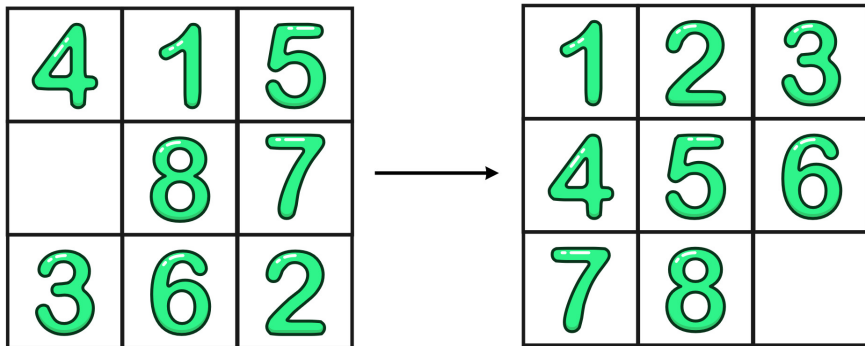
Domain definition

- *types*: tiles and numbers
- *predicates*: connection between tiles, location of numbers, ...
- *actions*: slide tile



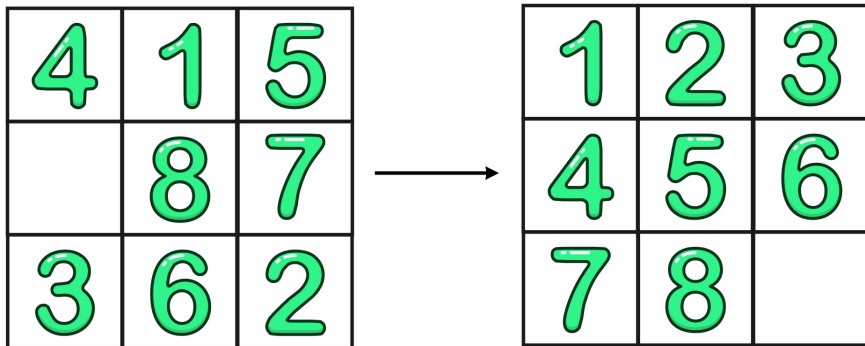
Problem definition

- *objects*: number 4, number 1, ...
- *initial state*:
- *goal condition*:



Problem definition

- *objects*: number 4, number 1, ...
- *initial state*: number 4 at top left tile, ...
- *goal condition*:



Problem definition

- *objects*: number 4, number 1, ...
- *initial state*: number 4 at top left tile, ...
- *goal condition*: number 1 at top left tile, bottom right tile empty, ...

- Many other things possible in PDDL
 - negative preconditions
(not (at ?p ?loc))
 - conditional effects
(when CONDITION EFFECT)
 - universally quantified formula
(forall (?a1 - type1 ?a2 - type2 ...) EFFECT)
 - existentially quantified formula
(exists (?a1 - type1 ?a2 - type2 ...) EFFECT)
 - action costs
(:functions (total-cost) - number); (increase (total-cost) 5) in effects

Links to information on CW






- General information about the whole Assignment #1 here
- Information about Assignment #1-1 - PDDL here

- First part of the Assignment #1
- **Task:** model given problem domain and problems in PDDL based on given descriptions and images
- **Points:** maximum 5
- **Deadlines**
 - 6.3.2023 - 23:59 (Monday)
 - 8.3.2023 - 23:59 (Wednesday)













































Grid-Mario

- Grid-based game with one agent
- Mechanics
 - Movement on the grid (4-neighborhood)
 - Pushing boxes
 - Using teleports
 - Pulling levers
 - Unlocking doors
 - Jumping on springs
- Everyone models the movement + 2 mechanics

Grid-Mario

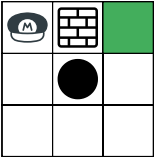
-  agent
-  wall
-  hole
-  goal
-  box

-  spring
-  key
-  lever
-  teleport
-  door

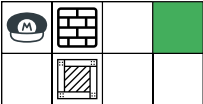
							
							
							
							
							
							
							
							

Grid-Mario

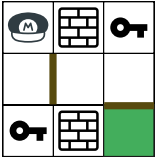
Movement



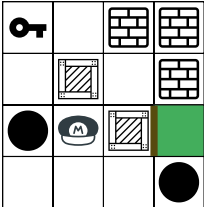
Boxes



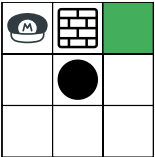
Keys



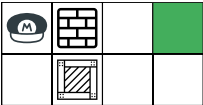
Boxes + keys



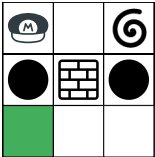
Movement



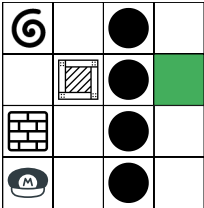
Boxes



Springs

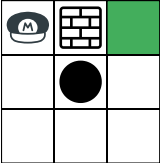


Boxes + springs

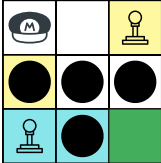


Grid-Mario

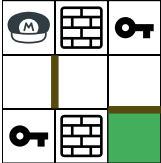
Movement



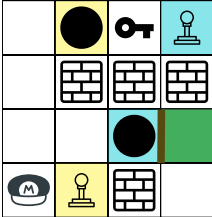
Levers



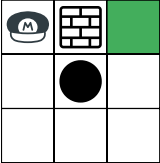
Keys



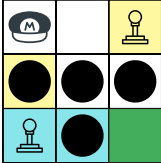
Levers + keys



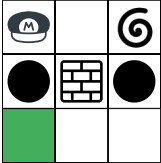
Movement



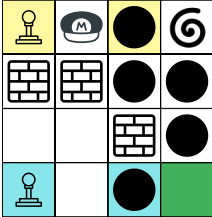
Levers



Springs

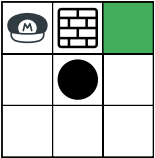


Levers + springs

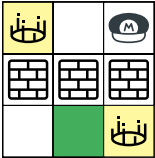


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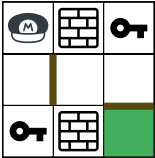
Movement



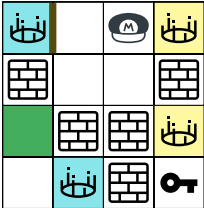
Teleports



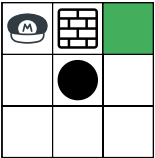
Keys



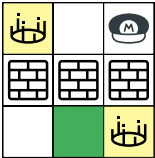
Teleports + keys



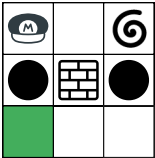
Movement



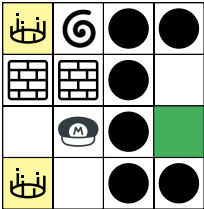
Teleports



Springs



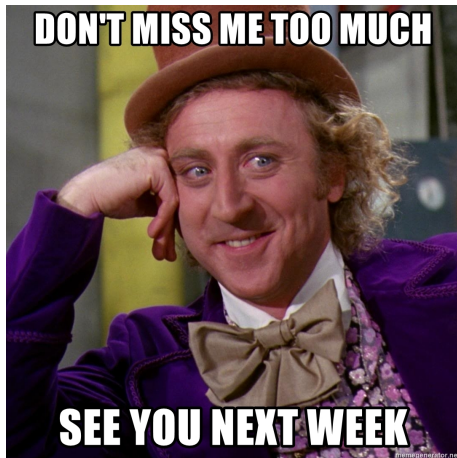
Teleports + springs



Submission

- No automatic evaluation
- Upload .zip archive to BRUTE with all PDDL files
 - domain.pddl - modeled domain
 - p01.pddl - problem instance that tests movement
 - p02.pddl - second problem instance (lever / box / teleport)
 - p03.pddl - third problem instance (keys / springs)
 - p04.pddl - last given problem instance testing all modeled mechanics
- Make sure all problems are solvable by the online editor/solver
- If anything seems unclear, please contact me

- You know motivation behind planning
- You are able to model problem and domains in PDDL
- You are able to read PDDL
- Assignment #1-1 - PDDL is assigned



Feedback form

